

# Assignment11

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- Description: Image denoising using least square regularization
- github: [https://github.com/mydream757/Computer\\_Vision](https://github.com/mydream757/Computer_Vision)

## 1. Import libraries

- import needed libraries.

```
In [1]: import matplotlib.pyplot as plt
import numpy as np
from scipy.sparse import coo_matrix
from scipy import signal
from skimage import io, color
from skimage import exposure
```

## 2. Set the image

- bring an image. I resized the given image to smaller one

```
In [2]: file_image      = 'cau-1.jpg'
        #read and set the image
im_color      = io.imread(file_image)
im_gray       = color.rgb2gray(im_color)
im            = (im_gray - np.mean(im_gray)) / np.std(im_gray)
(row, col)    = im.shape
```

- generate a noise image

```
In [3]: #generate noise
noise_std     = 0.2 # try with varying noise standard deviation
noise         = np.random.normal(0, noise_std, (row, col))
im_noise      = im + noise
```

- image vectorization

```
In [4]: #this is vectorization of the image
im_vector = im_noise.reshape(row*col)
n = im_vector.size
```

### 3. Define functions

- create\_A makes least square, 'A'

```
In [5]: #the function returns 'A'
def create_A(t):
    eigen = np.eye(n-1,n)
    dX = np.roll(eigen,1)
    minus = -np.eye(n-1,n)
    dX = dX + minus
    dY = minus
    for i in range(n-2):
        for k in range(n-1):
            if k+col<n-1 and dY[i][k]==-1:
                dY[i][k+col] = 1
    a_first = np.eye(row*col)

    A = np.vstack((a_first,np.sqrt(t)*dX))
    A = np.vstack((A,np.sqrt(t)*dY))

    return A;
```

- create\_B makes least square, 'b'

```
In [6]: #the function returns 'b'
def create_B(t):

    b_first = im_vector.reshape((n,1))
    b_second = np.zeros((n-1,1))
    b = np.vstack((b_first,b_second))
    b = np.vstack((b,b_second))
    return b;
```

### 4. Result of varing lamda

- iterate and show the results

```
In [7]: #iteration 11 times
for i in range(11):

    l = pow(2,i-5)
    #solve the least square problem.
    ans = np.dot(np.linalg.pinv(create_A(l)),create_B(l))

    #reshape to show image
    im_recon = ans.reshape((row,col))
    #gradient for computing error
    dX,dY = np.gradient(im_recon)
    #use sparse matrix because of matrix overflow
```

```

dX = coo_matrix(dX)
dY = coo_matrix(dY)

dX2 = dX.multiply(dX).todense()
dY2 = dY.multiply(dY).todense()

#compute error
error = (im_recon-im_noise)**2 + 1*(dX2+dY2)
#show the result
print('lamda: ', 1)
p1 = plt.subplot(2,2,1)
p1.set_title('original image')
plt.imshow(im, cmap='gray')
plt.axis('off')

p2 = plt.subplot(2,2,2)
p2.set_title('noisy image')
plt.imshow(im_noise, cmap='gray')
plt.axis('off')

p3 = plt.subplot(2,2,3)
p3.set_title('reconstruction')
plt.imshow(im_recon, cmap='gray')
plt.axis('off')

p4 = plt.subplot(2,2,4)
p4.set_title('error')
plt.imshow(error, cmap='gray')
plt.axis('off')

plt.show()

