# Graph Attention Networks

# Summary Notes by Max Guo July 5, 2022

(?) - denotes a lack of familiarity or understanding of a particular concept

#### 1 Information

• Year: 2018

• Conference: ICLR

• Authors:

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### 2 Research Problem

How can we extend Neural Network architectures to arbitrary graphs?

## 3 Existing Approaches and Shortcomings

- Graph Neural Networks (2005, 2009)
  - Generalize RNNs for general graphs.
  - Iteratively propagate node states until equilibrium, then apply NN to node states to get output per node.
- How can we *generalize convolutions* for graphs?
  - Spectral Approaches
    - \* Deal with spectral representation of a graph (graph Laplacian)
    - \* **Problem**: Trained models are not generalizable! Learned filters depend on the graph structure through the Laplacian eigenbasis (?)

#### - Non-spectral Approaches

- \* Define convolutions on the graph, directly
- \* Challenges: How can you define an operator with weight-sharing (like CNNs) that works with different sized neighborhoods?

- \* Noteworthy approach: GraphSAGE (Hamilton et al, 2017). (?)
  - · For each node, sample a fixed-size neighborhood and feed into an aggregator. Works well!
- Attention Mechanisms (2015, 2016)
  - A de facto standard in sequence tasks
  - Benefits: Deal with variable-sized inputs
  - Self-attention Attention mechanism computes a representation of a single sequence
    - \* (Vaswani et al, 2017) self-attention is *sufficient* for constructing a powerful model for state-of-the-art machine translation task performance.

## 4 High Level Contributions

The authors perform node-classification on graph data using an attention mechanism.

#### 5 Technical Contributions

#### 5.1 GAT Architecture

- Graph Attention Layer
  - Takes node features and returns node features

$$\mathbf{h} = \{\vec{h}_1, \dots, \vec{h}_N\} \longrightarrow \mathbf{h}' = \{\vec{h}_1', \dots, \vec{h}_N'\}$$
$$\vec{h}_i \in \mathbb{R}^F, \vec{h}_i' \in \mathbb{R}^{F'}$$

- Attention coefficients (importance of node j's features to node i):

$$e_{ij} = a(\mathbf{W}\vec{h}_i, \mathbf{W}\vec{h}_j) \tag{1}$$

Weight matrix  $\mathbf{W} \in \mathbb{R}^{F' \times F}$ 

attention mechanism a is single-layer feedforward LeakyReLU NN

- Normalization of attention coefficients, masking attention to be within a neighborhood:

$$\alpha_{ij} = \operatorname{softmax}_{j}(e_{ij}) = \frac{\exp(e_{ij})}{\sum_{k \in \mathcal{N}_{i}} \exp(e_{ik})}$$
 (2)

- Obtain the final node features:

$$\vec{h}_i' = \sigma \left( \sum_{j \in \mathcal{N}_i} \alpha_{ij} \mathbf{W} \vec{h}_j \right) \tag{3}$$

- Multi-headed attention (concatenate results from K independent attention mechanisms a)

$$\vec{h}_i' = \left| \left| \sum_{k=1}^K \sigma \left( \sum_{j \in \mathcal{N}_i} \alpha_{ij}^k \mathbf{W}^k \vec{h}_j \right) \right|$$
 (4)

Final layer employs averaging

#### • Advantages over Related Works

- Highly parallelizable across edges and nodes. Complexity is on par with GCNs

- Difference in importances assigned to nodes of a same neighborhood (differs from GCNs)
- Applicable to inductive learning (supervised learning)
- (Hamilton et al, 2017) samples fixed-size neighborhoods and requires consistent node-ordering in neighborhoods, whereas GATs do not assume any ordering.
- No assumption on node's structural properties

### 6 Experimentation

- Datasets: CORA, Citeseer, Pubmed (all citation networks), protein-protein interaction (PPI)
- Transductive learning (citation networks) label remainder of training dataset, vs inductive learning (PPI)
- (Skipping most experimental details...)
- Metrics: Accuracy for citation networks, micro-averaged F1 score for PPI
- Results: Improves upon GCNs by 1.5% on CORA, 1.6% on Citeseer, and 20.5% on GraghSAGE
- Perform a t-SNE visualization on the feature representations, showing clustering of the different node classes.

### 7 Further Work

- Practical problems (e.g. larger batch sizes)
- Model interpretability in attention mechanisms
- Graph classification, not just node classification
- $\bullet\,$  Incorporate edge features

## 8 My Questions and Thoughts

- How robust is the GAT architecture to different hyperparameters?
- What happens when you utilize more complicated attention mechanisms, or more complicated "single-layers"?
- Does this generalize to hyper-graphs?

# 9 Appendix

(Things I learned in the process of searching things up while reading this paper)

- Difference between semi-supervised and transductive learning:
  - Semi-supervised learning has the goal of generalizing based on a dataset with some labels given
  - Transductive learning has the goal of labeling the remainder of the dataset with some labels given
- Micro-averaged F1 Score (source: towardsdatascience):

- Recall the following definitions:

$$\begin{aligned} & \text{Precision } &= \frac{TP}{TP + FP} \\ & \text{Recall } &= \frac{TP}{TP + FN} \\ & \text{F1 Score} &= \frac{2(\text{Precision} * \text{Recall})}{\text{Precision} + \text{Recall}} \end{aligned}$$

- Multi-class approach: use one-vs-all approach. Different averaging techniques:
  - \* Macro-average: unweighted average
  - \* Weighted average: weight according to proportion of examples for each class
  - \* Micro-average: Same across micro-F1, micro-precision, micro-recall, and accuracy. Simply the proportion of observations classified correctly.