

# Geeks for Geeks: EcoTech DS Hackathon

## Project Documentation

### Skycam Images Based Cloud Coverage Prediction using CV & ML

**Team:** Infyzero

**Team Leader:** Siddharth Kulkarni

**Domain:** Climatic Patterns | Energy

**Tech Domain:** Computer Vision | Machine Learning

## Index

Sr. No.	Title		Page No.
1	Problem Statement & Objectives		2
2	Software Requirements		3
3	Methodology		-
	3.1	System Architecture	4
	3.2	Model Architecture	5
	3.3	Model Training & Evaluation	6
4	Deployment & Screenshots		8
5	Conclusion		10
6	Future Scope		10
7	Project Links		10

# 1. Problem Statement & Objectives

## 1.1 Problem Statement

To find the cloud coverage from a Skycam image. Skycam is an automated camera system to periodically record images of the entire sky from dusk until dawn. Skycam Image is generated from a Skycam device.

**Domain Knowledge:**

- First Image: Low Cloud Coverage
- Second Image: Moderate Cloud Coverage
- Third Image: High Cloud Coverage.

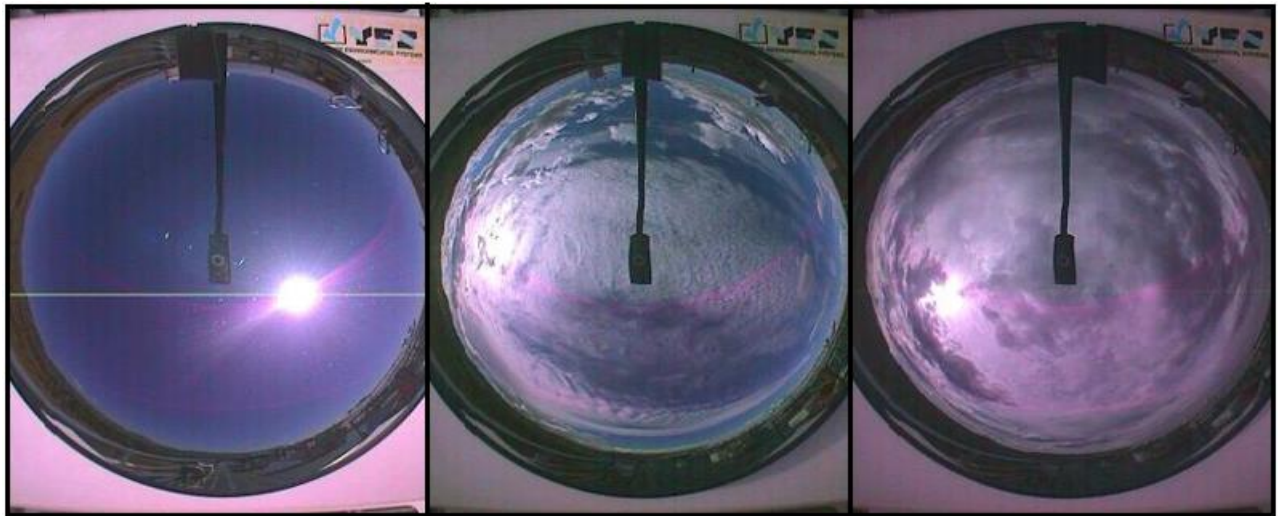


Fig: Sample Skycam Images

## 1.2 Objectives

- **Cloud Coverage Prediction:** To develop a robust model that accurately calculates cloud coverage from skycam images. This model aims to analyze the cloud formations in the provided images and provide a percentage indicating the extent of cloud coverage.
- **Automation:** Automate the process of cloud coverage assessment using sky images. This will reduce the need for manual monitoring and provide real-time information on the cloud conditions.

