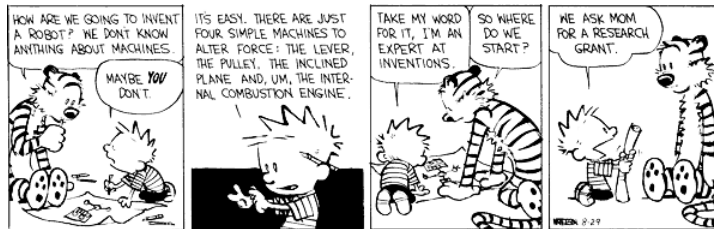


Constraint Satisfaction Problems

- CSP examples
- General search applied to CSP
- Backtracking
- Forward Checking
- Heuristics for CSPs



Constraint Satisfaction Problems (CSPs)

- Standard Search Problem:
 - State is a 'black box' – any data structure that supports goal test, evaluation, and successor
- CSP
 - State and goal test conform to a simple representation (problem specific)

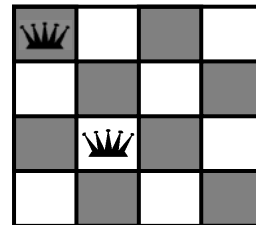
CSP

- Definition:

- Variables: X_1, X_2, \dots, X_n
- Constraints: C_1, C_2, \dots, C_m
- Each domain D_i for a variable X_i has a set of possible values $D_i = \{v_i^1, v_i^2, \dots, v_i^k\}$
- Each C_i specifies a subset of variables, and limits the combinations of values for that subset.
- A state is then an assignment of values to some or all of the variables $\{X_i = v_i^1, X_j = v_j^3, \dots\}$
- A solution is a complete assignment that satisfies all constraints
 - Sometimes an objective function must be maximized/minimized as well

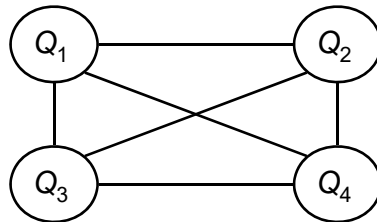
Example: 4-Queens

- Assume one queen in each column
- Which row does each go in?
 - Variables: Q_1, Q_2, Q_3, Q_4
 - Domains: $D_i = \{1, 2, 3, 4\}$
 - Constraints:
 - $Q_i \neq Q_j$ (cannot be in same row)
 - $|Q_i - Q_j| \neq |i - j|$ (or the same diagonal)
 - Translate each constraint into set of allowable values for its variables
 - E.g., values for (Q_1, Q_2) are:
 $(1, 3) (1, 4) (2, 4) (3, 1) (4, 1) (4, 2)$



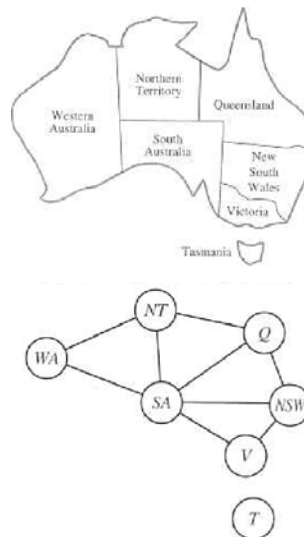
Constraint Graph

- Binary CSP - each constraint relates at most two variables, a binary constraint ($Q_2 \neq Q_4$)
- Higher order constraints can all be reduced to binary constraints with the introduction of auxiliary variables
- Constraint Graph – nodes are variables, arcs show constraints



Example: Map Coloring

- Color a map so that no adjacent territories have the same color
 - Variables:
territories C_i
 - Domains:
{Red, Green, Blue}
 - Constraints:
 $C_1 \neq C_2, C_2 \neq C_5, \dots$



Other Examples

- Assignment Problems
 - Who teaches which class
- Timetable Problems
 - Which class is offered when and where
- Hardware Configuration
- Spreadsheets
- Transportation Scheduling
- Factory Scheduling
- Floor Planning
- Note: Real world problems involve real-valued or continuous variables and sometimes preferences (represented as cost)

Applying Standard Search

- Start with straight-forward (dumb) approach
 - States are defined by the values assigned so far
 - Initial State: all variables unassigned
 - Operators: assign a value to an unassigned variable
 - Goal Test: all variables assigned, no constraints violated

