

CME 213, ME 339—Spring 2021

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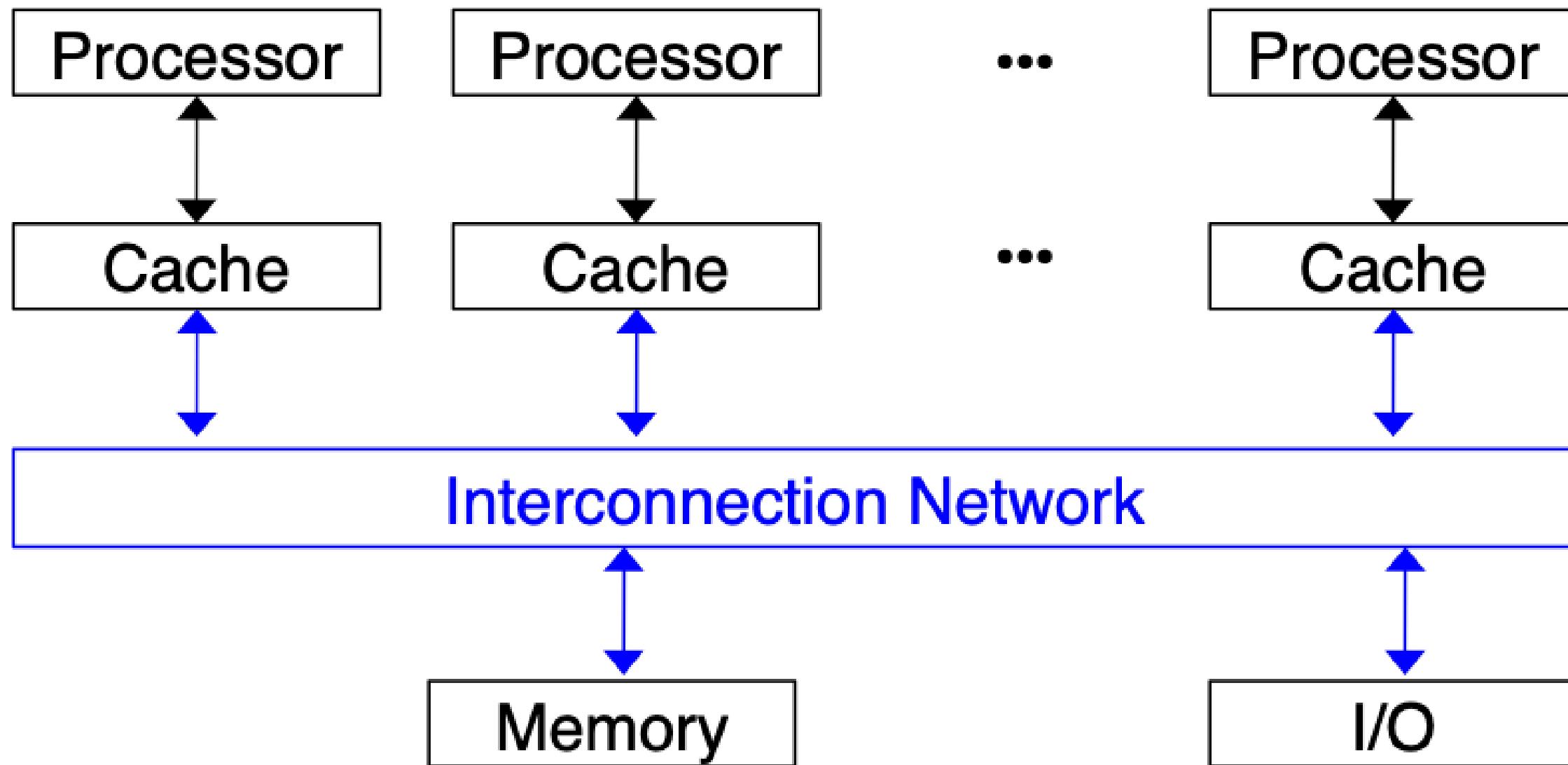
"Computers are getting smarter all the time. Scientists tell us that soon they will be able to talk to us.
(And by 'they', I mean 'computers'. I doubt scientists will ever be able to talk to us.)"

(Dave Barry)

Shared Memory Processor

Schematic

- A number of processors or cores
- A shared physical memory (global memory)
- An interconnection network to connect the processors with the memory



Process

Process: program in execution

Comprises: the executable program along with all information that is necessary for the execution of the program.

Thread

Thread: an extension of the process model.

Can be viewed as a "lightweight" process.

A thread may be described as a "procedure" that runs independently from the main program.

In this model, each process may consist of multiple independent control flows that are called **threads**

Imagine a program that contains a number of procedures.

