

Assignment12

December 13, 2018

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- Description: polynomial fitting with regularization
- github: https://github.com/mydream757/Computer_Vision

1. Import libraries

- import needed libraries.

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import numpy.linalg as linalg
```

2. Define functions

- make the clean data

```
In [2]: def fun(x):

    # f = np.sin(x) * (1 / (1 + np.exp(-x)))
    f = np.abs(x) * np.sin(x)
    return f
```

- create matrices of 'A' and 'b'

```
In [3]: def create_A(p, x, l):
    A = np.ones((x.shape))
    for i in range(p+1):
        if i != 0:
            A = np.vstack((A, pow(x,i)))
    A = A.T
    return A
def create_B(n,l,y):
    b = y.reshape((n,1))
    return b
```

- make a eigen matrix.

```
In [4]: def make_l(p):
        e = np.eye(p+1)
        e[0][0] = 0
        return e
```

- compute polynomial using coefficient

```
In [5]: def polyFunc(c,x):
        y = np.zeros(x.shape)

        for i in range(c.size):
            y = y + c[i]*pow(x,i)
        return y
```

3. set the data

- make the clean data and the noisy data

```
In [6]: num      = 1001
        std      = 5

        # x : x-coordinate data
        # y1 : (clean) y-coordinate data
        # y2 : (noisy) y-coordinate data

        n      = np.random.rand(num)
        nn     = n - np.mean(n)
        x      = np.linspace(-10,10,num)
        y1     = fun(x) # clean points
        y2     = y1 + nn * std # noisy points
```

- this is a container of optimal sets

```
In [7]: result_c = []
        result = np.zeros((10,num))
        result_e = np.zeros((10,1))
```

4. compute coefficient and show the results

- show the lamda changing when p is fixed and varing p

```
In [8]: for i in range(10):
        p = i+6 # p is 6 to 15

        for k in range(15):
            l = pow(2,k-8) # lambda = pow(2,-8) to pow(2,6)
```

```

A = create_A(p,x,l)
b = create_B(num,l,y2)
# the
rA = np.concatenate((A,np.sqrt(l)*make_l(p)),axis=0)
rb = np.concatenate((b,np.zeros(p+1).reshape((p+1,1))),axis=0)

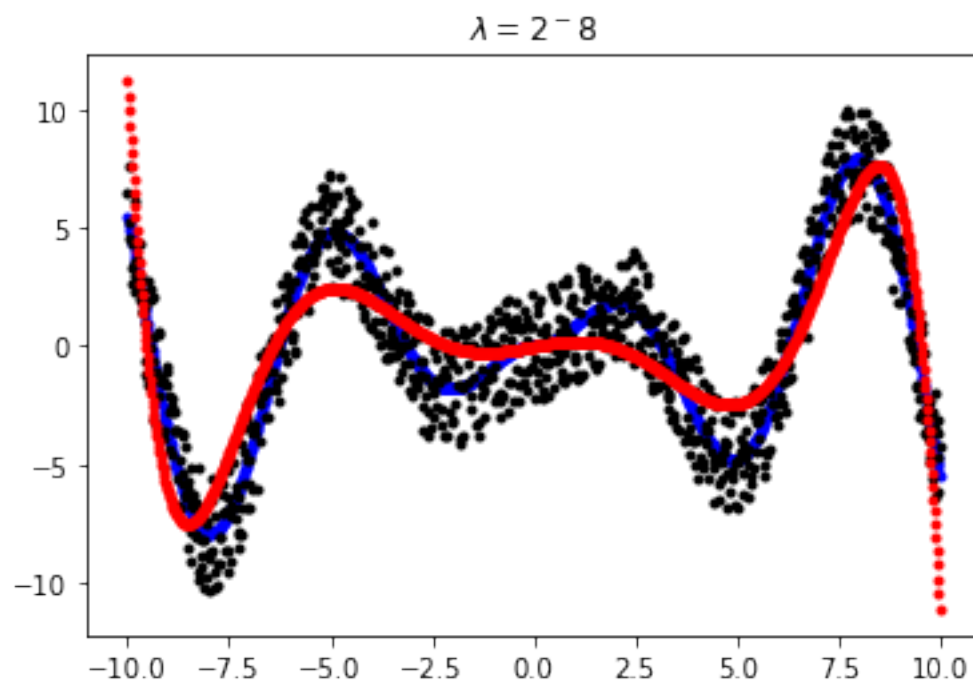
rATA = np.dot(rA.T,rA)
inverse = linalg.inv(rATA)
coeff = np.dot(np.dot(inverse,rA.T),rb)

y3 = np.dot(A,coeff)
r = np.dot(A,coeff) - b
energy = np.dot(r.T,r)
if i==2:
    print('P: ', p)
    #plot the varying lambda when p is fixed
    result_e[k:,0] = energy
    plt.title(r'$\lambda=2^{~\%d}$' %(k-8))
    plt.plot(x,y1,'b.', label = 'clean')
    plt.plot(x,y2,'k.', label = 'noisy')
    plt.plot(x,y3,'r.', label = 'poly fit with lambda')
plt.show()
if k==0:
    temp = energy
    result[i,] = y3.reshape((1001))
    result_c.append(coeff)
elif temp>energy:
    result[i,] = y3.reshape((1001))
    result_c.append(coeff)
    temp = energy