Implementation

- CSP state keeps track of which variables have values
- Each variable has a domain and a current value
- Constraints may be represented
 - Explicitly – as a set of allowable values, or
 - Implicitly – by a function that tests for satisfaction
- Datatype CSP-State
 - Components: Unassigned, set of variables not assigned
Assigned, set of variables that have values
- Datatype CSP-Var
 - Components: Name, for I/O purposes
Domain, a list of possible values
Value, a current value (if any)

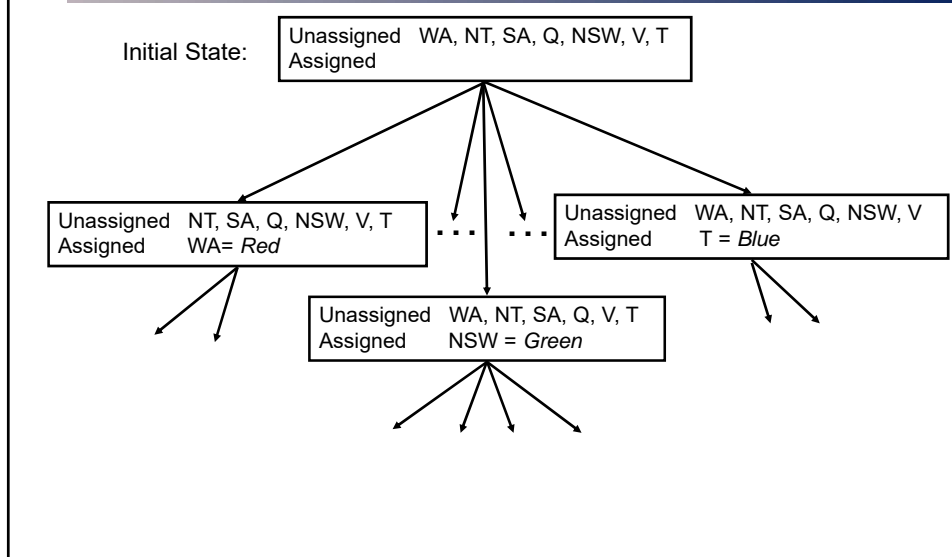
Searching for Map Coloring

Initial State:

Unassigned	WA, NT, SA, Q, NSW, V, T
Assigned	

What are the next states?

Searching for Map Coloring



Complexity of Simple Search

- Search algorithm to use?
 - Any uninformed search algorithm
- Maximum depth of space (m)
 - $m = n = |X|$
- Depth of solution space (d)
 - $d = n$
- Branching factor (b)
 - $b_0 = nd$
 - $b_1 = (n-1)d$ leaves = $n(n-1)d^2$
 - $b_2 = (n-2)d$ leaves = $n(n-1)(n-2)d^3$
 - ...
 - $n!d^n$ leaves in the tree

Making Improvements

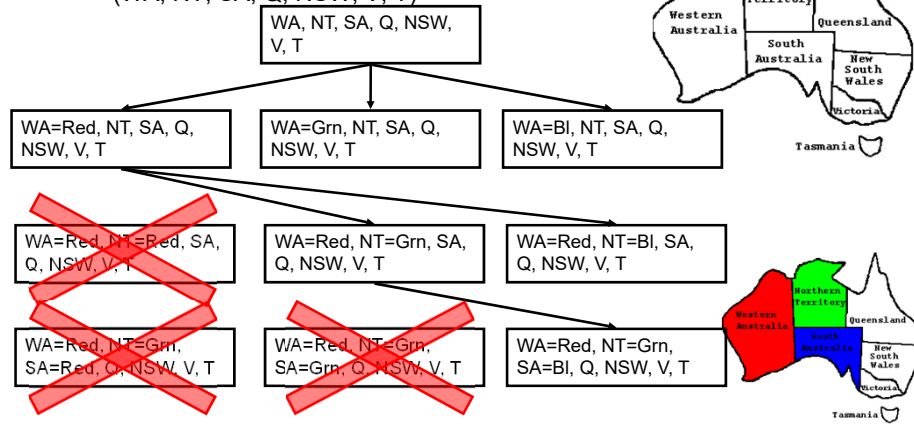
- Search for this type of problem can be improved significantly by noting
 - The order of the assignment variable assignment doesn't matter (commutative)
 - The same states appear many times in the tree
- If we want to improve this, we should enforce an ordering constraint to limit the repeated work.

