

# Ch 7. Point estimation

## Intro

### Definition

A function of random variables  $X_1, \dots, X_n$  is called *Statistic*.

### Definition

The probability distribution of a statistic  $T$  is called the sampling distribution of  $T$ .

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Let  $T = \bar{X}$ , then sampling distribution of  $T$  is

$$N(\quad, \quad).$$

If  $T = S^2$  then sampling distribution of  $S^2$  is

$$(n-1)S^2/\sigma^2 \sim \quad.$$

# Ch 7. Point estimation

## Intro

### Definition

An *estimator* is a function of random variables  $X_1, \dots, X_n$ ,  
 $T = W(X_1, \dots, X_n)$ .

◁ Note:

1. Estimator is actually a statistic.
2. Estimator is also random.
3. An *estimate* is a function of realized values of

$$X_1 = x_1, \dots, X_n = x_n. \quad t = W(x_1, \dots, x_n)$$

▷ Example:  $T = \bar{X}$ ,  $\hat{F}_n(x_0) = n^{-1} \sum_{i=1}^n I[X_i \leq x_0]$ ,  
 $T = (\bar{X}, S^2)$ .

# Ch 7. Point estimation

## Methods: MME

How to estimate the parametric function  $\tau(\boldsymbol{\theta})$  using the random sample  $X_1, \dots, X_n$  ? : MME, MLE, BE so on

Let  $X_1, \dots, X_n \stackrel{iid}{\sim} f(x|\boldsymbol{\theta})$ ,  $\boldsymbol{\theta} = (\theta_1, \dots, \theta_k) \in \Theta$ .

### Definition

$$\begin{array}{l|l} j^{th} \text{ Population moment: } \mu_j(\boldsymbol{\theta}) = E(X^j) & C\mu_j = E[(X - \mu)^j] \\ j^{th} \text{ Sample moment: } m_j = \frac{1}{n} \sum_{i=1}^n X_i^j & Cm_j = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^j \end{array}$$

◁ Note:

1.  $\mu_j$  is a function of  $\boldsymbol{\theta} = (\theta_1, \dots, \theta_k)$ .
2.  $E[m_j] = E\left[n^{-1} \sum_{i=1}^n X_i^j\right] = \mu_j$ .

# Ch 7. Point estimation

## Methods: MME

### Definition

MME of  $\boldsymbol{\theta} = (\theta_1, \dots, \theta_k)$ , denoted by  $\tilde{\boldsymbol{\theta}} = (\tilde{\theta}_1, \dots, \tilde{\theta}_k)$ , is defined as a solution of the system of equations

$$m_j = \mu_j(\theta_1, \dots, \theta_k), \quad j = 1, \dots, l$$

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Find MME of  $\boldsymbol{\theta} = (\mu, \sigma^2)$ .

$$m_1 = \bar{X} = \mu, \quad m_2 = \frac{1}{n} \sum_{i=1}^n X_i^2 = \mu^2 + \sigma^2.$$

$$\tilde{\mu} = \bar{X} \quad \text{and} \quad \tilde{\sigma}^2 = \frac{1}{n} \sum X_i^2 - \bar{X}^2 = \frac{1}{n} \sum (X_i - \bar{X})^2.$$

## Ch 7. Point estimation

Methods: MME

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Gamma}(\alpha, \beta)$ . Find MME of  $\theta = (\alpha, \beta)$ .

$$\text{Let } S^{*2} = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2.$$

$$\theta_1 \theta_2 = \bar{X}, \quad \theta_1 \theta_2^2 = S^{*2},$$

$$\Rightarrow \tilde{\theta}_1 = \frac{\bar{X}^2}{S^{*2}} \quad \tilde{\theta}_2 = \frac{S^{*2}}{\bar{X}}.$$

# Ch 7. Point estimation

## Methods: MME

◁ Note:

1. MM equations may have multiple solutions or no solution.  
The solution may fall outside of the parameter space. (Example 7.2.2)
2. MME may not be applicable if the population moments do not exist such as Cauchy distribution.
3. One may not successful considering the first  $k$ -moments.  
▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} f(x|\beta)$ , where

$$f(x|\beta) = \frac{1}{2\beta} e^{-|x|/\beta}.$$

## Ch 7. Point estimation

Methods: MLE

Given the sample observation (measurement, data), choose as the estimator of the population parameter the value that makes the observed sample result the most likely, i.e. maximize the *likelihood*

▷ Let  $X$  be a single observation from a discrete distribution taking the values  $\{0, 1, 2\}$ .

The data comes from one of two distributions:

	$P(X=0)$	$P(X=1)$	$P(X=2)$
$\theta = \theta_0$	.8	.1	.1
$\theta = \theta_1$	.2	.3	.5

$$\text{then } \hat{\theta} = \begin{cases} \theta_0 & \text{if } x = 0 \\ \theta_1 & \text{if } x = 1, 2 \end{cases}.$$

# Ch 7. Point estimation

Methods: MLE

## Definition

Let  $f(x_1, \dots, x_n | \theta)$  be the joint pdf/pmf of  $X_1, \dots, X_n$ . For a fixed  $x_1, \dots, x_n$ ,

$$L(\theta) = f(x_1, \dots, x_n | \theta)$$

as a function of  $\theta$ , is called the likelihood function.  $\ln[L(\theta)]$  is called the log likelihood function.

With discrete random variable,

$$L(\theta) = P(X_1 = x_1, \dots, X_n = x_n).$$

$$X_1, \dots, X_n \stackrel{iid}{\sim} f(x | \theta). \quad L(\theta) =$$



# Ch 7. Point estimation

Methods: MLE

## Definition

Let  $f(x_1, \dots, x_n | \theta)$ ,  $\theta \in \Theta$  be the joint pdf/pmf of  $X_1, \dots, X_n$ . Then for a given set of observations  $(x_1, \dots, x_n)$ , the *maximum likelihood estimate* of  $\theta$  is a point  $\theta_0 = h(x_1, \dots, x_n)$  satisfying

$$f(x_1, \dots, x_n | \theta_0) = \max_{\theta \in \Theta} f(x_1, \dots, x_n | \theta).$$

The *maximum likelihood estimator (MLE)* is defined as

$$\hat{\theta} = h(X_1, \dots, X_n).$$

# Ch 7. Point estimation

Methods: MLE

How to find MLE ?

