Course CS50 Assignment 0 – Pong Game Mohammad Ali Yaghan -

The first step was to allow the use to select whether he/she wants an automatic paddle, which one, or both (at the start state).



A global variable AUTO_MODE was created to store the user's choice (in the main.lua file) it default value is 0 (i.e. no auto paddels)

```
PADDLE_SPEED = 200

-- Auto mode

AUTO MODE = 0 --the auto mode tells the game if the paddels are automatically played in what sense

-- 0 -> no paddel is auto
-- 1 -> left paddel is auto
-- 2 -> right paddel is auto
-- 3 -> both paddels are auto

B--[[

Called just once at the beginning of the game; used to set up game objects, variables, etc. and prepare the game world.

Function love.load()
-- set love's default filter to "nearest-neighbor", which essentially
```

A call to a new function called: "determineAuto" from within "love.keypressed" was placed

```
11--
   □ function love.keypressed(key)
         -- `key` will be whatever key this callback detected as pressed
353 白
         if key == 'escape' then
              - the function LÖVE2D uses to quit the application
354
             love.event.quit()
         -- if we press enter during either the start or serve phase, it should
         -- transition to the next appropriate state
         elseif key == 'enter' or key == 'return' then
             if gameState == 'start' then
                 gameState = 'serve'
361
             elseif gameState == 'serve' then
                 gameState = 'play'
             elseif gameState == 'done' then
364
                 -- game is simply in a restart phase here, but will set the serving
                 -- player to the opponent of whomever won for fairness!
366
                 gameState = 'serve'
                 ball:reset()
                 -- reset scores to 0
869
                 player1Score = 0
                 player2Score = 0
                  -- decide serving player as the opposite of who won
371
                 if winningPlayer == 1 then
73
                     servingPlayer = 2
74
                 else
                     servingPlayer = 1
376
                 end
             end
378
         else
379
             determineAuto(key)
882
    end
883
84 pfunction determineAuto(key)
885 A
         if (key == 'L' or key == 'l') and (gameState == 'start' or gameState == 'done') then
386
             AUTO MODE = 1
         elseif (key == 'R' or key =='r') and (gameState == 'start' or gameState == 'done') then
387
             AUTO MODE = 2
         elseif (key == 'B' or key == 'b') and (gameState == 'start' or gameState == 'done') then
889
390
             AUTO MODE = 3
         end
    end
```

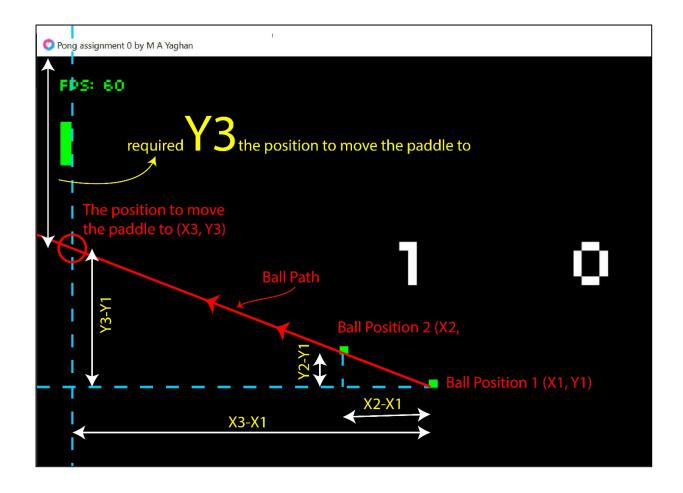
and a line was added to "love.draw" function to aske for user's input

```
drawing all of our game objects and more to the screen.
400 Ffunction love.draw()
             -- begin drawing with push, in our virtual resolution
             push:start()
403
404
             -----love.graphics.setBackgroundColor(100, 45, 55, 255)
             love.graphics.clear(0, 0, 0, 255)
406
407
             -- render different things depending on which part of the game we're in
408
             \quad \textbf{if} \ \ \mathsf{gameState} \ \textbf{==} \ \ \texttt{'start'} \ \ \textbf{then} \\
                   -- UI messages
410
                  love.graphics.setColor(0,
                  Josephics.printf('Welcome to Pong!', 0, 10, VIRTUAL_WIDTH, 'center')
love.graphics.printf('Press Enter to begin!', 0, 20, VIRTUAL_WIDTH, 'center')
love.graphics.printf('Press R or L to pick the Auto Paddel - B for both !', 0, 30, VIRTUAL_WIDTH, 'center')
412
414
                         ameState ==
                                       'serve' then
416
                  love.graphics.setFor
                  love.graphics.printf('Player' .. tostring(servingPlayer) .. "'s serve!",
```