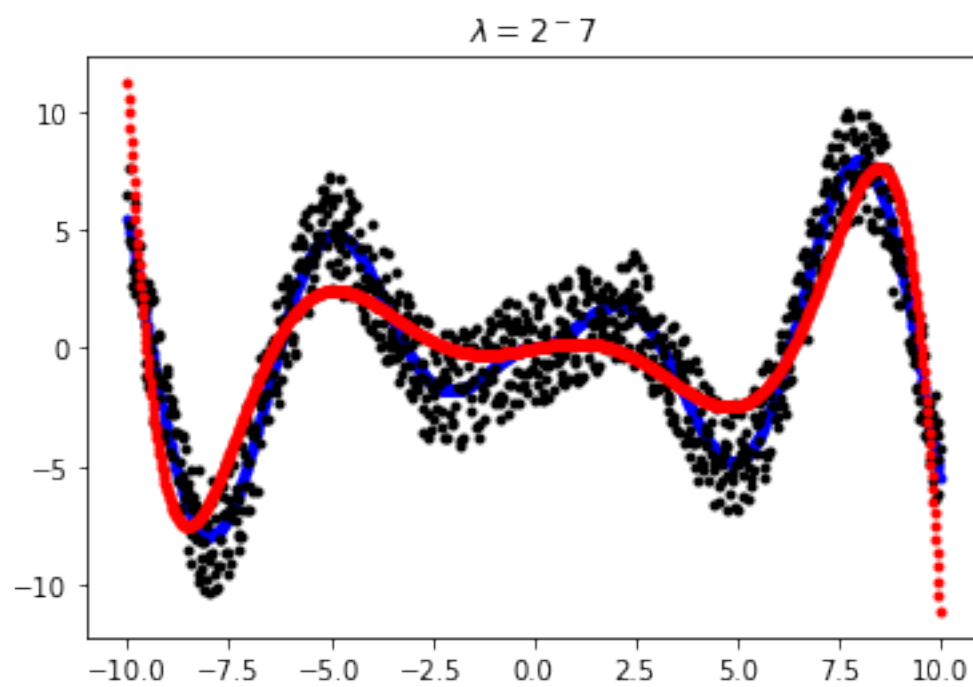
if i==2:
    fig = plt.figure()
    ax =[1,2,3,4,5,6,7,8,9,10]
    result_e.reshape((10,1))
    plt.plot(ax,result_e.reshape((10,1)), 'g-')
    plt.title('Error')
    frame = plt.gca()
    frame.axes.get_xaxis().set_visible(False)
    #frame.axes.get_yaxis().set_visible(False)
    plt.show()

```

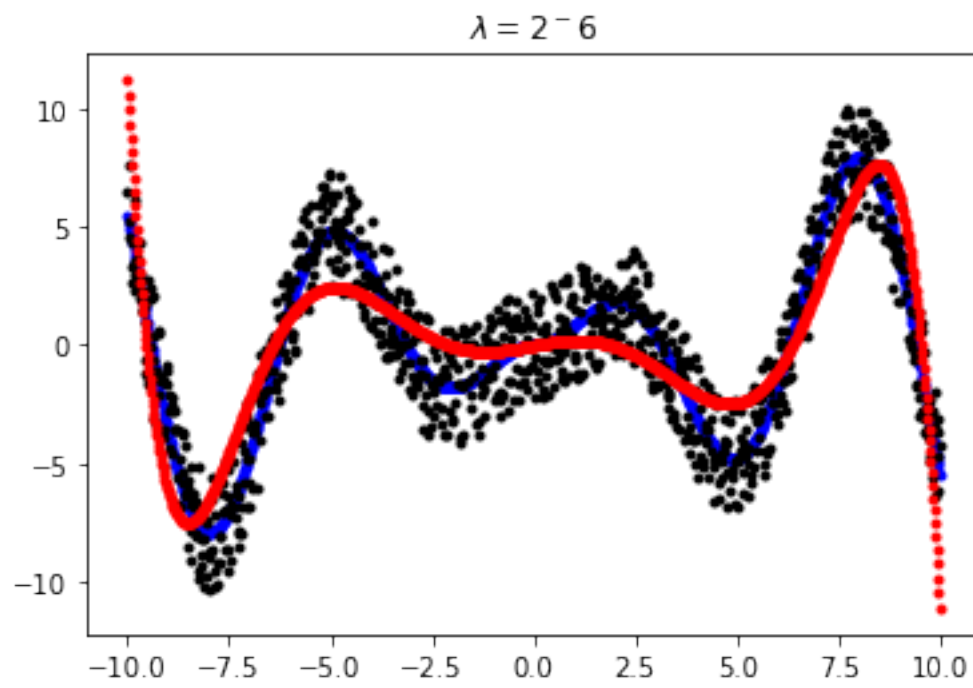
P: 8



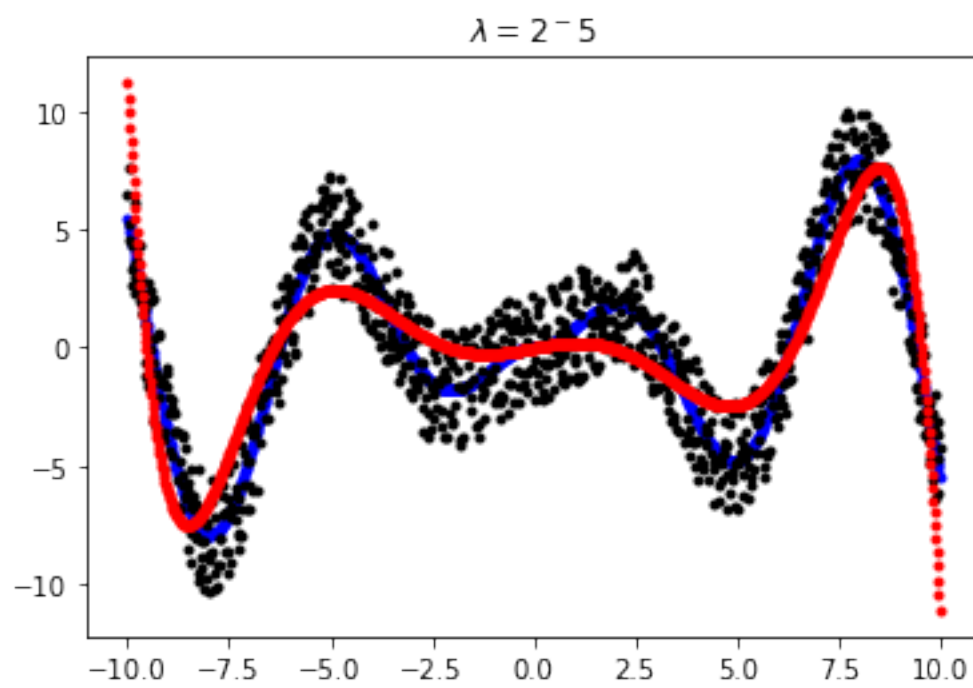
P: 8



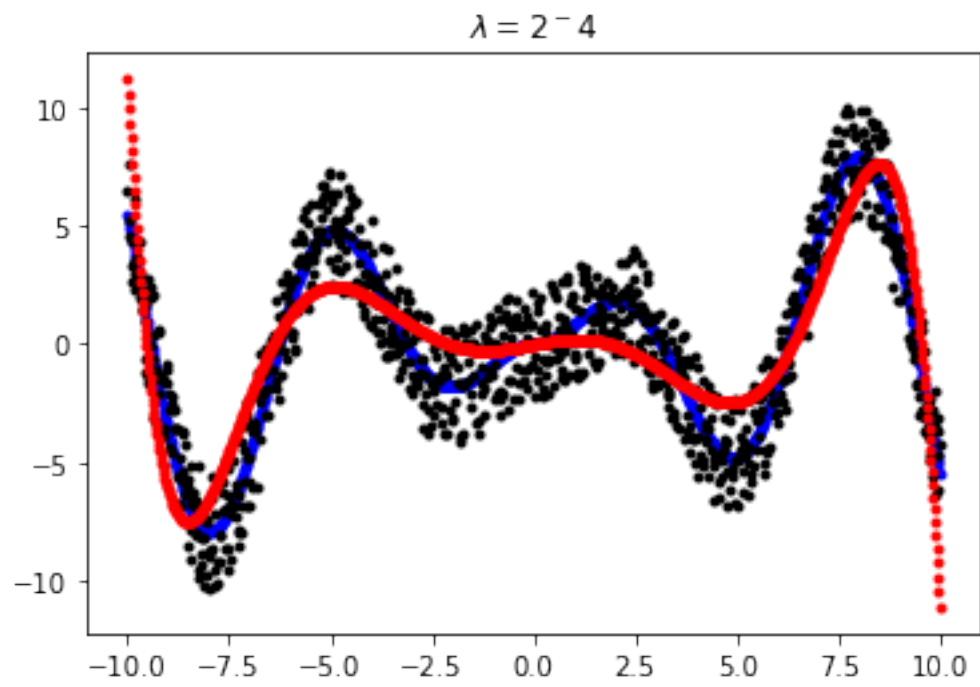
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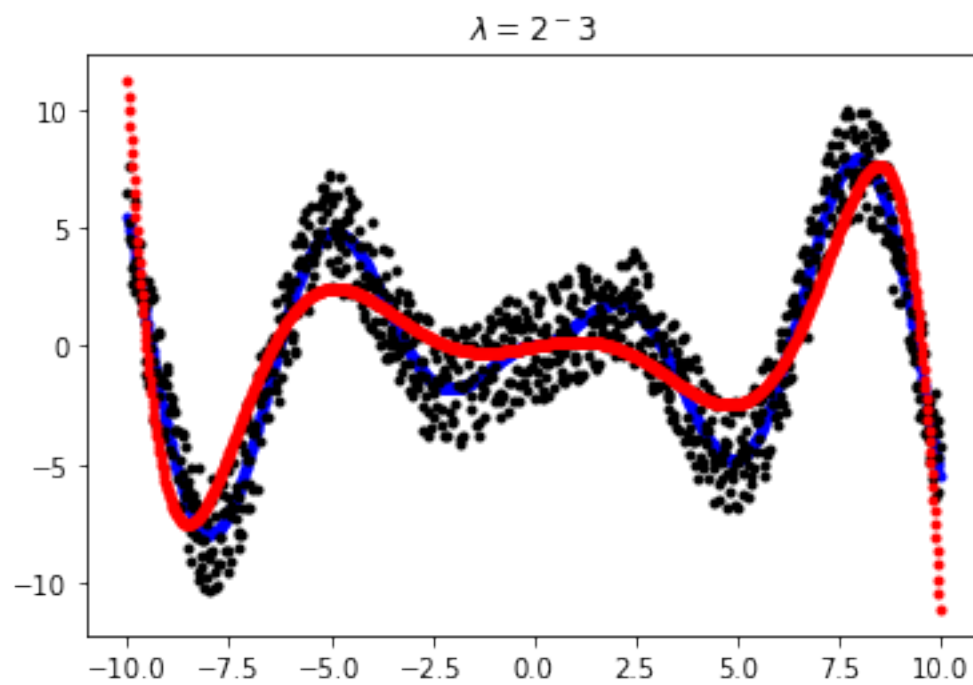
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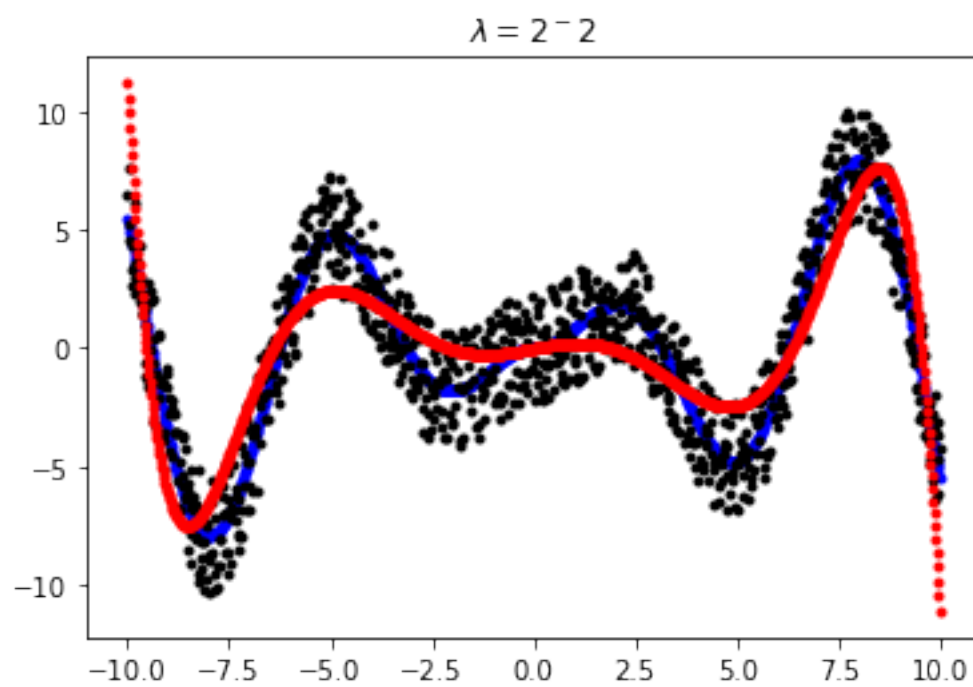
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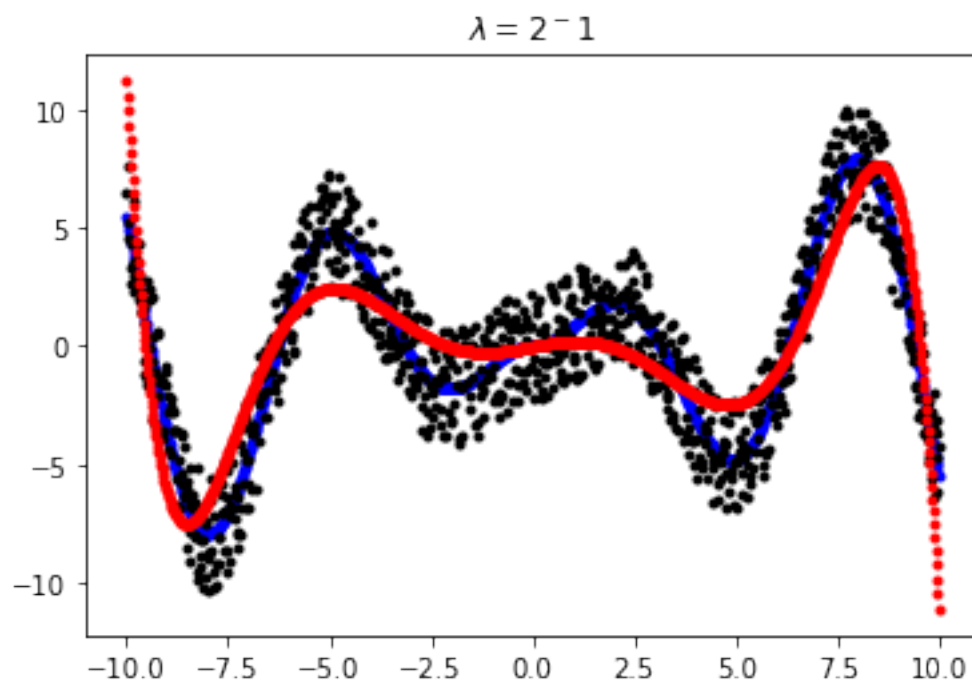
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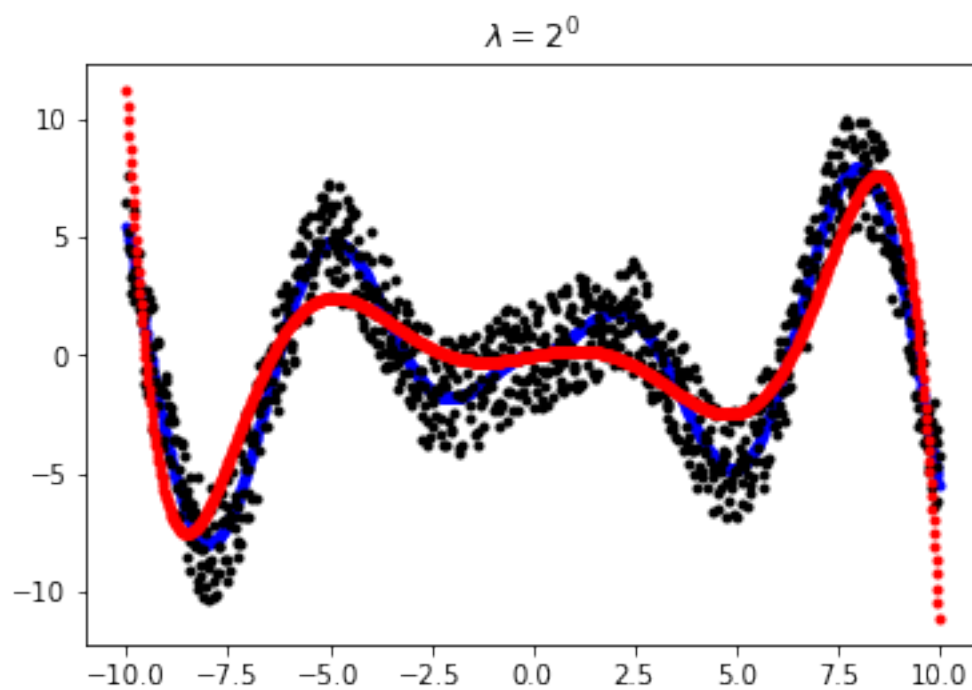