Then imagine these procedures being able to be scheduled to run **simultaneously and/or independently** by the operating system.

This describes a **multi-threaded program**.

Shared address space

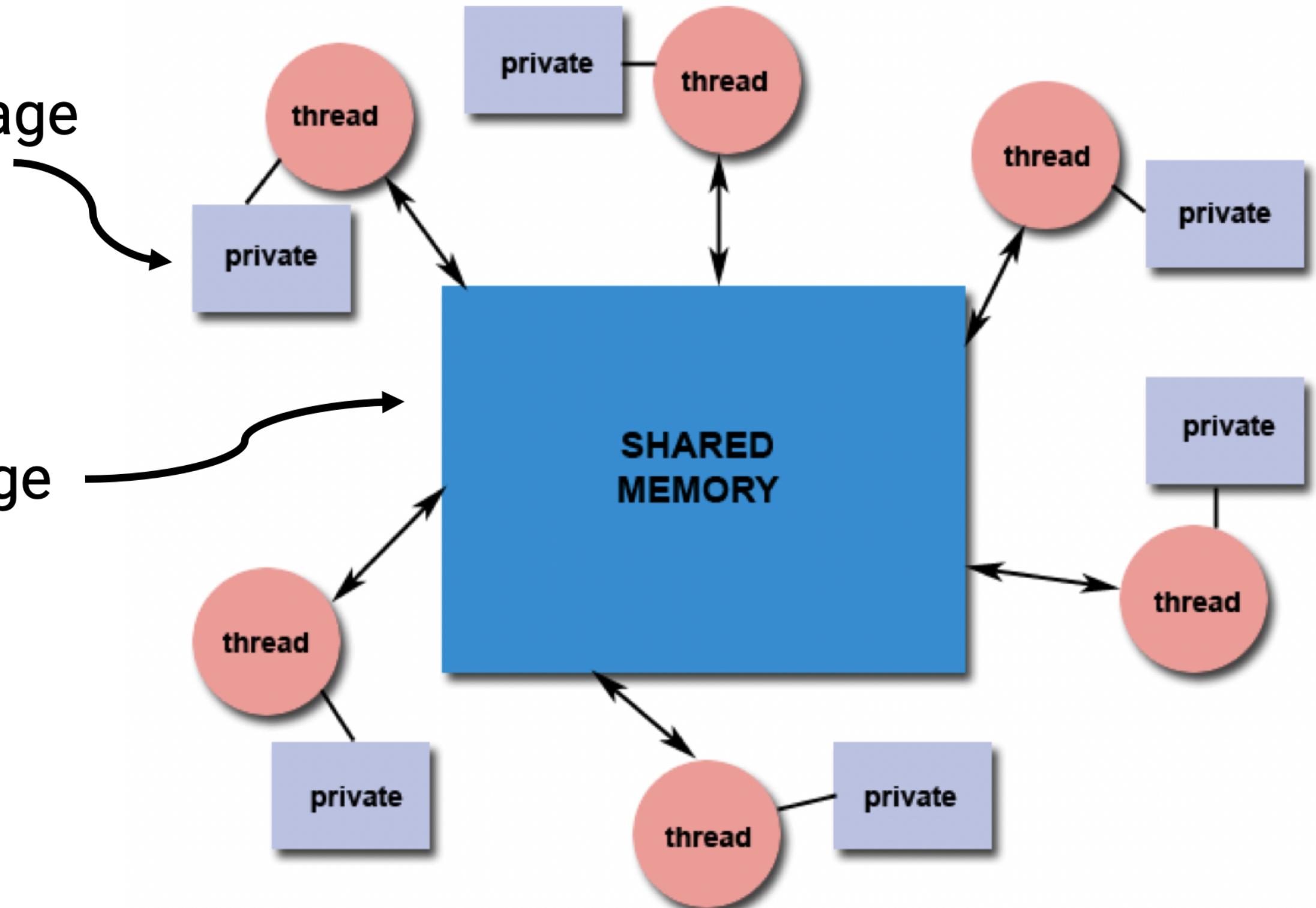
All the threads of one process share the address space of the process, i.e., they have a common address space.

When a thread stores a value in the shared address space, another thread of the same process can access this value.