```

```
lamda: 0.03125
```

original image



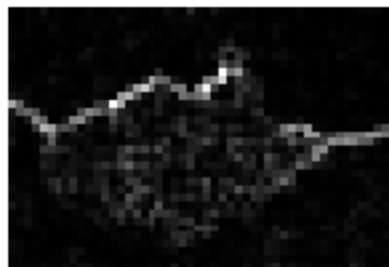
noisy image



reconstruction



error



lamda: 0.0625

original image



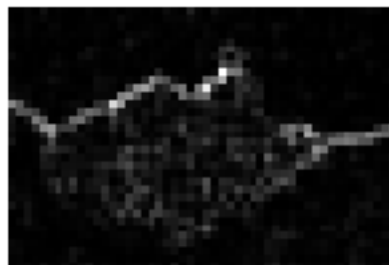
noisy image



reconstruction



error



lamda: 0.125

original image



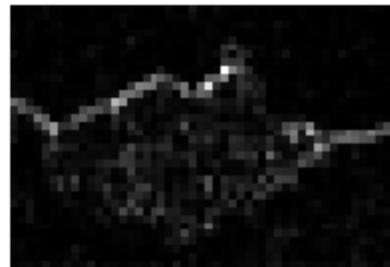
noisy image



reconstruction



error



lamda: 0.25

original image



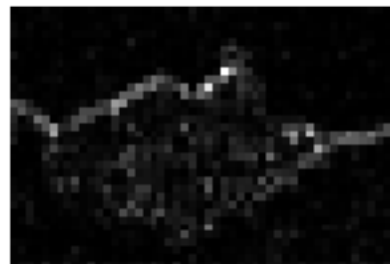
noisy image



reconstruction



error



lamda: 0.5

original image



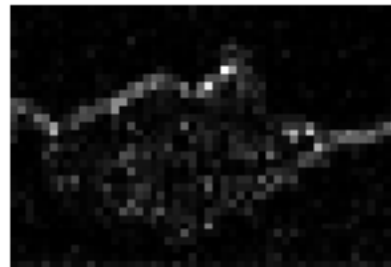
noisy image



reconstruction



error



lamda: 1

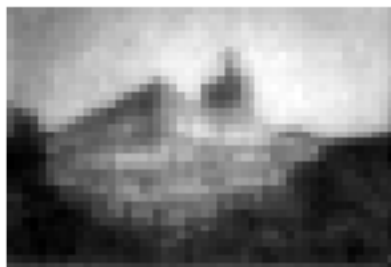
original image



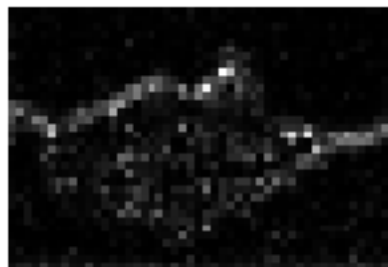
noisy image



reconstruction



error



lamda: 2

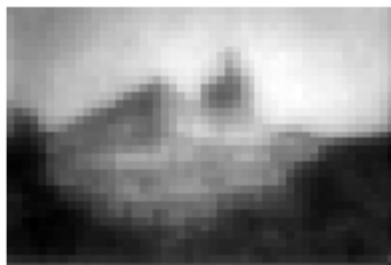
original image



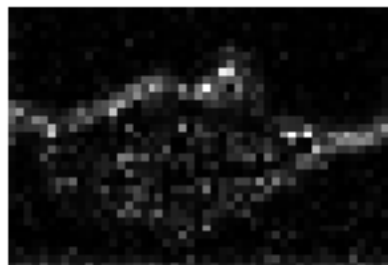
noisy image



reconstruction



error



lamda: 4

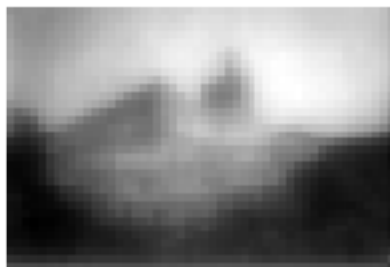
original image



noisy image



reconstruction



error



lamda: 8

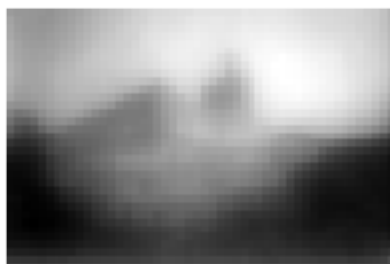
original image



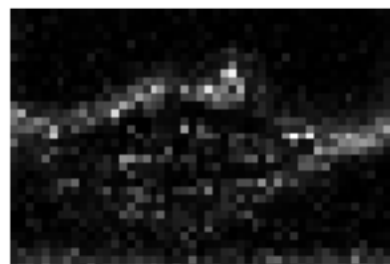
noisy image



reconstruction



error





lamda: 16

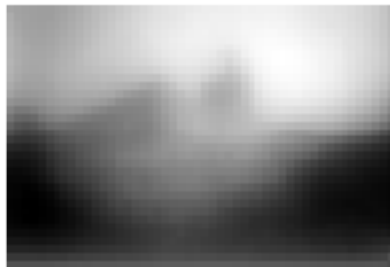
original image



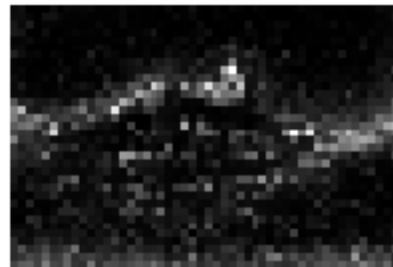
noisy image



reconstruction



error



lamda: 32

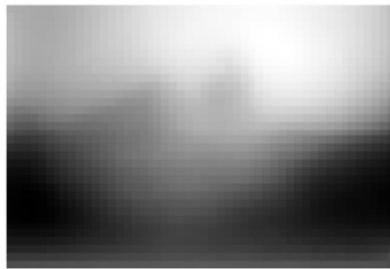
original image



noisy image



reconstruction



error

