

# COMS21103: Maximum Flow

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\*\*New

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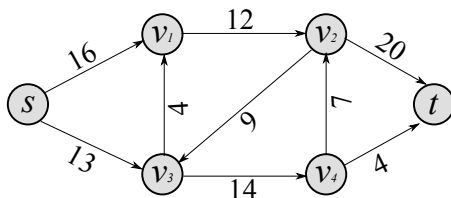
# Flow Networks

- ▶ You've previously looked at directed graphs, in order to find the shortest path from one point to another
- ▶ Directed graphs can also be interpreted as **flow networks**
- ▶ In a flow network, exactly one node is referred to as a **source**, and one node as a **sink**.
- ▶ The aim is to push the maximum amount of *material* from the source to the sink.

# Flow Network - Definitions

A *flow network*  $G = (V, E)$  is a directed graph in which each edge  $(u, v) \in E$  has a nonnegative *capacity*  $c(u, v) \geq 0$ . We distinguish two

vertices in a flow network: a **source**  $s$  and a **sink**  $t$ .

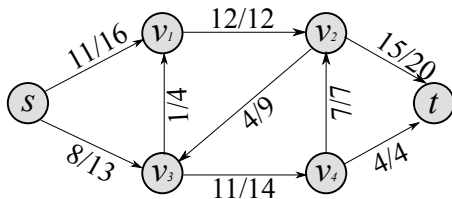


\*\* edges are removed from visualisation when  $c(u, v) = 0$

# Flow Network - Definitions

A *flow*  $f$  in the *network*  $G$  is a real-valued function  $f : V \times V \rightarrow \mathbb{R}$  that satisfies two conditions

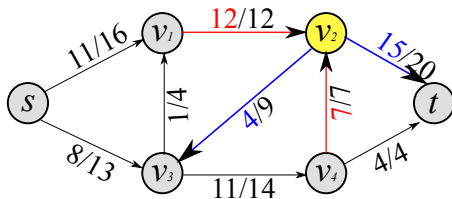
- ▶  $\forall u, v \in V \Rightarrow 0 \leq f(u, v) \leq c(u, v)$
- ▶  $\forall u \in V - \{s, t\} \Rightarrow \sum_{v \in V} f(u, v) = \sum_{v \in V} f(v, u)$



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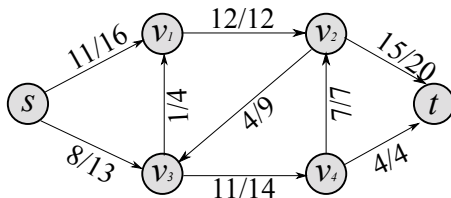
# Flow Network - Definitions

The **value**  $|f|$  of the flow function  $f$  is defined as

$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s)$$

is the total flow out of the source minus the flow into the source

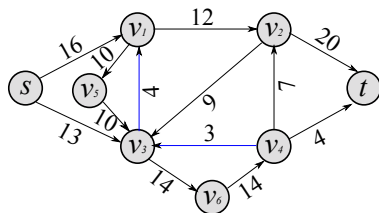
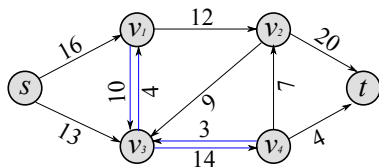
For the flow  $f$  below,  $|f| = f(s, v_1) + f(s, v_3) = 19$



# Max-Flow Problem

In the **maximum-flow problem**, we are given a flow network  $G$  with source  $s$  and sink  $t$ , and we wish to find a flow of maximum value.

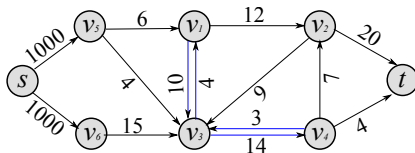
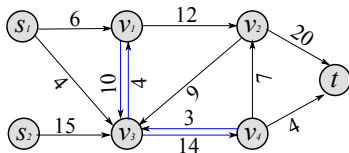
Even though the number of problems you can think of, with one source, one sink and non-antiparallel edges are limited. It is easy to re-formulate these cases as a flow network.



