

①

P7

score metric for (a, b) word pair $S_{a,b}(x, y) = \begin{cases} \cos(\bar{a} - \bar{b}, \bar{x} - \bar{y}) & \text{if } \|\bar{x} - \bar{y}\| \leq \delta \\ 0 & \text{otherwise} \end{cases}$

Analogy

word $\vec{w} \in \mathbb{R}^d$
 $\|\vec{w}\| = 1$

seed direction (she, he)

similarity th

1st experience

Direct gender bias

Definition

$$\text{Direct-bias}_C = \frac{1}{|N|} \sum_{w \in N_{\text{set}}} |\cos(\vec{w}, g)|$$

indirect

Bias Definition

$$\beta(w, v) = \left(w \cdot v - \frac{w_{\perp} \cdot v_{\perp}}{\|w_{\perp}\|_2 \|v_{\perp}\|_2} \right) / w \cdot v$$

gender subspace top principle component

strictness

?? confused here. projection

gender neutral word

(Described in next page)

$$w_{\perp} = w - w_g \quad ; \quad v_{\perp} = v - v_g \quad \left[w_g = (w \cdot g) g \right]$$

if 0 means no projection.

$$\text{if } w_g = w \Rightarrow w_{\perp} = 0$$

$$\text{then } \beta(w, v) = 1 \quad \forall$$

unit vector

$$\beta(w, v) = 0$$

orthogonal to each other

B subspace $\{b_1, \dots, b_k\} \in \mathbb{R}^d \quad \|k=1 \Rightarrow \text{vector.}$

original vector

Debiasing Algorithm: Projection direction $\vec{v}_B = \sum_{d=1}^k (\vec{v} \cdot \vec{b}_d) \vec{b}_d$

$$\beta \text{ value} = \frac{\vec{v}^T \vec{v}_B}{\|\vec{v}_B\|} \quad // \text{orthogonal project: } \vec{v} - \vec{v}_B$$

step 1: identify gender subspace:

Defining sets $D_1, \dots, D_n \subset W$

total words

$$\text{mean of } D_i \Rightarrow \mu_i = \sum_{w \in D_i} \vec{w} / |D_i|$$

$\{\vec{w} \in \mathbb{R}^d\}$ word vector $k \geq 1$

Let Bias subspace

$$C := \sum_{i=1}^b \sum_{w \in D_i} (\vec{w} - \mu_i)^T (\vec{w} - \mu_i) / |D_i| \quad \left[\begin{array}{l} k \text{ row of SVD} \\ \text{is bias subspace } B \end{array} \right]$$

(11)

p7

Hard de-biasing: $\bar{w} := (\bar{w} - \bar{w}_B) / \|\bar{w} - \bar{w}_B\|$ // reembedding definition.
 new embedding \nearrow orthogonal projection

\therefore word to Neutralize $N \subseteq W$

got matrix earlier \checkmark
 new \rightarrow step

family/Equality set $E = \{E_1, E_2, \dots, E_m\}$ // ?? what we want equidist.

$$E_i \subseteq W$$

finally all words will have similar component in gender neutral direction

$$\mu := \sum_{w \in E} \frac{w}{|E|}$$

$$v := \mu - \mu_B \quad \text{projection to } B \quad \text{orthogonal}$$

this term varies only for words in E set

$$\text{For } \forall \underline{w \in E}; \bar{w} := \bar{v} + \frac{\bar{w}_B - \mu_B}{\|\bar{w}_B - \mu_B\|}$$

Added for the bias component differences.

output subspace B , new embedding $\{\bar{w} \in \mathbb{R}^d\}_{w \in W}$

$$(\bar{v}_B, \bar{w}_{\perp B} = w - w_B)$$

soft bias Projection: $W \in \mathbb{R}^{d \times |\text{vocab}|}$ new -

$T \rightarrow$ transformation $d \times d$

$$\min_T \left\| (T^T W)^T (T W) - W^T W \right\|_F^2 + \lambda \left\| (T^T N)^T (T B) \right\|_F^2$$

matrix size vocab vocab
 optimisation problem
 [matrix of the neural embedding words]

Measurement of indirect bias: Between two gender neutral words (w, v)

$$\text{indirect bias } \beta(\bar{w}, \bar{v}) = \frac{\bar{w}^T \bar{v}}{\bar{w}^T \bar{v}} - \frac{\bar{w}_{\perp B}^T \bar{v}_{\perp B}}{\|\bar{w}_{\perp B}\| \|\bar{v}_{\perp B}\|} \Rightarrow \text{match in gender independent direction}$$

overall match.

①

P.9

simplified version of pagerank:

$$R(u) = c \sum_{v \in B_u} \frac{R(v)}{N_v} \rightarrow \text{Number of links from } u$$

Back link of u (towards u)

Normalization.

Recursive equation.

A matrix \rightarrow page \times page big matrix. $A_{u,v} = \frac{1}{N_u}$ if edge exists.0 if no edge between u, v eigenvalue \rightarrow A vector! (bad notation) $R = \frac{1}{c} A R$ \rightarrow eigen vector of A Eigen vector of $A \rightarrow$ symmetric matrix. \downarrow
All vectors are orthogonal.

Dominant eigenvector

 \rightarrow power iteration.

Ranksource modification.

$$R'(u) = \frac{c}{m} \sum_{v \in B_u} \frac{R'(v)}{N_v} + \frac{c}{m} E(u)$$

Source rank vector.

 L_1 norm, $\|R'\|_1 = 1$, c is maximized.if $E(u) > 0$ the u is reduced.

Decay factor.

All 1's matrix

$$R' = c(A R' + E) = c(A + E \times \frac{1}{m}) R'$$

Eigenvalue of this one.

since $\|R'\|_1 = 1$

(u)

P3 $R_0 \leftarrow s$ // random ints.

loop:

 $\rightarrow R_{i+1} \leftarrow AR_i$ // power iteration (PE)(dominant)
finding eig vector for A $\rightarrow d \leftarrow \|R_i\|_1 - \|R_{i+1}\|_1$ // constrained. $\rightarrow R_{i+1} \leftarrow R_{i+1} + dE$ // little move from PE $\rightarrow \delta \leftarrow \|R_{i+1} - R_i\|_1$ increases convergence,
maintain $\|R\|_1$,
// normalize.while $\delta > \epsilon$ // convergence

P12: Recommendation problem formulation.

$C \rightarrow$ set of users (userspace, \rightarrow name, age, demogreaph, ...)

$S \rightarrow$ possible items. (name, title, producers etc)

u , utility function, usefulness between (user, item)

$u: C \times S \rightarrow R$ (rating value \rightarrow utility)

so objective, $\forall c \in C$, $s_c' = \arg \max_{s \in S} u(c, s)$

Content based filtering methods:

focus on $u(c, s_i)$ user already has rated.

\rightarrow similar to previous s_i will be recommended

Term frequency $TF_{ij} = \frac{f_{ij}}{\max_k f_{k,j}}$; f_{ij} no time k word appear in document, d_j

inverse document frequency $IDF_i = \log \frac{N}{n_i}$; $N \rightarrow$ total documents.
 $n_i \rightarrow$ k_i appeared in how many documents.

term weight of keyword k_i , in document d_j

$$w_{ij} = TF_{ij} \times IDF_i$$

for content of document d_j

for all the key words k_i

$$\text{Content}(d_j) = (w_{1j}, w_{2j}, \dots, w_{kj})$$

(11)

P12

content based profile $(c) = \{w_{c1}, w_{c2}, \dots, w_{ck}\}$ for keyword (w) in system.

