UPS HAT (D)

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Overview

Introduction

The UPS HAT (D) is an uninterruptible power supply (UPS) expansion board specially designed for the Raspberry Pi series. Onboard switching Li battery charging chip with path management, boost converter chip, and voltage/current monitoring chip. Supports simultaneous charging and discharging, and can provide stable 5V voltage output. Also, you can monitor the parameters via the I2C interface, such as the battery voltage, current, and power. Supports displaying the battery level on the system, easy to check the battery's remaining capacity.



Feature

- Adopts pogo pins connector design, compatible with Raspberry Pi series boards.
- Onboard Li battery charging chip, with dynamic path management, a more stable power supply.
- Onboard boost converter chip for stable 5V power output.
- I2C bus communication, monitoring the battery voltage, current, power, and remaining capacity in real-time.
- Multi battery protection circuits: overcharge/discharge protection, over current protection, short circuit protection, more safe and stable.
- Onboard LED indicators for monitoring the battery operating status.
- Comes with online development resources and manuals.

Specification

OUTPUT VOLTAGE: 5VCONTROL BUS: I2C

■ BATTERY SUPPORT: 21700 rechargeable Li battery 3.6V

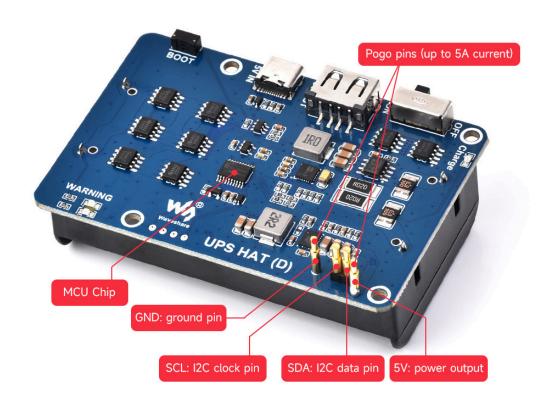
CHARGER SUPPORT: 5V, Type-C connectorCURRENT CAPACITY: 5000mAh (Standard)

■ DIMENSIONS: 56 × 85mm

MOUNTING HOLE SIZE: 3.0mm

Onboard Interface

Hardware Description



(/wiki/File:UPS HAT (D) Hard.jpg)

The USB Type C interface serves as the charging port with an input voltage of 5V. The LED lights up during charging and goes off when fully charged. The silk printing 'OFF/ON' indicates the power switch.

Note 1: Please switch the power switch to OFF when assembling or the board may be damaged as a result of a short circuit.

Note 2: When you connect the battery first, it is necessary to charge it or press the BOOT button to activate the battery protection chip for power output.

Note 3: When the battery is fully charged and connected to the charging power, the output current is approximately 4A. As the battery voltage decreases, the output current will also decrease. When connected to a heavy load, if the current drops too low, there may be unstable voltage boosting, leading to continuous restarts of the Raspberry Pi.

SAFETY CAUTIONS

- Li-ion and Li-po batteries are quite unstable. They may cause fire, personal injury, or property damage, if they're not properly recharged or used.
- Do not reversely connect the polarities when recharging or discharging the battery. Do not use inferior charger/charging panel to recharge the battery.
- Do not mix use old batteries with new ones, avoid using batteries of different brands.
- When buying Lithium battery, make sure the battery specification is compatible with the expansion board. Choose batteries from formal manufacturer, and ensure the batteries will work stably and safely by aging test.

- Lithium batteries have limited cycle life, they will also deteriorate as time goes by. Should be replaced with new ones when the batteries reaching their max cycle life, or working over two years, whichever comes first.
- Should be placed carefully and properly, keep it away from inflammables and explosives articles, away from children, avoid any safety accident caused by careless storage.

Raspberry Pi Demo

Enable I2C Interface

• Open the Raspberry Pi terminal and input the following commands to enter the configuration interface:

```
sudo raspi-config
Select Interfacing Options -> I2C -> yes to enable i2C kernel driver
```



(/wiki/File:RPI open i2c.png)

And then reboot the Raspberry Pi:

sudo reboot

INA219 Baterry Level Detection

To demonstrate this demo on the Raspberry Pi, you only need to insert the module into the Raspberry Pi headers or connect it to the I2C interface of the Raspberry Pi via a cable with VCC connected to 3.3V.

Enter the following command to run the demo:

```
sudo apt-get install p7zip
wget https://files.waveshare.com/wiki/UPS-HAT-D/UPS_HAT_D.7z
7zr x UPS_HAT_D.7z -r -o./
cd UPS_HAT_D
python3 INA219.py
```

The demo will output values such as battery voltage, current, power and the remaining battery capacity percentage after it runs.