## 2. Software Requirements

**Language Used:** Python

**Coding Platform:** Kaggle

**To Train CLIP Model:** GPU T4

### **AI/ML Libraries:**

- Data Preprocessing: numpy, pandas
- Data Modeling: catboost, transformers, timm, torch, CLIP
- Image Reading & Resizing: open-cv
- Model Saving: pickle

**Deployment Libraries:** Gradio

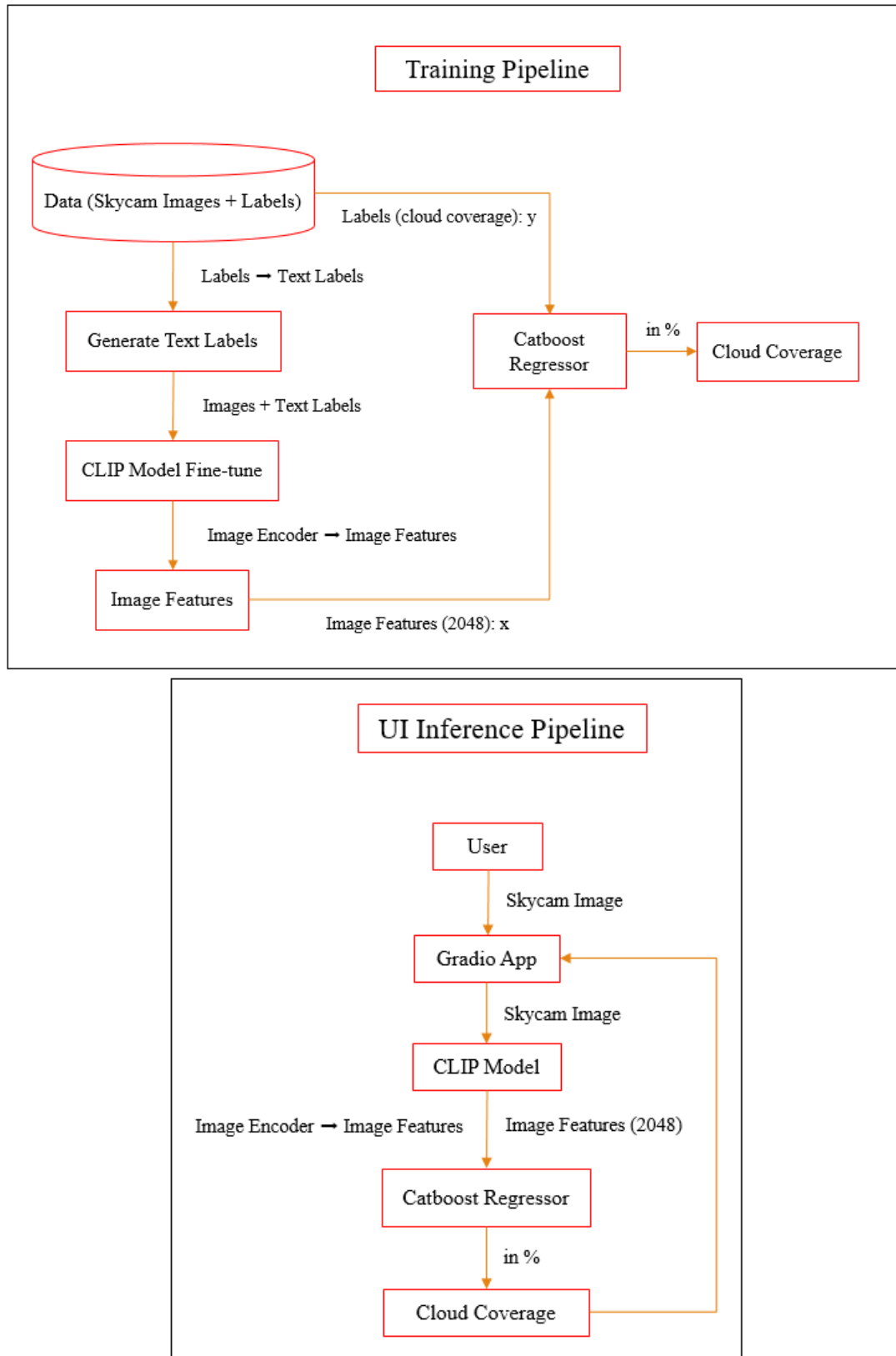
**Deployment Platform:** Hugging Face

### **Requirements.txt:**

- Gradio
- Timm
- opencv-python
- Catboost
- Transformers
- Torch
- git+https://github.com/openai/CLIP.git

