

Batch Normalization \rightarrow

samples
↓
 $x \rightarrow (m, n_x)$
 $y \rightarrow (m, n_y)$

$$\mu_e = \sum_p^M x_{pe} \cdot \frac{1}{N} \quad ; \quad \sigma^2 = \frac{1}{N} \sum_p^M (x_{pe} - \mu_e)^2$$

$$\hat{x} = \frac{x - \mu}{\sqrt{\sigma^2 + \epsilon}} \rightarrow \hat{x}_{ke} = \frac{x_{ke} - \mu_e}{\sqrt{\sigma_e^2 + \epsilon}}$$

$$y = \gamma \hat{x} + \beta \rightarrow \begin{pmatrix} y_{11} & y_{12} & \dots \end{pmatrix} = \begin{pmatrix} \gamma_1 \hat{x}_{11} + \beta_1 & \gamma_2 \hat{x}_{12} + \beta_2 & \dots \end{pmatrix}$$

$$y_{ke} = \gamma_e \hat{x}_{ke} + \beta_e \rightarrow \frac{\partial y_{ke}}{\partial x_{ij}} = \gamma_e (\delta_{ik} \delta_{jl}) \rightarrow \text{Element wise.}$$

$$\frac{\partial \mathcal{L}}{\partial x_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial \mathcal{L}}{\partial y_{kl}} \cdot \frac{\partial y_{kl}}{\partial x_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial \mathcal{L}}{\partial y_{kl}} \cdot \frac{\partial y_{kl}}{\partial \hat{x}_{ke}} \cdot \frac{\partial \hat{x}_{ke}}{\partial x_{ij}}$$

* Just derivation \rightarrow

$$\hat{x}_{ke} = x_{ke} - \mu_e = x_{ke} - \frac{1}{N} \sum_p^M x_{pe}$$

$$\frac{\partial \hat{x}_{ke}}{\partial x_{ij}} = \begin{vmatrix} 1 - \frac{1}{N} & \text{if } k=i, l \neq j \\ -1/N & \text{if } k \neq i, l=j \\ 0 & \text{otherwise} \end{vmatrix} = \delta_{lj} \left(\delta_{ik} - \frac{1}{N} \right)$$

* Variance \rightarrow

$$\sigma_l^2 = \sum_p^M (x_{pl} - \mu_l)^2 \cdot \frac{1}{N}$$

$$\begin{aligned} \frac{\partial \sigma_l^2}{\partial x_{ij}} &= \frac{1}{N} \cdot 2 \sum_p^M \frac{\partial (x_{pl} - \mu_l)}{\partial x_{ij}} \cdot (x_{pl} - \mu_l) = \frac{2 \delta_{lj}}{N} \sum_p^M (x_{pl} - \mu_l) \left(\delta_{p,i} - \frac{1}{N} \right) \\ &= \frac{2 \delta_{lj}}{N} \left[(x_{il} - \mu_l) + \underbrace{\frac{1}{N} \sum_p^M \mu_l - \frac{1}{N} \sum_p^M x_{pl}}_{\frac{N}{N} \mu_l - \mu_l} \right] = \\ &= \frac{2}{N} \delta_{lj} (x_{il} - \mu_l) \end{aligned}$$

* Norm \rightarrow

$$\begin{aligned} \frac{\partial \hat{x}_{kl}}{\partial x_{ij}} &= \frac{\partial (x_{kl} - \mu_l)}{\partial x_{ij}} (\sigma_l^2 + \varepsilon)^{-1/2} - \frac{1}{2} \frac{\partial \sigma_l^2}{\partial x_{ij}} (x_{kl} - \mu_l) (\sigma_l^2 + \varepsilon)^{-3/2} \\ &= \delta_{lj} \left(\delta_{k,i} - \frac{1}{N} \right) (\sigma_l^2 + \varepsilon)^{-1/2} - \frac{1}{N} \delta_{lj} (x_{il} - \mu_l) (x_{kl} - \mu_l) (\sigma_l^2 + \varepsilon)^{-3/2} \end{aligned}$$

* Cost function \rightarrow

$$\begin{aligned} \frac{\partial h}{\partial x_{ij}} &= \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial y_{kl}} \cdot \frac{\partial y_{kl}}{\partial \hat{x}_{kl}} \cdot \frac{\partial \hat{x}_{kl}}{\partial x_{ij}} = \\ &= \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial \hat{x}_{kl}} \cdot \delta_l \cdot \delta_{lj} (\sigma_l^2 + \varepsilon)^{-1/2} \left[\delta_{k,i} - \frac{1}{N} - \frac{1}{N} (x_{il} - \mu_l) (x_{kl} - \mu_l) (\sigma_l^2 + \varepsilon)^{-1/2} \right] \end{aligned}$$

$$= \frac{1}{N} (\tau_j^2 + \varepsilon)^{-1/2} \left[\frac{\partial h}{\partial y_{ij}} - \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}} - \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}} (x_{ij} - \mu_j) (x_{kj} - \mu_j) (\tau_j^2 + \varepsilon)^{1/2} \right]$$

$$= \frac{\tau_j}{N} (\tau_j^2 + \varepsilon)^{-1/2} \left[\frac{\partial h}{\partial y_{ij}} - \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}} - (x_{ij} - \mu_j) (\tau_j^2 + \varepsilon)^{-1/2} \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}} (x_{kj} - \mu_j) \right]$$

$$\frac{\partial h}{\partial y_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial y_{kl}} \cdot \frac{\partial y_{kl}}{\partial y_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial y_{kl}} \cdot \delta_{lj} \cdot \hat{x}_{kj} =$$

$$= \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}} \cdot \hat{x}_{kj}$$

$$\frac{\partial h}{\partial \beta_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial y_{kl}} \frac{\partial y_{kl}}{\partial \beta_{ij}} = \sum_{k=1}^M \sum_{l=1}^{n_y} \frac{\partial h}{\partial y_{kl}} \cdot \delta_{lj} = \sum_{k=1}^M \frac{\partial h}{\partial y_{kj}}$$