## Sync device data packet format

0	_ 1	2	3 4			
uint8 <b>cmd</b>				Description	Mode	Reply
uint8	uint32 <b>acq_period_us</b>			Set <u>A</u> cquisition period between frames/bursts	S	OK\n
uint8	uint32 <b>n_frames</b>			Start <u>C</u> ontinuous imaging	С	OK\n
uint8 <b>'D'</b>	uint32 <b>shutter_delay_us</b>			Set shutter <u>D</u> elay	CS	OK\n
uint8 <b>'E'</b>	uint32 <b>exp_time_us</b>			Set laser <u>E</u> xposure time	CS	OK\n
uint8 <b>'F'</b>	uint32 fluidics_frame		me	Set frame for micro <u>f</u> luidic trigger	CS	OK\n
uint8 <b>'I'</b>	uint32 cam_readout_us		ıt_us	Set camera readout <u>I</u> nterval	CS	OK\n
uint8	uint8 lasers	bool ALEX		Set <u>L</u> aser shutter states	CS	OK\n
uint8 'M'				<u>M</u> anually open laser shutters	NA	OK\n
uint8				Stop acquisition ( <u>Q</u> uit)	CS	OK\n
uint8	uint8 addr			Read register	NA	uint8 <b>value</b>
uint8 <b>'S'</b>	uint32 <b>n_frames</b>			Start <u>S</u> troboscopic imaging	S	OK\n
uint8 'W'	uint8 addr	uint8 value		<u>W</u> rite register	NA	
0	1	2	3 4			

## Legend

Normal font shows data type (uint8, uint16).

Bold font shows member names.

Gray hatched areas are filled with ZERO.

Modes: C - continuous, S - stroboscopic (includes ALEX and timelapse)

## **Notes**

Each data packet is always 5 byte long. If shorter than that, pad it with zeros.

On startup, the system prints Synchronization device is ready. Firmware version: <x.y.z>\n Wrong formatted packets are silently ignored (wrong command or too short data packet). If a command has wrong argument values, the reply is  $ERR \setminus n$  (NOT IMPLEMENTED) Once the data acquisition is completed, the reply is DONE \n