- Using differentiation, - Direct maximization, - Numerical evaluation

- Assume  $L(\theta)$  is twice differentiable in the interior points of  $\Theta$ . Then  $\hat{\theta}$  maximizes  $L(\theta)$  if

1.  $\hat{\theta}$  is the unique value satisfying

$$\frac{dL(\theta)}{d\theta} \left( \frac{d \ln[L(\theta)]}{d\theta} \right) \Big|_{\hat{\theta}} = 0$$

$$\frac{d^2 L(\theta)}{d\theta^2} \left( \frac{d^2 \ln[L(\theta)]}{d\theta^2} \right) \Big|_{\hat{\theta}} < 0$$

2. The maximizer does not occur at the boundary.

## Ch 7. Point estimation

### Methods: MLE

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Known  $\mu$  and Unknown  $\sigma$

$$L(\theta, \sigma^2 | \mathbf{x}) = (2\pi\sigma^2)^{-n/2} \exp\left\{-\frac{1}{2\sigma^2} \sum (x_i - \theta)^2\right\}$$

$$l(\theta, \sigma^2 | \mathbf{x}) = -\frac{n}{2} \log 2\pi - \frac{n}{2} \log \sigma^2 - \frac{1}{2\sigma^2} \sum (x_i - \theta)^2$$

$$0 = \frac{\partial l}{\partial \theta} = \frac{1}{\sigma^2} \sum (x_i - \theta) \Rightarrow \sum x_i - n\theta = 0 \Rightarrow \hat{\theta} = \bar{x};$$

$$0 = \frac{\partial l}{\partial \sigma^2} = -\frac{n}{2\sigma^2} + \frac{1}{2\sigma^4} \sum (x_i - \theta)^2.$$

$$\hat{\sigma}^2 = n^{-1} \sum (x_i - \bar{x})^2.$$

# Ch 7. Point estimation

## Methods: MLE

▷ Example:  $X_{ij}$ ,  $i = 1, \dots, s$ ;  $j = 1, \dots, n$  independently distributed as normal distribution with mean  $\mu_i$  and variance  $\sigma^2$ . Find the mle of  $\mu_i$  and  $\sigma^2$ .

$$L = (\sqrt{2\pi\sigma^2})^{-ns} \exp\left(-\sum_{i=1}^s \sum_{j=1}^n \frac{(x_{ij} - \mu_i)^2}{2\sigma^2}\right)$$

$$l = \ln L = -\frac{ns}{2} \ln(2\pi) - \frac{ns}{2} \ln(\sigma^2) - \sum_{i=1}^s \sum_{j=1}^n \frac{(x_{ij} - \mu_i)^2}{2\sigma^2}$$

$$\frac{\partial l}{\partial (\mu_i)} = \frac{1}{\sigma^2} \sum_{j=1}^n (x_{ij} - \mu_i) = 0, \quad i = 1, 2, \dots, s,$$

$$\frac{\partial l}{\partial (\sigma^2)} = -\frac{ns}{2\sigma^2} + \sum_{i=1}^s \sum_{j=1}^n \frac{(x_{ij} - \mu_i)^2}{2(\sigma^2)^2} = 0$$

$$\hat{\mu}_i = \bar{X}_{i\bullet}, \quad \hat{\sigma}^2 = \frac{1}{ns} \sum_{i=1}^s \sum_{j=1}^n (X_{ij} - \bar{X}_{i\bullet})^2$$

# Ch 7. Point estimation

Methods: MLE

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(p)$ .

$$L(p|\mathbf{x}) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} = p^{\sum x_i} (1-p)^{n-\sum x_i}$$

$$l(p|\mathbf{x}) = \sum x_i \log p + (n - \sum x_i) \log(1-p)$$

$$\frac{\partial l}{\partial p} = \frac{\sum x_i}{\hat{p}} - \frac{n - \sum x_i}{1 - \hat{p}} = 0 \text{ (if } \hat{p} \notin \{0, 1\} \text{)}. \Rightarrow \hat{p} = \bar{x}.$$

## Theorem

Let  $\hat{\theta}$  be the mle of  $\theta$ . Then for any parametric function  $\tau(\theta)$ , the mle of  $\tau(\theta)$  is defined to be  $\tau(\hat{\theta})$

# Ch 7. Point estimation

Methods: MLE

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Find mle of  $e^\mu$ ,  $\mu^2$ ,  $\sigma/\mu$  and  $P[X \leq a]$ .

◁ Note:

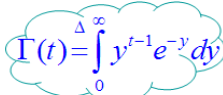
1. It is possible that the likelihood equations do not have closed-form solution. May need a numerical method.
2. When the likelihood function is not differentiable, we may maximize  $L(\boldsymbol{\theta})$  directly.

## Ch 7. Point estimation

Methods: MLE

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Gamma}(\alpha, \beta)$ .

$$\alpha = \theta_1, \beta = \theta_2$$

$$L(\theta_1, \theta_2 | x_1, \dots, x_n) = \left[ \frac{1}{\Gamma(\theta_1) \theta_2^{\theta_1}} \right]^n (x_1 x_2 \cdots x_n)^{\theta_1 - 1} \exp \left( - \sum_{i=1}^n x_i / \theta_2 \right)$$


The likelihood equations do not have closed-form solution.

Example (Uniform Distribution). Let  $X_1, \dots, X_n$  be iid with the uniform  $(0, \theta)$  density, i.e.,

$$f(x; \theta) = \begin{cases} 1/\theta, & 0 < x \leq \theta \\ 0, & \text{elsewhere} \end{cases}$$

Find the  $\hat{\theta}_{MLE}$ .

- We have

$$L(\theta; x_1, x_2, \dots, x_n) = \frac{1}{\theta^n}, \quad 0 < x_i \leq \theta$$

which is an ever-decreasing function of  $\theta$ .

- The maximum of such functions cannot be found by differentiation. Note that

$$0 < x_i \leq \theta \quad \longrightarrow \quad \theta \geq \max(x_i)$$

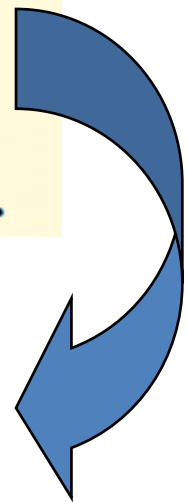


- $L$  can be made no larger than  $\frac{1}{[\max(x_i)]^n}$  and the unique MLE  $\hat{\theta}$  of  $\theta$  is the  $n$ th order statistic  $\max(X_i)$ .

$$E[\max(X_i)] = n\theta / (n + 1).$$

- The MLE of the parameter  $\theta$  is biased.

$$\begin{aligned} E[\max(X_i)] &= \int_0^\theta x \cdot n f(x) F^{n-1}(x) dx \\ &= n \int_0^\theta x \cdot \frac{1}{\theta} \left(\frac{x}{\theta}\right)^{n-1} dx = \frac{n}{n+1} \theta. \end{aligned}$$



## Ch 7. Point estimation

### Methods: Bayes estimation

So far,  $X_1, \dots, X_n \stackrel{iid}{\sim} f(x|\theta)$ , where  $\theta$  is **unknown** and is assumed **fixed**. In **Bayesian** framework,  $\theta$  is assumed **random**. The distribution of  $\theta$  is called **prior distribution**, denoted by

$$\theta \sim \pi(\theta), \quad \theta \in \Theta.$$

▷ Example: Machine that stamps out parts for cars.  $\theta$ =fraction of defective. On a certain day, 10 pieces are examined.

$$X_i = \begin{cases} 1, & \text{if } i\text{th piece is defective,} \\ 0, & \text{otherwise,} \end{cases}$$

$i = 1, \dots, 10$ . MME or MLE ?