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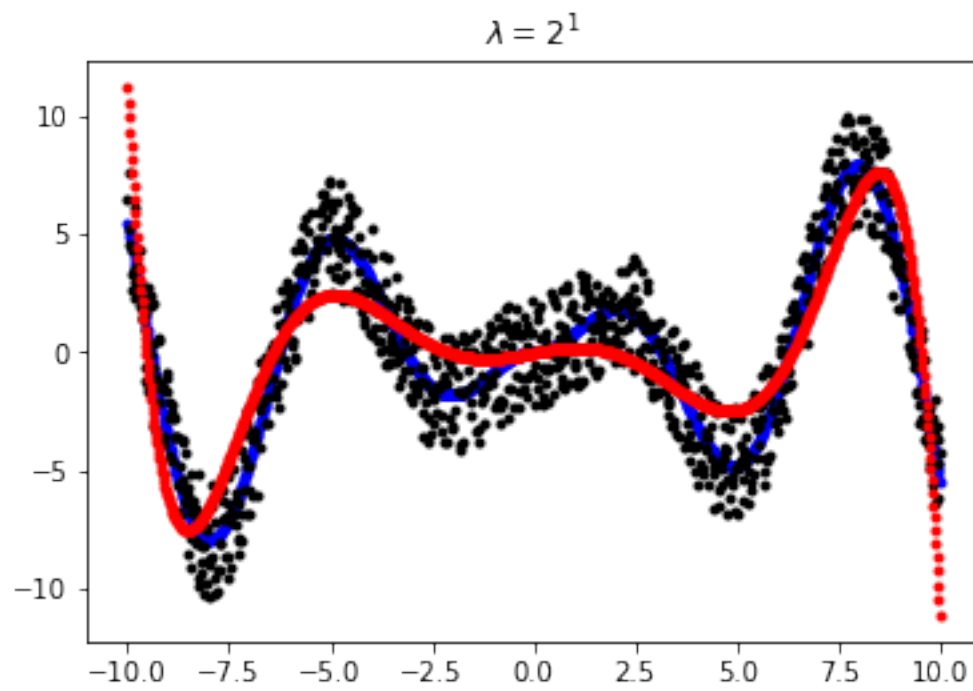
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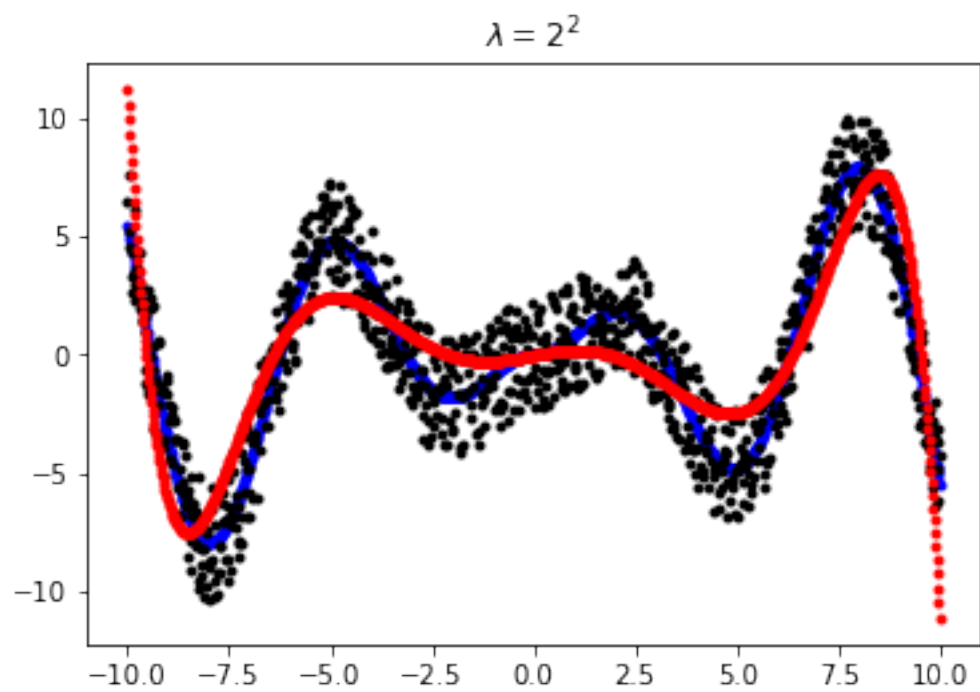
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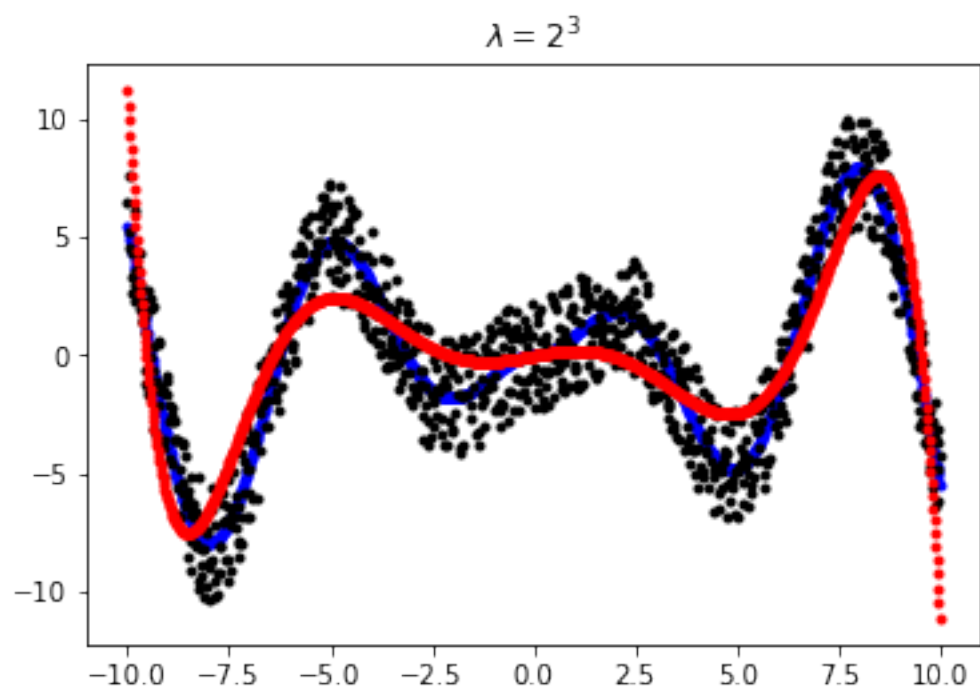
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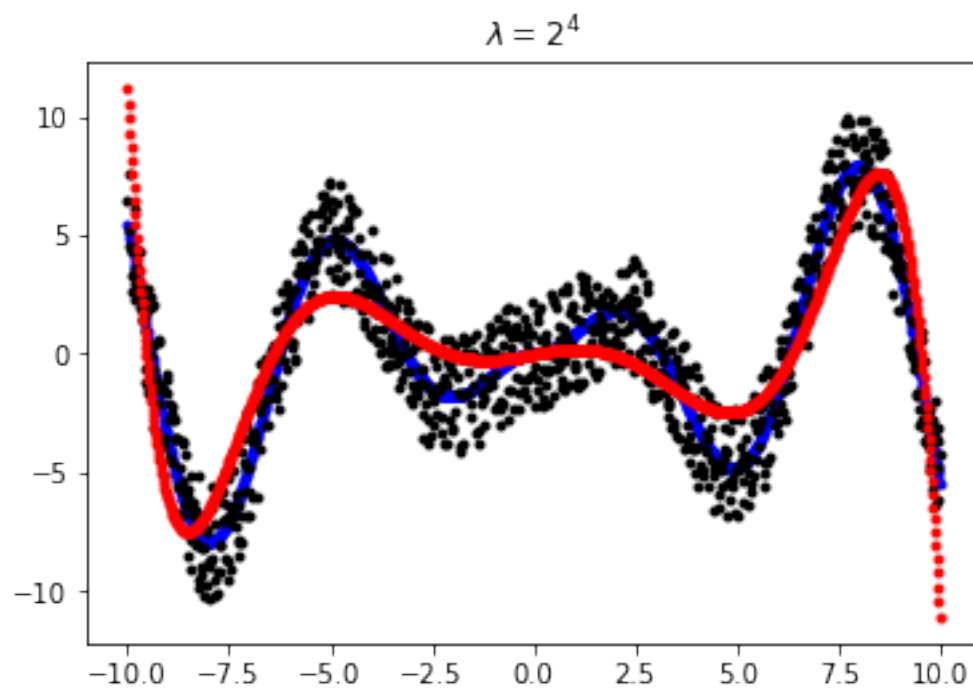
P: 8



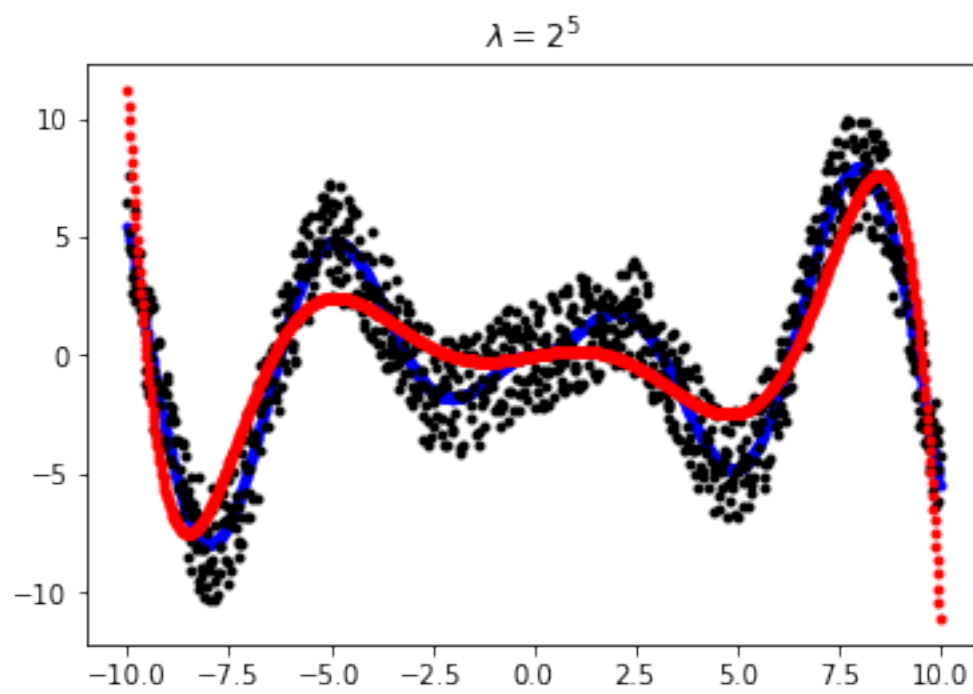
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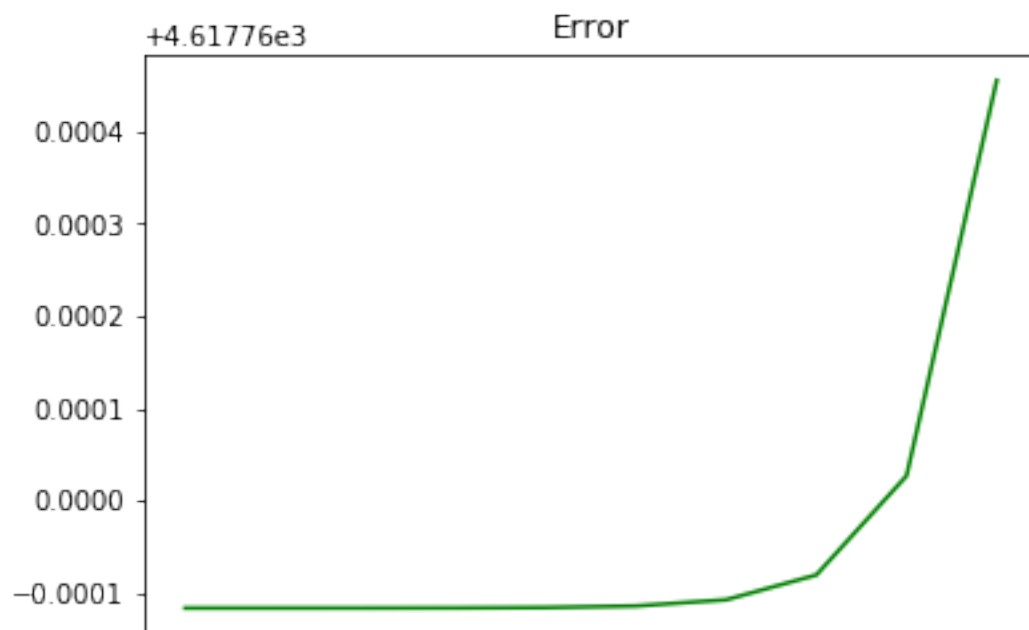
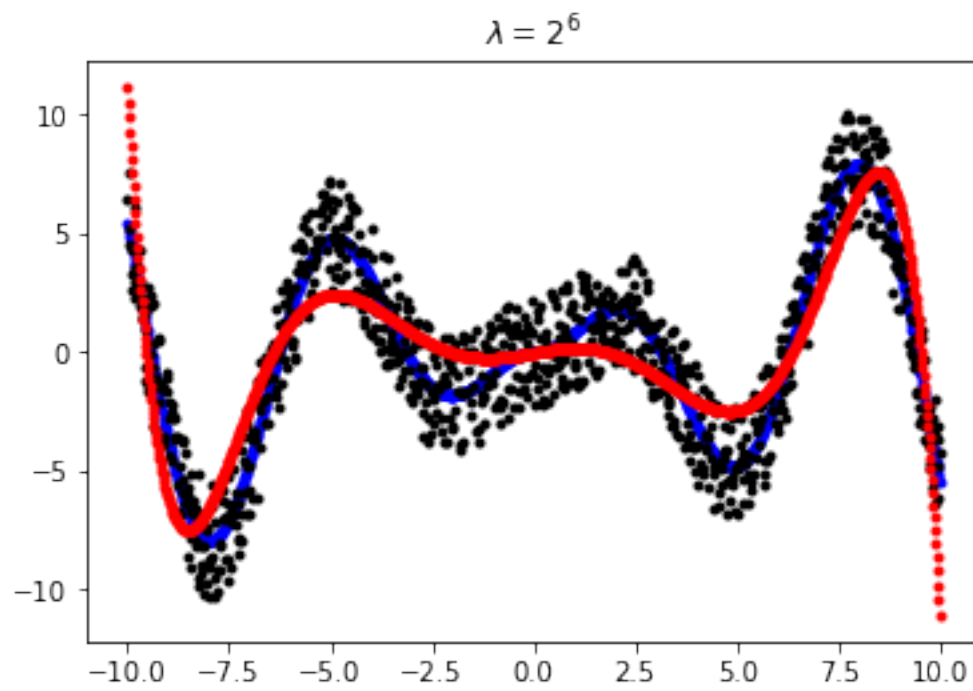
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P: 8

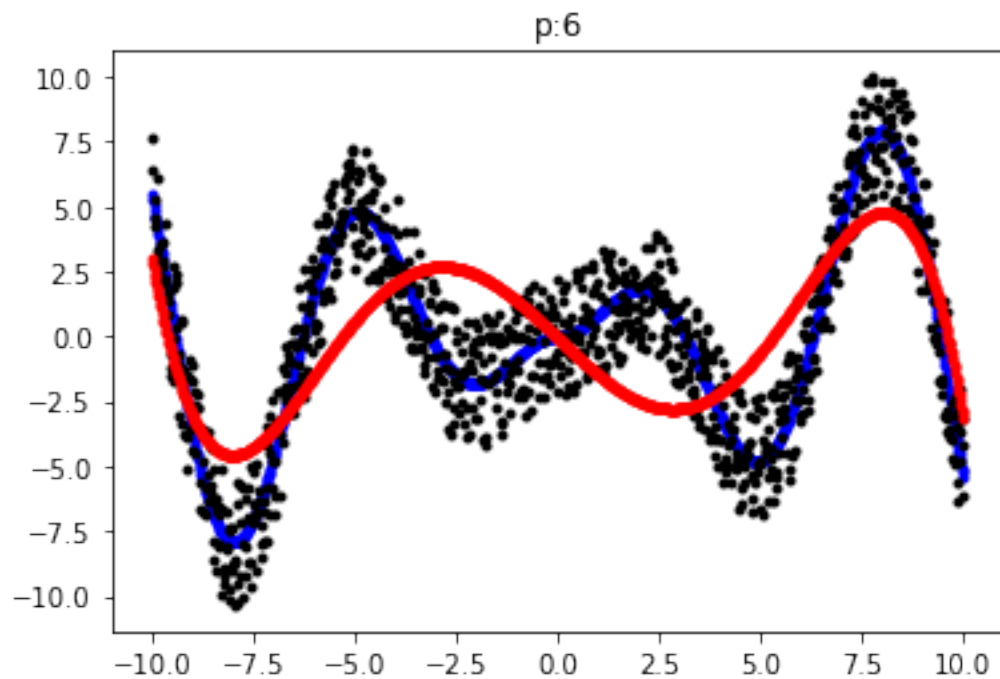


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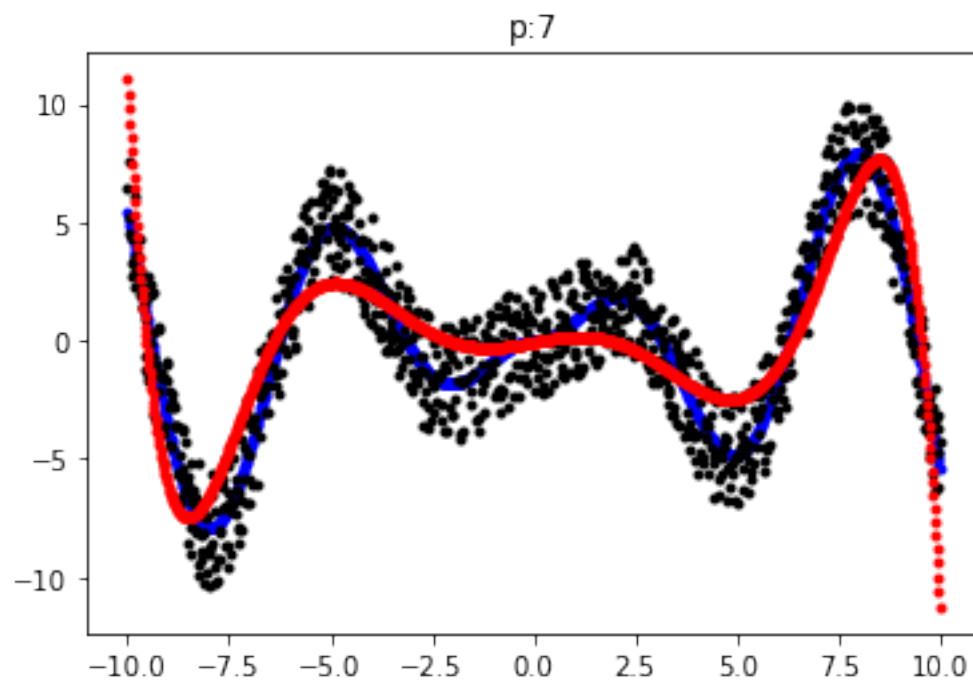


- optimal sets I found when p is from 6 to 15