The utility function $u(c, s) = \text{score}(\text{content based prof } (c), \text{Content}(s))$

$$u(c, s) = \cos(\vec{w}_c, \vec{w}_s) = \frac{\vec{w}_c \cdot \vec{w}_s}{\|\vec{w}_c\|_2 \times \|\vec{w}_s\|_2}$$

collaborative method:

$$u(c, s) \leftarrow u(c', s) ; c' \in C \text{ \& } c' \approx c$$

(similar user group)
(peer)

① memory based / Heuristic.

rating, $(r_{cs}) =$ aggregate $r_{c',s}$ // impute unknown value.
 not given but estimated \uparrow gives ratings

Agg. function can be?

$$r_{cs} = \begin{cases} \text{a) } \frac{1}{N} \sum_{c' \in C} r_{c',s} \\ \text{b) } k \sum_{c' \in C} \text{sim}(c, c') \times r_{c',s} \\ \text{c) } \bar{r}_c + k \sum_{c' \in C} \text{sim}(c, c') \times (r_{c',s} - \bar{r}_{c'}) \end{cases}$$

more like collaboration. term.

where, $k = \frac{1}{\sum_{c' \in C} |\text{sim}(c, c')|}$ (normalizing constant)

$$\bar{r}_c = \left(\frac{1}{|S_c|} \right) \sum_{s \in S_c} r_{cs} \quad \text{where } S_c = \{s \in S \mid r_{c,s} \neq \emptyset\}$$

(Average rating)

(11)

P12

Pearson coefficient based similarity

$$\text{sim}(x, y) = \frac{\sum_{s \in S_{xy}} (\hat{r}_{x,s} - \bar{r}_x) (\hat{r}_{y,s} - \bar{r}_y)}{\sqrt{\sum_{s \in S_{xy}} (\hat{r}_{x,s} - \bar{r}_x)^2 \sum_{s \in S_{xy}} (\hat{r}_{y,s} - \bar{r}_y)^2}}$$

Iterate over (s) item

Alternatively, Cosine based similarity.
for each item (s)

(ii) model based Algorithm:

$$\hat{r}_{c,s} = E(\pi_{c,s}) = \sum_{i=0}^n i \times \Pr(\pi_{c,s} = i) \quad \hat{r}_{c,s'}, s' \in S_c$$

①

P 13 selected dimensionality f :

$q_i \in \mathbb{R}^f$ // item

$p_u \in \mathbb{R}^f$ // user.

interaction between user u & item i

the approx. rating $\hat{r}_{ui} = q_i^T p_u$ — ①

how to get it?

SVD? but empty elements??

imputation \rightarrow bad idea.

So, optimization problem:

$$\min_{p, q} \sum_{(u,i) \in K} (r_{ui} - q_i^T p_u)^2 + \lambda (\|q_i\|^2 + \|p_u\|^2) \quad \text{--- ②}$$

set of given training set (previously observed)
(explicitly feedback points)

Learning methods

① SGD

$$e_{ui} := r_{ui} - q_i^T p_u$$

$$q_i \leftarrow q_i + \delta (e_{ui} \cdot p_u - \lambda q_i) \quad \text{// Gradient descent}$$

δ is changed by internal calculation

$$p_u \leftarrow p_u + \delta (e_{ui} \cdot q_i - \lambda p_u) \quad \text{// fact}$$

②

Alternate // ALS

to solve nonconvexity \rightarrow fix one, and solve for the other.

(11)

P 13existence of product/user bias.

modify eq (1) by $\boxed{b_{ui} = \mu + b_i + b_u}$

So, $r_{ui} = \underbrace{\mu + b_i + b_u}_{\text{overall rating}} + q_i^T p_u \quad \text{--- (iv)}$

Now the optimization problem changes to,

$$\min_{p, q, b} \sum_{(u,i) \in K} (r_{ui} - \mu - b_i - q_i^T p_u)^2 + \lambda (\|p_u\|^2 + \|q_i\|^2 + b_u^2 + b_i^2) \quad \text{--- (v)}$$

// may bias the model.

Additional input source: cold start overcome. $N(u)$ + implicit preference on items by the users.

$$\boxed{x_i \in \mathbb{R}^f} \quad // \text{ item association}$$

$$\sum_{i \in N(u)} x_i \quad // \text{ sum of implicit preference}$$

Normalization $\Rightarrow \frac{1}{|N(u)|^{0.5}} \sum_{i \in N(u)} x_i^{4.5} \quad // \text{ empirical.}$

user Attributes $\rightarrow A(u)$ set $\Rightarrow \boxed{y_a \in \mathbb{R}^f}$ ^{associated} factors to the attributes.
elements.

Now overall: $r_{ui} = \mu + b_i + b_u + q_i^T \left[p_u + \frac{1}{|N(u)|^{0.5}} \sum_{i \in N(u)} x_i + \sum_{a \in A(u)} y_a \right] \quad \text{--- (6)}$

two extra terms.

(11)

P13

Temporal dynamics:

including time $\hat{r}_{ui}(t) = \underbrace{\mu}_{\text{static}} + \underbrace{b_i(t)}_{\text{item bias}} + \underbrace{b_u(t)}_{\text{user bias}} + \underbrace{q_i^T p_u(t)}_{\text{static} \rightarrow \text{human behavior dynamics}}$

input with confidence level:

$$\min_{p, q, b} \sum_{(i, u) \in K} c_{ui} (\underbrace{r_{ui}}_{\substack{\updownarrow \\ \text{modified} \\ \text{confidence term}}} - \mu - b_u - b_i - p_u^T q_i)^2 + \lambda (\|p_u\|^2 + \|q_i\|^2 + b_u^2 + b_i^2)$$

(Variational Lower bound)

$z \rightarrow x$
 $p(x) \rightarrow$ Prob dist. over variable
 $p(x) \rightarrow$ pdf of distribution x
 Latent observed.

Posterior
$$P(z|x) = \frac{P(x|z) P(z)}{\int_z P(x|z) P(z)}$$

Derivation 1: $\log p(x) = \log \int_z p(x, z)$ / (-) of information $p(x)$ value

(-) or 0 max. $= \log \int_z p(x, z) \frac{q(z)}{p(z)} dz$

$L = \mathbb{E}_q[\log p(x|z)]$
 $-KL[q(z)||p(z)]$ ELBO

$\geq \mathbb{E}_q[\log \frac{p(x, z)}{q(z)}]$ "Jensen's inequality"

$= \mathbb{E}_q[\log p(x, z)] + H(z)$ // entropy def.

Negative > 1 / is overall (-)
 Always else $p(x) = 0$: no info.

Interpret: (-) of information $>$ ELBO // reverse it - (interesting)
 No more info than $-|ELBO|$ in $p(x)$
 \Rightarrow more info than $|ELBO|$

Derivation 2: $KL(q(z)||p(z|x)) = \int q(z) \log \frac{q(z)}{p(z|x)} dz$

(Backward KL)??

$= -L + \log p(x)$ // easy $p(z|x) = \frac{p(x, z)}{p(x)}$

// missed margin of $q(z)$
 to estimate $p(z|x)$
 (failed) if large
 got L $p(x)$

fixed \uparrow
 $\therefore \log p(x) = L + KL(q(z)||p(z|x)) > 0$

Interpretation:

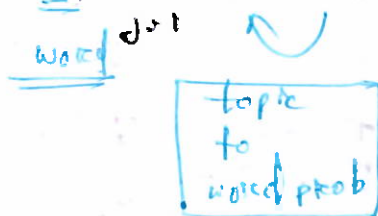
if 0 then $L = \log p(x)$

By making elbo highest means $q(z) \approx p(z|x)$

successful posterior estimation.

P15

$$P(w_i) = \sum_{j=1}^T P(w_i | z_i = j) P(z_i = j) \quad // \text{model itself}$$



No. document $\rightarrow D$
No. of topic $\rightarrow T$

(Distribution over Dist.)

(Multinomial probs are also from Dist.)
↓
Dirichlet (conjugate prior)

D documents, T topics b W unique words.

$$P(w | z = j) = \phi_w^{(j)} \quad // \text{multinomial distribution (T of them)}$$

$$P(z = j) = \theta_j^{(d)} \quad // \text{multinomial (document to topic)}$$

Now the objective

$$\text{Maximize } P(w | \theta, \phi)$$

modified objective for dirichlet distribution.

LDA

$$\max_{\theta, \phi} P(w | \theta, \phi) = \int P(w | \phi, \theta) P(\theta | \alpha) d\alpha \quad // \text{But intractable??}$$

dirichlet parameter α (as conjugate prior for multinomial)
determined by variation bayes / Expectation propagation.

