

Midterm Review

1. Solution of equations

Solve for $f(x)=0$ for $x \in [a,b]$

① Existence

② Fixed pt iter.

③ Convergence

④ iterative methods

① if $f(a) \cdot f(b) < 0$, then $\exists \pi \in [a,b]$ s.t. $f(\pi)=0$

② Solving for $f(x)=0 \Leftrightarrow \underbrace{g(x)=x}$ for suitable choice of g .
existence?
if $g(x) \in [a,b] \forall x \in [a,b]$, exist!

Fixed point iteration:

If $g(x)$ is $C[a,b]$, given $x_0 \in [a,b]$, define $x_{k+1} = g(x_k)$ for $k=0,1,2,\dots$

③ Convergence

• (strongest)

If $\exists L < 1$, s.t. $\forall x,y \in [a,b]$, $|g(x)-g(y)| \leq L \cdot |x-y|$, then converges regardless of choice of starting point.

\uparrow
 $\max_{x \in [a,b]} |g'(x)|$ if $g \in C^1$

• (weaker)

Let ξ be the fixed point of g . If $g \in C^1$ and $|g'(\xi)| < 1$, then converges if we start sufficiently close to ξ .

Stability of fixed point

- ξ is stable if fixed point iteration converges to ξ whenever x_0 close to ξ . $\Leftrightarrow |g'(\xi)| < 1$
- ξ is unstable if no fixed point iteration started close to ξ converges, unless $x_0 = \xi$. $\Leftrightarrow |g'(\xi)| > 1$
- $|g'(\xi)| = 1$, neither .. or ..

Eg: Let $f(x) = xe^x - 1$. Show that $f(x)$ has unique root on \mathbb{R} .

1° existence. $f(0) = -1$, $f(1) = e - 1 > 0 \Rightarrow \exists$ root on $[0,1]$.

2° uniqueness. For $x \leq 0$, $xe^x \leq 0$, so $f(x) \leq -1$

For $x > 0$, $f'(x) = xe^x + e^x = (x+1)e^x > e^x > 1$

$\Rightarrow f$ is strictly increasing $\forall x > 0$.

\Rightarrow the solution we found in $[0,1]$ must be unique.

eg: $x_{k+1} = \varphi(x_k) = x_k - \lambda f'(x_k)$, $\lambda > 0$, $f \in C^2$

① What are the fixed points of this iteration?

Sol: If x is a fixed point, then $\underline{x} = \varphi(x) = x - \lambda f'(x) \Rightarrow f'(x) = 0$.

② Assume $f''(x) > c > 0$. What choice of λ will the fixed points iteration converges for any initial condition x_0 ?

Sol: need $|\varphi'(x)| < 1$

$$\varphi'(x) = 1 - \lambda f''(x) < 1 - \lambda c \quad \forall x$$

$$\text{Want } |\varphi'(x)| < 1 \Rightarrow \underbrace{1 - \lambda c < 1}_{\text{true}} \text{ and } 1 - \lambda c > -1$$

$$-\lambda c > -2$$

$$\lambda c < 2$$

$$\boxed{\lambda < \frac{2}{c}}$$

• Speed of convergence

The sequence $\{x_k\}$ converges linearly if

$$\lim_{k \rightarrow \infty} \frac{|x_{k+1} - \bar{x}|}{|x_k - \bar{x}|} = \mu \in \mathbb{R}$$

$$\mu \in (0, 1)$$

converges with order 1.

$$\begin{cases} \mu = 0 & \text{super-linear} \\ \mu \in (0, 1) & \text{linear} \\ \mu = 1 & \text{sub-linear} \end{cases}$$

④ Iterative methods for root finding

① Newton's method,

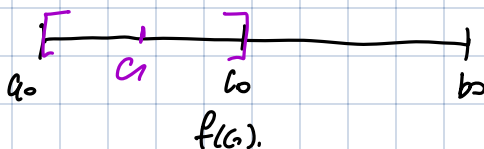
$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}, \quad k = 0, 1, \dots, \quad f'(x_k) \neq 0.$$

If converges, $f'(\bar{x}) \neq 0$, quadratic
 — — — $f'(\bar{x}) = 0$, linear

\bar{x} is the root of f , i.e., $f(\bar{x}) = 0$.

