

A

B

C

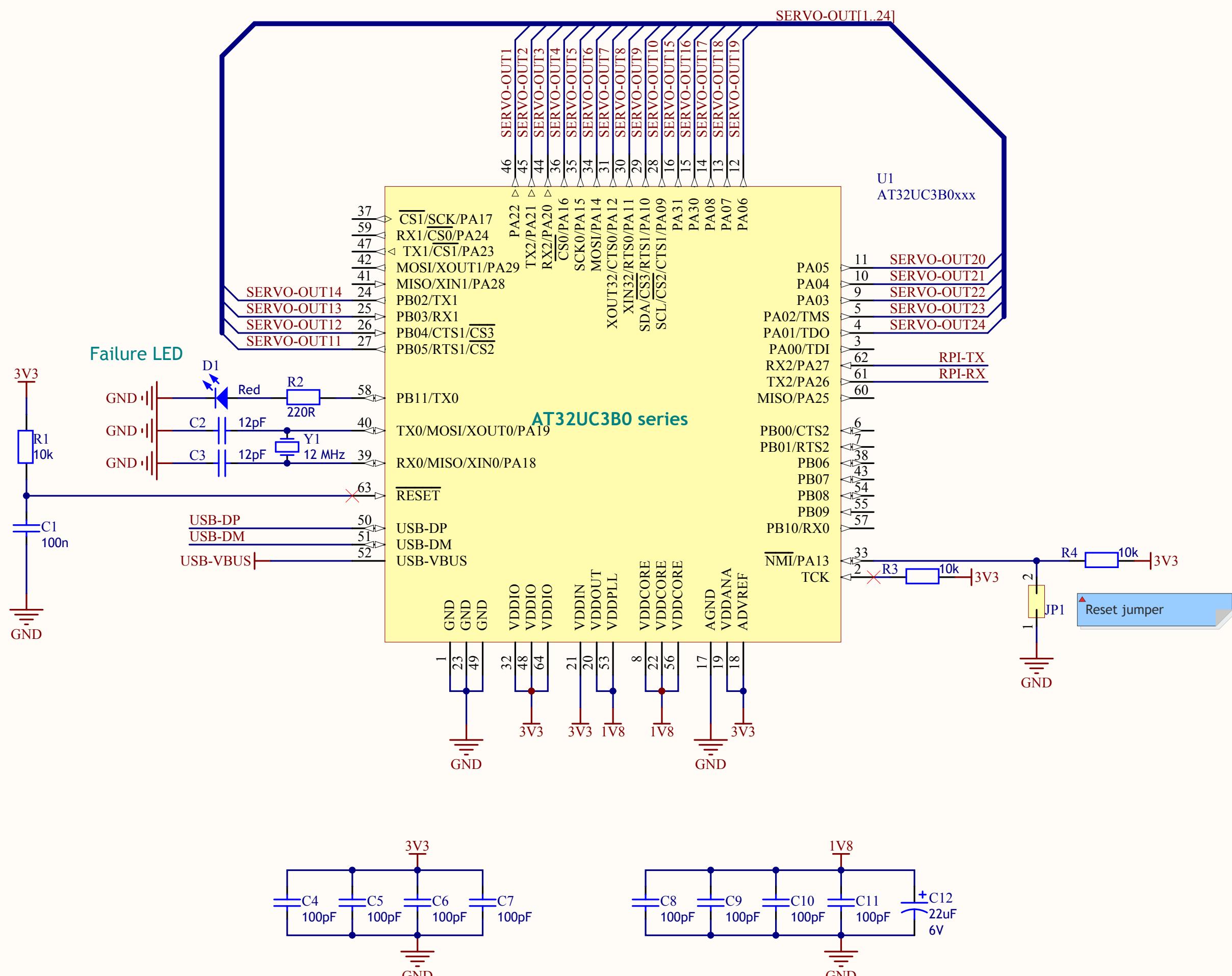
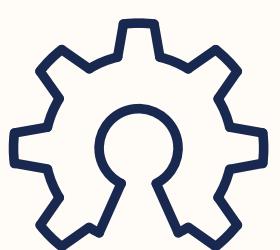
D