# Max-Flow Problem

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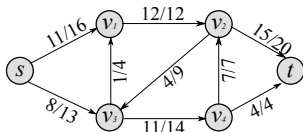
# Ford-Fulkerson Method - Definitions

Given a flow network  $G = (V, E)$  and a flow  $f$ , the **residual network** of  $G$  induced by  $f$  is  $G_f = (V, E_f)$  where

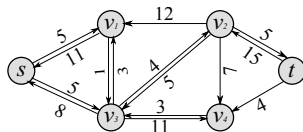
$$E_f = \{(u, v) \in V \times V : c_f(u, v) > 0\}$$

where

$$c_f(u, v) = \begin{cases} c(u, v) - f(u, v) & \text{if } (u, v) \in E \\ f(v, u) & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$



$f$



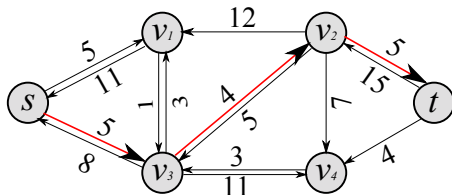
$G_f$

# Ford-Fulkerson Method - Definitions

An **augmenting path**  $p$  is a simple path from  $s$  to  $t$  in the residual network  $G_f$ .

The **residual capacity** of the augmenting path  $p$  is given by

$$c_f(p) = \min\{c_f(u, v) : (u, v) \text{ is on } p\}$$



In the example above,  $c_f(p) = \min\{5, 4, 5\} = 4$

# Ford-Fulkerson Method - Definitions

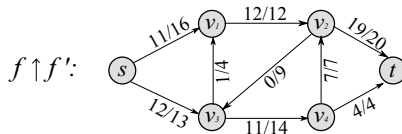
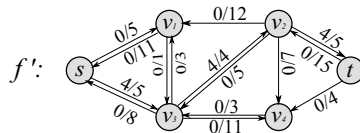
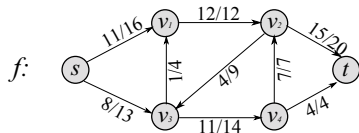
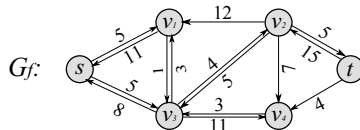
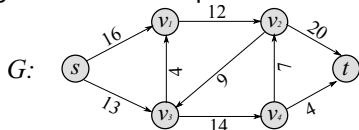
If  $f$  is a flow in  $G$  and  $f'$  is a flow in the corresponding residual network  $G_f$ , then  $f \uparrow f'$  is the **augmentation** of flow  $f$  by  $f'$  defined as:

$f \uparrow f' : V \times V \Rightarrow \mathbb{R}$  such that

$$f \uparrow f' = f(u, v) + f'(u, v) - f'(v, u)$$

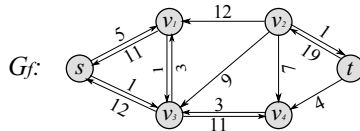
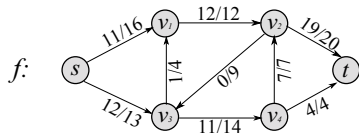
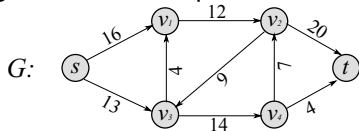
# Ford-Fulkerson Method - Definitions

Augmentation example:



# Ford-Fulkerson Method - Definitions

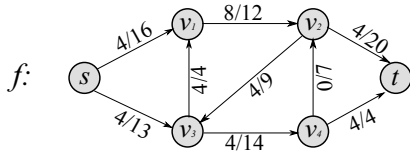
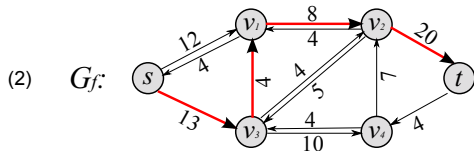
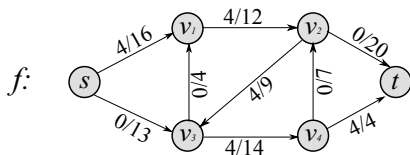
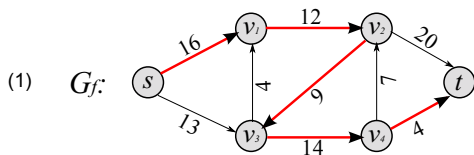
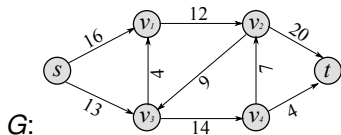
Augmentation example - continued:



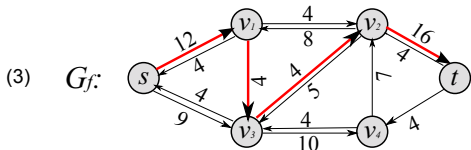
# Ford-Fulkerson Method - Basic Algorithm

```
FORD-FULKERSON-METHOD( $G, s, t$ )  
begin  
    initialise flow  $f$  to 0  
    while there exists an augmentation path  $p$  in  
        the residual network  $G_f$  do  
        augment flow  $f$  along  $p$   
    end  
end
```

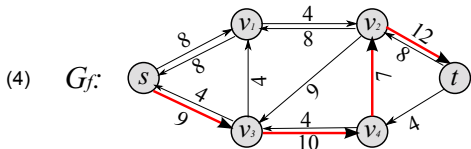
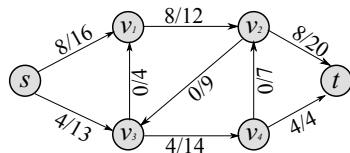
# Ford-Fulkerson Method - Example



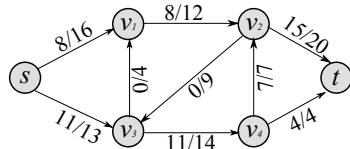
# Ford-Fulkerson Method - Example



$f$ :

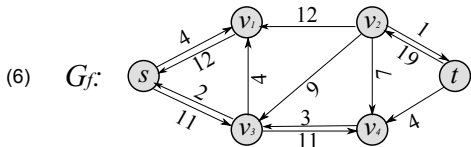
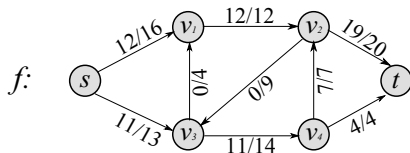
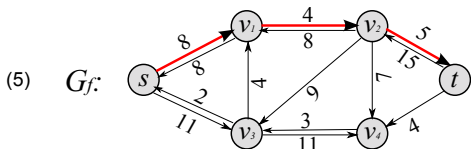


$f$ :





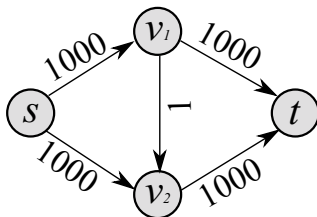
# Ford-Fulkerson Method - Example



# Basic Algorithm - Time Analysis

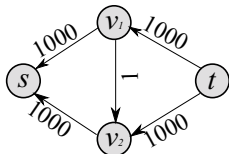
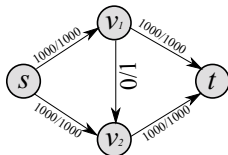
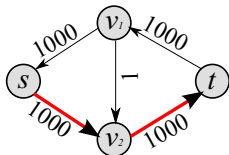
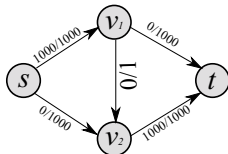
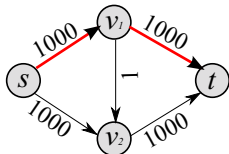
- ▶ running time depends on the order of selecting augmenting paths  $p$ .
- ▶ if we choose poorly ...