The complete model (Gibbs sampling usage opportunity)

$$\left\{ \begin{array}{ll} w_i | z_i, \phi^{z_i} \sim \text{discrete}(\phi^{z_i}) & // \text{from earlier} \\ \phi \sim \text{Dir}(\beta) & // \text{new [conjugate prior]} \\ z_i | \theta^{d_i} \sim \text{Discrete}(\theta^{d_i}) & // \text{earlier} \\ \theta \sim \text{Dir}(\alpha) & // \text{new [conjugate prior]} \end{array} \right.$$

α, β hyperparameter.

(11)

p15

By integrating w.r.t. $\theta, \beta, \Rightarrow P(w, z)$

$$P(w, z) = P(w|z) P(z)$$

where,

$$P(w|z) = \left(\frac{\Gamma(w\beta)}{\Gamma(\beta)^w} \right)^T \prod_{j=1}^T \frac{\pi_w \Gamma(n_j^{(w)} + \beta)}{\Gamma(n_j^{(w)} + w\beta)}$$

Annotations:
 - j topics
 - π_w no. time
 - Γ Gamma function.
 - $n_j^{(w)}$ word w j topic (Assign)
 - β // see wiki multinomial approx.
 - (2)

$$\Gamma(z) = \int_0^\infty x^{z-1} e^{-x} dx$$

Similarly,

$$P(z) = \left(\frac{\Gamma(T\alpha)}{\Gamma(\alpha)^T} \right)^D \prod_{d=1}^D \frac{\pi_d \Gamma(n_d^{(d)} + \alpha)}{\Gamma(n_d^{(d)} + T\alpha)}$$

Annotations:
 - d no. of time
 - π_d word w from doc d j topic (Assign)
 - $n_d^{(d)}$ distinct from early.
 - (3)

$$\Rightarrow P(z|w) = \frac{P(w, z)}{\sum_z P(w, z)}$$

Annotations:
 - Again Intractable T^n terms
 - So require Approximation

↓
 solve it by MCMC (Gibbs Sampling).

require $P(z_i | z_{-i}, w)$

using the earlier (2) and (3) we get. (by cancellation)

$$P(z_i | z_{-i}, w) \propto \frac{\pi_{w_i} \Gamma(n_{-i,j}^{(w_i)} + \beta)}{\Gamma(n_{-i,j}^{(w_i)} + w\beta)} \cdot \frac{\pi_{d_i} \Gamma(n_{-i,j}^{(d_i)} + \alpha)}{\Gamma(n_{-i,j}^{(d_i)} + T\alpha)}$$

Annotations:
 - π_{w_i} prob of w_i under topic j
 - $n_{-i,j}^{(w_i)}$ \rightarrow not include current assignment (z_i)
 - π_{d_i} prob of topic j in document d_i
 - $n_{-i,j}^{(d_i)}$ just need counter

(11)

P15: for single sample: (using just count)

$$\hat{\phi}_j^{(w)} = \frac{n_j^{(w)} + \beta}{n_j^{(w)} + \beta}$$

// for new word w
and new topic z .

$$\hat{\theta}_j^{(d)} = \frac{n_j^{(d)} + \alpha}{n_j^{(d)} + T\alpha}$$

Solved by Gibbs Sampling

Alternates: Variational bayes (?), Expectation propagation (?)

Total hyperparameters: $\alpha, \beta, T \rightarrow$ (varied across)

(fixed it in experiment) \downarrow Topic Number ??

This is model selection?

Target: $P(w|T)$ \uparrow topic Number.
 \downarrow All words
 Approximated by $P(w|z, T) \Rightarrow P(z|w, T)$ posterior

P16

Expected value.

$$\tilde{P}(f) = \sum_{x,y} \tilde{P}(x,y) f(x,y) \quad \text{Empirical} \quad \text{①} \quad \frac{1}{n} \times \text{no of times } (x,y) \text{ appears. (training data)}$$

training data

calculate from data.

$\tilde{P}(x) \sim x$

$\tilde{P}(y|x)$ given

$f(x,y) = P(f)$ indicator function

feature function

we require $\tilde{P}(f) = P(f)$

train model (training data)

(empirical of x)

Explicitly, $\sum_{x,y} \tilde{P}(x) P(y|x) f(x,y) = \sum_{x,y} \tilde{P}(x,y) f(x,y)$

model training data

constraint equation

Key goal

$$\mathcal{C} = \{ P \in \mathcal{P} \mid P(f_i) = \tilde{P}(f_i) \text{ for } i = 1, \dots, n \}$$

Entropy: $H(x) = - \sum_x P(x) \log \left(\frac{1}{P(x)} \right)$

Fig 1

Conditional Entropy, $H(P) = - \sum_{x,y} \tilde{P}(x) P(y|x) \log P(y|x) \geq 0$

All the 2 possible data prob

model

lower bound

sure model

(set of probabilities distribution) $H(P)$

Maximum Entropy: $P_* \in \mathcal{C}$ satisfy $\tilde{P}(f) = P(f)$

train model

uniform case

upper bound.

uniform case entropy.

log 1/y

cardinality of y

well defined & unique.

\Rightarrow To select a model from a set of prob. distributions, that has maximum entropy.

Parametric Form:

find P_* - $\arg \max_{P \in \mathcal{C}} H(P)$ primal optimization.

Lagrangian $\Lambda(P, \lambda) = H(P) + \sum_i \lambda_i (P(f_i) - \tilde{P}(f_i))$

training (ground truth)

Now, $P_\lambda = \arg \max_{P \in \mathcal{P}} \Lambda(P, \lambda)$

(model)

$\Psi = \Lambda(P_\lambda, \lambda)$ // max value // dual function.

P 15

solving, $\underbrace{p_\lambda(y|x)}_{\text{model}} = \frac{1}{Z_\lambda(x)} \underbrace{\exp \left(\sum_i \lambda_i f_i(x, y) \right)}_{\substack{\text{normalization} \\ \text{w.r.t. } y}}$ ↑ unknown (solved later) λ^*

$\Psi(\lambda) = - \sum_x \tilde{p}(x) \log Z_\lambda(x) + \sum_i \lambda_i \tilde{p}(f_i)$

Dual optimization find $\lambda^* = \underset{\lambda}{\operatorname{argmax}} \Psi(\lambda)$ // maximize

$\lambda^* \rightarrow$ parametric form

Relation to maximum likelihood: Training data.

$$L_P(P) = \log \prod_{x,y} \underbrace{P(y|x)}_{\text{model}}^{\tilde{p}(x,y)} = \sum_{x,y} \tilde{p}(x,y) \log P(y|x)$$

By definition, $\Psi(\lambda) = L_P(P_\lambda)$ // see earlier section.

$P^* \in \mathcal{C}$ with maximized entropy is parametric model from $\underbrace{P_\lambda(y|x)}_{\text{family}}$ that maximize the likelihood of training sample \tilde{p}

Table 1 Summary

Compute the Params: ① $f_i(x, y) \geq 0$

Algo: Input Iterative Scaling.

input: $f_1, \dots, f_n \rightarrow$ empirical $\tilde{p}(x, y)$

output: λ_i^* , P_λ

1. $\lambda_i = 0$ ($i = 1 \dots n$)

2. $i \in \{1 \dots n\}$

See the algorithm

①

P19

$x_i \in \mathbb{R}^n$; $i = 1, \dots, L$ observations. \rightarrow ex. $y_i \in \{1, -1\}$

$f(x, \alpha) \rightarrow$ approximation

Expectation of test error.

parameter

$$R(\alpha) = \int \frac{1}{2} |y - f(x, \alpha)| dP(x, y) \quad // \text{true}$$

$$R_{\text{emp}}(\alpha) = \frac{1}{2L} \sum_{i=1}^L |y_i - f(x_i, \alpha)| \quad // \text{Approximation}$$

vc confidence

Connection between them

Vapnik, 1995

$$R(\alpha) \leq R_{\text{emp}}(\alpha) + \sqrt{\left(\frac{h(\log(2L/h) + 1) - \log(n/4)}{L} \right)}$$

Here, $0 \leq \eta \leq 1$; with prob $(1 - \eta)$ holds.

$L \rightarrow$ example

$h \rightarrow$ vc dimension.