(/wiki/File:UPS_HAT_(D)05.png)

Note: If the current is negative, it indicates the battery output current (the Raspberry Pi load current), and if the current is positive, it represents the battery charging current.

When the system load is high and the battery voltage is low, it is undesirable to see that the battery current may be insufficient, leading to continuous system restarts. In practical applications, you can prevent this by shutting down the system automatically when the battery voltage is too low.

In the example demo, battery voltage checking has been added. If the battery voltage is too low and there is no external charging power, the demo will shut down the system within 60 seconds.

The demo will display the following statement to indicate that the battery voltage is too low, and it is necessary to charge it promptly, otherwise, the demo will shut down automatically:

```
Voltage Low, please charge in time, otherwise, it will shut down in 58 s
```

Battery Level Display

Open the terminal and execute:

```
cd ~/UPS_HAT_D
./main.sh #Do not add 'sudo'
sudo reboot
```

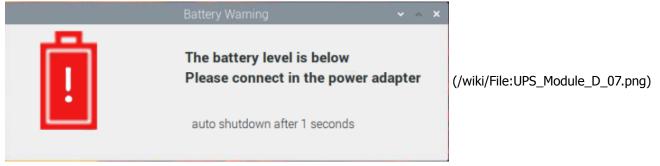
After rebooting, if you see a battery icon in the upper right corner, it indicates that the settings have been successful. When you move the mouse cursor to the battery icon, it will display information about the battery capacity, voltage and remaining charge.



If the above operation takes no effect, you can test it as below:

```
cd ~/UPS_HAT_D
DISPLAY=':0.0' python3 batteryTray.py
```

The demo displays a battery icon in the upper right corner if it runs successfully. If you don't see the battery icon and there is no report for the cause of the error, you should check the I2C interface, and whether the library is installed. When the battery level drops below 5%, a low battery warning will appear. After 60 seconds, it will power off automatically. If you plug in the power supply to charge the battery during the warning, it will exit the warning interface.



If the test of "python3 batteryTray.py" in the Bookworm system works correctly, follow these steps to add auto-start:

```
sudo nano /etc/rc.local
```

Add the following content:

```
sleep 5
cd /home/username/UPS_HAT_D/
python3 batteryTray.py
```

Save and restart.

Boot When Power Applied

When a low voltage is detected, you can use a demo to control the Raspberry Pi to save data before shutting down, thereby avoiding data loss due to sudden power loss.

However, after the Raspberry Pi powers off, it will not automatically restart when power is applied again. But you can start the Raspberry Pi by pulling the GPIO3 pin (or the SCL pin) low.

To detect I2C addresses, open the terminal and execute the following command.

```
i2cdetect -y 1
```

Among these, 0x43 is the address of INA219 and 0x2D is the i2c address of the MCU chip. Run the following instructions to check the register values. The 0x00,0x01,0x02 registers are 0x0a, 0x0b, 0x0c respectively.

```
pi@raspberrypi:~ $ i2cdump -y 1 0x2D
lo size specified (using byte-data access)
                                                                0123456789abcdef
00: 0a 0b 0c c0 58 a0 2a 20 06 03 db 26 46 23 al 3a
10: 03 8b 59 19 99 3f 15 90 da 65 ae f2 a3 e4 b4 8b
                                                                ????X?* ???&F#?:
20: fa c7 7f 37 e4 31 f3 a4 12 12 14 20 33 39 0d b2
                                                                ???7?1????? 39??
30: 41 cd 44 64 le fc bd b1 76 3e 24 10 b0 cc f9 fe
                                                                A?Dd?????v>$?????
   55 72 21 01 1f 37 c0 69 f9 2e cc 94 ff c7 79 47 da 0b 6b 7f cc 57 8b 53 86 80 d4 f8 f8 f4 5b d3
                                                                Ur!??7?i?.??.?yG
                                                                ??k??W?S??????[?
60: ab 3a bf f3 0d 04 al 76 cf 69 86 4d 9d e5 ee a2
                                                                                        (/wiki/File:UPS HAT D 09.png)
   30 44 ad f3 31 fc 58 f9 cf 33 0a 47 87 c3 cd dc a5 e3 8e a8 f1 c2 f9 38 d6 6f 25 5b a9 45 2a 53
                                                                0D??1?X??3?G????
                                                                ???????8?o%[?E*S
90: e5 b2 18 39 a4 e0 e9 f2 65 a4 f4 f0 e2 cf 10 86
a0: bf ca 7c ae 28 30 46 fb c7 74 62 45 7f d0 3b de
                                                                ??|?(0F??tbE??;
00: 6f 1f 53 5c 00 a8 cf 49 b1 8f 3e e0 4d 69 7e 99
                                                                o?S\.??I??>?Mi~?
    el 97 a2 c5 9b ec 8f 8c dl 8a f6 23 cb 8b
    3a 84 cc 92 c3 27 b2 28 92 d6 98 47 13 a5 6d 1c
                                                                :????'?(???G??m?
eO: d6 c4 a5 f6 56 e7 5b 64 0c 75 8a 64 cf a6 e2 73
                                                                ????V?[d?u?d???s
f0: 06 la e8 ab cf f1 59 f6 fd 71 b7 66 fa 77 28 01
                                                                ??????Y??q?f?w(?
```