Backtracking Search

- A modified depth-first search
 - Fixed order of assignment
 - Always make assignments in the same order
 - Reduces branching factor from $\sum_{i=1..n} |D_i|$ to $|D_i|$
 - Check for violated constraints
 - Don't create successors that violate a constraint
 - Don't expand a state that violates a constraint

Backtracking Search Example

- Coloring the map of Australia
 - Domain: {Red, Green, Blue}
 - Instantiate variables in order: (WA, NT, SA, Q, NSW, V, T)



Problems with Backtracking Search

- If we select the wrong branch, we can explore all possible paths even if there is no way to succeed.



- Backtracking Search is basically uninformed search for CSPs
- Can solve up to 15-Queens in a reasonable time

Forward Checking

- An additional improvement is to consider the variable constraints for selection as far in advance as possible.
 - Whenever a variable X is assigned, delete from variable Y 's domain any value inconsistent with the value chosen for X .
- Can solve up to 30-Queens in a reasonable time

Forward Checking

- Choose a color for Western Australia

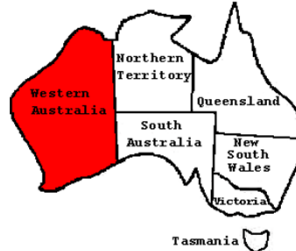
	Red	Grn	Blue
Western Australia			
Northern Territory			
South Australia			
Queensland			
New South Wales			
Victoria			
Tasmania			



Forward Checking

- Choose a color for Western Australia

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X		
South Australia	X		
Queensland			
New South Wales			
Victoria			
Tasmania			



Forward Checking

- Choose a color for the Northern Territory

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	
Queensland		X	
New South Wales			
Victoria			
Tasmania			



Forward Checking

- Choose a color for Queensland

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	X
Queensland		X	√
New South Wales			X
Victoria			
Tasmania			



Forward Checking

- Because South Australia is overconstrained, we must back up as in Backtracking Search

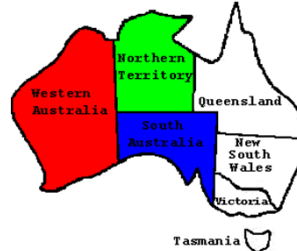
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	X
Queensland		X	√
New South Wales			X
Victoria			
Tasmania			



Forward Checking

- Choose a color for the South Australia

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland		X	X
New South Wales			X
Victoria			
Tasmania			



Help!

- Forward checking can help out some.
 - Went from solving 15-Queens to 30-Queens
- In the real-world, problems are much more complex
- The answer is?

Heuristics for CSPs

- We can make more intelligent decisions on
 - Which value to choose for each variable
 - Which variable to assign next
- Given WA = Red, NT = Green choose Q?
- Given WA = Red, NT = Green, choose what?
- Can solve n-Queens for $n = 1000$



Heuristics for CSPs

- We can make more intelligent decisions on
 - Which value to choose for each variable
 - Which variable to assign next
- Given WA = Red, NT = Green choose Q?
 - Q = Red: the least constraining value
- Given WA = Red, NT = Green, what next?
 - Select for SA: the most constrained state
- Can solve n-Queens for $n = 1000$



Heuristic Forward Checking

- Select most constrained state first, Western Australia

	Red	Grn	Blue
Western Australia			
Northern Territory			
South Australia			
Queensland			
New South Wales			
Victoria			
Tasmania			



Heuristic Forward Checking

- Choose a color for Western Australia

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X		
South Australia	X		
Queensland			
New South Wales			
Victoria			
Tasmania			



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, Northern Territory

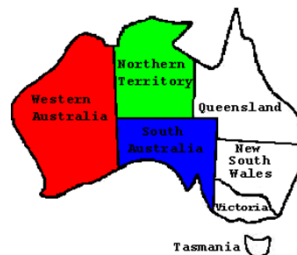
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	
Queensland		X	
New South Wales			
Victoria			
Tasmania			



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, South Australia

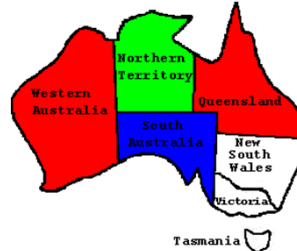
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland		X	X
New South Wales			X
Victoria			X
Tasmania			



