

MUHAMMAD YASIR KHAN

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EDUCATION

- National University of Sciences & Technology** Islamabad, Pakistan
BE. Electronics Engineering Oct. 2008 - Aug. 2012
 - Relevant courses: Embedded Systems, Embedded C, Computer Networks, Digital and Analog Electronics and Systems Design, Operating Systems, Microprocessors, Verilog, Signal Processing

SKILLS

Languages: ARM GNU Assembly, C, C++, Python, Bash

Software: Firmware development, Linux kernel/driver development, Linux device-tree and BSP work, u-boot customization, embedded application development on RTOS (μ C/OS- II and FreeRTOS), source management using Git

Hardware: Digital and analog circuit design, using logic analyzer and oscilloscope, prototyping, system integration, design and fabrication of PCB with SMT components, reading datasheets and schematics

Processors/Platforms: ARM Cortex M4, STM32, ESP8266, Arduino, PIC, AVR, Beaglebone Black

SDK/Frameworks: Yocto Project, STM32CubeMX, ESP IDF, ROS

Communication protocols TCP/IP, MQTT, UART, I2C, SPI, USB

Tools: Kicad (PCB design), Linux command-line tools for compilation, make, cmake

Documentation Writing technical documents, user guides, reviews

CERTIFICATIONS

- Robotic Software Engineer Nanodegree Term 1 *Udacity*
- ROS for Beginners: Basics, Motion and OpenCV *Udemy*
- Embedded Linux kernel & driver development *Mentor Graphics*
- ARM Cortex M4 microcontroller programming *Mentor Graphics*
- ARM Assembly Language from Ground Up *Udemy*
- Introduction to RTOS *Udemy*
- Beginner to advanced C++ programming *Udemy*
- Learn advanced C++ programming *Udemy*
- Modern C++ Concurrency in depth *Udemy*

EXPERIENCE

- Nixplay** Sheung Wan, Hong Kong
Embedded Software Engineer Jan. 2019 - present
 - Developed a multi-threaded firmware for a more responsive digital photo frame and resolved multimedia playback issues.
 - Developed a Yocto Linux based platform for digital signage.
- The Hong Kong Polytechnic University** Hung Hom, Hong Kong
Lead Engineer Aug. 2017 - Oct. 2018
 - Developed hardware and software for an IoT based hydroponic farming system.
 - Designed and fabricated a small footprint wireless environment sensor board with SMT components and wrote it's firmware.
 - Developed the nutrient level monitoring and auto-feed system.
 - Developed the plant imaging system using embedded serial camera and lens assembly.
 - Developed the firmware for LED based grow lights.

- Setup a local IoT server for data collection and device control.
- Modified a commercial wine keeper to grow plants inside it.
- Developed a touch based control panel with UI written in Qt5 to control the wine keeper.

• **Mentor Graphics**

Lahore, Pakistan

Sr. Software Development Engineer

Nov. 2013 - June 2017

- Developed customized Embedded Linux using Yocto Project.
- Developed Yocto Project based Linux BSPs for different hardware platforms including iMX6Q and Xilinx Zynq.
- Debugged and resolved Linux system issues.
- Became proficient in configuring/patching/compiling the Linux kernel and writing device drivers.
- Developed the Mentor's multi-core AMP framework for booting the Linux and Nucleus RTOS in parallel on separate cores of a multi-core ARM processor with a shared memory based communication channel and zero-copy transfer.
- Contributed in open source community and successfully submitted several patches upstream.

• **East West Infiniti (Pvt) Ltd.**

Islamabad, Pakistan

System Design Engineer

Oct. 2012 - Oct. 2013

- Worked on developing an autonomous air-boat. Integrated various on-board sensors and wrote the PID based control software for the GPS navigation.
- Developed the SONAR based sea tide measurement system.
- Added the wireless connectivity to different products using Wi-Fi, Zigbee and GPRS.
- Designed electronic circuits and wrote firmware for the company's numerous projects.

PROJECTS

- **Firmware for Digital Photo Frame:** Wrote a multi-threaded firmware for a mass-produced consumer electronic device capable of multimedia playback. Resolved multimedia issues and utilized the limited resources efficiently to create a responsive user experience.
- **Embedded Linux using Yocto Project:** Developed customized Embedded Linux systems for multiple processor boards using Yocto Project. Developed Linux userspace applications, libraries and kernel drivers.
- **Udacity Robotic Software Engineer Term 1:** Image processing using OpenCV, inverse kinematic analysis of a multi-DOF arm, 3D point cloud object detection and classification using SVM algorithm, training neural networks and Fully Convolutional Network based object tracking.
- **IoT based hydroponic farming:** Developed the hardware and software for IoT based hydroponic farming system. Wrote RTOS based firmware for custom designed wireless environment sensor, LED control and automatic nutrient monitoring and control system. Setup a local IoT web server based on ThingsBoard. Also developed the touch control panel for the device based on Qt5 and Linux.
- **Beaglebone Green Product Review:** Participated as a reviewer in the Beaglebone Green roadtest program conducted by Element14. As a part of the test, explored creating a robotics development platform based on Beaglebone Green running ROS and the Grove connector system of the Beagleboard Green. Submitted a detailed report on the Element14 community website after completion which has received the highest user rating out of all the submissions in the same program.
- **Technical Blogs:** Here's the link to my medium profile where I've written few technical blogs, including the above mentioned Beaglebone Green product review. <https://medium.com/@yasir.gandapur>
- **Autonomous air-boat:** Worked on the development of an air-boat including its mechanical assembly and electronics. Integrated electronics and sensors and implemented a PID based control software for GPS navigation. Conducted extensive experimental testing of the boat in a public lake.