A

B

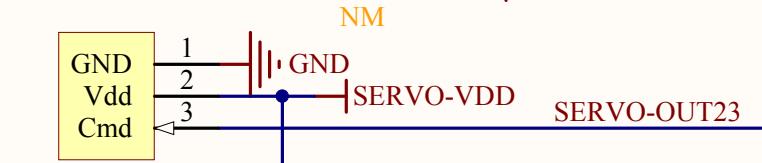
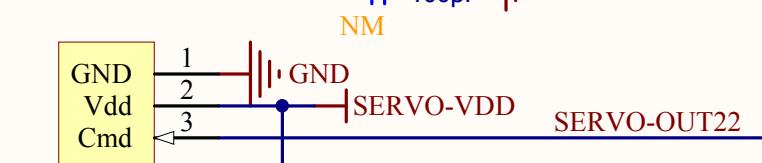
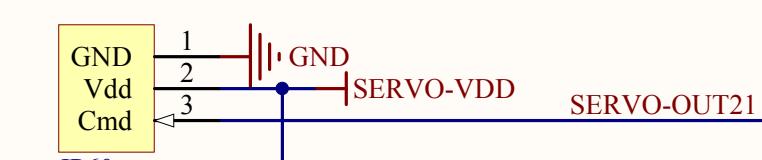
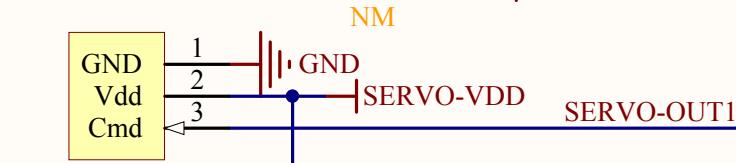
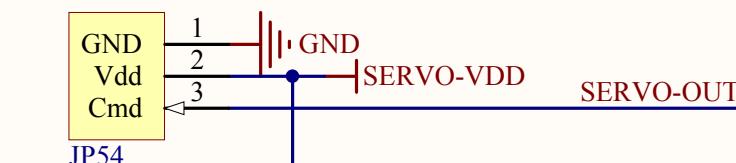
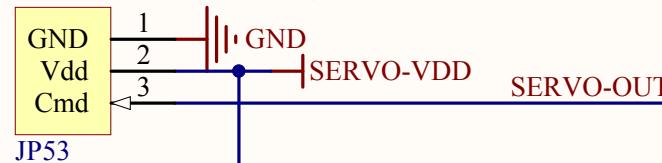
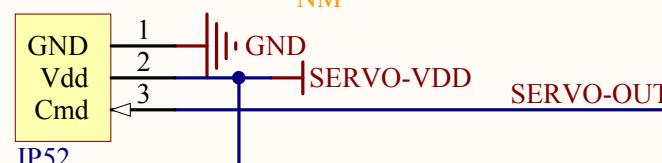
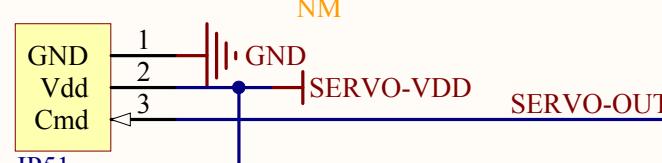
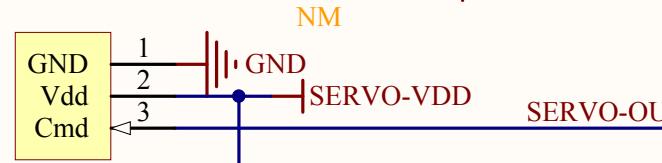
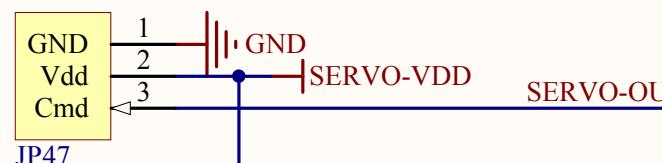
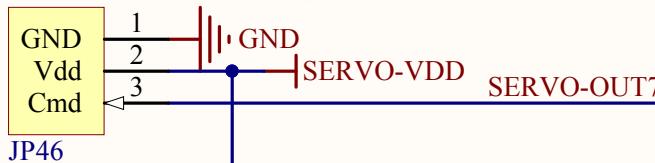
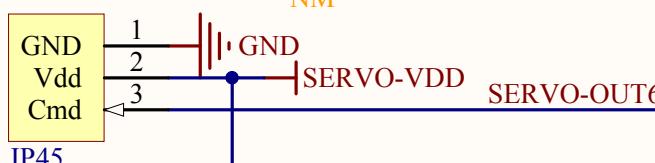
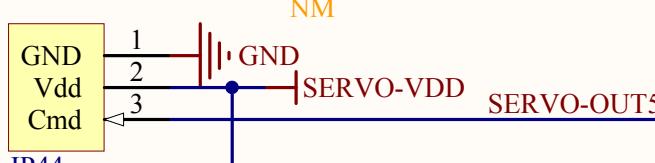
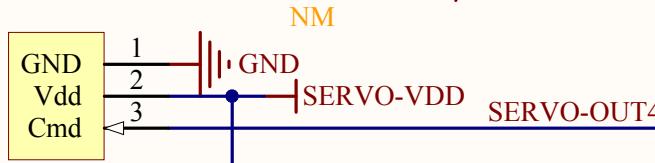
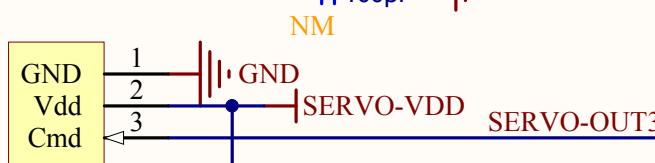
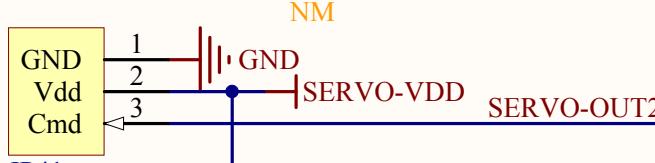
C