$n \uparrow$
 $h \downarrow$ we want
 $L \uparrow$

set to minimize this bound

[vc confidence lower \rightarrow the better] (may overfit)

The vc dimension: increases function capacity \uparrow confidence boundary (higher is Bad)

∞ infinite vc dimension $f(x, \alpha) = \theta(\sin(\alpha x))$, $x, \alpha \in \mathbb{R}$

$$x_i = w^{-i}$$

y_i -- Assign anything.

$$\alpha = \pi \left(1 + \sum_{i=1}^L \frac{(1 - y_i) w^i}{2} \right)$$

true Approximate

vc dimension $\neq \infty$

shattering depends on choice of points.

choose points that can be shattered.

Separable Case

① satisfying hyperplane: $\underline{w} \cdot \underline{x} + b = 0$ (HP)
 & Linear \nearrow
 normal to HP.
 projection to HP = $-\underline{b}$
 bias
 (All points projected as $-b$ amount)
 (nice)

Separable cases
 $\left\{ \begin{array}{l} x_i \cdot \underline{w} + b \geq 1 ; \text{ overshoot in projection } y_i = +1 \\ x_i \cdot \underline{w} + b \leq -1 ; y_i = -1 \end{array} \right.$

$$\Rightarrow y_i (x_i \cdot \underline{w} + b) - 1 \geq 0 \quad \forall$$

introducing lagrangian $\alpha_i, i=1 \dots d$; $\alpha_i \geq 0$
 multiply & add all.

$$L_P = \frac{1}{2} \|\underline{w}\|^2 - \sum_{i=1}^L \alpha_i y_i (x_i \cdot \underline{w} + b) + \sum_{i=1}^L \alpha_i$$

primal problem.

$$\left\{ \begin{array}{l} \underline{w} = \sum_i \alpha_i y_i x_i \quad // \text{ solution.} \\ \sum \alpha_i y_i = 0 \end{array} \right.$$

Now the dual problem.

putting values \hookrightarrow

$$L_D = \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j (\underline{x}_i \cdot \underline{x}_j)$$

// dual formulation
kernel idea.

use $K(\underline{x}_i, \underline{x}_j)$ in nonlinear case

KKT condition:

$$\frac{\partial}{\partial \underline{w}_0} L_P = \underline{w}_0 - \sum_i \alpha_i y_i x_i = 0 \quad ; i=1 \dots d$$

$$\frac{\partial}{\partial b} L_P = y_i (\underline{x}_i \cdot \underline{w} + b) - 1 \geq 0 \quad ; \sum_i \alpha_i y_i = 0$$

$$y_i (\underline{w} \cdot \underline{x}_i + b) - 1 \geq 0 \quad i=1 \dots d$$

$$\alpha_i \geq 0 \quad \forall i$$

$$\alpha_i (y_i (\underline{w} \cdot \underline{x}_i + b) - 1) = 0 \quad \forall i$$

(if separable)

P19 Non linear SVM:

$\phi: \mathbb{R}^d \rightarrow \mathcal{H}$ Higher dimension Projection.

$$K(\underline{x}_i, \underline{x}_j) = \phi(\underline{x}_i) \cdot \phi(\underline{x}_j)$$

need \mathcal{H} of $|\mathcal{H}|$ dimensional??

How to use the kernel??

→ we just need dot product.

test phase → $f(x) = \sum_{i=1}^{N_S} \alpha_i y_i \phi(\underline{s}_i) \cdot \phi(x) = \sum_{i=1}^{N_S} \alpha_i y_i \underbrace{K(\underline{s}_i, x)}_{\text{only need this}} + b$

using the train data
No of support vector

mercer's Condition:- $(\mathcal{H}, \phi)(d \rightarrow \mathcal{H})$

$\checkmark K(\underline{x}, \underline{y}) = \sum_i \phi(\underline{x})_i \phi(\underline{y})_i$ mapping exists

if $\forall g(x) \geq 0$ that satisfy.

$\int g(x)^2 dx$ is finite.

then

$\int K(\underline{x}, \underline{y}) g(\underline{x}) g(\underline{y}) d\underline{x} d\underline{y} \geq 0 \Rightarrow \text{Positive Semidefinite (PSD)}$

open Question: How to formulate ϕ ?

since VC dimension is $|\mathcal{H}| + 1$ // in this case

so $|\mathcal{H}| \uparrow$ bad generalize.

Radial basis kernel:

$K(\underline{x}, \underline{y}) = e^{-\|\underline{x} - \underline{y}\|^2 / 2\sigma^2}$ // maybe infinite VC Dimension.

→ two layer sigmoid NN.

(generalize
n vs 1 classifier)

1. Layer I N_S weights each d_1 dimensional

2. Layer II N_S weights (α_i)

finally Sigmoid.

(iii)

F19

Nonseparable Case:

may cause

error

$$\underline{x}_i^T \underline{w} + b \geq 1 - \underline{\epsilon}_i \quad ; \quad y_i = +1$$

$$\underline{x}_i^T \underline{w} + b \leq -1 + \underline{\epsilon}_i \quad ; \quad y_i = -1$$

$$\epsilon_i \geq 0 \quad \forall i$$

if any $\epsilon_i > 1$ error occurs.

$\sum_i \epsilon_i$ = upper bound of training error.

Dual problem) $L_D = \sum_i \alpha_i - \frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j \underline{x}_i^T \underline{x}_j$

Subject to: $0 \leq \alpha_i \leq C$ → use parameter.
 $\sum \alpha_i y_i = 0$ (higher penalty to error)

Solution is $\underline{w} = \sum_{i=1}^{N_S} \alpha_i y_i \underline{x}_i$

skip gram model maximize $\frac{1}{T} \sum_{t=1}^T \sum_{\substack{-c \leq j \leq c \\ j \neq 0}} \log P(w_{t+j} | w_t)$
 sequence of words $\{w_1, w_2, \dots, w_T\}$

So, maximizing $P(w_{t+j} | w_t)$ is

defined as $P(w_o | w_I) = \frac{\exp(v_{w_o}^T v_{w_I})}{\sum_w \exp(v_w^T v_{w_I})}$
 $\begin{cases} c \uparrow \\ \text{training time} \uparrow \\ \text{Accuracy} \uparrow \end{cases}$

$\begin{cases} v_{w_o} = \text{output vector reps.} \\ v_{w_o} = \text{input vector reps} \end{cases}$ $w=1$
 \rightarrow All the words ?? [huge computation]
 v_{w_o} - vector representation of w_o (via Network)

$w \rightarrow$ huge size !!

Each word has two reps
 \rightarrow input v_w
 \rightarrow output v_w'

Hierarchical Softmax: Need $\log w$ nodes.

$$P(w | w_I) = \prod_{j=1}^{L(w)-1} \sigma \left(\left[n(w_j, d) = 1 \right] v_{n(w_j, d)}^T v_{w_I} \right)$$

$\begin{cases} 1 \text{ if true, else } 0 \end{cases}$

\rightarrow care about input/output representation. [computation $\propto L(w)$]

Negative Sampling should be high (interesting)

NEG objective: $\log \sigma(v_{w_o}^T v_{w_I}) + \sum_{i=1}^K E_{w_i \sim P_n(w)} [\log \sigma(-v_{w_i}^T v_{w_I})]$

\Downarrow row of matrix positive
 \uparrow $w_i \sim P_n(w)$ different choices
 \rightarrow negative word how (neg)
 \Downarrow should be low & negative

$$\sigma(x) = \frac{1}{1 + \exp(-x)}$$

// modified NCE

subsampling of freq words.

Discarding prob

$$P(w_i) = 1 - \sqrt{\frac{t}{f(w_i)}}$$

word frequency.

// Discarding prob.

✓ $f(w_i) \uparrow$ $P(w_i) \uparrow$

✓ $f(w_i) \downarrow$ $P(w_i) \downarrow$

(High freq words discarded more)

Balance between rare & frequent words.