Ex.



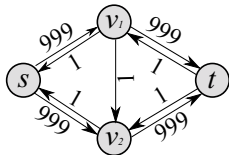
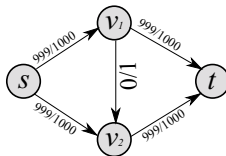
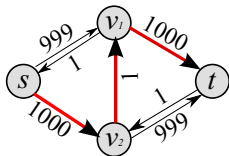
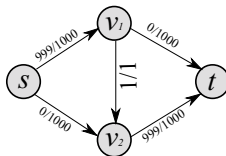
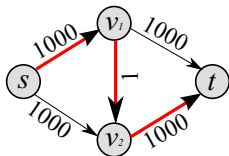
# Basic Algorithm - Time Analysis

Good Choice:



# Basic Algorithm - Time Analysis

Bad Choice:



# Basic Algorithm - Time Analysis

- ▶ running time depends on the order of selecting augmenting paths  $p$ .
- ▶ if we choose poorly...
- ▶ To prove the time bound:
  - ▶ each iteration takes  $E$  time, where  $E$  is the number of edges in the network
  - ▶ the flow network increases by at least one unit in each iteration.
  - ▶ For the max flow  $f^*$ , the maximum value  $|f^*|$  denotes a bound in the number of iterations
- ▶ The total running time is thus  $O(|f^*|E)$

# Edmonds-Karp Algorithm

- ▶ Choose the augmenting path as the *shortest path* from  $s$  to  $t$  at each step
- ▶ Let  $\delta_f(u, v)$  be the shortest-path distance from  $u$  to  $v$  in  $G_f$ , where each edge has a unit distance.

## Lemma

*For a network  $G = (V, E)$  with source  $s$  and sink  $t$ , then for all vertices  $v \in V - \{s, t\}$ , the shortest path  $\delta_f(s, v)$  in the residual network  $G_f$  increases monotonically with each flow augmentation.*

## Lemma

*If the Edmonds-Karp algorithm is run on a flow network  $G = (V, E)$  with source  $s$  and sink  $t$ , the total number of augmentations performed by the algorithm is  $O(VE)$ .*

# Edmonds-Karp Algorithm

## Proof.

- ▶ Each augmentation path has at least one critical edge that disappears from the residual network.
- ▶ If the edge  $(u, v)$  disappears, it cannot reappear until the flow from  $u$  to  $v$  is decreased.

$$\begin{aligned}\delta_{f'}(s, u) &= \delta_{f'}(s, v) + 1 \\ &\geq \delta_f(s, v) + 1 && \text{from previous lemma} \\ &= \delta_f(s, u) + 2\end{aligned}$$



# Edmonds-Karp Algorithm

## Proof.

continued..

- ▶ From the time  $(u, v)$  becomes critical, to the time it next becomes critical, the distance from  $s$  to  $u$  increases by at least 2
- ▶ Until  $u$  becomes unreachable from the source, if ever, its distance would be at most  $|V| - 2$
- ▶ After the first time, it becomes critical at most  $(|V| - 2)/2$  times.
- ▶ There are at most  $O(E)$  pairs of vertices in the residual network.
- ▶ Total number of critical edges is  $O(VE)$