D

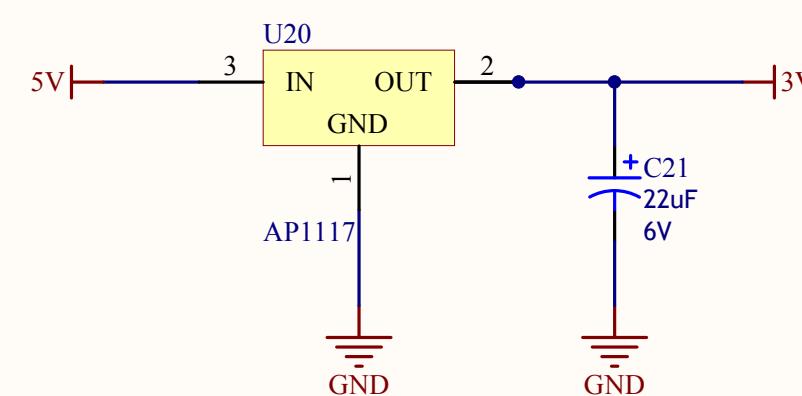
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open hardware

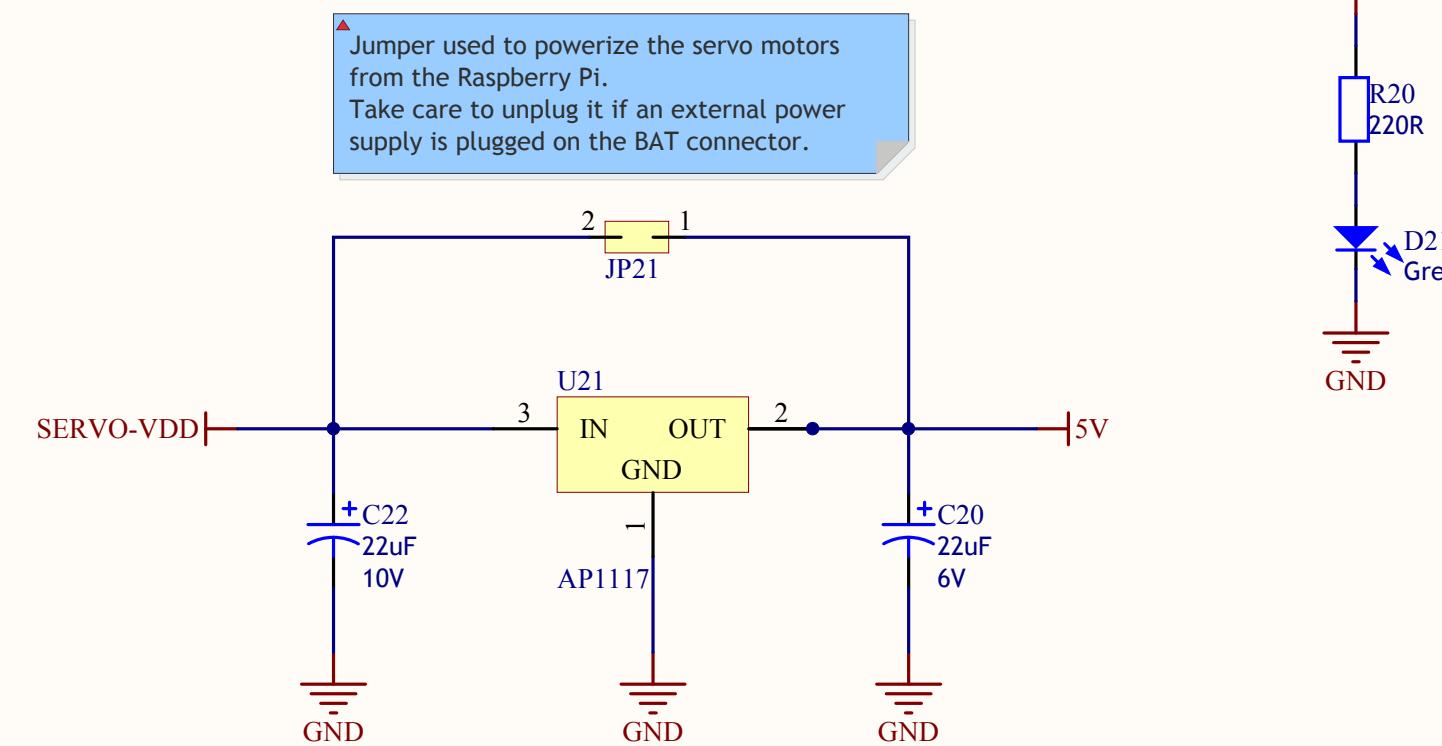
A

Title **OpenSCB: SERVO Outputs**Size: **A4** Number: **1** Revision: **0.2**Date: **20/08/2012** Time: **23:46:16** Sheet **2** of **4**File: **C:\Users\Matthieu\Desktop\Serve.my-pi\Schematics\SERVO-Outputs.SchDoc***OpenSCB*

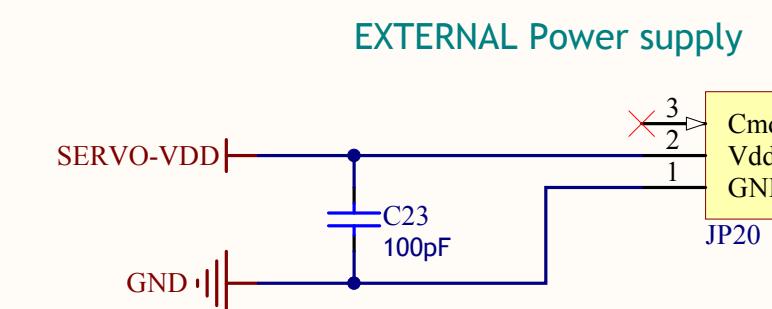
A



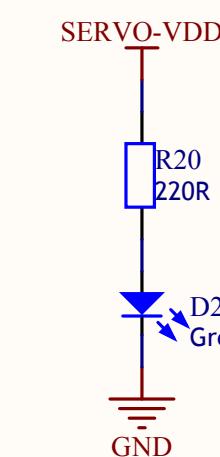
B



External power supply. Connect this to a battery or any power source < 10 V (servo motors usually require 6V max)