Bigram skip:

(Phrase selection)

score(w_i, w_j) =

$$\frac{\text{count}(w_i, w_j) - \delta}{\underbrace{\text{count}(w_i)}_{\text{unigram } w_i} \times \underbrace{\text{count}(w_j)}_{\text{unigram } w_j}}$$

bigram

①

P21

The probabilistic model:

$$P(\{s_t, y_t\}) = P(s_1) P(y_1 | s_1) \prod_{t=2}^T P(s_t | s_{t-1}) P(y_t | s_t)$$

\downarrow observed, D
 \downarrow Hidden state, k

$\underbrace{\prod_{t=2}^T P(s_t | s_{t-1}) P(y_t | s_t)}_{\text{separable. Conditional Independence.}}$

Let, k states,

 $P(s_t | s_{t-1}) \Rightarrow k \times k$ matrix (Transition matrix) ^{state}
 $P(y_t | s_t) \Rightarrow k \times D$ observation matrix

 \longrightarrow modeled by GMM/Neural Networks.

what if: $s_t = s_t^{(1)}, s_t^{(2)}, \dots, s_t^{(m)}$ } factorial HMM !!

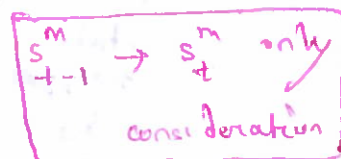
\downarrow \downarrow \downarrow
 $k^{(m)}$ possible values. each

 $k^{(m)} = k$ // simplicity
Then, k^m states $k^m \times k^m$ state transition matrix!!
 \rightarrow impossible to work with

 \rightarrow Requires constraint on state tx. mat.
factorial HMM \rightarrow underlying state tx is constrained

$$P(s_t | s_{t-1}) = \prod_{m=1}^M P(s_t^{(m)} | s_{t-1}^{(m)})$$

Decoupled.



p21

observation:

→ $D \times D$ variance matrix

$$P(Y_t | s_t) = |C|^{1/2} (2\pi)^{-D/2} \exp \left\{ -\frac{1}{2} (Y_t - \mu_t)' C^{-1} (Y_t - \mu_t) \right\}$$

for all m th contribution

$$\mu_t = \sum_{m=1}^M w_t^{(m)} s_t^{(m)}$$

probabilistic

columns are contribution of each states → $D \times 1$ finally.

state variable $s_t^{(m)} \Rightarrow K \times 1$ vectors. → only one 1 (one hot encoding)

→ depends on $s_t^{(m)}$ value

Learning & Inference:Expectation maximization: param learning

$$Q(\phi^{\text{new}} | \phi) = E \left\{ \log P(s_t, Y_t | \phi^{\text{new}}) \mid \phi, \{Y_t\} \right\} \quad \text{--- (5)}$$

↓
current param
new params.

$$p_t^{(m)} = P(s_t^{(m)} | s_{t-1}^{(m)})$$

Factorial HMM: $\phi = \{ \underline{w}^{(m)}, \underline{\pi}^{(m)}, p^{(m)}, \underline{c} \}$ // find all of these parameters.

↓
 $p(s_t^{(m)})$

E step:compute Q : Expand s by using forward equations.

→ can be expressed as Expectation of

$$E \{ \cdot | \phi, Y_t \} \Rightarrow \underbrace{\langle s_t^{(m)} \rangle}_{\text{state occupation}} ; \underbrace{\langle s_t^{(m)} \cdot s_t^{(n)} \rangle}_{\substack{\text{two states} \\ \text{jointly}}} ; \underbrace{\langle s_{t-1}^{(m)} s_t^{(m)} \rangle}_{\substack{\text{state transition} \\ \sum_t K \times K \text{ mat}}}$$

state occupation
 s_t $K \times 1$ vec.

M step: maximize Q using Jensen's inequality.

solved by: weighted linear regression.

Gibbs Sampling: Inference:

$$s_t^{(m)} \sim p(s_t^{(m)} | \underbrace{\{s_t^{(n)} : n \neq m\}}_{\text{Neigh}}, \underbrace{s_{t-1}^{(m)}}_{\text{past}}, \underbrace{s_{t+1}^{(m)}}_{\text{future}}, \underbrace{y_t}_{\text{observation}})$$

$$\propto p(s_t^{(m)} | s_{t-1}^{(m)}) p(s_{t+1}^{(m)} | s_t^{(m)}) p(y_t | s_t^{(m)}, \dots, s_t^{(m)}, \dots, s_t^{(m)})$$

↑ state transition
↑ state transition
graphical model design itself

↓ markovian

completely factorized Variational Inference:

$$\begin{aligned} \underbrace{\log p(\{y_t\})}_{\textcircled{1}} &= \log \sum_{\{s_t\}} p(\{s_t, y_t\}) \\ &= \log \sum_{\{s_t\}} q(\{s_t\}) \frac{p(\{s_t, y_t\})}{q(\{s_t\})} \\ &\geq \underbrace{\sum_{\{s_t\}} q(\{s_t\}) \log \left[\frac{p(\{s_t, y_t\})}{q(\{s_t\})} \right]}_{\textcircled{2}} \end{aligned}$$

The difference between $\textcircled{1}$ & $\textcircled{2}$ is $|\textcircled{1} - \textcircled{2}|$ // simple math.

$$KL(q||p) = \sum_{\{s_t\}} q(\{s_t\}) \log \left[\frac{q(\{s_t\})}{p(s_t | y_t)} \right]$$

→ change parameter of $q(\{s_t\})$ to minimize:

p > 1

(iv)

$$Q(\{s_t | \theta\}) = \prod_{t=1}^T \prod_{m=1}^M Q(s_t^{(m)} | \theta_t^{(m)})$$

time step possible steps at each t.

vector itself.

$$\theta_t^{(m)} = \begin{bmatrix} \theta_{t,1}^{(m)} \\ \theta_{t,2}^{(m)} \\ \vdots \end{bmatrix}$$

$$Q(s_t^{(m)} | \theta_t^{(m)}) = \prod_{k=1}^K \left(\theta_{t,k}^{(m)} \right)^{s_{t,k}^{(m)}}; \quad s_{t,k}^{(m)} \in \{0, 1\}$$

vector element multinomial chain state k , at time t

multiply. with $\sum_{k=1}^K s_{t,k}^{(m)} = 1$ only one is 1 else 0

$$s_t^{(m)} = \begin{bmatrix} s_{t,1}^{(m)} \\ s_{t,2}^{(m)} \\ \vdots \end{bmatrix}$$

$\theta_t^{(m)}$ → state occupation prob. with multinomial rep. $s_t^{(m)}$ under distribution Q

$$\theta_t^{(m) \text{ New}} = \phi \left\{ W^{(m)'} C^{-1} \tilde{y}_t^{(m)} - \frac{1}{2} \Delta^{(m)} + (\log P^{(m)}) \theta_{t-1}^{(m)} + (\log P^{(m)})' \theta_{t-1}^{(m)} \right\}$$

vector softmax elementwise vector of diagonal elements $W^{(m)'} C^{-1} W^{(m)}$

residual error $\tilde{y}_t^{(m)} = y_t - \sum_{l \neq m} W^{(l)} \theta_t^{(l)}$

Structured Variational Inference:

$$Q(\{s_t\} | \theta) = \frac{1}{Z_Q} \prod_{m=1}^M Q(s_1^{(m)} | \theta) \prod_{t=1}^T Q(s_t^{(m)} | s_{t-1}^{(m)}, \theta)$$

normalized

$$Q(s_1^{(m)} | \theta) = \prod_{k=1}^K \left(h_{1,k}^{(m)} \pi_k^{(m)} \right)^{s_{1,k}^{(m)}}$$

$$Q(s_t^{(m)} | s_{t-1}^{(m)}, \theta) = \prod_{k=1}^K \left(h_{t,k}^{(m)} \sum_{j=1}^K P_{k,j}^{(m)} s_{t-1,j}^{(m)} \right)^{s_{t,k}^{(m)}}$$

P21

(v)

$$Q(s_t^{(m)} | s_{t-1}^{(m)}, \theta) = \prod_{k=1}^K \left(h_{t,k}^{(m)} \prod_{j=1}^K (p_{k,j}^{(m)})^{s_{t-1,j}^{(m)}} \right)$$

one hot vectors.