# 3. Methodology

## 3.1 System Architecture



## 3.2 Model Architecture

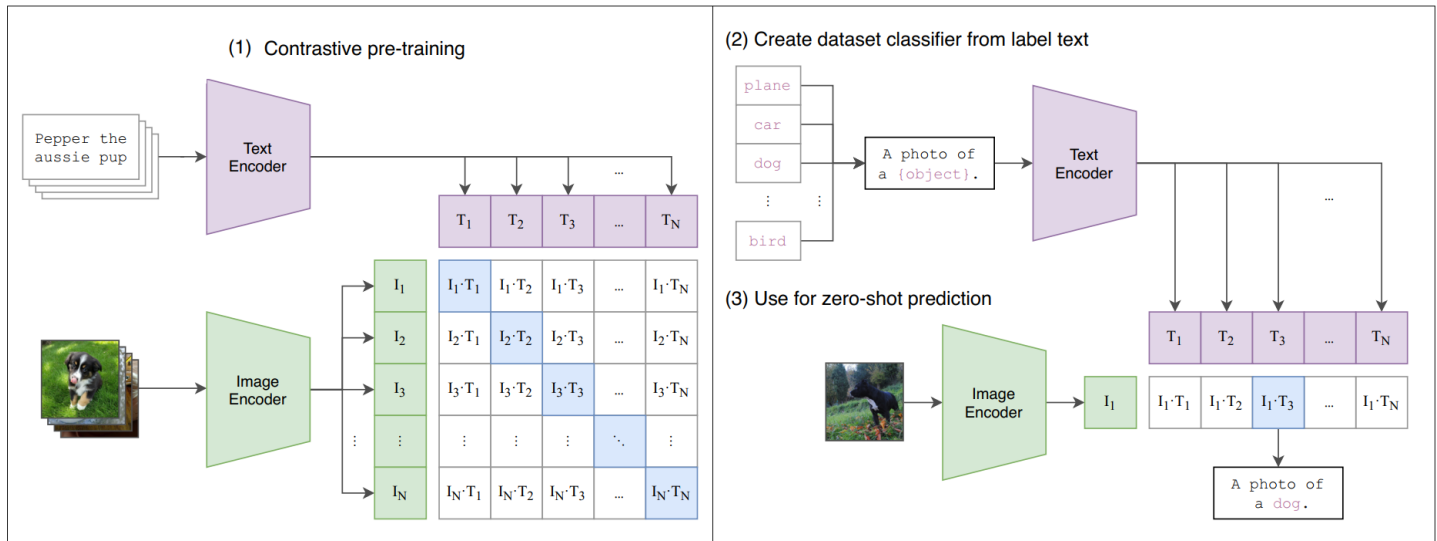


Fig: CLIP Model Architecture

### Clip Model Working:

- Contrastive Language Image Pretraining (CLIP) Model is used for image text similarity problems.
- We aim for CLIP model just to extract features out of skycam images.
- To train CLIP Model: Resnet50 Image Encoder is used, Distilled Bert Text Encoder is used.
- Image Encoder: Converts Image to Features in vector format.
- Text Encoder: Converts Text to Features in vector format.
- Projection Head: Transforms image vector & text vector to fixed size of 2048 and apply dot product.
- Calculates Similarity Score between input image, image feature, and text feature.