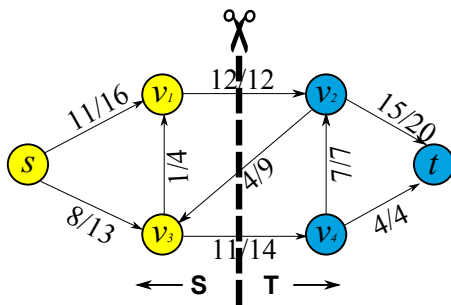


# Edmonds-Karp Algorithm

- ▶ Total number of critical edges, and thus number of iterations, is  $O(VE)$
- ▶ Each iteration runs in  $O(E)$  times
- ▶ Total running time of the Edmonds-Karp algorithm is  $O(VE^2)$

# Cuts of Flow Networks - Definition

A **cut**  $(S, T)$  of flow network  $G = (V, E)$  is a partition of vertices  $V$  into  $S$  and  $T = V - S$  such that  $s \in S$  and  $t \in T$ .



# Cuts of Flow Networks - Definition

If  $f$  is a flow, then the **net flow**  $f(S, T)$  across the cut is defined to be

$$f(S, T) = \sum_{u \in S} \sum_{v \in T} f(u, v) - \sum_{u \in S} \sum_{v \in T} f(v, u)$$

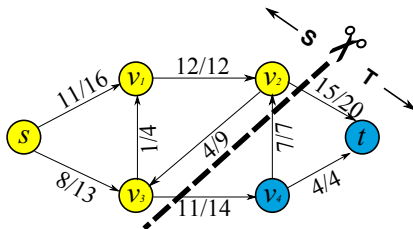
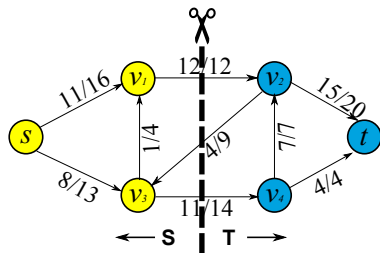
The **capacity** of the cut is

$$c(S, T) = \sum_{u \in S} \sum_{v \in T} c(u, v)$$

The **minimum cut** of a network is a cut whose capacity is minimum over all cuts of the network.

# Cuts of Flow Networks - Definition

Calculate the *net flow* and the *capacity* of these two cuts...



What do you conclude?

# Cuts of Flow Networks - Definition

## Lemma

*Let  $f$  be a flow in a flow network  $G$  with source  $s$  and sink  $t$ , and let  $(S, T)$  be any cut of  $G$ , then  $f(S, T) = |f|$*

# Cuts of Flow Networks - Definition

## Proof.

$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s) \quad (1)$$

$$= \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s) + \sum_{u \in S - \{s\}} \left( \sum_{v \in V} f(u, v) - \sum_{v \in V} f(v, u) \right) \quad (2)$$

$$= \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s) + \sum_{u \in S - \{s\}} \sum_{v \in V} f(u, v) - \sum_{u \in S - \{s\}} \sum_{v \in V} f(v, u) \quad (3)$$

$$= \sum_{v \in V} \left( f(s, v) + \sum_{u \in S - \{s\}} f(u, v) \right) - \sum_{v \in V} \left( f(v, s) + \sum_{u \in S - \{s\}} f(v, u) \right) \quad (4)$$

$$= \sum_{v \in V} \sum_{u \in S} f(u, v) - \sum_{v \in V} \sum_{u \in S} f(v, u) \quad (5)$$

$$= \sum_{v \in S} \sum_{u \in S} f(u, v) + \sum_{v \in T} \sum_{u \in S} f(u, v) - \sum_{v \in S} \sum_{u \in S} f(v, u) - \sum_{v \in T} \sum_{u \in S} f(v, u) \quad (6)$$

$$= \sum_{v \in T} \sum_{u \in S} f(u, v) - \sum_{v \in T} \sum_{u \in S} f(v, u) \quad (7)$$

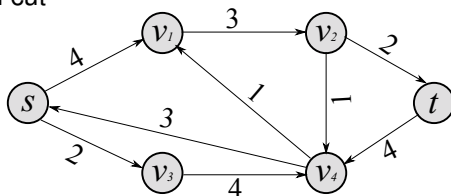
$$= f(S, T) \quad (8)$$

# Max Flow - Min Cut

## Theorem

*The value of the maximum flow is equal to the capacity of the minimum cut*

Find the minimum cut



# Application - Image Segmentation

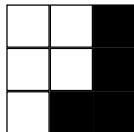
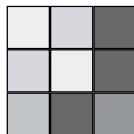
Max-Flow Min-Cut has been used for image segmentation.





