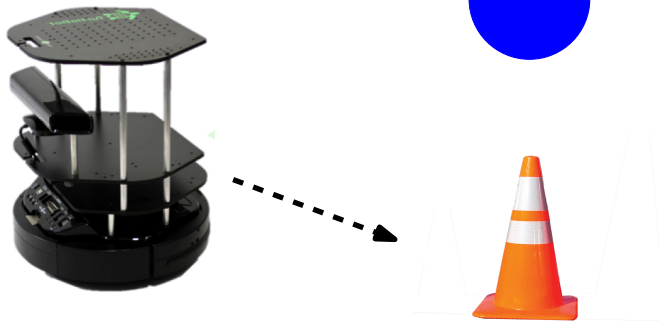


“move to the cone”



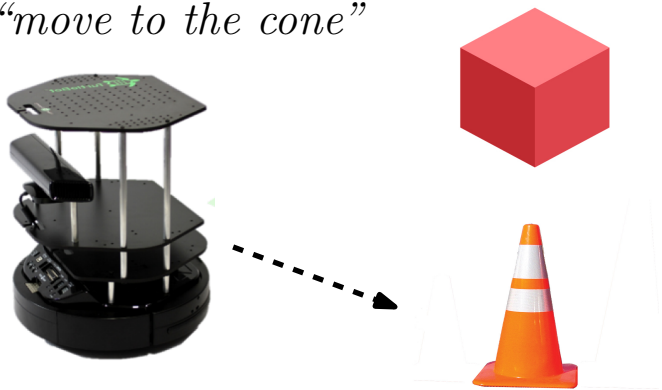
(a)

The robot learns
what a cone is.



(b)

“move to the cone”



(c)

The robot moves to
the known object.



(d)