# Ch 7. Point estimation

## Methods: Bayes estimation

▷ Example -continued: Now assume that mechanic knows something about  $\theta$  and gives a statistical model for  $\theta$

$$\pi(\theta) = 6\theta(1 - \theta), \quad 0 \leq \theta \leq 1.$$

Prior distribution of  $\theta$  is ?

- ▶ In Bayesian frame, what is the goal of the inference about  $\theta$  ?
- ▶ Then, How should we use the data  $X_1 = x_1, \dots, X_n = x_n$  to achieve the goal ?

# Ch 7. Point estimation

## Methods: Bayes estimation

The conditional distribution of  $\theta$  conditioning on  $X_1 = x_1, \dots, X_n = x_n$  is called **posterior distribution** of  $\theta$ .

$$\begin{aligned}\pi(\theta|x_1, \dots, x_n) &= \frac{f(x_1, \dots, x_n, \theta)}{m(x_1, \dots, x_n)} \\ &= \begin{cases} \frac{\pi(\theta)f(x_1, \dots, x_n|\theta)}{\sum_{\theta \in \Theta} \pi(\theta)f(x_1, \dots, x_n|\theta)} \\ \frac{\pi(\theta)f(x_1, \dots, x_n|\theta)}{\int_{\theta \in \Theta} \pi(\theta)f(x_1, \dots, x_n|\theta)d\theta} \end{cases}\end{aligned}$$

- Any Bayesian inference is based on this posterior distribution of  $\theta$ .

## Example 1

Let  $X_1, \dots, X_n$  be i.i.d. Bernoulli( $p$ ).

$$\pi(p) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1} \quad (p \in (0,1))$$

$$f(\mathbf{x}|p) \sim p^{\sum x_i} (1-p)^{n-\sum x_i}.$$

We determine the Bayes estimator of  $p$ .

$$\begin{aligned} \pi(p|\mathbf{x}) &= \frac{f(\mathbf{x}|p)\pi(p)}{f(\mathbf{x})} \\ &= \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\sum x_i + \alpha - 1} (1-p)^{n - \sum x_i + \beta - 1} \\ &= \frac{\frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\sum x_i + \alpha - 1} (1-p)^{n - \sum x_i + \beta - 1}}{\int_0^1 \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\sum x_i + \alpha - 1} (1-p)^{n - \sum x_i + \beta - 1} dp} \end{aligned}$$

$$= \frac{\Gamma(n + \alpha + \beta)}{\Gamma(\sum x_i + \alpha) \Gamma(n - \sum x_i + \beta)} p^{\sum x_i + \alpha - 1} (1 - p)^{n - \sum x_i + \beta - 1}.$$

$$p | \mathbf{x} \sim \text{Beta}(\sum x_i + \alpha, n - \sum x_i + \beta)$$

So the Bayes estimator is

$$E(p | \mathbf{x}) = \frac{\sum x_i + \alpha}{n + \alpha + \beta}.$$

Note: We must choose  $\alpha$  and  $\beta$  somehow. (Often used is  $\alpha = \beta = 1$  which makes  $\pi(p)$  uniform. In that case we are not using prior information about  $p$ ).

Our prior has mean  $\frac{\alpha}{\alpha + \beta}$ , so without seeing the data we use this. The MLE is  $\frac{\sum x_i}{n}$ .

Then the Bayes estimate

$$\frac{\sum x_i + \alpha}{n + \alpha + \beta} = \left( \frac{\alpha + \beta}{n + \alpha + \beta} \right) \left( \frac{\alpha}{\alpha + \beta} \right) + \left( \frac{n}{n + \alpha + \beta} \right) \frac{\sum x_i}{n},$$

a weighted average of the prior mean and the MLE.

Note that

$$\pi(p|\mathbf{x}) = \frac{f(\mathbf{x}|p)\pi(p)}{f(\mathbf{x})} \propto f(\mathbf{x}|p)\pi(p)$$

$$\propto p^{\sum x_i} (1-p)^{n-\sum x_i} p^{\alpha-1} (1-p)^{\beta-1}$$

$$\propto p^{\sum x_i + \alpha - 1} (1-p)^{n - \sum x_i + \beta - 1}.$$

$$p|\mathbf{x} \sim \text{Beta}\left(\sum x_i + \alpha, n - \sum x_i + \beta\right)$$



## Example 2

Let  $X_1, \dots, X_n$  be i.i.d.  $\text{Poisson}(\lambda)$ .

$$\pi(\lambda) = \frac{\lambda^{\alpha-1} e^{-\lambda/\beta}}{\Gamma(\alpha) \beta^\alpha}, \quad 0 < \lambda < \infty; \text{Gamma}(\alpha, \beta)$$

$$f(\mathbf{x}|\lambda) \sim \frac{e^{-n\lambda} \lambda^{\sum x_i}}{x_1! x_2! \cdots x_n!}$$

We determine the Bayes estimator of  $\lambda$ .

$$\pi(\lambda|\mathbf{x}) = \frac{f(\mathbf{x}|\lambda) \pi(\lambda)}{f(\mathbf{x})} \propto f(\mathbf{x}|\lambda) \pi(\lambda)$$

$$\propto e^{-n\lambda} \lambda^{\sum x_i} \lambda^{\alpha-1} e^{-\lambda/\beta}$$

$$\propto \lambda^{\sum x_i + \alpha - 1} e^{-\lambda(n + \frac{1}{\beta})}$$

$$\sim \text{Gamma}(\sum x_i + \alpha, \frac{1}{n + 1/\beta})$$

$$E(\lambda|\mathbf{X}) = \frac{\sum x_i + \alpha}{n + 1/\beta}$$

In each of these examples, the prior and posterior distributions have the same form.

In such cases, the distribution of the prior and sampling distribution of  $\mathbf{x}$  are said to be **conjugate**.

Choosing a conjugate prior has the advantage of allowing us to write a closed form expression for the posterior and for the estimator. It makes the computation easier.