### 3.3 Model Training & Evaluation

- CLIP : Total Epochs : 12
- CLIP : Image Encoder : Resnet50
- CLIP : Text Encoder : DistilledBert
- Catboost Model : Iterations : 700
- Catboost Model : Learning Rate : 0.1
- Catboost Model : Max Depth : 8
- Catboost Model : Eval Metrics : RMSE
- Catboost Model TEST Metrics : RMSE : 10.19 | R2 : 0.88
- Catboost Model Output:
  - Low Cloud Cover: 0% - 33%
  - Moderate Cloud Cover: 33% - 66%
  - High Cloud Cover: 66% - 100%

```
# Pretrained Model Usage
model = CLIPModel().to(CFG.device)
params = [
    {"params": model.image_encoder.parameters(), "lr": CFG.image_encoder_lr},
    {"params": model.text_encoder.parameters(), "lr": CFG.text_encoder_lr},
    {"params": itertools.chain(
        model.image_projection.parameters(), model.text_projection.parameters()
    ), "lr": CFG.head_lr, "weight_decay": CFG.weight_decay}
]
optimizer = torch.optim.AdamW(params, weight_decay=0.)
lr_scheduler = torch.optim.lr_scheduler.ReduceLROnPlateau(
    optimizer, mode="min", patience=CFG.patience, factor=CFG.factor
)
step = "epoch"

Downloading model.safetensors:  0%|          | 0.00/102M [00:00<?, ?B/s]

Downloading model.safetensors:  0%|          | 0.00/268M [00:00<?, ?B/s]

# Model Training
best_loss = float('inf')
for epoch in range(CFG.epochs):
    print(f"Epoch: {epoch + 1}")
    model.train()
    train_loss = train_epoch(model, train_loader, optimizer, lr_scheduler, step)
    model.eval()
    with torch.no_grad():
        valid_loss = valid_epoch(model, valid_loader)

    if valid_loss.avg < best_loss:
        best_loss = valid_loss.avg
        torch.save(model.state_dict(), "best.pt")
        print("Saved Best Model!")

    lr_scheduler.step(valid_loss.avg)
```

Fig: CLIP Model Fine-tuning Code: Total Epochs: 12

### Catboost Model

```
CB_model = CatBoostRegressor(iterations = 700, learning_rate = 0.1, max_depth = 8, eval_metric = 'RMSE', random_seed = 48)

CB_model.fit(train_features.cpu().numpy(), train_labels.cpu().numpy(),
             eval_set = (valid_features.cpu().numpy(), valid_labels.cpu().numpy()),
             use_best_model = True, plot = True, verbose = 50)
```

```
MetricVisualizer(layout=Layout(aligned='stretch', height='500px'))
```

0:	learn: 28.1361841	test: 28.2423136	best: 28.2423136 (0)	total: 2.13s	remaining: 24m 49s
50:	learn: 11.5614561	test: 11.9335237	best: 11.9335237 (50)	total: 1m 3s	remaining: 13m 21s
100:	learn: 10.7263689	test: 11.4059249	best: 11.4059249 (100)	total: 2m 1s	remaining: 12m 1s
150:	learn: 10.0566562	test: 11.0617557	best: 11.0617557 (150)	total: 3m	remaining: 10m 55s
200:	learn: 9.5172739	test: 10.8473396	best: 10.8473396 (200)	total: 3m 58s	remaining: 9m 51s
250:	learn: 9.0923719	test: 10.6886373	best: 10.6886373 (250)	total: 4m 55s	remaining: 8m 47s
300:	learn: 8.7042622	test: 10.5734544	best: 10.5734544 (300)	total: 5m 51s	remaining: 7m 45s
350:	learn: 8.3755575	test: 10.4773273	best: 10.4773273 (350)	total: 6m 47s	remaining: 6m 45s
400:	learn: 8.0759744	test: 10.3938604	best: 10.3938604 (400)	total: 7m 44s	remaining: 5m 46s
450:	learn: 7.7814581	test: 10.3233375	best: 10.3233375 (450)	total: 8m 42s	remaining: 4m 48s
500:	learn: 7.5160766	test: 10.2628795	best: 10.2628795 (500)	total: 9m 39s	remaining: 3m 50s
550:	learn: 7.2897423	test: 10.2027638	best: 10.2027638 (550)	total: 10m 35s	remaining: 2m 51s
600:	learn: 7.0611325	test: 10.1574324	best: 10.1574324 (600)	total: 11m 33s	remaining: 1m 54s
650:	learn: 6.8320990	test: 10.1136860	best: 10.1136860 (650)	total: 12m 30s	remaining: 56.5s
699:	learn: 6.6529638	test: 10.0780409	best: 10.0780409 (699)	total: 13m 25s	remaining: 0us

```
bestTest = 10.07804086
```

```
bestIteration = 699
```

Fig: Hyperparameter Tuned Catboost Regressor Model

CatBoost Regressor Metrics			
-	Train Data	Validation Data	Test Data
MAE	4.43	6.3	6.36
RMSE	6.65	10.07	10.19
R2	0.95	0.89	0.88
Total Records	70168	30072	33414

Fig: Catboost Model Metrics

## 4. Deployment & Screenshots

- Developed a Gradio app which takes a skycam image as input and outputs predicted cloud coverage in percentage.
- Developed app consists Fine-tuned CLIP model and Trained Catboost Model.
- Deployed the app to Hugging Face Spaces.