$$\theta = \{ \pi^{(m)}, p^{(m)}, h_t^{(m)} \}$$

$K \times 1 \rightarrow$ prob of observation $P(y_t | s_t)$

for each K setting $s_t^{(m)}$

$$Q(s_{t,j}^{(m)} = 1 | \theta) = h_{t,j}^{(m)} P(s_{t,j}^{(m)} = 1 | \phi)$$

\Rightarrow having an observation at $t=1$, under $s_{t,j}^{(m)} = 1$
has prob of $h_{t,j}^{(m)}$

Can be proved that, $KL(Q||P)$ is minimized.

$$h_t^{(m) \text{ new}} = \exp \left\{ w^{(m)'} e^{-1} \tilde{y}_t^{(m)} - \frac{1}{2} \Delta^{(m)} \right\}$$

recal $\rightarrow y_t = \sum_{k \neq m} w^{(k)} \langle s_t^{(k)} \rangle$

connected to ELBO bound

$$F(q, \phi) = \mathbb{E}_Q \left\{ \log P(y, s | \phi) \right\} - \mathbb{E}_Q \log \{ Q(s) \} \leq \log P(y)$$

(-) value. \rightarrow reverse it (interesting)
No more info than ELBO

①

P22

Problem formulation:

$\{A_1, A_2, \dots, A_m\} \rightarrow m$ smart phone.

$A_i = \{A_{i1}, \dots, A_{iL}\}$ // complete trace for A .

$A_{ij} = \{t_{ij}, x_{ij}, y_{ij}\}$ // temporal/spatial information.

Query $Q = \{Q_1, \dots, Q_f\}$; $f \ll L$ time.

Targets k relevant trajectories of Q from A site

Trajectory comparison function $LESS(Q, A_i)$
 compare their trajectory.

Longest Common SubSequence (LCSS)

By definition:

$$LESS_{\delta, \epsilon}(A, B) = \begin{cases} 0, & A \text{ OR } B = \emptyset \\ 1 + LESS_{\delta, \epsilon}(\text{Head}(A), \text{Head}(B)) & \text{if: } |a_{x:L_1} - b_{x:L_2}| < \epsilon \text{ (time)} \\ & |a_{y:L_1} - b_{y:L_2}| < \epsilon \text{ (x coordinate)} \\ & |L_1 - L_2| < \delta \text{ (time, y coordinate)} \\ \max(LESS_{\delta, \epsilon}(\text{Head}(A), B), LESS_{\delta, \epsilon}(A, \text{Head}(B))) & \text{otherwise} \end{cases}$$

time matching window, spatial matching window
 Both are application Specific.

[iterative Algorithm]

$(x, y \text{ at time } t)$

$\text{Head}(A) = ((a_{x:1}, a_{y:1}), \dots, (a_{x:L-1}, a_{y:L-1}))$

P22

Bounding above LCSS: easier computation.

$$LCSS(MBE_Q, A_i) = \sum_{j=1}^{|A_i|} \begin{cases} 1, & \text{if } A_i[j] \text{ within envelop.} \\ 0, & \text{otherwise.} \end{cases}$$

MBE_Q : Minimum Bounding Envelop of Query Q.

MBE_Q is the area between high envelop & $EnvHigh[i]$
Low envelop. $EnvLow[i]$

$$EnvHigh[i] = \max(Q[j] + \epsilon); |i-j| \leq \delta$$

$$EnvLow[i] = \min(Q[j] - \epsilon); |i-j| \leq \delta$$

unique solution

$\left\{ \begin{array}{l} G \rightarrow \text{recovers the training data distribution} \\ D \rightarrow \frac{1}{2} \text{ everywhere} \end{array} \right.$

Adversarial Nets:

gen $\sim p_g$

noise vector $z \rightarrow \text{map } G(z, \theta)$

\Downarrow

differentiable function (MLP) multi layer perceptron

$D(x, \theta_D)$ / differentiable MLP.

\rightarrow Discrimination $\rightarrow x$ from data / G ??

$$\min_{G_D} \max_D V(D, G) = \mathbb{E}_{\substack{\text{emp} \\ \text{data}(w)}} \left\{ \log[D(w)] \right\} + \mathbb{E}_{\substack{\text{emp} \\ p_z(z)}} \left\{ \log[1 - D(G(z))] \right\}$$

\Rightarrow iterative numerical approach:

$\left\{ \begin{array}{l} k \text{ step of } D \rightarrow \text{to keep near optimal (inner loop)} \\ 1 \text{ step of } G \rightarrow \text{changes slowly enough.} \end{array} \right. \quad \left\{ \begin{array}{l} \text{ML/PCD way??} \end{array} \right.$

Theory: Algorithm 1 \Rightarrow crack of jack.

understanding sequence: when D is optimal \Rightarrow ?? \checkmark
 How/when G is optimal | D is optimal \checkmark
 what happens when D is optimal ?? \checkmark
 what happens when both are optimal

for no of train

mnest
loop
keep k
near optimal

for k in range (k)sample $z^1, \dots, z^m \rightarrow P_g(z)$ sample $x^1, \dots, x^m \rightarrow P_{data}(x)$ update θ_D by ascending ~~grad~~ stochastic grad.

$$\nabla_{\theta_D} \frac{1}{m} \sum_{i=1}^m [\log D(x_i) + \log (1 - D(G(z_i)))] \quad // \text{maximize}$$

→ end for

sample m noise $\{z^1, \dots, z^m\}$ Update the gen. θ_g descending gradient

$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m \log (1 - D(G(z_i))) \quad // \text{minimize}$$

end for.

global optimality: $P_g = P_{data}$.loop 1: For G fixed,

$$D_{G^*}(x) = \frac{P_{data}(x)}{P_{data}(x) + P_g(x)} \quad // \text{optimal Discriminator (maximize)}$$

training criterion:

$$V(G, D) = \int_x P_{data}(x) \log(D(x)) dx + \int_z P_g(z) \log(1 - D(G(z))) dz$$

$$= \int_x P_{data}(x) \log(D(x)) dx + \int_z P_g(z) \log(1 - D(G(z))) dz$$

for any function $y \rightarrow a \log y + b \log(1-y)$ achieves its maximum in $[0, 1]$ at $\frac{a}{a+b} = y$

$$\underline{C(G)} = \max_D V(G, D)$$

$$= E_{x \sim P_{\text{data}}} [\log D_G^*(x)] + E_{z \sim P_z} [\log (1 - D_G^*(G(z)))]$$

$$= E_{x \sim P_{\text{data}}} [\log D_G^*(x)] + E_{x \sim P_g} [\log (1 - D_G^*(x))] \quad // \text{from earlier argument } (y = \frac{a}{a+b}) \text{ maximized}$$

$$= E_{x \sim P_{\text{data}}} \left[\log \frac{P_{\text{data}}(x)}{P_{\text{data}}(x) + P_g(x)} \right] + E_{x \sim P_g} \left[\log \frac{P_g(x)}{P_{\text{data}}(x) + P_g(x)} \right]$$

Now D is set to tune $P_g(x)/G(x)$ to minimize this — (1)

The global minima for $C(G)$ is if $P_g(x) = P_{\text{data}}(x)$

Now D fails to comprehend

in that case,

$$E_{x \sim P_{\text{data}}} \left[\log \frac{P_{\text{data}}(x)}{P_{\text{data}}(x) + P_g(x)} \right] + E_{x \sim P_g} \left[\log \frac{P_g(x)}{P_{\text{data}}(x) + P_g(x)} \right] =$$

$$= -\log 2 - \log 2 = -2 \log 2$$

Re organizing the equation (1) we get P_g may not be optimal

$$C(G) = -\log 4 + E_{x \sim P_{\text{data}}} \left[\log \frac{P_{\text{data}}(x)}{\frac{P_{\text{data}}(x) + P_g(x)}{2}} \right] + E_{x \sim P_g} \left[\log \frac{P_g(x)}{\frac{P_{\text{data}}(x) + P_g(x)}{2}} \right]$$

$$= -\log 4 + \underbrace{KL \left(P_{\text{data}} \parallel \frac{P_{\text{data}} + P_g}{2} \right) + KL \left(P_g \parallel \frac{P_{\text{data}} + P_g}{2} \right)}$$

$$= -\log 4 + 2 JS(P_{\text{data}} \parallel P_g) \quad // \text{Jensen-Shannon Divergence}$$

for optimal $G^* \Rightarrow C(G) = -\log 4$!! if P_g is optimal if only
minimum for optimal D ($P_g = P_{\text{data}}$)

Because G is too good
 Not because D is bad
 D is still OPTIMAL

P 29

convergence of Algo: ⁽¹⁾ 1st discrimination reaches optimal ⁽²⁾ $D^*(x) = P_{data} / (P_g + P_{data})$ and P_g is updated to improve.