Private storage

Data exchange



Threads

Threads are everywhere

- C++ threads (11): `std::thread`
- C threads: Pthreads
- Java threads: `Thread thread = new Thread();`
- Python threads:
`t = threading.Thread(target=worker)`
- Cilk: `x = spawn fib (n-1);`
- Julia: `r = remotecall(rand, 2, 2, 2)`
- OpenMP

C++ threads exercise

Open the file `cpp_thread.cpp`

Type `make` to compile

thread constructor

```
thread t2(f2, m);
```

Creates a thread that will run function f2 with argument m

Reference argument

```
thread t3(f3, ref(k));
```

If a reference argument needs to be passed to the thread function, it has to be wrapped with `std::ref`.

thread join

```
t1.join();  
t2.join();  
t3.join();
```

Calling thread waits (blocks) for t1 to complete
(i.e., finishes running f1)

Required before results of t1 calculations become "usable"

Complete exercise with t4 and f4

```
void f4() { /* todo */ }

int main(void)
{
    thread t4(); // todo
    // call f4() using thread t4; add m and k */
}
```

How can we "return" values from asynchronous functions?

Difficulty: these functions can run at any time

1. How do we allocate resources to store return value?
2. How do we query the return value?

Answer

Use promise and future

promise

Holds value to be returned

`future`

Allows to query the value

promise/future exercise

Open `cpp_thread.cpp`

accumulate()

```
void accumulate(vector<int>::iterator first,
                vector<int>::iterator last,
                promise<int> accumulate_promise)
{
    int sum = 0;
    auto it = first;
    for (; it != last; ++it)
        sum += *it;
    accumulate_promise.set_value(sum); // Notify future
}
```

main()

```
promise<int> accumulate_promise; // Will store the int
future<int> accumulate_future = accumulate_promise.get_future();
thread t5(accumulate, vec_1.begin(), vec_1.end(),
          move(accumulate_promise));
// move() will "move" the resources allocated for accumulate_promise

// future::get() waits until the future has a valid result and retrieves it
cout << "result of accumulate_future [21 expected] = "
    << accumulate_future.get() << '\n';
```

promise/future exercise

Complete 2nd part of cpp_thread.cpp

max.promise and get_max()

What is the point of promise and future?

Why not use a reference and set the value?

The function associated with a thread can run at any time.

So to make sure a variable has been updated,

we need to use `my_thread.join()`

`promise/future` is a more flexible mechanism

As soon as `set_value` is called on the `promise`,

the value can be acquired using the `future`

promise/future allow flexible and efficient communication between threads



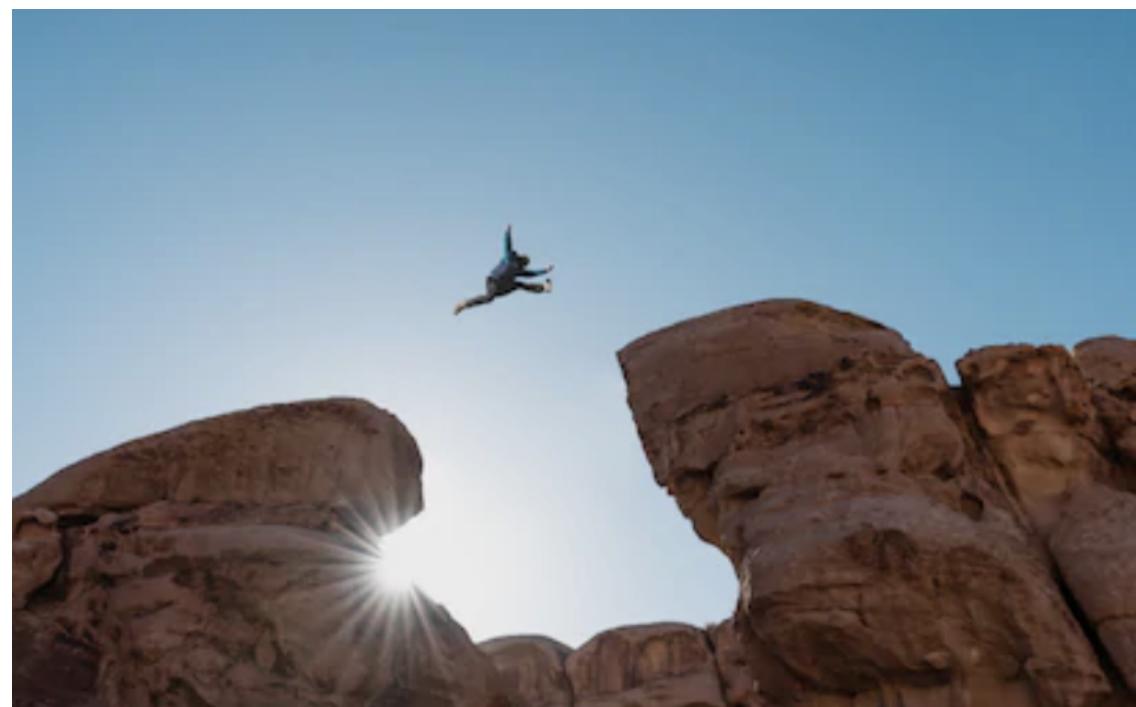
See for more information

<https://en.cppreference.com/w/cpp/thread/thread>

Thread coordination



The risks of multi-threaded programming



A well-known bank company has asked you to implement a multi-threaded code to perform bank transactions