In the "love.update" where the paddles are moved, a condition to check the AUTO_MODE value was added to decide whether to allow any paddle to be moved by the key's input

```
-- paddles can move no matter what state we're in
240
241
          if AUTO MODE == 0 or AUTO MODE == 2 then --player1 is not auto
242
243
              if love.keyboard.isDown('w') then
244
                  player1.dy = -PADDLE SPEED
245
              elseif love.keyboard.isDown('s') then
246
                 player1.dy = PADDLE_SPEED
247
              else
                 player1.dy = 0
248
249
              end
          else -- player 1 is in auto mode
              if ball.x - ball.PrevX < 0 then -- the ball is moving towards player1
                  player1:movePaddleTo (findBallintersecting (ball.x, ball.y, ball.PrevX, ball.PrevY, 10))
              elseif ball.x - ball.PrevX > 0 then --the ball is moving away
   player1:movePaddleTo(VIRTUAL_HEIGHT / 2)
254
              -- if it was 0 then do nothing it is the initial stage
256
              end
          end
           - plaver 2
          if AUTO MODE == 0 or AUTO MODE == 1 then --palyer2 is not auto
              if love.keyboard.isDown('up') then
                  player2.dy = -PADDLE SPEED
              elseif love.keyboard.isDown('down') then
264
                 player2.dy = PADDLE_SPEED
                  player2.dy = 0
              end
          else -- player2 is in auto mode
              if ball.x - ball.PrevX > 0 then --the ball is moving towards player2
269
                 player2:movePaddleTo(findBallintersecting (ball.x, ball.y, ball.PrevX, ball.PrevY, VIRTUAL WIDTH-10))
              elseif ball.x - ball.PrevX < 0 then --ball is moving away form player2
                 player2:movePaddleTo(VIRTUAL_HEIGHT / 2)
              -- if it was 0 then do nothing it is the initial stage
274
              end
276
          -- update our ball based on its DX and DY only if we're in play state;
          -- scale the velocity by dt so movement is framerate-independent
          if gameState == 'play
              ball:update(dt)
                                                                      length: 15,261 lines: 466
                                                                                             Ln:351 Col:25 Sel:15|1
```

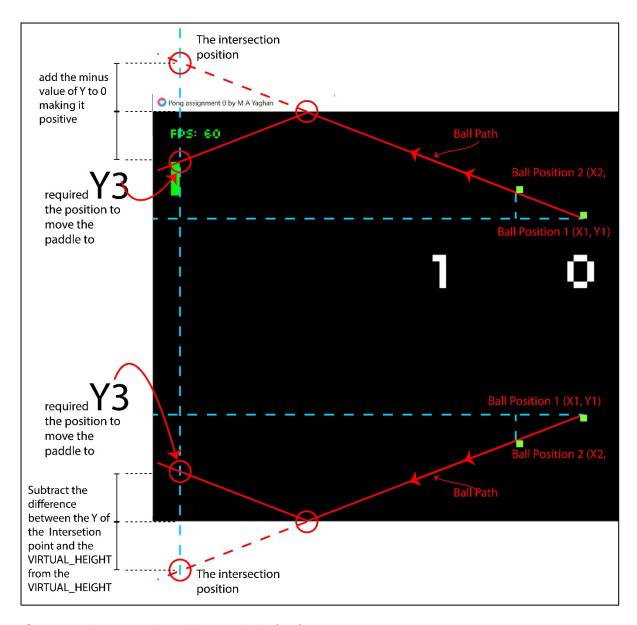
Second, the logic to anticipate where to move the paddle to be able to collide with the ball can be explained in the following drawing