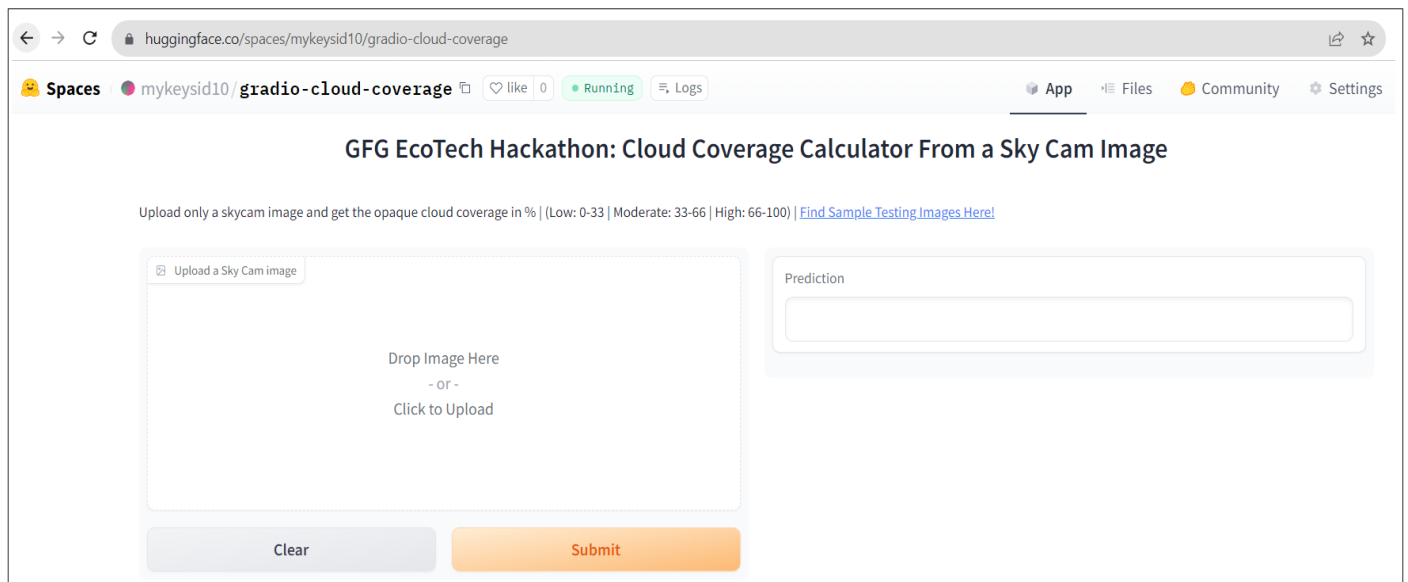


Fig: Hugging Face Deployed UI

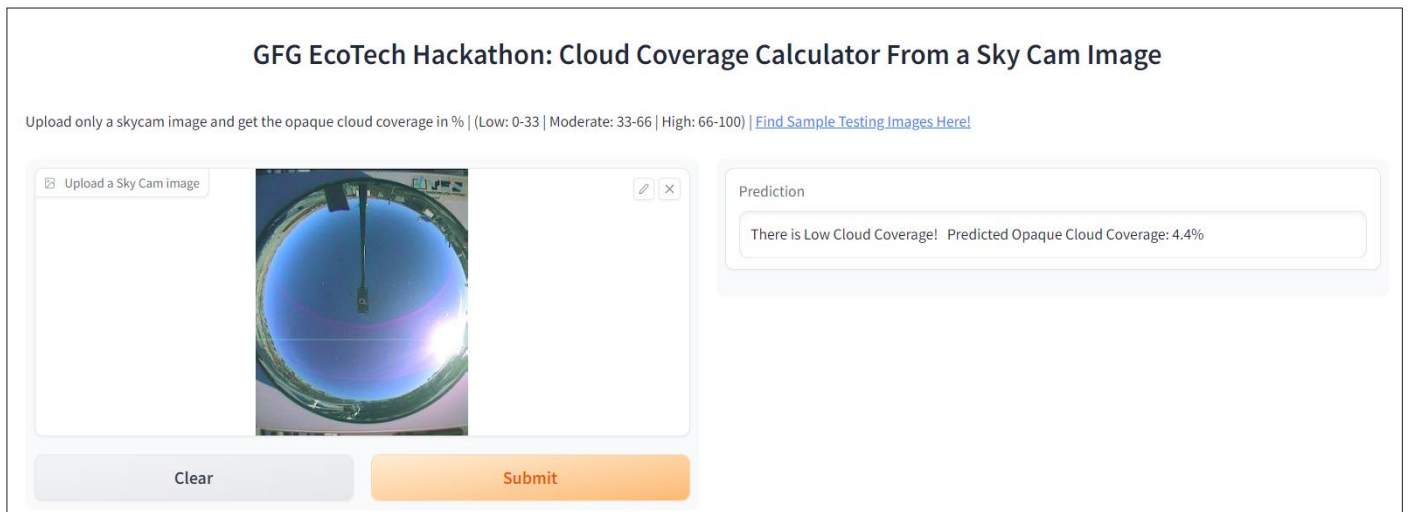



Fig: Low Cloud Coverage Sample



### GFG EcoTech Hackathon: Cloud Coverage Calculator From a Sky Cam Image

Upload only a skycam image and get the opaque cloud coverage in % | (Low: 0-33 | Moderate: 33-66 | High: 66-100) | [Find Sample Testing Images Here!](#)

Upload a Sky Cam image



Clear

Submit

Prediction


There is Moderate Cloud Coverage! Predicted Opaque Cloud Coverage: 43.6%

Fig: Moderate Cloud Coverage Sample

### GFG EcoTech Hackathon: Cloud Coverage Calculator From a Sky Cam Image

Upload only a skycam image and get the opaque cloud coverage in % | (Low: 0-33 | Moderate: 33-66 | High: 66-100) | [Find Sample Testing Images Here!](#)

Upload a Sky Cam image



Clear

Submit

Prediction


There is High Cloud Coverage! Predicted Opaque Cloud Coverage: 85.5%

Fig: High Cloud Coverage Sample

### GFG EcoTech Hackathon: Cloud Coverage Calculator From a Sky Cam Image

Upload only a skycam image and get the opaque cloud coverage in % | (Low: 0-33 | Moderate: 33-66 | High: 66-100) | [Find Sample Testing Images Here!](#)

Upload a Sky Cam image



Clear

Submit

Prediction

There is High Cloud Coverage! Predicted Opaque Cloud Coverage: 80.8%

Fig: Other Variants High Cloud Coverage Sample