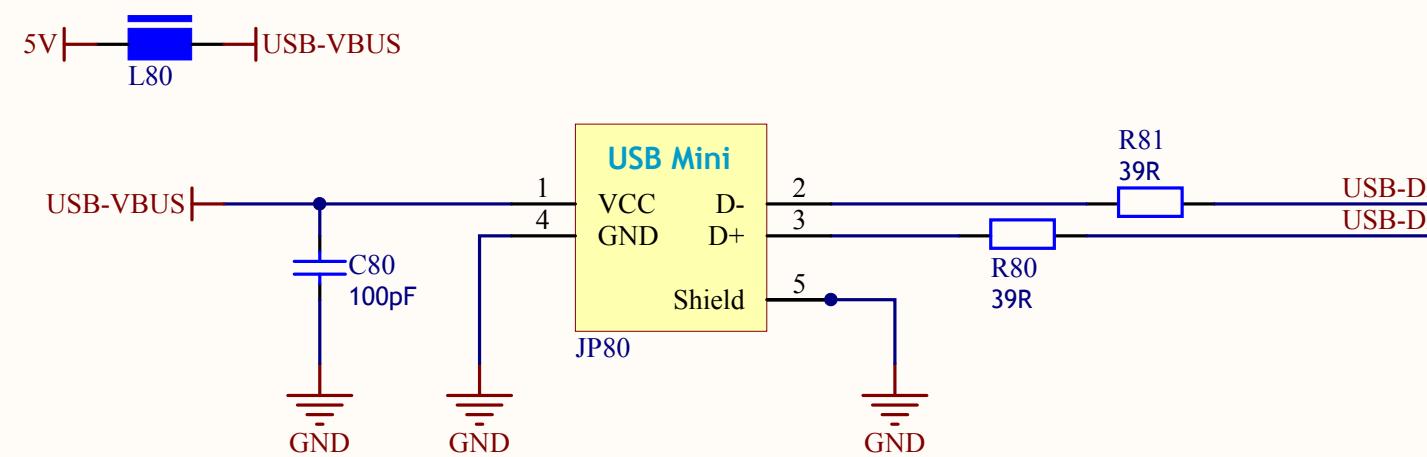
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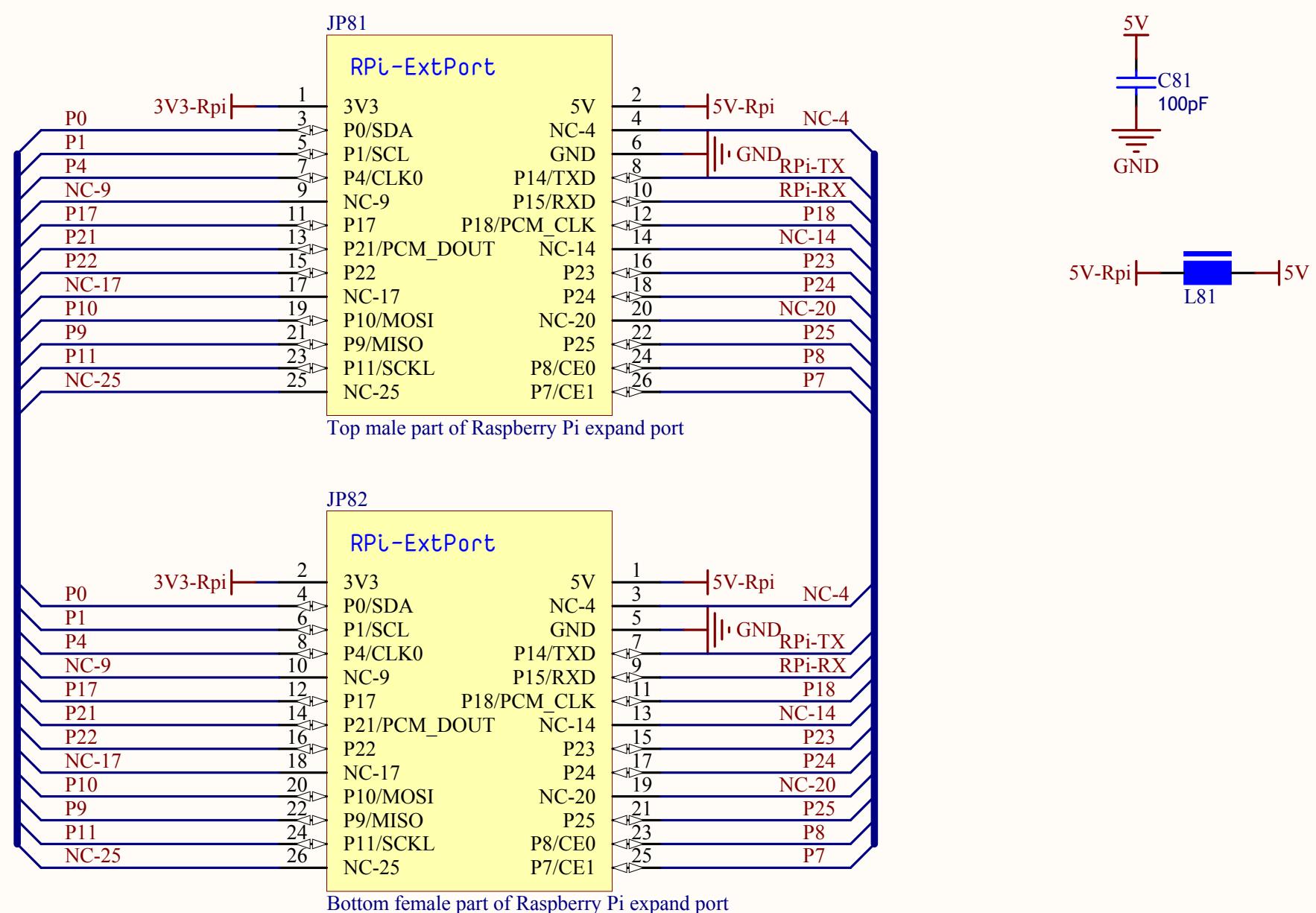
D