⁽¹⁾
$$E_{x \sim P_{data}} [\log D_g^*(x)] + E_{x \sim P_g} [\log (1 - D_g^*(x))]$$

⁽²⁾ P_g converge to P_{data} .
 \Downarrow
 MLP via function $g(z; \theta_g)$ ^{optimize this instead of P_g}
 (multiple critical point) ^(multiple local optima)
 theory \rightarrow (not yet)

D vs Ad: G must not be trained too much!! (D must be mode collapse!! convergence??) (sync with G)

Ad: only backpropagation
 Large distribution learning.

\rightarrow if D is too strong to learn nothing?? \leftarrow

Joint dist $P(x, h | \eta) = P(x | h) P(h | \eta)$

\uparrow hidden
 \uparrow obs \downarrow param

$$P(h | x, \eta) \propto P(h, x | \eta)$$

predictive, $P(x_{\text{new}} | x) = \int P(x_{\text{new}} | h) P(h | x, \eta) dh$

mixture (dir)

$$P(p_{1:k}, \theta, z_{1:n} | x_{1:n})$$

\downarrow mean \downarrow class \downarrow observ

Generative probabi. mod:

mixture prior $\left\{ \begin{array}{l} \theta \sim \text{Dirichlet}(\alpha) \\ \mu_k \sim N(0, \sigma_0^2) \end{array} \right.$

global hid var

① mixture assignment $z_n | \theta \sim \text{Dirichlet}(\theta)$?

② Data point $x_n | z_n, \mu \sim N(\mu_{z_n}, 1)$

easy posy:- sample $\theta \rightarrow$ corresponding μ_{1-k} for each data point estimate $z_n \leftarrow 1 \dots k \rightarrow$ given the distribution.

Paper 30

②

joint distribution:

$$p(\theta, \mu, z, x | \sigma_0^2, \alpha) = p(\theta | \alpha) \prod_{k=1}^K p(\mu_k | \sigma_0^2) \prod_{i=1}^N p(z_i | \theta) p(x_i | z_i, \mu)$$

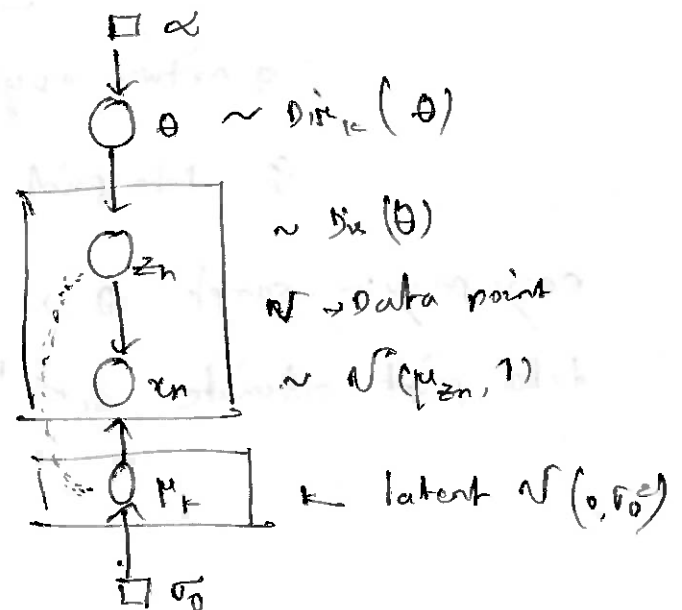
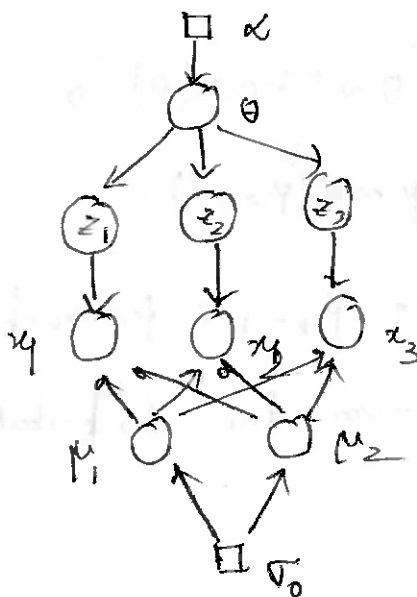
Posterior

$$p(\theta, \mu, z | x, \sigma_0^2, \alpha) = \frac{p(\theta, \mu, z, x | \sigma_0^2, \alpha)}{\int p(x | \sigma_0^2, \alpha)}$$

Predictive Distribution.

$$p(x_{\text{new}} | x, \sigma_0^2, \alpha) = \int \left(\sum_{z_{\text{new}}} p(z_{\text{new}} | \theta) p(x_{\text{new}} | z_{\text{new}}, \mu, \sigma_0^2) p(\theta, \mu | x, \sigma_0^2, \alpha) \right) d\theta \cdot d\mu$$

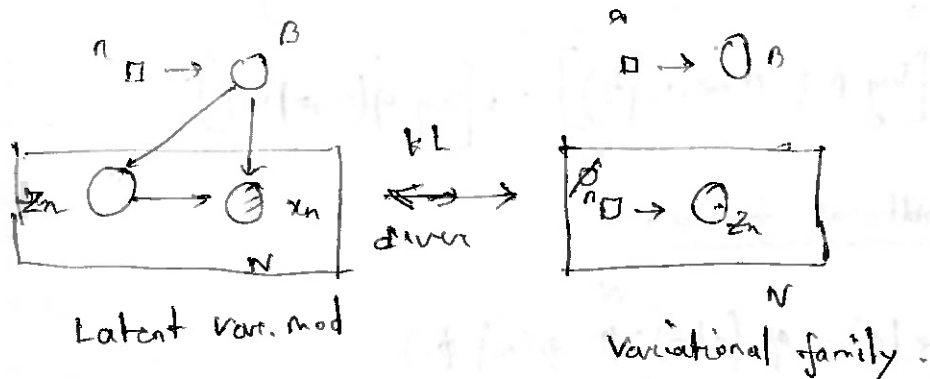
The graphical model:



Example model:

- (i) linear factor model: PCA, factor model. (graph 3)
- (ii) mixed membership model:
- (iii) Matrix factorization model:
- (iv) Time Series
 - ~~Time Series models~~ Hidden Markov model
 - Kalman filter

Posterior Inference With mean field : Variational method.



Conditional Conjugate model:

$$p(\beta, z, x | \eta) = p(\beta | \eta) \prod_{n=1}^N p(z_n | \beta) p(x_n | z_n, \beta)$$

\uparrow local latent \uparrow mixture prop
 \downarrow global latent \downarrow changes so local

Always fixed

Posterior:

$$p(\beta, z | x) = \frac{p(\beta, z, x)}{\int \int p(\beta, z, x) d\beta dz} \rightarrow \text{now? problem!}$$

P 30

(15)

Dependent

$$P(x|\eta) = h(x) \exp(\eta^T \phi(x) - a(\eta)) \sim \text{exponential family,}$$

base measure.

some suff. stat. (good read)

natural param.

log normalizer.

mean field variational model: Approximate Posterior:

variational objective function

$\sigma^* = \arg \min_{\sigma} KL(q(\beta, z | \sigma) || p(\beta, z | x))$

(good read)

$$\mathcal{L}(\sigma) = E[\log p(\beta, z, x | \eta)] - E[\log q(\beta, z | \sigma)]$$

mean field variational family:

$$q(\beta, z | \sigma) = q(\beta | \lambda) \prod_{n=1}^N q(z_n | \phi_n)$$

$$\sigma = \{\lambda, \phi_{1-N}\} \text{ only.}$$

Coordinate Ascent Variational Inference:

$$\lambda^* = E_q[\eta_\beta(z, x)] \quad \text{global}$$

$$\phi_n^* = E_q[\eta_z(\beta, x_n)]$$

local

$$q(\mu, z) = \prod_{i=1}^k q(\mu_i | x_i) \prod_{n=1}^N q(z_n | \phi_n)$$

Model Criticism: exploration & prediction.