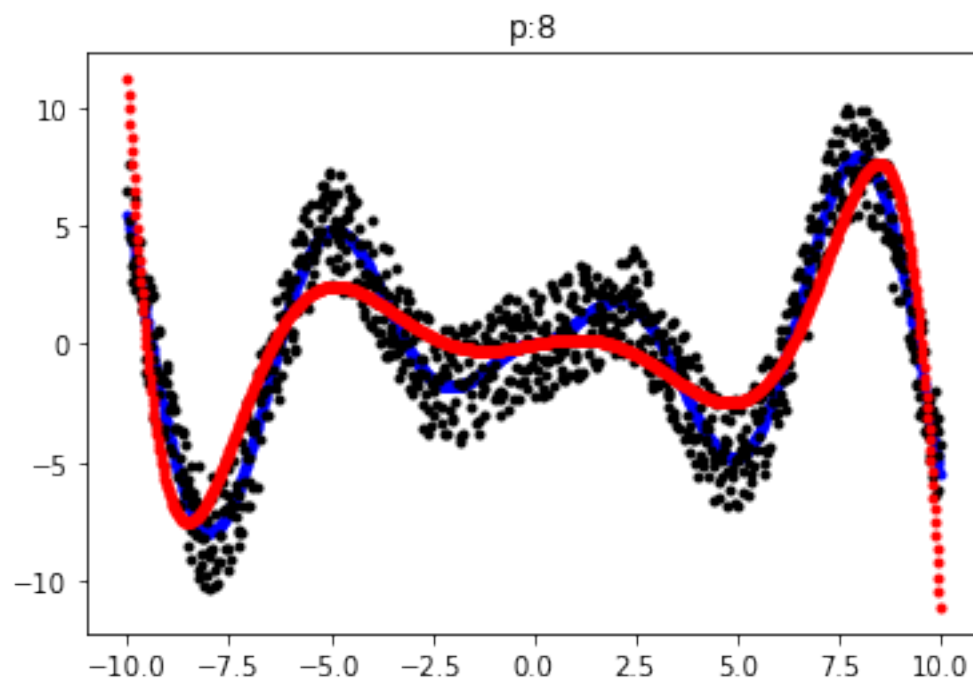
```
In [13]: for i in range(10):
          p = i+6
          plt.title('p:%d' %p)
          plt.plot(x,y1,'b.', label = 'clean')
          plt.plot(x,y2,'k.', label = 'noisy')
          plt.plot(x,result[i,],'r.', label = 'poly fit with 1')
          plt.show()
          print('coefficients')
          print(result_c[i])
```



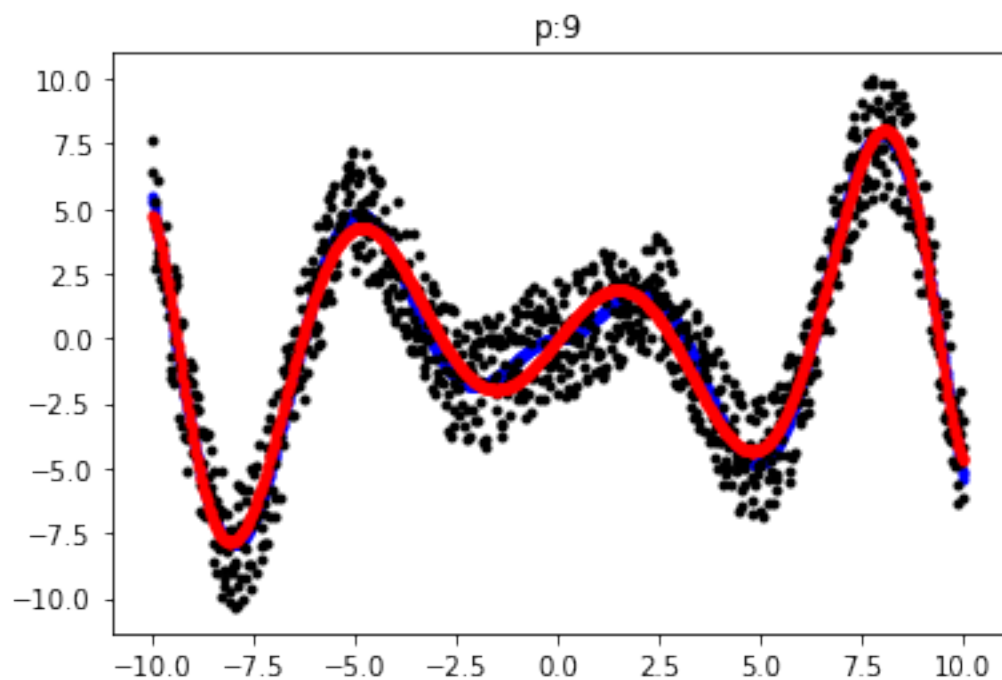
```
coefficients
[[-6.14232481e-02]
 [-1.48540601e+00]
 [-2.02124907e-04]
 [ 6.89243990e-02]
 [ 1.24849795e-04]
 [-5.71532826e-04]
 [-1.27004342e-06]]
```



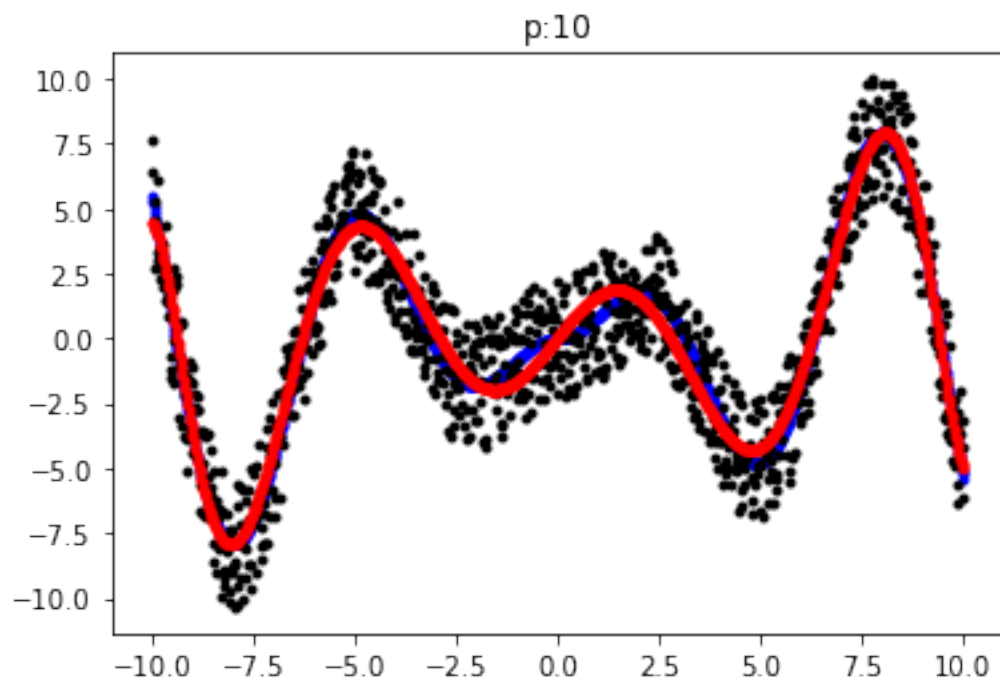
```
coefficients  
[[-6.14232481e-02]  
 [ 3.27685350e-01]  
 [-2.02124907e-04]  
 [-9.39309382e-02]  
 [ 1.24849795e-04]  
 [ 3.00418766e-03]  
 [-1.27004342e-06]  
 [-2.20915311e-05]]