Title <b>OpenSCB: POWER</b>			OpenSCB
Size: A4	Number:	Revision: 0.2	
Date: 20/08/2012	Time: 23:46:17	Sheet 3 of 4	
File: C:\Users\Matthieu\Desktop\Serve.my-pi\Schematics\Power.SchDoc			

A

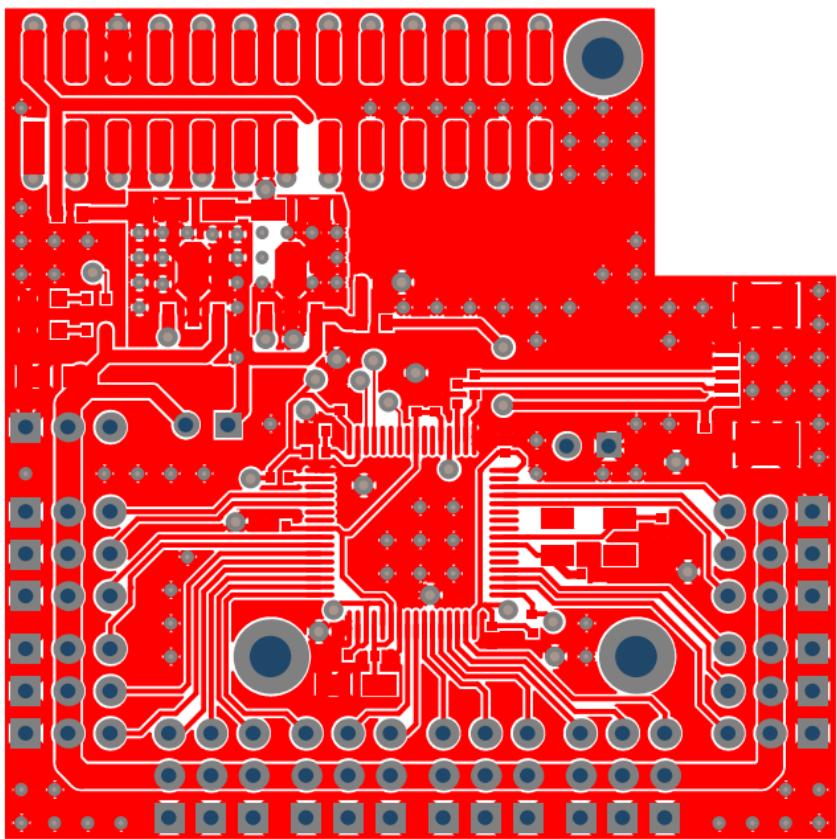


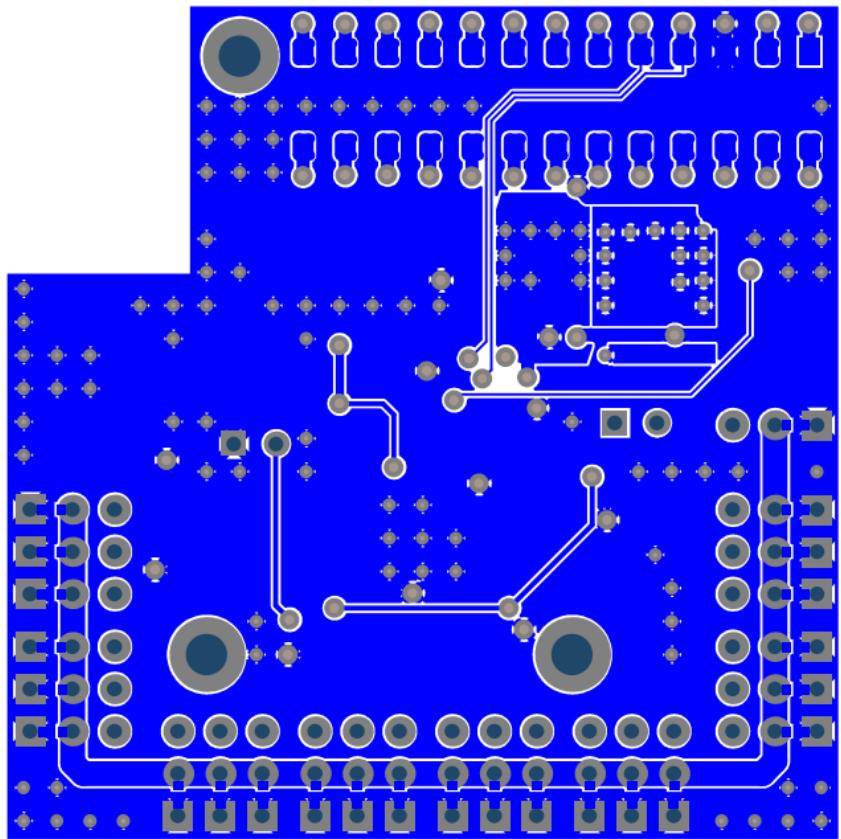
B