## Examples of conjugate priors

- Bernoulli model with a Beta prior on  $0 < p < 1$
- Poisson model with a Gamma prior on  $0 < \lambda < \infty$
- Normal model with a Normal prior on  $-\infty < \mu < \infty$
- Normal model with an Inverse Gamma prior on  $-\infty < \sigma^2 < \infty$  (i.e. a Gamma prior on  $0 < \frac{1}{\sigma^2} < \infty$ ).
- Gamma model with a Gamma prior on  $0 < \beta < \infty$

### Example 3

Let  $X_1, \dots, X_n$  be i.i.d.  $N(\mu, \sigma^2)$ .

$$\pi(\mu) \sim N(\eta, \tau^2)$$

$$f(\mathbf{x}|\mu) \sim N(\mu, \sigma^2)$$

Here  $\sigma^2$ ,  $\eta$ , and  $\tau^2$  are all assumed to be known. We determine the Bayes estimator of  $\mu$ .

# Ch 7. Point estimation

## Mean Squared Error: MSE

- May have more than one choice of the estimator of the parameter.
  - ▶ Need to evaluate the estimators so that we can choose the best one.
  - ▶ Need a criterion to evaluate the estimator. (Unbiasedness, MSE, Consistency, BLUE, UMVUE)

### Definition

An estimator  $W(X_1, \dots, X_n)$  of a parametric function  $\tau(\theta)$  is said to be an *unbiased* estimator (UE) if

$$E_{\theta}(W) = \tau(\theta), \quad \text{for all } \theta \in \Theta.$$

# Ch 7. Point estimation

## Mean Squared Error: MSE

### Definition

The function

$$\text{BIAS}_\theta(W) = E_\theta(W) - \tau(\theta)$$

is called the *bias* of  $W$  as an estimator of  $\tau(\theta)$ .

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Find an unbiased estimator for  $\mu$  and  $\sigma^2$ . What about the MLE of  $\sigma^2$  ?

Q) If  $W$  is an UE of  $\theta$ , then is  $\tau(W)$  UE of  $\tau(\theta)$  ? Yes/No

▷ Example-Continued:  $S^2$  is an UE of  $\sigma^2$ . Is  $S$  unbiased for  $\sigma$  ?

## Ch 7. Point estimation

### Mean Squared Error: MSE

#### Definition

The *Mean Squared Error (MSE)* of an estimator  $W$  of a parameter  $\theta$  is the function of  $\theta$  defined by

$$\text{MSE}_{\theta}(W) = E_{\theta}(W - \theta)^2.$$

◁ Note:  $\text{MSE}_{\theta}(W) = \text{Var}_{\theta}(W) + [\text{BIAS}_{\theta}(W)]^2$

MSE has two components, one that measures precision (variance), and one that measures accuracy (bias).

## Example

Let  $X_1, \dots, X_n$  be i.i.d.  $N(\mu, \sigma^2)$ . We  $E(\bar{X}) = \mu$  and  $E(S^2) = \sigma^2$  for all  $\mu$  and  $\sigma^2$ , so they are both unbiased.

The MSEs of these estimators are

$$\text{Var}(\bar{X}) = \sigma^2 / n, \text{Var}(S^2) = 2\sigma^4 / (n-1).$$

(Recall that  $\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2$ , and that  $\text{Var}(\chi_v^2) = 2v$ ).

Which one is better?

$$\text{MLE } \hat{\sigma}^2 = n^{-1}(n-1)S^2, \quad \tilde{\sigma}^2 = S^2 \quad ?$$



For the MLE (and MOM) estimator of  $\sigma^2$ ,

$$\hat{\sigma}^2 = \frac{1}{n} \sum (x_i - \bar{x})^2 ,$$

$$E(\hat{\sigma}^2) = \frac{n-1}{n} E(S^2) = \frac{n-1}{n} \sigma^2 .$$

Thus

$$Bias(\hat{\sigma}^2) = E(\hat{\sigma}^2) - \sigma^2 = \frac{n-1}{n} \sigma^2 - \sigma^2 = \frac{-\sigma^2}{n}$$

$$Var(\hat{\sigma}^2) = \left( \frac{n-1}{n} \right)^2 Var(S^2) = 2(n-1) \sigma^4 / n^2$$

$$\text{Hence, } MSE(\hat{\sigma}^2) = Var \hat{\sigma}^2 + (Bias \hat{\sigma}^2)^2$$

$$= 2(n-1) \sigma^4 / n^2 + (-\sigma^2 / n)^2$$

$$= \left[ (2/n) - (1/n^2) \right] \sigma^4 < 2\sigma^4 / (n-1)$$

## Ch 7. Point estimation

### Mean Squared Error: MSE

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(p)$ . With Beta prior, the Bayes estimator is

$$\hat{p}_B = \frac{n\bar{X} + \alpha}{\alpha + \beta + n}.$$

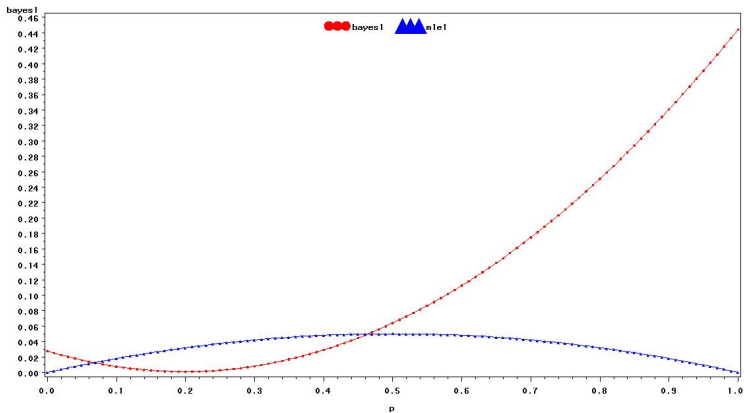
The MLE of  $p$  is  $\hat{p} = \bar{X}$ . Compare the MSE of two estimators.

e.g.  $\alpha=5, \beta=20$

# Ch 7. Point estimation

## Mean Squared Error: MSE

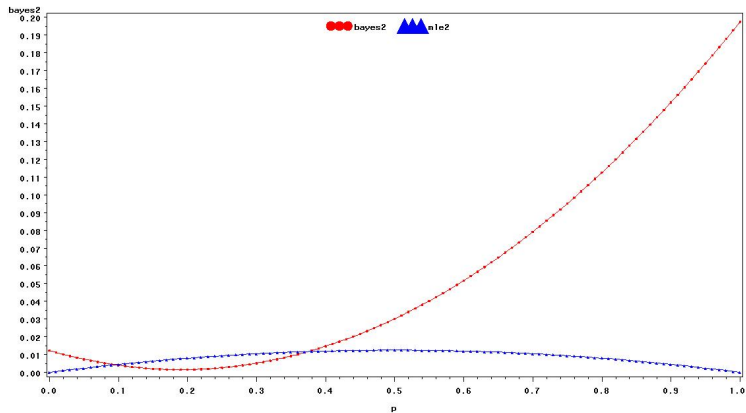
MSE of Bayes and ML estimator ( $n=5$ )