```



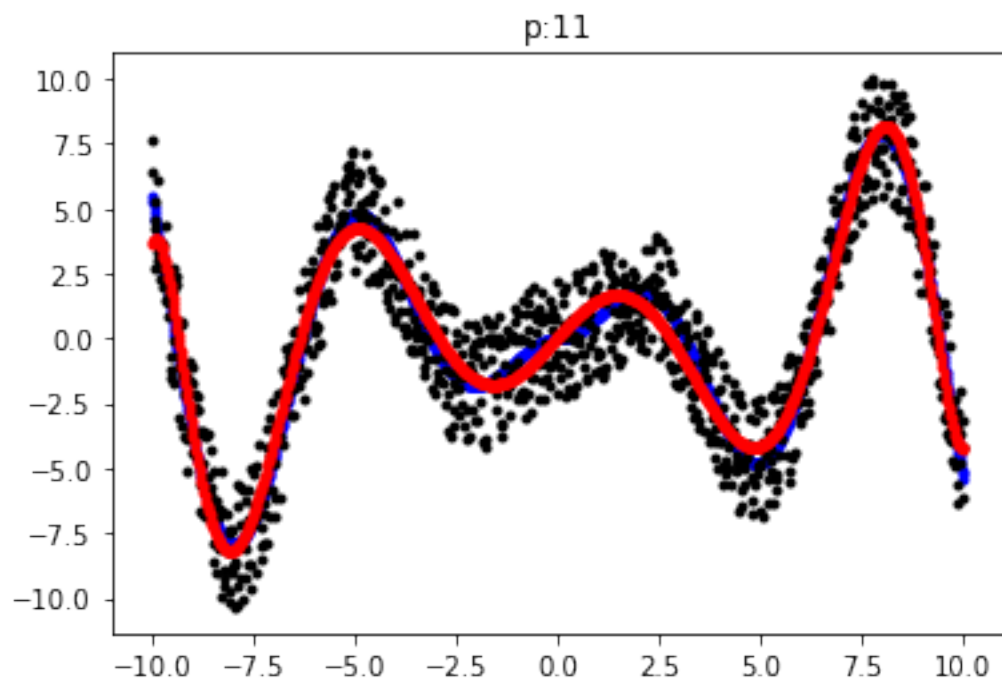
```
coefficients  
[[-2.36538705e-02]  
 [ 3.27685350e-01]  
 [-1.37722636e-02]  
 [-9.39309382e-02]  
 [ 8.69733159e-04]  
 [ 3.00418766e-03]  
 [-1.41558336e-05]  
 [-2.20915311e-05]  
 [ 6.88944736e-08]]
```



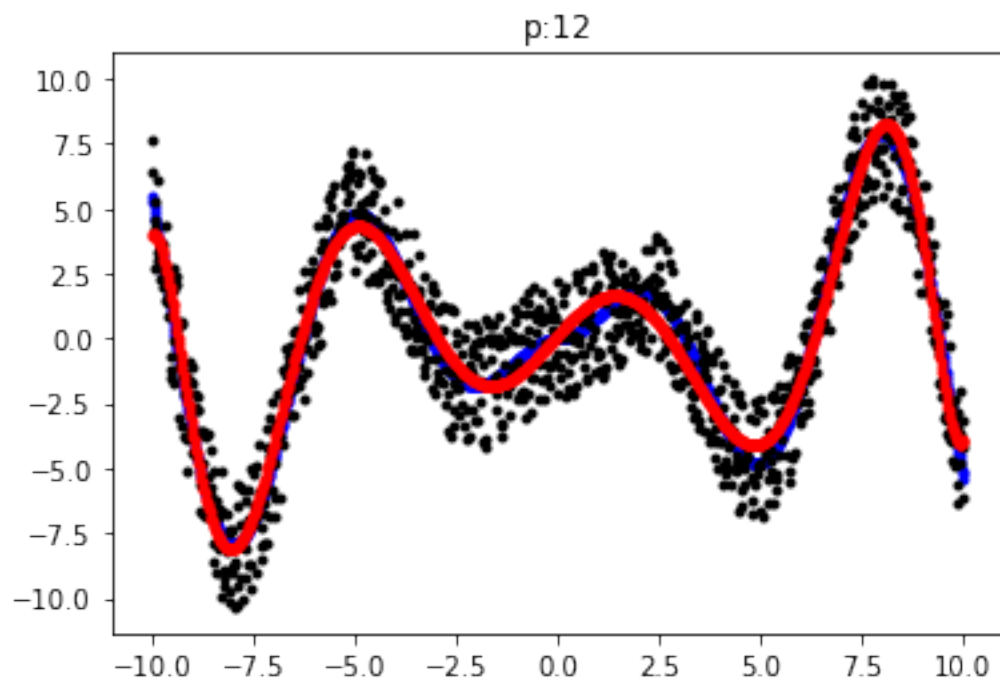
```
coefficients  
[[-2.36538705e-02]  
 [ 1.97805559e+00]  
 [-1.37722636e-02]  
 [-3.35509361e-01]  
 [ 8.69733159e-04]  
 [ 1.24071959e-02]  
 [-1.41558336e-05]  
 [-1.56155489e-04]  
 [ 6.88944737e-08]  
 [ 6.31831151e-07]]
```

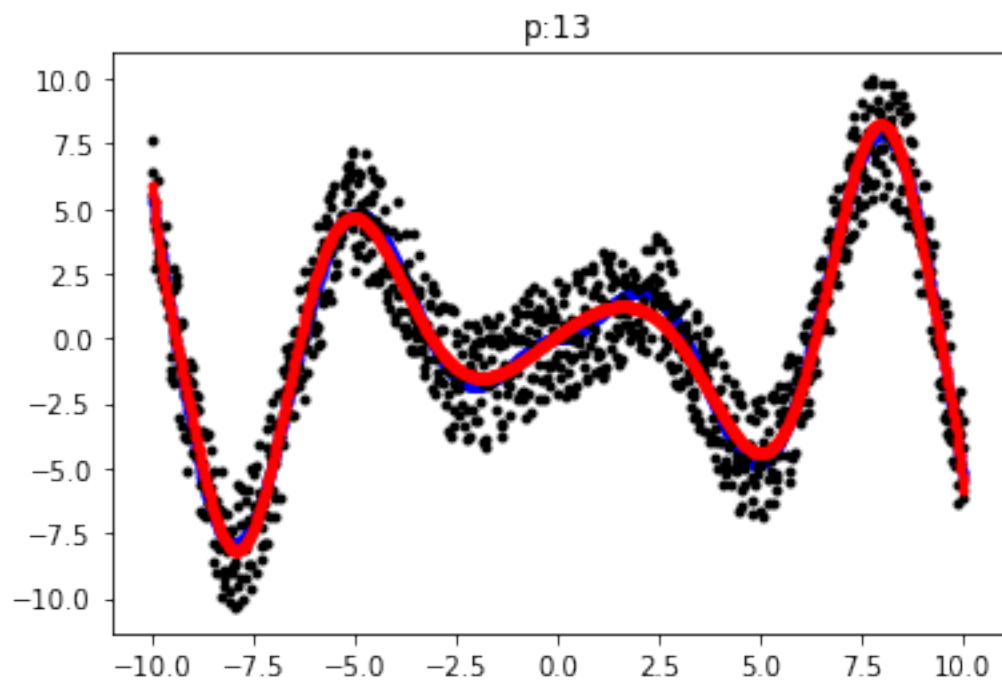
```
coefficients  
[[ 5.95497500e-02  
 [ 1.97805559e+00  
 [-5.94445390e-02  
 [-3.35509361e-01  
 [ 4.82022940e-03  
 [ 1.24071959e-02  
 [-1.32437970e-04  
 [-1.56155489e-04  
 [ 1.50235481e-06  
 [ 6.31831151e-07  
 [-6.04048493e-09]]
```