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, Queensland

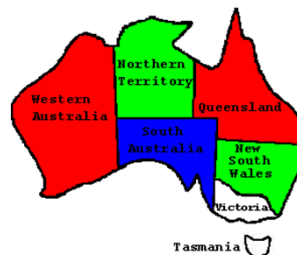
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland	√	X	X
New South Wales	X		X
Victoria			X
Tasmania			



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, New South Wales

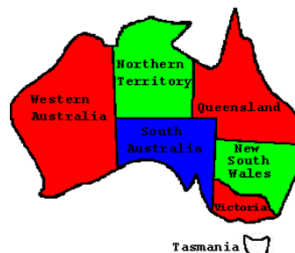
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland	√	X	X
New South Wales	X	√	X
Victoria		X	X
Tasmania			



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, Victoria

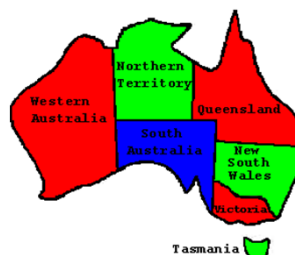
	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland	√	X	X
New South Wales	X	√	X
Victoria	√	X	X
Tasmania	X		



Heuristic Forward Checking

- Choose a color for the 'most' constrained state, Victoria

	Red	Grn	Blue
Western Australia	√	X	X
Northern Territory	X	√	X
South Australia	X	X	√
Queensland	√	X	X
New South Wales	X	√	X
Victoria	√	X	X
Tasmania	X	√	X



Search Based CSP

- Dumb search can solve CSPs but does not take advantage of knowledge of states
- Backtracking search fixes the order of expansion to prune the search
- Forward checking search attempts to prune paths that can never reach a goal state
- Heuristics such as most constrained variable or least constrained value yield dramatic improvements

Iterative Algorithms for CSPs

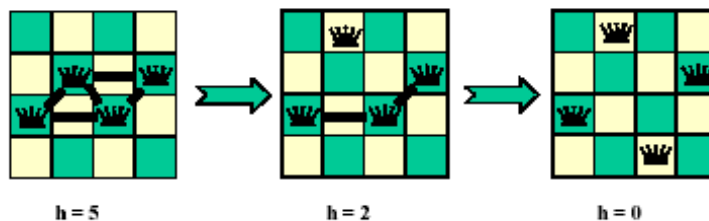
- Hill-climbing and Simulated annealing typically work with “complete” states, i.e., all variables assigned
- To apply to CSPs
 - Allow state with unsatisfied constraints
 - Operators reassign variable values
- Variable selection
 - Randomly select any conflicted variable

min-conflict Heuristic

- Choose value that violates the fewest constraints, i.e., hill-climb with
- $h(n) = \#$ violated constraints

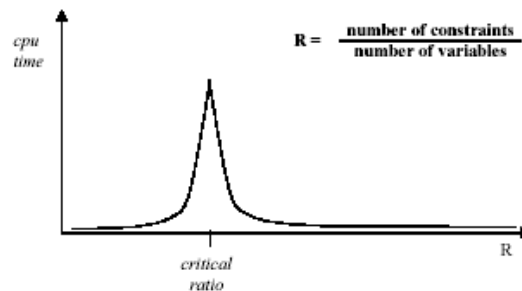
Example: 4-Queens

- States: 4 queens in 4 columns
- Operators: move queen in column
- Goal test: no attacks
- Evaluation: $h(n) =$ number of attacks



min-conflicts Performance

- Given a random initial state, can solve n -queens in almost constant time for arbitrary n with high probability
- The same appears to be true for any randomly generated CSP except in a narrow range of the ratio



CSP Summary

- CSPs are defined by
 - A set of variables V_i with values from domain D_i
 - Set of constraints specifying allowable combinations of values for subsets of variables
- Traditional search is not efficient
 - Order of assignment is irrelevant
 - Adding assignments cannot correct a violated constraint

CSP Summary

- Backtracking search is depth-first search with a fixed order of assignment that checks for violated constraints
- Forward checking tracks legal values for unassigned variables and ends when a variable has no legal values
- Heuristics make a huge improvement in speed
- Iterative algorithms can work with *min-conflict* heuristic

Next Time

- Game Playing
 - Can we use what we have learned about search to develop computer programs that beat the worlds best human players at their own game?