# Ch 7. Point estimation

## Mean Squared Error: MSE

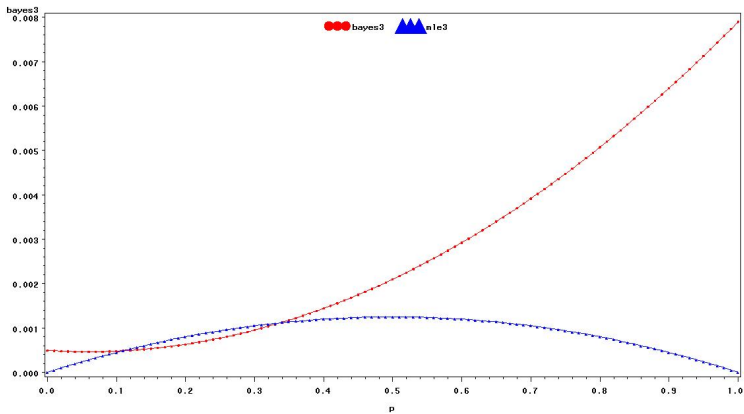
MSE of Bayes and ML estimator ( $n=20$ )



# Ch 7. Point estimation

## Mean Squared Error: MSE

MSE of Bayes and ML estimator ( $n=200$ )



# Ch 7. Point estimation

## UMVUE

### Definition

Let  $f(\mathbf{x}|\theta) = f(x_1, \dots, x_n|\theta)$  be the pdf/pmf of  $X_1, \dots, X_n$ . An estimator  $W$  is said to be *Uniform Minimum Variance Unbiased Estimator* (UMVUE) for  $\tau(\theta)$  if

1.  $E_{\theta}(W) = \tau(\theta)$
2.  $Var_{\theta}(W) < \infty$
3. For any other UE of  $\tau(\theta)$ , say  $\tilde{W}$ ,

$$Var_{\theta}(W) \leq Var_{\theta}(\tilde{W}) \quad \text{for all } \theta \in \Theta$$

◁ Note: UMVUE may not exist. If it does, it is essentially unique.

## Ch 7. Point estimation

### UMVUE: CRLB

Then, how to get the UMVUE ?

1. Using Cramér-Rao Lower Bound (CRLB)
2. Using complete and sufficient statistic and Rao-Blackwell, Lehmann-Scheffe Theorem.

- Idea of using CRLB;  
Show that for any UE,  $\tilde{W}$ , of  $\tau(\theta)$ ,

$$\text{Var}_{\theta}(\tilde{W}) \geq c(\theta) \quad \text{for all } \theta \in \Theta$$

and if we can find an UE,  $W$ , such that

$$\text{Var}_{\theta}(W) = c(\theta) \quad \text{for all } \theta \in \Theta$$

then we can conclude  $W$  is the UMVUE of  $\tau(\theta)$ .

## Ch 7. Point estimation

### UMVUE: CRLB

#### Theorem

Let  $f(\mathbf{x}|\theta)$  be the pdf/pmf of  $X_1, \dots, X_n$ . Assume

1.  $\Theta$  is an open space(subset) of  $R$ .
2.  $\{\mathbf{x} : f(\mathbf{x}|\theta) > 0\}$  does not depend on  $\theta$ .
3.  $\partial f(\mathbf{x}|\theta)/\partial \theta$  exist on  $\Theta$
4. For any estimator  $\tilde{W}$  with  $E_\theta \tilde{W}^2 < \infty$ , for all  $\theta \in \Theta$ , we have

$$\frac{\partial}{\partial \theta} E_\theta \tilde{W} = \frac{\int \tilde{W} [\frac{\partial}{\partial \theta} f(\mathbf{x}|\theta)] d\mathbf{x}}{\sum \tilde{W} [\frac{\partial}{\partial \theta} f(\mathbf{x}|\theta)]}$$

5.

$$E_\theta \left[ \left( \frac{\partial \ln f(\mathbf{x}|\theta)}{\partial \theta} \right)^2 \right] < \infty$$



## Ch 7. Point estimation

UMVUE: CRLB

### Theorem (Continued)

*Then for any UE of a differentiable parametric function  $\tau(\theta)$ ,*

$$\text{Var}_{\theta}(W) \geq \frac{[\tau(\theta)']^2}{E_{\theta} \left[ \left( \frac{\partial \ln f(\mathbf{x}|\theta)}{\partial \theta} \right)^2 \right]}.$$

◁ Note:

► The five conditions are called CR regularity conditions.

►

$$I_n(\theta) = E_{\theta} \left[ \left( \frac{\partial \ln f(\mathbf{x}|\theta)}{\partial \theta} \right)^2 \right]$$

is called the information number or fisher information of the sample.

Under regularity conditions,

$$1 = \int_{-\infty}^{\infty} f(x; \theta) dx = \int_S f(x; \theta) dx \Rightarrow 0 = \int_S \frac{\partial f(x; \theta)}{\partial \theta} dx.$$

$$\Rightarrow 0 = \int_S \frac{\partial f(x; \theta) / \partial \theta}{f(x; \theta)} f(x; \theta) dx,$$

$$\Rightarrow 0 = \int_S \frac{\partial \ln f(x; \theta)}{\partial \theta} f(x; \theta) dx \quad (1)$$

$$\Rightarrow E \left[ \frac{\partial \ln f(X; \theta)}{\partial \theta} \right] = 0; \quad (2)$$

We differentiate (1) again,

$$0 = \int_s \frac{\partial^2 \ln f(x; \theta)}{\partial \theta^2} f(x; \theta) dx + \int_s \frac{\partial \ln f(x; \theta)}{\partial \theta} \frac{\partial \ln f(x; \theta)}{\partial \theta} f(x; \theta) dx.$$

$$\text{Let } I(\theta) = E \left[ \left( \frac{\partial \ln f(X; \theta)}{\partial \theta} \right)^2 \right], \quad (3)$$

we call  $I(\theta)$  **Fisher information**.

$$I(\theta) = - \int_{-\infty}^{\infty} \frac{\partial^2 \ln f(x; \theta)}{\partial \theta^2} f(x; \theta) dx. \quad (4)$$

**Fisher information**  $I(\theta)$  is also

$$I(\theta) = \text{Var} \left( \frac{\partial \ln f(X; \theta)}{\partial \theta} \right).$$

$$I(\theta) = E \left[ \left( \frac{\partial \ln f(X; \theta)}{\partial \theta} \right)^2 \right] = E \left[ -\frac{\partial^2 \ln f(X; \theta)}{\partial \theta^2} \right]$$

We call  $\left( \frac{\partial \ln f(X; \theta)}{\partial \theta} \right)$  the score function.