```
coefficients  
[[ 5.95497500e-02  
 [ 1.74712679e+00  
 [-5.94445390e-02  
 [-2.85572347e-01  
 [ 4.82022940e-03  
 [ 9.41682967e-03  
 [-1.32437970e-04  
 [-8.36743804e-05  
 [ 1.50235481e-06  
 [-1.31749155e-07  
 [-6.04048493e-09  
 [ 2.90977520e-09]]
```

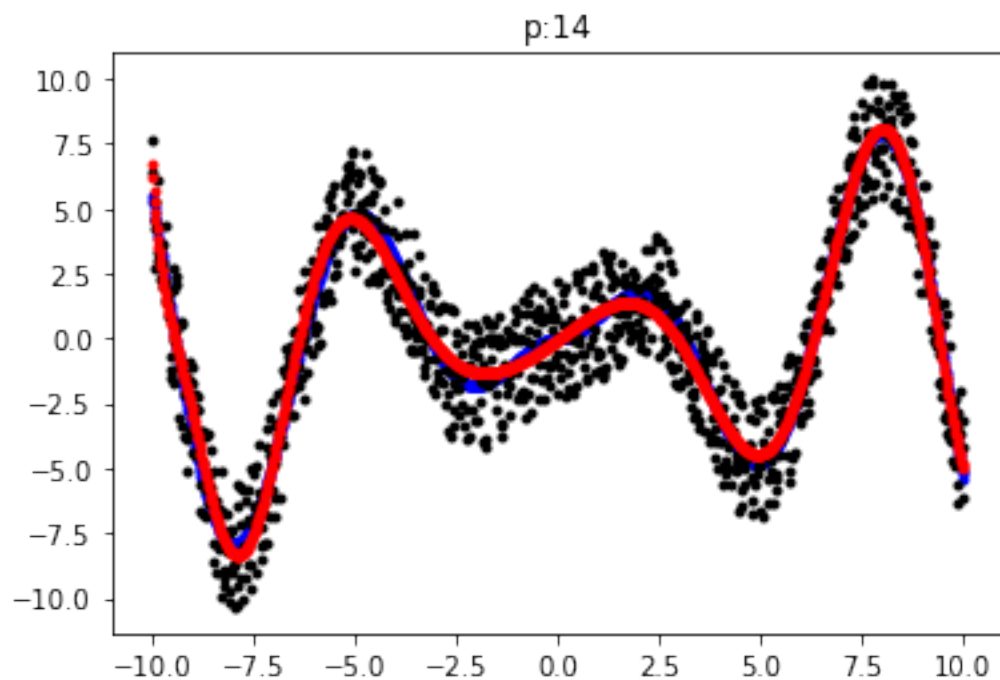


