CHECK LIST

Human-Humanoid Imitation: A Study on Movement Variability

Miguel P. Xochicale Participant: p___; Date:__/__ /2017 Time: ___:__

1.	Informa	tion	ı				
\circ	1.1 Part	icipa	ant Information Sheet	○ 1.2 Anthropometric Data			
	1.3 Sitti	ng t	he participant on the Chair				
		_	ecording Video	○ 1.5 Show particip	ant n to	the camera	
	1.4 Duai	0 100	cording video	1.0 Show particip	an p 00	one camera	
2.	Setting	$\mathbf{U}\mathbf{p}$	Sensors				
0	3.1.a Hu	ımaı	n-Image Int [NO BEAT]				
[Status	Status Description					
Ī		Hor Normal					
Ī	☐ Ver Normal						
Ī		☐ Hor Fast					
Ī		□ Ver Fast					
			-		G		
	Status Description				Status HRI		
	HII □ Create Data Path						
	☐ Turn ON the sensors						
		☐ Pair the sensor [sensor number and port number]					
		Set the sampling rate to 50 Hz					
		Open settings for Time Sync parameters					
		Compute the Time Sync parameters					
		PrintScreen the Time Sync parameters and Save Capture					
			Close settings and set parameters				
		Start Recording data Shake all sensors					
_					1	D.1.	
\bigcirc	○ 2.1.a Attach Sensors to the Participant (check sensor orientation)						
			Sensors to the Participant	2.2.b Attach Sens		Participant	
	(check sensor orientation)			(check sensor orientation)			
3.	Experim						
	() 3.1.a	Hu	man-Image Int [NO BEAT]				
	Stat	us	Description				
			Hor Normal				
			Ver Normal				
			Hor Fast				
			Ver Fast				
○ 3.2.b Human-Robot Int [BEAT]							
	Stat	us	Description				
			$./\mathrm{HN.sh}\;\mathrm{p}_{}$				

./VN.sh p__ ./HF.sh p__ ./VF.sh p__ \bigcirc 3.2.a Human-Image Int [BEAT]

Status	Description		
	aplay HN_beat.wav		
	aplay VN_beat.wav		
	aplay HF_beat.wav		
	aplay VF_beat.wav		

4. Stop

- 4.1.a Stop Sensor Recording

○ 4.2.a Save Data

 $\bigcirc\,$ 4.2.b Save Data

○ 4.3.a Disconect Sensors

 \bigcirc 4.3.b Disconect Sensors

 \bigcirc 4.1.b Stop Sensor Recording

 \bigcirc 4.4 Stop Video Recording

5. Notes