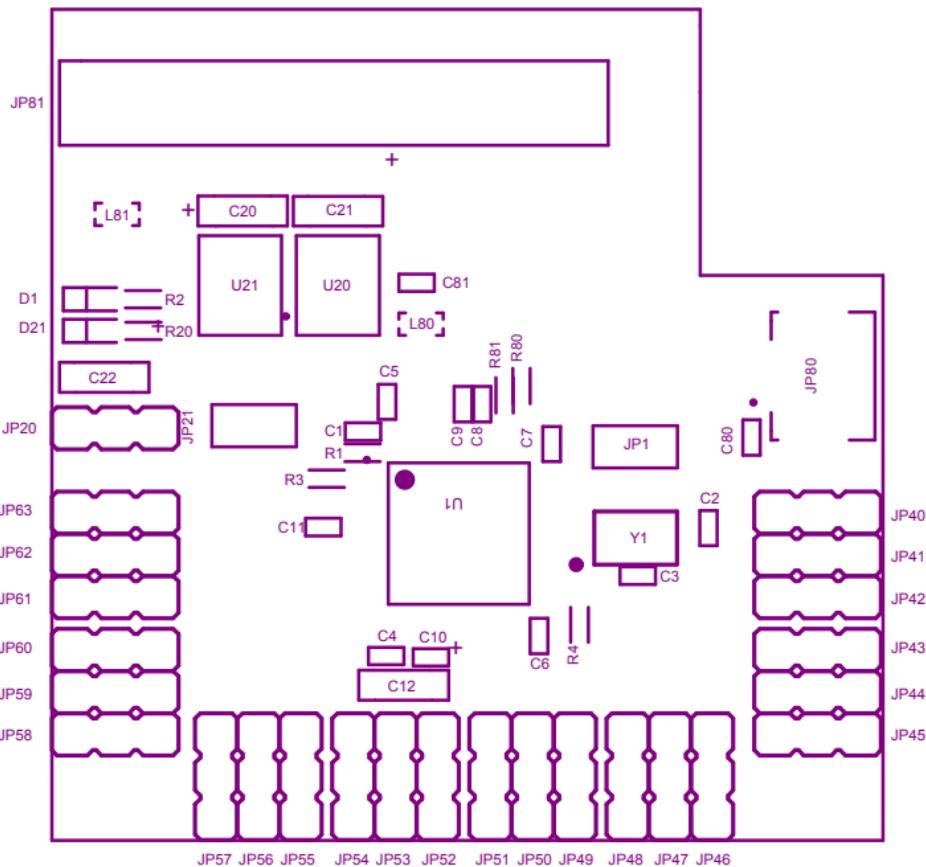
C

Title <b>OpenSCB: COM</b>		
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Date: 20/08/2012	Time: 23:46:17	Sheet 4 of 4
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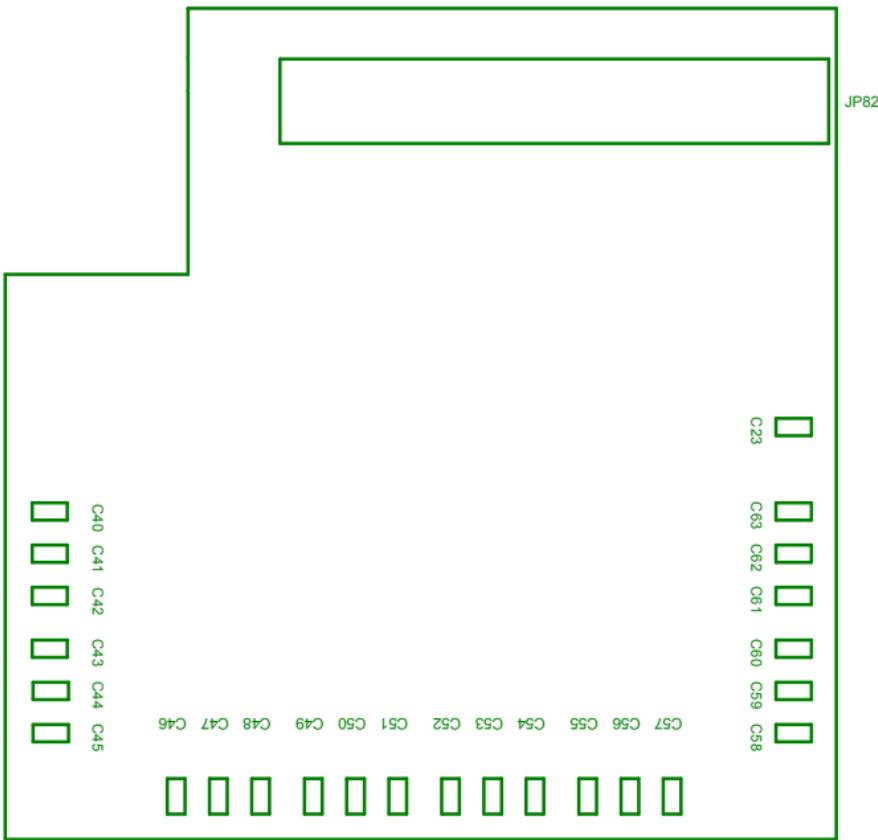




