

①

## ② unsupervised Data Augmentation (UDA)

UDA: Target model  $P(y|x)$   $P_L(x)$  // Labeled data dist  
 $P_U(x)$  // unlabeled data dist.

Perfect model  $f^*$

Supervised Augmentation:  $\hat{x} \sim q(\hat{x}|x)$

UDA: input  $x$ :  $P_\theta(y|x)$   $\xrightarrow[\text{Divergence}]{\text{minimize}}$   $D(P_\theta(y|x) \| P_\theta(y|\hat{x}, t))$   
 $P_\theta(y|x, \epsilon)$   $\xleftarrow{\text{noise}}$

quality??  
 $\hat{x} = q(x, \epsilon)$

Supervised.

Total Objective

$$\min_{\theta} \mathcal{J}(\theta) = \underbrace{E_{x_1 \sim P_L(x)} \left[ -\log P_\theta(f^*(y) | x_1) \right]}_{\text{Supervised}} + \lambda \underbrace{E_{x \sim P_U(x)} E_{\hat{x} \sim q(\hat{x}|x)} \left[ CE \left( \underbrace{P_\theta(y|x)}_{\text{fixed copy (no grad)}} \| \underbrace{P_\theta(y|\hat{x})}_{\text{updated net copy}} \right) \right]}_{\text{unsupervised}}$$

Sharpening Prediction: indicator

$$\frac{1}{|B|} \sum_{x \in B} I(\max_{y'} P_\theta(y'|x) > \beta) CE \left( \text{sharp } P_\theta(y|x) \| P_\theta(y|\hat{x}) \right)$$

$$P_\theta^{\text{sharp}}(y|x) = \frac{\exp(z_y/c)}{\sum_{y'} \exp(z_{y'}/c)}$$

logit label for  $y$