↓
inference about
hidden vars.

↓ distribution

$$P(x_{\text{new}}|x) = \underbrace{\int p(\beta|x)}_{\text{not available}} \left(\int p(z_{\text{new}}|\beta) p(x_{\text{new}}|z_{\text{new}}, \beta) dz_{\text{new}} \right) d\beta$$

Predictive Sample Reuse:

$$l_n = \log P(x_n | x_{(-n)}^{\uparrow})$$

$$= \log \int \left(\int p(x_n | z_n) q(z_n) dz_n \right) q_{(-n)}^{(n)}(x_n) d\beta \quad p(\beta, z, x)$$

$$P(\beta, z | x_{(-n)})$$

$$\text{full likelihood} \quad \sum_{n=1}^N l_n$$

Posterior Predictive Check:

→ test statistics

$$PPC = P(T(x^{\text{rep}}) > T(x) | \alpha)$$

↓

Data drawn from hypothetical feature. obs.

$$PPC = P(T(x^{\text{rep}}, \beta) > T(x, \beta) | \alpha)$$

$$P(\beta, x^{\text{rep}} | x) = p(\beta | x) p(x^{\text{rep}} | \beta)$$

$$PPC = \int p(\beta | x) \int p(x^{\text{rep}} | \beta) 1_{[T(x^{\text{rep}}, \beta) > T(x, \beta)]} dx^{\text{rep}} d\beta$$

(vi)

P 10

$$T(x^+, p^+) > T(u, n^+)$$

$$T(x, p) = \frac{1}{N} \sum_{n=1}^N \log(x_n | p) \text{ may be } T$$

PPC is adaptive.

Basics

①

Batch Normalization in CNN: input $[N, c, H, W] \Rightarrow [i, c, j, k]$

Annotations:
- Batch size: N
- Height: H
- Width: W
- Filter channel: c
- for all items some filter c

$$\Rightarrow \mu_{B,c} = \frac{1}{NHW} \sum_{i=1}^N \sum_{j=1}^H \sum_{k=1}^W x_{i,c,j,k}$$

for each channel we get 1 value
So total C value.

$$\Rightarrow \sigma_{B,c}^2 = \frac{1}{NHW} \sum_{i=1}^N \sum_{j=1}^H \sum_{k=1}^W \frac{(x_{i,c,j,k} - \mu_{B,c})^2}{\neq 1}$$

$$\Rightarrow \text{final output } \hat{x}_{i,c,j,k} = \frac{x_{i,c,j,k} - \mu_{B,c}}{\sqrt{\sigma_{B,c}^2 + \epsilon}}$$

\Rightarrow Do calculation for each $c \in C$ channels.

More formally,

$$\hat{x}_{i,c,j,k} = \gamma \left(\frac{x_{i,c,j,k} - \mu_{B,c}}{\sqrt{\sigma_{B,c}^2 + \epsilon}} \right) + \beta$$

Solves ① Internal Covariate Shift. (each ~~zero~~ zero mean, var=1)

\rightarrow features distribution differs internally.

\rightarrow inside the neural Network (layer-layer)

② Robust Network creation \rightarrow less prone to perturbation

③ Learning faster.

Basic

(11)

Instance Normalization (IN) / Layer Normalization

$$IN(x_{i,c,j,k}) = \gamma \left(\frac{x_{i,c,j,k} - \mu_{i,c}}{\sqrt{\sigma_{i,c}^2 + \epsilon}} \right) + \beta$$

where,

$$\mu_{i,c} = \frac{1}{HW} \sum_{j=1}^H \sum_{k=1}^W x_{i,c,j,k}$$

summed out.

$$\sigma_{i,c}^2 = \frac{1}{HW} \sum_{j=1}^H \sum_{k=1}^W (x_{i,c,j,k} - \mu_{i,c})^2$$

Instance: for each n & c

Adaptive Instance Normalization (AdaIN)

$$AdaIN(x_{i,c}, y) = \gamma(y) \left(\frac{x_{i,c} - \mu_{i,c}}{\sqrt{\sigma_{i,c}^2 + \epsilon}} \right) + \beta(y)$$

$\gamma(y)$ is σ (var) \rightarrow conditional
 $\beta(y)$ is μ (mean) \rightarrow adaptive term.

$\rightarrow 0$ if y is constant \rightarrow retrieve if y is constant
 \rightarrow High if y varies a lot. \rightarrow should be 0 mean.

Alternative

Layer Normalization

$$LN(x_{i,c,j,k}) = \gamma \frac{x_{i,c,j,k} - \mu_i}{\sqrt{\sigma_i^2 + \epsilon}}$$

$$\mu_i = \frac{1}{H} \frac{1}{CW} \sum_{c=1}^C \sum_{j=1}^H \sum_{k=1}^W x_{i,c,j,k}$$

selecting subset leads to group Normaliza.
summed out.

(11)

Basicmultinomial distribution:total n trialEach trial: possible k outcomes $\{E_1, E_2, \dots, E_k\}$ with prob $\{p_1, \dots, p_k\}$ respectively.Let's assume E_1 happens n_1 times, E_2 happens n_2 times, ..., $E_k \rightarrow n_k$ times.So, $n_1 + n_2 + \dots + n_k = n$ // as n trial.

$$\text{So, } P = \frac{n!}{n_1! n_2! \dots n_k!} p_1^{n_1} p_2^{n_2} \dots p_k^{n_k}$$

$$= \frac{n!}{n_1! n_2! \dots n_k!} \prod_{i=1}^k p_i^{n_i}$$

$$= n! \prod_{i=1}^k \frac{p_i^{n_i}}{n_i!}$$

straight extensions.

Binomial distribution: Bernoulli trials. n times flipping x positive $n-x$ negatives.

$$P(X=x | n, p) = {}^n C_x p^x (1-p)^{n-x}$$

↓ (Distribution over Distribution)

Beta distribution (prior to Dirichlet Distribution)what if the p is a distribution itself??

$$p \in [0, 1]$$

$$\text{Now, } P(p | \alpha, \beta) = \frac{1}{B(\alpha, \beta)} p^{\alpha-1} (1-p)^{\beta-1}$$

Beta is conjugate prior for binomial

$$B(\alpha, \beta) = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} = \frac{\Gamma(\alpha-1)\Gamma(\beta-1)}{\Gamma(\alpha+\beta-1)} \text{ // continuous estimation.}$$

Conjugate priors:

for some likelihood function, if we choose certain prior the posterior ends up being the same function \rightarrow then conjugate priors.

Dirichlet Distribution: Extended from ^{Conjugate prior for} multinomial probs.

what about the probs of multinomials p_1, \dots, p_K ??

① $\sum p_i = 1$ // already known ^{condition} as each event prob needs to be 1.

$$P(p = \{p_i\} | \alpha_i) = \frac{\prod_i \Gamma(\alpha_i)}{\Gamma(\sum_i \alpha_i)} \prod_i p_i^{\alpha_i - 1}$$

$\downarrow \alpha_i - 1$
 \searrow to multinomial

\rightarrow Generalization of Beta.

\rightarrow Distribution over multinomials.

Conjugate prior of multinomial

\rightarrow given the data the $\{p_i\}$ will also be Dirichlet distribution.

* Beta/Gamma functions are different:

$$\text{Beta}(x, y) = B(x, y) = \frac{\Gamma(x) \Gamma(y)}{\Gamma(x+y)} \quad \nearrow \text{binomial coeffs.}$$

$$\Gamma(z) = \int_0^\infty x^{z-1} e^{-x} dx; \quad \Re(z) > 0$$

$\Gamma(z) = (z-1)!$ if z is a natural number ≥ 0 positive integer.