# TOP Assembly layout



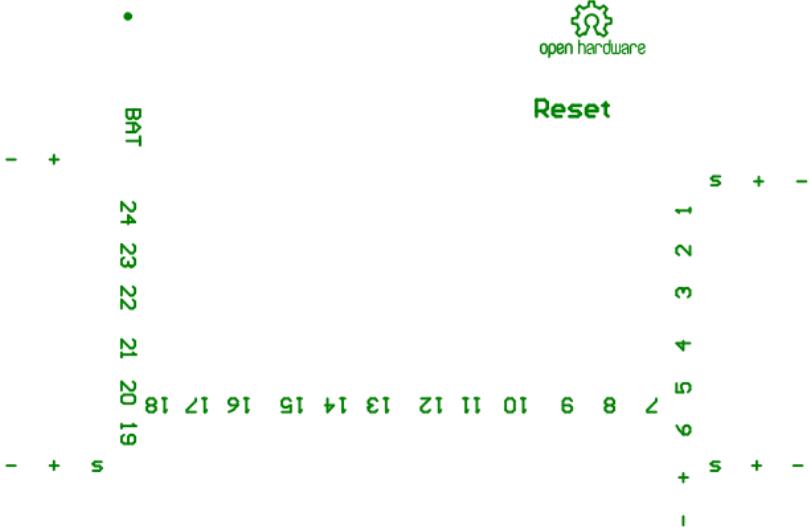
# BOTTOM Assembly layout



**Serve.my-pi.org**  
rev A  
24 ch servo board  
for Raspberry Pi



**Reset**



Serve.my-pi.org  
24 ch servo board  
for Raspberry Pi

rev A



Reset

BAT

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