```
coefficients  
[[ 1.39017592e-01]  
 [ 1.74712679e+00]  
 [-1.21308970e-01]  
 [-2.85572347e-01]  
 [ 1.25382309e-02]  
 [ 9.41682967e-03]  
 [-4.81639036e-04]  
 [-8.36743805e-05]  
 [ 8.59723003e-06]  
 [-1.31749155e-07]  
 [-7.21301101e-08]  
 [ 2.90977520e-09]  
 [ 2.29862609e-10]]
```

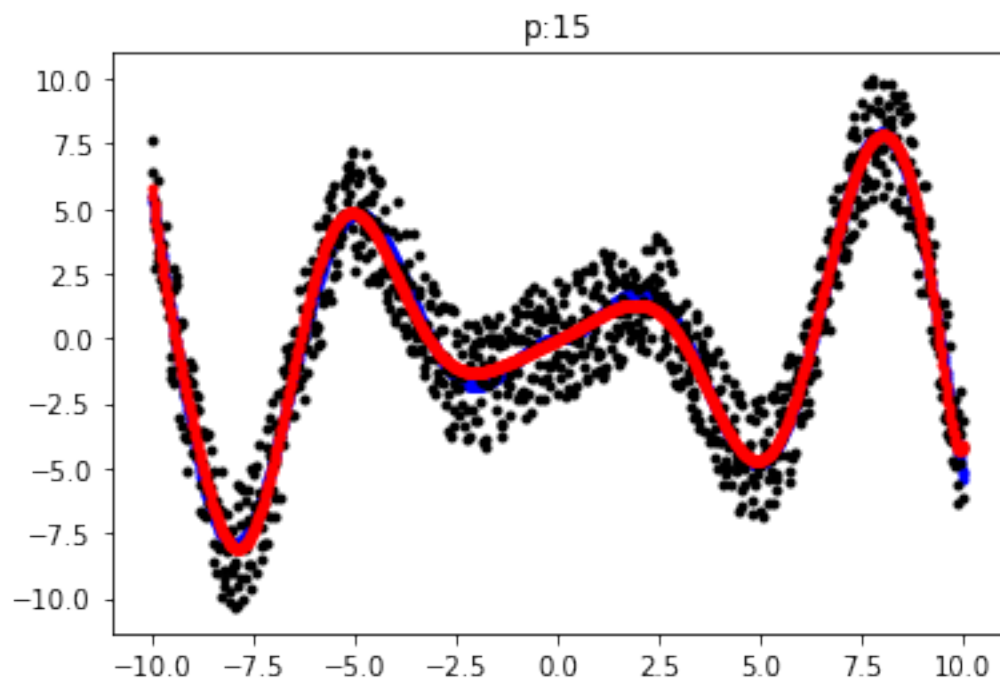


coefficients