According to two positions of the ball, its straight path will collide with the vertical line of the paddle (here the left paddle, but the logic works for both). The Y value for the intersection point (Y3 in the figure) will be deducted from the following formula

$$Y3 = \frac{(Y2 - Y1)}{(X2 - X1)} \times (X3 - X1) + Y1$$

In case of the intersection point was bellow zero or higher than the VIRTUAL_HEIGHT then a reflection in the path occurs according to the following figure



If Y3 < 0 then Y3 should equal abs(Y3)

If Y3 > VIRTUAL HEIGHT then

Y3 should equal VIRTUAL_HEIGHT - (Y3- VIRTUAL_HEIGHT)

In order to determine the ball path two extra attributes has to be added to the ball class (PrevX and PrevY) in the initialization of Ball:init

```
Ball = Class{}
5
6
   □function Ball:init(x, y, width, height)
        self.x = x
9
        self.y = y
20
        self.width
         self.height = height
21
2
         self.PrevX = self.x
23
         self.PrevY = self.v
24
5
         -- these variables are for keeping track
        -- X and Y axis, since the ball can move
6
        self.dy = 0
        self.dx = 0
9
    end
```

And they will be updated in the "Ball:update" function

```
60
   end
61
62
   □function Ball:update(dt)
63
         self.PrevX = self.x
64
         self.PrevY = self.y
         self.x = self.x + self.dx * dt
65
         self.y = self.y + self.dy * dt
66
67
    end
68
```

To find the position to move the paddle to, I added a function in the main file

```
if bxpast == bx then
    return VIRTUAL_HEIGHT / 2
else
    Yinter = ((Xedge - bx)*(bypast - by))/(bxpast - bx) + by

if (Yinter > 0) and (Yinter < VIRTUAL_HEIGHT) then -- it is within the wall
    return Yinter
    elseif Yinter < 0 then
        Yinter = -Yinter -- it should reflect
        return Yinter
    else
        Yinter = VIRTUAL_HEIGHT - (Yinter - VIRTUAL_HEIGHT) -- it should reflect
        return Yinter
    else
        Yinter = VIRTUAL_HEIGHT - (Yinter - VIRTUAL_HEIGHT) -- it should reflect
        return Yinter
    end
end
return VIRTUAL_HEIGHT / 2 --in case of an unexpected situation retun the mid poi
end</pre>
```

It will return the position as explained or the mid-point is case of undefined situations.

Then we will need a function that actually moves the paddle to a predefined position. I added Paddle:movePaddleTo (YPos) to the Paddle class

```
53
    -- a function that moves the paddle towards a defined YPos
55 ☐ function Paddle:movePaddleTo (YPos)
        Mvalue = math.random(1, AUTO MISTAKE) -- the value to make a mistake
57 🖨
        if self.y > YPos + Mvalue then
             self.dy = -PADDLE SPEED
58
59
         elseif self.y < YPos - Mvalue then</pre>
60
             self.dy = PADDLE SPEED
61
         else -- the paddle is in the YPos
62
             self.dy = 0 -- here try to make tollerence
63
         end
64
   end
65
66
```

AUTO_MISTAKE is a global variable defined in the main fine that is randomized every time making it possible for the paddle to miss on the ball.

```
VIRTUAL_HEIGHT = 244

AUTO_MISTAKE = 120 -- a random number to create a mistake in the auto play mode

virtual_Height = 244
```

The greater the value the less accurate the paddle is.

Finally, you can play the game, the files are attached, THANK YOU.

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3rd March 2020