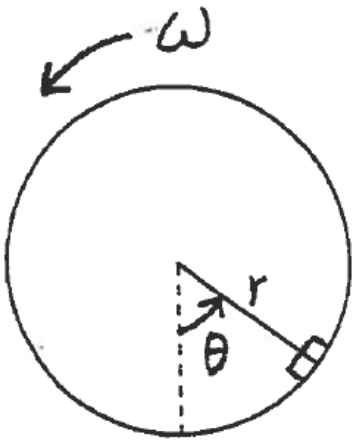


### Sample 1a



The drum shown above rotates in the vertical direction with constant angular velocity  $\omega = 5.8$  rad/s. A small block is initially at the lowest position ( $\theta = 0$ ) and is held in place against the inner surface of the drum by static friction, where the coefficient of friction  $\mu = .6$ . The angles  $\theta$  where the block starts and stops slipping are given by the equation:

$$\mu g \cos \theta + \mu r \omega^2 = g \sin \theta$$

where  $r = 13$  in (this must be converted to feet) and  $g = 32.2$  ft/s<sup>2</sup>.

Write a MATLAB program that uses Newton's Method to calculate the angles  $\theta$  where the block starts and stops slipping. Use  $50^\circ$  and  $150^\circ$  as the initial guesses for  $\theta$  and  $1e-7$  as the accuracy factor. Run the program separately for each initial guess. The output of these two runs should look like this:

Output of first run:     $\theta = 66.57597$

Output of second run:     $\theta = 175.35154$

### Sample 1b

Repeat Sample 1a but this time, instead of implementing Newton's Method in the main program, call a function that uses Newton's Method to calculate  $\theta$ . Name this function `newton`.

### Sample 1c

Repeat Sample 1b but this time let the program generate the initial guesses for  $\theta$  and calculate both values of  $\theta$  in just one run of the program. The output of this one run should look like this:

$\theta = 66.57597$

$\theta = 175.35154$