Application	Bridge	Inspection	Scene Investifi Develo	parment Platfo	rm Inspection Enfiro	nment Survey	ing aissance Surviv
System							
ICARUS ver 2	X	Χ	Χ	Χ	Χ	Χ	Χ
ICARUS ver 1	Х	Х	Х	Χ	Х	Х	Х
<u>ArduCopter</u>	-	-	Х	Χ	-	-	-
AR Parrot Drone	-	-	Х	Х	-	Х	-
Dragan Flyer VI	X	Х	-	Х	Х	Х	Х

Capability	Advanced Hover	Automatic Takeoff/Hover/Landing	Autonomous Navigation	Manual Control	Calibration via Test-Stand	Vehicle Health System	Collapsible Frame	Configurable Payloads	Extended Range	Extended Flight Duration	Image Capture	Obstacle Avoidance	Swarm Autonomy	Terrain Following	Audible Vehicle Status	Video Transmission	WiFi Repeater	Wireless Airborne Programming	Wireless Charging other Systems
System																			
<u>ICARUS ver 2</u>	Χ	Χ	Χ	Χ	Χ	Χ	-	F	F	F	F	F	F	F	F	F	F	F	F
ICARUS ver 1	1	Χ	Х	Χ	Χ	Χ	1	1	F	F	F	F	F	F	F	F	F	F	-
<u>ArduCopter</u>	-	Х	Χ	Х	-	-	-	-	-	-	-	Χ	-	Χ	-	-	-	-	-
AR Parrot Drone	-	-	1	Χ	-	1	-	-	-	-	1	1	-	-	1	Χ	-	-	-
Dragan Flyer VI	-	Х	1	Χ	-	Χ	Χ	Χ	Χ	-	Χ	1	-	-	1	Χ	-	-	-

Technology	COAxial F	Rotors	nd/Control Netw	ork Monitoring Navigation Unit Navigation Unit	Janagement Primary	Secondary Contr	oller implement	ation at Navigation 30 Feed	Dack Automati
System	ĺ			•	•	•	-		<u></u>
ICARUS ver 2	Х	Х	Х	Х	Х	Х	Х	F	F
ICARUS ver 1	-	Х	Х	Х	Х	-	Х	F	F
ArduCopter	-	-	Х	Х	-	-	Х	-	-
AR Parrot Drone	-	-	-	-	-	-	-	-	-
Dragan Flyer VI	Х	Х	Х	-	-	-	-	-	-

	CLanding Pad Audio Co	mmands hor	e Controlled Cellular 1	Network Data Stor	138e ote	face Matlab	groperability RCU Test	RIC Cont	tol St.
Technology	Audio	Cel-Pric	Cellular	Data St	GCS-III.	JAUS II.	RCUTE	RIC Cont	safety Sy'
System									
ICARUS ver 2	F	F	F	F	F	F	F	F	F
ICARUS ver 1	F	F	-	F	F	F	F	-	F
<u>ArduCopter</u>	-	-	-	-	-	-	-	Х	X
AR Parrot Drone	-	Х	-	-	-	-	-	-	X
<u>Dragan Flyer VI</u>	-	-	-	Х	-	-	-	-	Х

Technology	stem SATCOM	SLAW	Target	Detection Wireless
System				
ICARUS ver 2	F	F	F	F
ICARUS ver 1	-	-	F	-
<u>ArduCopter</u>	_	-	-	-
AR Parrot Drone	-	-	-	-
<u>Dragan Flyer VI</u>	_	-	-	-