Proof: The proof is an application of the Cauchy-Schwartz inequality, which says that  $\left[ \text{Cov}(Y, Z) \right]^2 \leq (\text{Var}Y)(\text{Var}Z)$  or

$$\frac{\left[ \text{Cov}(Y, Z) \right]^2}{\text{Var}Z} \leq \text{Var}Y.$$

We let  $Y \equiv W(\mathbf{X})$  and  $Z \equiv \frac{\partial}{\partial \theta} \log f(\mathbf{X}|\theta)$ .

First we show that

$$\frac{d}{d\theta} E_{\theta} W(\mathbf{X}) = E_{\theta} \left[ W(\mathbf{X}) \frac{\partial}{\partial \theta} \log f(\mathbf{X}|\theta) \right],$$

which is a covariance from (2)

$$E_{\theta} \left[ \frac{\partial}{\partial \theta} \log f(\mathbf{X}|\theta) \right] = 0.$$

## Ch 7. Point estimation

### UMVUE: CRLB

- ▶ When

$$\frac{\partial^2 \ln f(\mathbf{x}|\theta)}{\partial \theta^2}$$

exist, then

$$I_n(\theta) = -E_\theta \left[ \left( \frac{\partial^2 \ln f(\mathbf{x}|\theta)}{\partial \theta^2} \right) \right]$$

- ▶ The five conditions are usually satisfied with exponential family.
- ▶ If  $X_1, \dots, X_n \stackrel{iid}{\sim} f(x|\theta)$  then

$$Var_\theta(W) \geq \frac{[\tau(\theta)']^2}{n E_\theta \left[ \left( \frac{\partial \ln f(x|\theta)}{\partial \theta} \right)^2 \right]}.$$

## Ch 7. Point estimation

### UMVUE: CRLB

Here

$$\begin{aligned} I_n(\theta) &= nE_{\theta} \left[ \left( \frac{\partial \ln f(x|\theta)}{\partial \theta} \right)^2 \right] \\ &= -nE_{\theta} \left[ \left( \frac{\partial^2 \ln f(x|\theta)}{\partial \theta^2} \right) \right] \\ &\doteq nI_1(\theta) \end{aligned}$$

Proof:

$$I_n(\theta) = Var \left( \frac{\partial \ln f(\theta; \mathbf{X})}{\partial \theta} \right) = Var \left( \sum_{i=1}^n \frac{\partial \ln f(X_i; \theta)}{\partial \theta} \right) = nI(\theta).$$

## Ch 7. Point estimation

### UMVUE: CRLB

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ ,  $\sigma^2$  in known. Find the CRLB and the UMVUE.

$$f(x, \theta) = \frac{1}{\sqrt{2\pi}\sigma_0} \exp\left\{-\frac{(x - \theta)^2}{2\sigma_0^2}\right\}.$$

$$\ln f(x, \theta) = -\ln(\sqrt{2\pi}\sigma_0) - \frac{(x - \theta)^2}{2\sigma_0^2}.$$

$$\frac{\partial \ln f(x, \theta)}{\partial \theta} = \frac{x - \theta}{\sigma_0^2},$$

$$\frac{\partial^2 \ln f(x, \theta)}{\partial \theta^2} = -\frac{1}{\sigma_0^2}.$$

$$I(\theta) = \frac{1}{\sigma_0^2}.$$

CRLB=?, UMVUE=?



## Ch 7. Point estimation

### UMVUE: CRLB

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Poisson}(\lambda)$ . Find the CRLB and the UMVUE.

$$\begin{aligned} I_n(\lambda) &= nI(\lambda) = -nE_{\lambda} \left[ \frac{\partial^2}{\partial \lambda^2} \log \left( \frac{e^{-\lambda} \lambda^X}{X!} \right) \right] \\ &= -nE_{\lambda} \left[ \frac{\partial^2}{\partial \lambda^2} (-\lambda + X \log \lambda - \log X!) \right] = \frac{n}{\lambda}. \end{aligned}$$

CRLB=?, UMVUE=?

## Ch 7. Point estimation

### UMVUE: CRLB

#### Theorem

$X_1, \dots, X_n \stackrel{iid}{\sim} f(x|\theta)$ . Let  $W$  be an unbiased estimator of  $\tau(\theta)$ .  
Then  $\text{Var}_\theta(W)$  attains the CRLB if and only if

$$a(\theta) [W - \tau(\theta)] = \frac{\partial}{\partial \theta} \ln[f(x_1, \dots, x_n|\theta)]$$

for some function  $a(\theta)$ .

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . UMVUE of  $\mu, \sigma^2$ ?

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Uniform}(0, \theta)$ .

The Cramer-Rao inequality is not applicable to this pdf.

(See the Leibniz rule, Theorem 2.4.1, Page 69)

## Ch 7. Point estimation

### UMVUE: Complete Sufficient Statistics

#### Theorem (Rao-Blackwell)

*Let  $W$  be any unbiased estimator of  $\tau(\theta)$  and let  $T$  be a sufficient statistic for  $\theta$ . Define  $\phi(T) = E_{\theta}(W|T)$ . Then*

$$E_{\theta}[\phi(T)] = \tau(\theta)$$

*and*

$$\text{Var}_{\theta}[\phi(T)] \leq \text{Var}_{\theta}[W]$$

*for all  $\theta$ . That is,  $\phi(T)$  is a uniformly better unbiased estimator of  $\tau(\theta)$  than  $W$ .*

Proof:  $E[Y] = E[E(Y|X)]$

$$\text{var}[Y] = \text{var}[E(Y|X)] + E[Y - E(Y|X)]^2$$

## Ch 7. Point estimation

### UMVUE: Complete Sufficient Statistics

- Properties of the best unbiased estimator or UMVUE

If  $W$  is a best estimator of  $\tau(\theta)$ , then  $W$  is unique.