② Secant Method. $f'(x_k) \approx \frac{f(x_k) - f(x_{k-1})}{x_k - x_{k-1}}$

③ Bisection Method.
 $f(a_0) \cdot f(b_0) < 0$



• if $f(a_0) f(c_0) < 0$, the next interval $[a_0, c_0]$

• if $f(b_0) f(c_0) < 0$, — — — $[c_0, b_0]$

eg: $f(x) = xe^x - 1$. Use Newton's method w/ $x_0 = 0$, find x_1 and x_2 .

$$x - \frac{f(x)}{f'(x)} = x - \frac{xe^x - 1}{xe^x + e^x} = \frac{x^2 e^x - 1}{(x+1)e^x}$$

$$\Rightarrow x_1 = 0 - \frac{0e^0 - 1}{0e^0 + e^0} = 1.$$

$$x_2 = 1 - \frac{1 \cdot e - 1}{1 \cdot e + e} = 1 - \frac{e - 1}{2e} = \frac{2e - e + 1}{2e} = \frac{e + 1}{2e}.$$

2. Solutions of systems of linear equations

Solve the system $Ax=b$

① existence of solution

② LU decomposition

③ Pivoting.

unique sol if A is invertible

② LU decomposition

$$A=LU, \quad L = \begin{pmatrix} 1 & & & \\ x & \ddots & & 0 \\ x & x & \ddots & \\ x & - & - & 1 \end{pmatrix}, \quad U = \begin{pmatrix} x & x & x & x \\ 0 & \ddots & & \\ & & \ddots & \\ & & & x \end{pmatrix}$$

L : obtained while doing Gaussian elimination on A (row operations)

U : result of A after Gaussian elimination.

Given $A=LU$, $Ax=LUx=b \Rightarrow \begin{cases} Ly=b & \text{forward} \\ Ux=y & \text{backward} \end{cases}$

Cost of LU: $\frac{2}{3}n^3 - \frac{1}{2}n^2$

--- forward/backward: $2n^2$

Eg: $A = \begin{pmatrix} 4 & 2 & 0 & 0 \\ 2 & 5 & 4 & 0 \\ 0 & 4 & 6 & 3 \\ 0 & 0 & 3 & 6 \end{pmatrix}$

$L = \begin{pmatrix} 1 & & & \\ 1/2 & 1 & & \\ 0 & 1 & 1 & \\ 0 & 0 & 3/2 & 1 \end{pmatrix}$

$\frac{a_{21}}{a_{11}} = \frac{2}{4} = \frac{1}{2}$

$a_{21} - \frac{a_{21}}{a_{11}} a_{11} = 0$

$\begin{pmatrix} 4 & 2 & 0 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 4 & 6 & 3 \\ 0 & 0 & 3 & 6 \end{pmatrix}$

$\rightarrow \frac{a_{32}}{a_{22}} = \frac{4}{4} = 1$

$\begin{pmatrix} 4 & 2 & 0 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 3 & 6 \end{pmatrix}$

$\rightarrow \frac{a_{43}}{a_{33}} = \frac{3}{2}$

$\begin{pmatrix} 4 & 2 & 0 & 0 \\ 0 & 4 & 4 & 0 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 3/2 \end{pmatrix}$

$6 - \frac{3}{2} \times 3 = 6 - \frac{9}{2} = \frac{12-9}{2} = \frac{3}{2}$

U

③ Pivoting. $PA=LU \Leftrightarrow A=P^T LU$ (b/c $P^T=P^{-1}$)

↳ get the largest entry in the diagonal

: dividing by 0 is dangerous, and dividing by a small number causes large error.

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

To switch the 2nd & 3rd row of A,

multiply A by $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

3. Norms and Conditioning

Given $Ax=b$, how sensitive is x to changes in A and/or b ?

① Conditioning ② norms ③ Condition #.

↳ Small change in b may cause large change in x

⇒ Want a bound on the change of x

$$A(x+\delta x) = b + \delta b$$

$$\Rightarrow \| \delta x \| \leq \underbrace{K(A)}_{\text{condition number}} \cdot \| \delta b \| \quad \text{or} \quad \frac{\| \delta x \|}{\| x \|} \leq \underbrace{K(A)}_{\text{condition number}} \cdot \frac{\| \delta b \|}{\| b \|}.$$

② Norms.

• $\|v\| \geq 0$ and $\|v\|=0$ iff $v=0$

• $\|\lambda v\| = |\lambda| \cdot \|v\|$. $\forall v \in V$.

• $\|v+w\| \leq \|v\| + \|w\|$.

Vector Norms: $\|v\|_2 = \left(\sum_{i=1}^n |v_i|^2 \right)^{1/2}$

$$\|v\|_1 = \sum_{i=1}^n |v_i|$$

$$\|v\|_\infty = \max_{1 \leq i \leq n} |v_i|$$

Matrix Norms: $\|A\|_\infty = \max_{x \neq 0} \frac{\|Ax\|_\infty}{\|x\|_\infty} = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$ (largest row sum)

$$\|A\|_1 = \max_{x \neq 0} \frac{\|Ax\|_1}{\|x\|_1} = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|$$
 (largest column sum)

$$\|A\|_2 = \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2} = \max_{1 \leq i \leq n} \sqrt{\lambda_i(A^T A)}$$

③ Condition numbers. $K(A) = \|A\| \cdot \|A^{-1}\|$

Thm: $\frac{\| \delta x \|}{\| x \|} \leq K(A) \cdot \frac{\| \delta b \|}{\| b \|}$