Goal: allow deposits

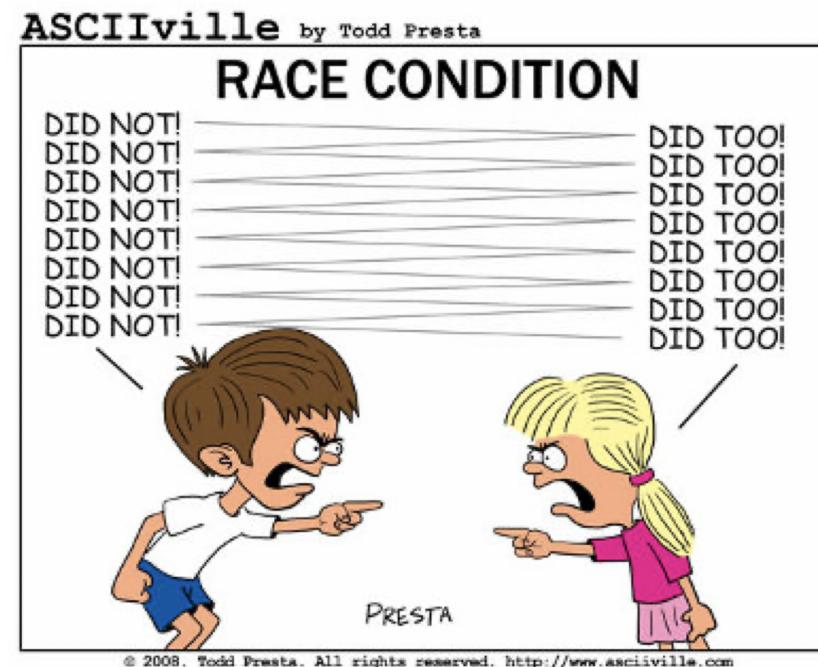
1. Clients deposit money and the amount gets credited to their accounts.
2. But, a result of having multiple threads running concurrently the following can happen:



Thread 0	Thread 1	Balance
Client requests a deposit	Client requests a deposit	\$1000
Check current balance = \$1000		
Ask for deposit amount = \$100	Check current balance = \$1000	
	Ask for deposit amount = \$300	
Compute new balance = \$1100	Compute new balance = \$1300	\$1300
Write new balance to account	Write new balance to account	\$1100

This is called a race condition

The final result depends on the precise order in which the instructions are executed



Race condition

Occurs when you have a sequence like

READ/WRITE

or

WRITE/READ

performed by different threads

Threads race to fill-up a todo-list



Thread 0

Thread 0 wants to add new to-do item.

Thread 0 closes lock. Add entry in list.

Thread 0 is done with the to-do list. It opens the lock.

Thread 1

Thread 1 wants to use the lock. It has to wait.

Thread 1 can close the lock and add entry in list.

Mutex

A mutex can only be in two states: locked or unlocked.

Once a thread locks a mutex:

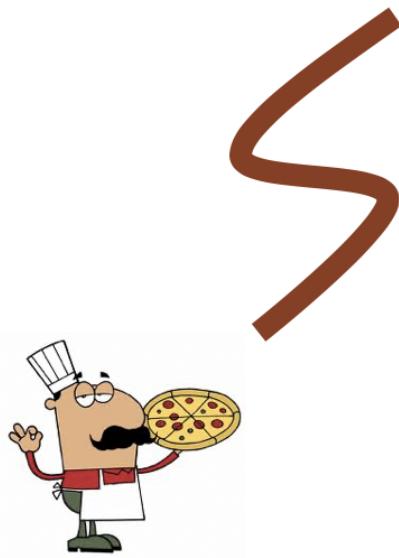
- Other threads attempting to lock the same mutex are blocked.
- Only the thread that initially locked the mutex has the ability to unlock it.

This allows to protect regions of code.



Only one thread at a time can execute that code.

Pizza cook



Receives all the orders.
Prepares all the pizzas.

**Ask delivery team to
deliver pizzas to
customers**

Pizza delivery team



- Checks the addresses for customers
- Deliver pizza



**Go back;
check if there
are orders left.**

Open mutex_demo.cpp

```
void PizzaDeliveryPronto(int thread_id)
{
    g_mutex.lock();
    while (!g_task_queue.empty())
    {
        printf("Thread %d: %s\n", thread_id, g_task_queue.front().c_str());
        g_task_queue.pop();
        g_mutex.unlock();

        Delivery();
        g_mutex.lock();
    }
    g_mutex.unlock();
    return;
}
```