**Proof:** Suppose  $W'$  is another best unbiased estimator, and consider the estimator  $W^* = \frac{1}{2}(W + W')$ . Note that  $E_{\theta}W^* = \tau(\theta)$  and

$$\begin{aligned}\text{Var}_{\theta} W^* &= \text{Var}_{\theta} \left( \frac{1}{2}W + \frac{1}{2}W' \right) \\ &= \frac{1}{4}\text{Var}_{\theta} W + \frac{1}{4}\text{Var}_{\theta} W' + \frac{1}{2}\text{Cov}_{\theta}(W, W') \\ &\leq \frac{1}{4}\text{Var}_{\theta} W + \frac{1}{4}\text{Var}_{\theta} W' + \frac{1}{2}[(\text{Var}_{\theta} W)(\text{Var}_{\theta} W')]^{1/2} \\ &= \text{Var}_{\theta} W.\end{aligned}$$

we can have equality only if  $W' = a(\theta)W + b(\theta)$ .

$$E_{\theta}W' = E_{\theta}W \qquad \text{Var}_{\theta} W = \text{Var}_{\theta} W'$$

Hence  $a(\theta) = 1$ ,  $b(\theta) = 0$  and  $W = W'$ , showing that  $W$  is unique.

## Ch 7. Point estimation

### UMVUE: Complete Sufficient Statistics

#### Theorem (Lehmann-Scheffe)

*Let  $X_1, \dots, X_n$  have joint pmf/pdf  $f(\mathbf{x} : \theta)$ ,  $\theta \in \Theta$ . Suppose  $T$  is a complete and sufficient statistic. If  $\phi(T)$  is an unbiased estimator of  $\tau(\theta)$  and it is a function of  $T$  only then  $\phi(T)$  is the UMVUE of  $\tau(\theta)$ .*

◁ Note:

1. If we can find an unbiased estimator  $\phi(T)$  of  $\tau(\theta)$  which is a function of CSS  $T$  only then it is the UMVUE
2. For any unbiased estimator of  $\tau(\theta)$ ,  $W$ ,  $E(W|T)$  is the UMVUE of  $\tau(\theta)$ .

## Example

Let  $X_1, X_2, \dots, X_n$  be i.i.d.  $N(\mu, \sigma^2)$ , where both  $\mu$  and  $\sigma^2$  are unknown.

Then  $(\sum X_i, \sum X_i^2)$  is a complete sufficient statistic (and thus so is  $(\bar{X}, S^2)$ ).

Since  $S^2$  is unbiased for  $\sigma^2$ , and is a function of the complete sufficient statistic, it is UMVUE.

## Example

Let  $X_1, X_2, \dots, X_n$  be i.i.d.  $Unif(0, \theta)$ .  
 $Y = X_{(n)}$  is a complete sufficient statistic.

The density of  $Y$  is

$$f_Y(y) = \frac{ny^{n-1}}{\theta^n}, \quad 0 < y < \theta.$$

So  $EY = \frac{n}{n+1}\theta$ . Hence  $\frac{n+1}{n}X_{(n)}$  is an unbiased estimator of  $\theta$ . Since  $X_{(n)}$  is complete and sufficient, this is the UMVUE.

## Ch 7. Point estimation

### UMVUE: Complete Sufficient Statistics

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Binomial}(k, \theta)$ . Find the UMVUE of  $\theta$  and  $k\theta(1-\theta)^{k-1}$ .

$$\tau(\theta) = P(X=1) = k\theta(1-\theta)^{k-1}$$

The CSS  $\sum_{i=1}^n X_i \sim \text{Binomial}(kn, \theta)$ .

$$\text{An UE } I(X_1=1) = \begin{cases} 1 & \text{if } X_1=1 \\ 0 & \text{otherwise} \end{cases}.$$

$$\phi\left(\sum X_i\right) = E\left[I(X_1=1) \mid \sum X_i\right] = \dots = \frac{k \binom{(n-1)k}{\left(\sum_{i=1}^n X_i\right)-1}}{\binom{nk}{\sum_{i=1}^n X_i}}$$



$$\begin{aligned}
\phi\left(\sum X_i\right) &= E\left[I\left(X_1=1\right)\middle|\sum X_i=t\right] \\
&= P\left[\left(X_1=1\middle|\sum X_i=t\right)\right] \\
&= \frac{P\left[X_1=1 \text{ and } \sum X_i=t\right]}{P\left[\sum X_i=t\right]} \\
&= \frac{P\left[X_1=1 \text{ and } \sum_{i=2}^n X_i=t-1\right]}{P\left[\sum_{i=1}^n X_i=t\right]} \\
&= \frac{P\left[X_1=1\right] P\left[\sum_{i=2}^n X_i=t-1\right]}{P\left[\sum_{i=1}^n X_i=t\right]}
\end{aligned}$$

$$= \frac{\left[ k\theta(1-\theta)^{k-1} \right] \left[ \binom{(n-1)k}{t-1} \theta^{t-1} (1-\theta)^{(n-1)k-(t-1)} \right]}{\binom{nk}{t} \theta^t (1-\theta)^{nk-t}}$$

$$= \frac{k \binom{(n-1)k}{t-1}}{\binom{nk}{t}} = \frac{k \binom{(n-1)k}{\left(\sum_{i=1}^n X_i\right) - 1}}{\binom{nk}{\sum_{i=1}^n X_i}}$$

is UMVUE.

# Ch 7. Point estimation

## Decision Theory: Loss function optimality

- ▶ Data:  $\mathbf{X}$
- ▶ Model(Distribution):  $f(\mathbf{x}|\boldsymbol{\theta})$ ,  $\boldsymbol{\theta} \in \Theta$
- ▶ Action space:  $\mathcal{A}$   
Point estimation:  $\mathcal{A} = \Theta$   
Testing:  $\mathcal{A} = \{\text{Reject } H_0, \text{Accept } H_0\}$
- ▶ Loss function:  $L(\boldsymbol{\theta}, a)$
- ▶ Decision rule:  $\delta(\mathbf{x}) : \text{Sample space} \rightarrow \mathcal{A}$
- ▶ Risk function: Expected loss

$$R(\boldsymbol{\theta}, \delta) = E [L(\boldsymbol{\theta}, \delta(\mathbf{X}))] = \int L(\boldsymbol{\theta}, \delta(\mathbf{x})) f(\mathbf{x}|\boldsymbol{\theta}) dx$$

- ▶ Goal: Find  $\delta(\mathbf{x})$  that has small risk somehow.

## Ch 7. Point estimation

### Decision Theory: Loss function optimality

#### Definition

A real valued function  $L(\boldsymbol{\theta}, a)$  satisfying

1.  $L(\boldsymbol{\theta}, a) \geq 0$  for all  $\theta, a$
2.  $L(\boldsymbol{\theta}, a) = 0$  for  $a = \theta$

is called a *loss function* of the action  $a$ .

#### Definition

Let  $\delta(\mathbf{X})$  be an estimator of a parametric function  $\tau(\boldsymbol{\theta})$ . Then

$$R(\boldsymbol{\theta}, \delta) = E [L(\boldsymbol{\theta}, \delta(\mathbf{X}))]$$

is called the *risk function* of  $\delta(\mathbf{X})$  in estimating  $\tau(\boldsymbol{\theta})$ .