```
[[ 1.39017587e-01]
 [ 1.12721255e+00]
 [-1.21308967e-01]
 [-9.99569883e-02]
 [ 1.25382305e-02]
 [-6.32993154e-03]
 [-4.81639018e-04]
 [ 4.85103473e-04]
 [ 8.59722969e-06]
 [-1.00660423e-05]
 [-7.21301069e-08]
 [ 8.58351816e-08]
 [ 2.29862598e-10]
 [-2.65269812e-10]]
```



```
coefficients  
[[-4.39434506e-02]  
 [ 1.12721254e+00]  
 [ 7.04306740e-02]  
 [-9.99569861e-02]  
 [-1.99946842e-02]  
 [-6.32993171e-03]  
 [ 1.57480295e-03]  
 [ 4.85103479e-04]  
 [-5.29768709e-05]  
 [-1.00660424e-05]  
 [ 8.70181051e-07]  
 [ 8.58351825e-08]  
 [-6.89504835e-09]  
 [-2.65269814e-10]  
 [ 2.10989203e-11]]
```



```
coefficients  
[[-4.39435413e-02]  
 [ 7.96280697e-01]  
 [ 7.04307674e-02]  
 [ 3.10624511e-02]  
 [-1.99946994e-02]  
 [-2.12375501e-02]  
 [ 1.57480388e-03]  
 [ 1.22905442e-03]  
 [-5.29768982e-05]  
 [-2.90416012e-05]  
 [ 8.70181461e-07]  
 [ 3.44095246e-07]  
 [-6.89505140e-09]  
 [-2.04978305e-09]  
 [ 2.10989292e-11]  
 [ 4.91916231e-12]]
```