⑯ Pseudo 3D CNN

Residual units: $x_{t+1} = h(x_t) + F(x_t)$

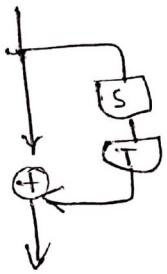
- x_{t+1} → output of t^{th} block.
- x_t → input of t
- h → identity map

P3D Block design:

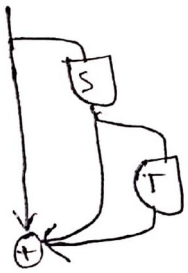
S → 2D spatial filter

T → 1d temporal filter.

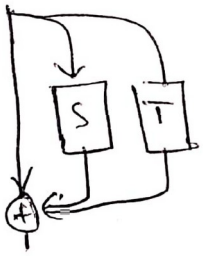
i) P3D - A



ii) P3D C



iii) P3D - B



Scanned with CamScanner