

Swapping Assignment between multiple view of same images.

swAV

image x_n

augmented view x_{n+}

2 standard resolution + V additional
low resolution crop.

$\Rightarrow (v+2)$ images.

$z_{n+} = f(x_{n+})$ // after normalization.

code q_{n+} from z_{n+} to a set of

k trainable normal vectors $\{c_1, \dots, c_k\}$
prototypes.

\longrightarrow weight of dense layer!!

z_t, z_s augmented representation

$q_t, q_s \rightarrow$ their corresponding code.

$$L(z_t, \frac{z}{2}) = \underbrace{L(z, q_t) + L(z_t, q_s)}_{\text{swapping}}$$

→ overall prototypes.

$$L(z_s, q_t) = - \sum_k q_s^{(k)} \log p_t^{(k)}$$

$$p_t^{(k)} = \frac{\exp\left(\frac{1}{\alpha} z_t^T c_k\right)}{\sum_{k'} \exp\left(\frac{1}{\alpha} z_t^T c_{k'}\right)}$$

total loss function:

$$-\frac{1}{2} \sum_{n=1}^N \sum_{t \sim n} \left[\frac{1}{\alpha} z_{nt}^T c_{q_{ns}} + \frac{1}{\alpha} z_{ns}^T c_{q_{nt}} - \log \sum_{k=1}^K \exp\left(\frac{z_{nt}^T c_k}{\alpha}\right) - \log \sum_{k=1}^K \exp\left(\frac{z_{ns}^T c_k}{\alpha}\right) \right]$$

$$\left\{ \begin{array}{l} C \in D \times k \\ z \in D \times 1 \\ q \in k \times 1 \end{array} \right.$$

prototypes $c \in \mathbb{D} \times 1$

Computing Codes online:

cluster Assignment:

Assign B samples $[z_1, \dots, z_B]$
to k (prototype) cluster $[c_1, \dots, c_k]$

Requires mapping Q

Equipartition constraint
(to avoid collapse)

Splitting data uniformly $n = \frac{1}{k} 1_k$

$$c = \frac{1}{B} 1_B$$

$$Q = \left\{ Q \in \mathbb{R}_+^{k \times B} \mid Q 1_B = \frac{1}{k} 1_k, Q^T 1_k = \frac{1}{B} 1_B \right\}$$

[each cluster is selected B/k times]

Cost matrix $:- C^T z$

[solve this under equipartition constraint]

$M \rightarrow D \times D$ cost matrix.

$x \rightarrow C$ mapping (PDF)

by transport matrix P

total cost $= \langle P, m \rangle$ / Frobenious product.

$$P \in \left\{ A \in \mathbb{R}_+^{D \times D} \mid A \mathbf{1}_D = r; A^T \mathbf{1}_D = c \right\}$$

then, $d_m(r, c) = \min_P \langle P, m \rangle$

Optimal transport problem?

$$\min_{Q \in \mathcal{Q}} \langle Q, -C^T z \rangle + \epsilon H(Q)$$

regularizer.

Solution: $Q^* = \text{Diag}(u) \exp\left(\frac{C^T z}{\epsilon}\right) \text{Diag}(v)$

... ..

$u \in \mathbb{R}^k$
 $v \in \mathbb{R}^B$ } non negative
computed by small mat mul.

(Sikhos - knopp algorithm)