## 5. Conclusion

- Successfully build an application which intakes a skycam image and predicts the opaque cloud coverage in percentage with a **RMSE** of **10.19** on Test Data & **R<sup>2</sup>** of **0.88**.
- This model aims to analyze the cloud formations in the provided images and provide a percentage indicating the extent of cloud coverage and also outputs Cloud Coverage Level.

## 6. Future Scope

- Accurate **weather monitoring** is crucial for various applications including agriculture and disaster management. Cloud coverage is a key parameter in weather forecasting and automating its assessment can improve weather predictions.
- Providing **real-time information** on cloud coverage can benefit industries that rely on weather conditions, such as renewable energy generation, outdoor event planning, and transportation.
- The integration of the cloud coverage model with skycam can serve as an **early warning system** for impending storms or heavy rains and climatic drifts. This can help in taking preventive measures and ensuring public safety.

## 7. Project Links

Github Repo URL: <https://github.com/mykeysid10/EcoTech-Data-Science-GfG-Hackathon-Cloud-Coverage-Calculator>

Webapp URL: <https://huggingface.co/spaces/mykeysid10/gradio-cloud-coverage>

Data & Models URL: [https://drive.google.com/drive/folders/14Fk5nWNNQT5Dk0J7KVO4VNCgUxxJTG6Y?usp=drive\\_link](https://drive.google.com/drive/folders/14Fk5nWNNQT5Dk0J7KVO4VNCgUxxJTG6Y?usp=drive_link)

Demo Video Link: <https://www.youtube.com/watch?v=b8qGr6CowWs>