## **Data packet format**

| uint8<br><b>cmd</b>       |                           |                           |                           |                           |                           |                           |                           |                           | Member                   | Description                             | Reply                 |
|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|---------------------------|--------------------------|---|-----------------------|
| uint8<br><b>bytes</b> [0] | uint8<br><b>bytes</b> [1] | uint8<br><b>bytes</b> [2] | uint8<br><b>bytes</b> [3] | uint8<br><b>bytes</b> [4] | uint8<br><b>bytes</b> [5] | uint8<br><b>bytes</b> [6] | uint8<br><b>bytes</b> [7] | uint8<br><b>bytes</b> [8] | uint8 <b>bytes</b> [9]   |   |                       |
| uint8<br><i>'R'</i>       | uint8<br>addr             |                           |                           |                           |                           |                           |                           |                           | struct Register <b>R</b> | Read register                           | uint8<br><b>value</b> |
| uint8<br><b>'W'</b>       | uint8<br>addr             | uint8<br><b>value</b>     |                           |                           |                           |                           |                           |                           | struct Register <b>R</b> | <u>W</u> rite register                  | OK\n                  |
| uint8<br><b>'F'</b>       | fluidics_                 | t16<br>delay_m<br>s       |                           |                           |                           |                           |                           |                           | struct Fluidics <b>F</b> | Set <u>F</u> luidics<br>injection delay | OK\n                  |
| uint8                     | uint8<br>active           | uint8<br>idle             | bool<br><b>ALEX</b>       |                           |                           |                           |                           |                           | struct Shutter <b>L</b>  | Set <u>L</u> aser<br>shutter states     | OK\n                  |
| uint8<br><b>'C'</b>       | uint16 exp_time_n64us     |                           | uint16<br><b>n_frames</b> |                           |                           |                           |                           |                           | struct Timer1 <b>T</b>   | Start<br><u>C</u> ontinuous<br>timer    | OK\n                  |
| uint8<br><b>'S'</b>       | uint16 exp_time_n64us     |                           | uint16<br>n_frames        |                           | uin<br>interfi<br>time_   | _                         | uin<br>timela<br>dela     | apse_                     | struct Timer1 <b>T</b>   | Start<br><u>S</u> troboscopic<br>timer  | OK\n                  |
| uint8<br><b>'E'</b>       |                           | t16<br><b>e_n64us</b>     |                           |                           |                           |                           |                           |                           | struct Timer1 <b>T</b>   | Change<br><u>E</u> xposure time         | OK\n                  |
| uint8<br><b>'Q'</b>       |                           |                           |                           |                           |                           |                           |                           |                           |                          | Stop timer<br>( <u>Q</u> uit)           | OK\n                  |

## Legend

Color shows belonging to a particular data structure.

Normal font shows data type (uint8, uint16).

Bold font shows member names.

Bold italic shows constant values.

Gray hatched areas are filled with ZERO.

## **Notes**

Each data packet is always 9 byte long. If shorter than 9 bytes, pad it with zeros.

On startup, the system prints Arduino is ready. Firmware version:  $\langle x,y,z \rangle / n$ 

Wrong formatted packets are silently ignored (wrong command or shorter than 9 bytes).

If a command has wrong arguments, the reply is  $ERR \setminus n$ 

Once the data acquisition is completed, the reply is  $\textit{DONE} \setminus n$