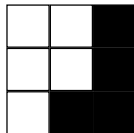
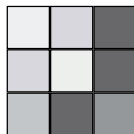
# Application - Image Segmentation

For an image of  $3 \times 3$  pixels, you aim to label each pixel as *foreground* or *background*



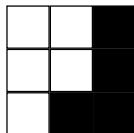
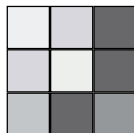
# Application - Image Segmentation

Each pixel is represented by a single node, neighbouring pixels are connected by an edge



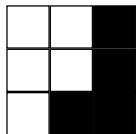
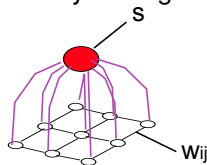
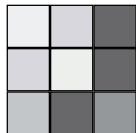
# Application - Image Segmentation

The edge weight is usually represented by the difference in colour (/intensity) between neighbouring pixels



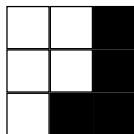
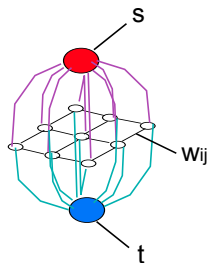
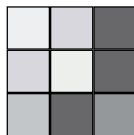
# Application - Image Segmentation

This is transformed to a network flow by adding a *source*.



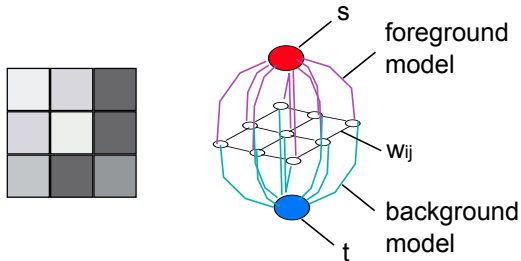
# Application - Image Segmentation

... and a *sink*.



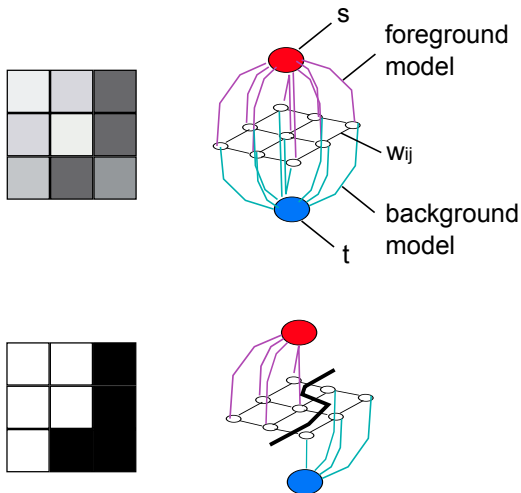
# Application - Image Segmentation

The flow from the source is represented by the foreground model and to the sink is represented by the background model



# Application - Image Segmentation

The max-flow min-cut would result in an image segmentation



# Further Reading

- ▶ **Introduction to Algorithms**

T.H. Cormen, C.E. Leiserson, R.L. Rivest and C. Stein.  
MIT Press/McGraw-Hill, ISBN: 0-262-03293-7.

- ▶ Chapter 26 – Maximum Flow

- ▶ **GrabCut: Interactive foreground extraction using iterated graph cuts**

C. Rother, V. Kolmogorov, and A. Blake.  
ACM Trans. Graph., 2004