# Ch 7. Point estimation

## Decision Theory: Loss function optimality

▷ Example:

1. Squared error loss

$$L(\theta, \delta(\mathbf{X})) = (\delta(\mathbf{X}) - \theta)^2, \quad R(\boldsymbol{\theta}, \delta) = E [(\delta(\mathbf{X}) - \theta)^2]$$

2. Absolute error loss

$$L(\theta, \delta(\mathbf{X})) = |\delta(\mathbf{X}) - \theta|, \quad R(\boldsymbol{\theta}, \delta) = E [|\delta(\mathbf{X}) - \theta|]$$

3. Stein's loss

$$L(\theta, \delta(\mathbf{X})) = \frac{\delta(\mathbf{X})}{\theta} - 1 - \ln \left( \frac{\delta(\mathbf{X})}{\theta} \right)$$

# Ch 7. Point estimation

## Decision Theory: Loss function optimality

### Definition

1. An estimator  $\delta_1(\mathbf{X})$  is said to be at least *as good as* another estimator  $\delta_2(\mathbf{X})$  if

$$R(\theta, \delta_1(\mathbf{X})) \leq R(\theta, \delta_2(\mathbf{X}))$$

for all  $\theta \in \Theta$ .

2. An estimator  $\delta_1(\mathbf{X})$  is *better than*  $\delta_2(\mathbf{X})$  if

$$R(\theta, \delta_1(\mathbf{X})) \leq R(\theta, \delta_2(\mathbf{X}))$$

for all  $\theta \in \Theta$  and

$$R(\theta, \delta_1(\mathbf{X})) < R(\theta, \delta_2(\mathbf{X}))$$

for at least one  $\theta \in \Theta$ .

## Ch 7. Point estimation

### Decision Theory: Loss function optimality

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(p)$ .

$$L(\theta, \delta(\mathbf{X})) = (\delta(\mathbf{X}) - \theta)^2. \quad \delta_1(\mathbf{X}) = \bar{X},$$

$$\delta_2(\mathbf{X}) = \frac{n\bar{X} + \sqrt{n/4}}{n + \sqrt{n}}.$$

Figure 7.3.1 (page 333)

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, 1)$ .  $L(\theta, \delta(\mathbf{X})) = (\delta(\mathbf{X}) - \theta)^2$ .  
 $\delta_1(\mathbf{X}) = c$ ,  $\delta_2(\mathbf{X}) = \bar{X}$ .

## Ch 7. Point estimation

### Decision Theory: Loss function optimality

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ . Estimation of  $\sigma^2$  using different loss function. We restrict our estimator of the form  $\delta_b(\mathbf{X}) = bS^2$ . The loss function considered are squared error loss, Stein's loss.

Let  $Y = \sum_{i=1}^n (X_i - \bar{X})^2$ ,

Since  $Y / \sigma^2 \sim \chi^2(n-1)$ ,  $E(Y) = (n-1)\sigma^2$ ,  $\text{var}(Y) = 2(n-1)\sigma^4$

$$E[(cY - \sigma^2)^2] = \text{var}(cY) + [E(cY) - \sigma^2]^2$$

$$= 2c^2(n-1)\sigma^4 + [c(n-1) - 1]^2\sigma^4 = [(n^2-1)c^2 - 2(n-1)c + 1]\sigma^4$$

$$\arg \min_c E[(cY - \sigma^2)^2] = 1 / (n+1)$$



# Ch 7. Point estimation

## Decision Theory: Loss function optimality

- ▶ In general, there does not exist an estimator  $\delta(\mathbf{X})$  such that for any other estimator  $\tilde{\delta}(\mathbf{X})$  we have

$$R(\theta, \delta(\mathbf{X})) \leq R(\theta, \tilde{\delta}(\mathbf{X}))$$

for all  $\theta \in \Theta$ .

- ▶ To define the best estimator w.r.t. the given loss function, we can proceed two ways.
  1. Restrict attention to a smaller class of estimators such as unbiased estimators or linear estimators
  2. Define a criterion for comparing estimators such minimax or Bayes rule

# Ch 7. Point estimation

## Decision Theory: Loss function optimality

### Definition

An estimator  $\delta(\mathbf{X})$  is called a *minimax estimator* if

$$\max_{\theta \in \Theta} R(\theta, \delta(\mathbf{X})) \leq \max_{\theta \in \Theta} R(\theta, \tilde{\delta}(\mathbf{X}))$$

for all other estimator  $\tilde{\delta}(\mathbf{X})$ .

### Definition

The *Bayes risk* of an estimator  $\delta(\mathbf{X})$  w.r.t. prior distribution  $\pi(\theta)$  is defined as

$$B(\pi, \delta(\mathbf{X})) = E_{\pi} [R(\theta, \delta(\mathbf{X}))] = \int R(\theta, \delta(\mathbf{X})) \pi(\theta) d\theta$$

# Ch 7. Point estimation

## Decision Theory: Loss function optimality

### Definition

An estimator  $\delta(\mathbf{X})^\pi$  is said to be a *Bayes estimator* w.r.t. prior distribution  $\pi(\theta)$  if it minimizes Bayes risk over all estimators.

That is

$$B(\pi, \delta(\mathbf{X})^\pi) = \inf_{\tilde{\delta}} B(\pi, \tilde{\delta}(\mathbf{X}))$$

Note that

$$\begin{aligned} B(\pi, \delta(\mathbf{X})^\pi) &= \int_{\Theta} R(\theta, \delta) \pi(\theta) d\theta = \int_{\Theta} \left( \int_{\mathcal{X}} L(\theta, \delta(\mathbf{x})) f(\mathbf{x}|\theta) d\mathbf{x} \right) \pi(\theta) d\theta. \\ &= \int_{\mathcal{X}} \left[ \int_{\Theta} L(\theta, \delta(\mathbf{x})) \pi(\theta|\mathbf{x}) d\theta \right] m(\mathbf{x}) d\mathbf{x}. \end{aligned}$$

### Theorem

Consider a point estimation problem for a real-valued parameter  $\theta$ . The Bayes estimator is  $E(\theta|\mathbf{X})$  for squared error loss and median of  $\pi(\theta|\mathbf{X})$  for absolute error loss.

## Ch 7. Point estimation

### Decision Theory: Loss function optimality

▷ Example:  $X_1, \dots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(p)$ .  $\theta \sim \text{Uniform}(0, 1)$ . Find the Bayes estimator with squared error loss function.

$$E(p|\mathbf{x}) = \frac{\sum x_i + \alpha}{n + \alpha + \beta}. \quad \alpha = \beta = 1$$

**Homework:** p355~364

7.6, 7.7, 7.10, 7.24, 7.37, 7.44, 7.45(a)&(c), 7.48