Eg: (a) For two invertible matrices, show that $K(AB) \leq K(A) \cdot K(B)$

Sln: $K(AB) = \|AB\| \cdot \|B^{-1}A^{-1}\|$

$$\leq \|A\| \cdot \|B\| \cdot \|B^{-1}\| \cdot \|A^{-1}\|$$

$$= K(A) \cdot K(B).$$

(b) Compute the condition number of the matrices using $\|\cdot\|_1$ and $\|\cdot\|_\infty$ norm:

(i) $\begin{pmatrix} a+1 & a \\ a & a-1 \end{pmatrix} = A$

(ii) $\begin{pmatrix} 0 & 1 \\ -2 & 0 \end{pmatrix} = B$

$$A^{-1} = \frac{1}{a^2 - 1 - a^2} \begin{pmatrix} a-1 & -a \\ -a & a+1 \end{pmatrix}$$

$$= \begin{pmatrix} 1-a & a \\ a & 1-a \end{pmatrix}$$

$$\|A\|_1 = \max \{ |a+1| + |a|, |a| + |a-1| \} \Rightarrow K_1(A) = \max \{ |a+1| + |a|, |a| + |a-1| \}^2$$

$$\|A^{-1}\|_1 = \|A\|_1$$

$$K_\infty(A) = K_1(A)$$

(ii) $B = \begin{pmatrix} 0 & 1 \\ -2 & 0 \end{pmatrix} \quad B^{-1} = \frac{1}{0+2} \begin{pmatrix} 0 & -1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1/2 \\ 1 & 0 \end{pmatrix}$

$$\Rightarrow \|B\|_1 = 2, \quad \|B^{-1}\|_1 = 1 \Rightarrow K_1(B) = 2$$

$$\|B\|_\infty = 2, \quad \dots \dots \dots K_\infty(B) = 2.$$

4. Least Squares.

Solve the overdetermine system $Ax = b$.

$(m > n)$

$$\begin{matrix} m \\ \boxed{A} \\ n \end{matrix} \quad \begin{matrix} n \\ \boxed{x} \end{matrix} = \begin{matrix} m \\ \boxed{b} \end{matrix}$$

① Least square

$$\min_x \|Ax - b\|_2$$

② normal equations

$$A^T A x = A^T b$$

if A is full rank,
 $\text{rank}(A) = n$.
 then $A^T A$ invertible
 \Rightarrow unique solution x

③ QR factorization,

Eg: $\left. \begin{aligned} x_1 + 2x_3 &= 1 \\ x_2 + 3x_3 &= 0 \\ -x_1 + x_2 + x_3 &= 0 \\ -x_2 - 3x_3 &= 1 \end{aligned} \right\} \quad A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ -1 & 1 & 1 \\ 0 & -1 & -3 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$

$$\min_{x \in \mathbb{R}^3} \|Ax - b\|_2 \Leftrightarrow A^T A x = A^T b.$$

$$A^T A = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & -1 \\ 2 & 3 & 1 & -3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ -1 & 1 & 1 \\ 0 & -1 & -3 \end{pmatrix} = \begin{pmatrix} 2 & -1 & 1 \\ -1 & 3 & 7 \\ 1 & 7 & 23 \end{pmatrix}$$

↑
NOT invertible!

$$A^T b = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & -1 \\ 2 & 3 & 1 & -3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$$

$$\left(\begin{array}{ccc|c} 2 & -1 & 1 & 1 \\ -1 & 3 & 7 & -1 \\ 1 & 7 & 23 & -1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 7 & 23 & -1 \\ -1 & 3 & 7 & -1 \\ 2 & -1 & 1 & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|c} 1 & 7 & 23 & -1 \\ 0 & 10 & 30 & -2 \\ 0 & -15 & -45 & 3 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|c} 1 & 7 & 23 & -1 \\ 0 & 10 & 30 & -2 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

x_3 : free

$$\cdot 10x_2 + 30x_3 = -2$$

$$x_2 = -\frac{1}{5} - 3x_3$$

$$\cdot x_1 + 7x_2 + 23x_3 = -1$$

$$x_1 + 7(-\frac{1}{5} - 3x_3) + 23x_3 = -1$$

$$x_1 = \frac{2}{5} - 2x_3$$

\Rightarrow All x satisfying $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2/5 - 2x_3 \\ -1/5 - 3x_3 \\ x_3 \end{pmatrix}$ solve the least square problem.

③ QR factorization:

$$\begin{array}{c} m \\ \left| \begin{array}{c} \boxed{A} \end{array} \right. \end{array} \begin{array}{c} n \\ \end{array} = \begin{array}{c} m \\ \left| \begin{array}{c} \boxed{Q} \end{array} \right. \end{array} \begin{array}{c} n \\ \end{array} \begin{array}{c} n \\ \left| \begin{array}{c} \boxed{R} \end{array} \right. \end{array} \begin{array}{c} n \\ \end{array}$$

↑
 $Q^T Q = I$
 Q has orthonormal columns

Using $A = QR$, we can solve the least square $\min_x \|Ax - b\|$ by

$$Rx = Q^T b$$

Gram-Schmidt