After changing the value of the 0x01 register to 0x55, the MCU will start detecting the charging port after 30 seconds, and if power is available then pull the GPIO3 pin low to boot the Raspberry Pi.

Run the following command to set the 0x01 register to 0x55.

```
i2cset −y 1 0x2d 0x01 0x55
```

Note 1: The Raspberry Pi needs to be turned off immediately after setting 0x01 to 0x55, otherwise the start when power applied function cannot be enabled when the incoming power pulls the GPIO3 pin low.

Note 2: The start when power applied function has been added to the sample demo.

Resource

Document

Schematic (https://files.waveshare.com/wiki/UPS-HAT-D/UPS_HAT_(D)_Schematic.pdf)

UPS-HAT-D 3D Drawing (https://files.waveshare.com/wiki/UPS-HAT-D/UPS-HAT-D%203D%20Drawing.zip)

Demo Code

Demo code (https://files.waveshare.com/wiki/UPS-HAT-(D)/UPS_HAT_D.7z)

Related Resource

INA219 Datasheet (https://files.waveshare.com/upload/1/10/Ina219.pdf)

FAQ

Question: Why is there no output after removing or mounting the battery?

Answer:

• To resume output after changing the battery, you need to charge the battery first or press the BOOT button to activate the battery protection circuit. Then, switch the power to ON to enable output.

Question: What is the output current?

Answer:

- The output current is approximately 4A when the battery is fully charged and connected to a charging power supply. However, as the battery voltage decreases, the output current will decrease accordingly. If the current is insufficient, the system will automatically shut down.
- If you connect a high-power load, there may be insufficient current, resulting in unstable voltage boosting, which can lead to the Raspberry Pi continuously restarting.

Question: Why does the remaining battery capacity reading fluctuate and is not accurate?

Answer:

- The remaining battery capacity is estimated based on the battery voltage. When charging, the voltage will be slightly higher than the actual battery voltage, so there will be a momentary voltage spike when the power is connected.
- In ideal conditions, a fully charged battery is 4.2V. However, in reality, after reaching full charge, the voltage may drop slightly, being a bit lower than 4.2V.

Question: What is the battery specification?

Answer:

21700 Lithium batteries with an outline diameter of 21mm and a height of 70.0mm. The standard voltage is 3.7V and the voltage is 4.2V after fully charged.

Question: What about the charging LED indicator?

Answer:

The blue LED indicator is on when charging and turns off after fully charging. The blue LED indicator blinks when the product is out of work.

Question: Why is the printed current negative?

Answer:

As it powers the Raspberry Pi, the current output.

Question: How to charge the batteries?

Answer:

Connect a 5V USB to the module's USB Type C port, not the USB Type C port on the Raspberry Pi.

Question: IO ERROR is prompted when running the demo?

Answer:

- I2C is not enabled, please enable the I2C of the Raspberry Pi.
- The poor contact of the pogo pins, and you can detect whether the device is recognized with the following commands:

Install i2c-tools. To check the I2C address easily, you can input the following commands in the console:

```
sudo apt-get install i2c-tools
```

After installation, you can check the I2C address with the following commands:

```
sudo i2cdetect —y 1
```

If UPS HAT is inserted by default, you can get the following result after running the commands:

If it is not recognized:

It is recommended to lock the screws and solder the pin headers for better contact.

Support

Technical Support

If you need technical support or have any feedback/review, please click the **Submit Now** button to submit a ticket, Our support team will check and reply to you within 1 to 2 working days. Please be patient as we make every effort to help you to resolve the issue.

Working Time: 9 AM - 6 PM GMT+8 (Monday to Friday)

Submit Now (https://service.waves hare.com/)

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