

# Mayank Kumar Pal

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## Education

- **Master** of Technology in Electronics and Communication Engineering,  
**Indraprastha Institute of Information Technology (IIIT)**, New Delhi, India Aug 2019 - May 2020 (Expected)
  - Dual Degree
  - **Thesis advisor**: Prof. [Sanjit K. Kaul](#)
- **Bachelor** of Technology in Electronics and Communication Engineering,  
**Indraprastha Institute of Information Technology (IIIT)**, New Delhi, India Aug 2015 - May 2019
  - **Thesis Title** : A Reinforcement Learning Approach to Jointly Adapt Vehicular Communications and Planning for Optimized driving. [\[Slides\]](#), [\[Video\]](#)
  - **Supervisor** : Prof. [Sanjit K. Kaul](#) co-advised by Prof. [Saket Anand](#).

## Research Interests

### 1. Reinforcement Learning and Deep Reinforcement Learning

- Relevant Coursework
  - (a) Reinforcement Learning (Markov decision process, Policy & Value iteration, Monte carlo and TD difference learning, Policy gradients, Deep-Q networks)

### 2. Deep Learning and Machine Learning

- Relevant Coursework
  - (a) Machine Learning (Regression, Support Vectors Machine, Perceptron, Deep neural networks)
  - (b) Machine Learning Techniques for Real-time Control (Robot Fundamentals, Lyapunov Stability Analysis, Adaptive neural network based control)

### 3. Heterogeneous Computing

- Relevant Coursework
  - (a) Intelligent Applications Implementation on Heterogeneous Platforms (Implemented Convolutional and Recurrent neural networks architectures on GPU and FPGA using OpenCL)

## Work Experience

- Undergraduate Researcher at **Cyber-Physical Systems Laboratory** Aug 2017 - Apr 2019  
Indraprastha Institute of Information Technology, New Delhi, India
  - Developed a simulation platform to model Vehicle-to-Infrastructure (V2I) conditions for Autonomous Driving. Implemented occupancy grids, Intelligent driver model, Multiple lanes. [\[Source Code\]](#)
  - Integrated simulator with [rllib](#) library to train and evaluate planning and querying policies learned using Reinforcement Learning. [\[Trained Policy\]](#)
- Machine Learning intern at **Philips Innovation Campus**, May 2018 - Jul 2018  
Manyata Tech Park, Bengaluru, India
  - Intent Classification - Built prediction models to classify the intent of the user query. Same models were then used to suggest alternative sentences based on the similarity score of the query. [\[Report\]](#)
  - Named Entity Recognition - Identifying/Extracting named entities like name, locations, organization, quantities etc. from the unstructured text.

# Projects

1. **Understanding Deep Learning Optimization Algorithms using visualizations.** [\[Video\]](#)
  - Visualization of various deep learning optimization algorithms implemented using PyTorch's automatic differentiation tool and optimizers.
  - It demonstrates how the iterative methods approaches to the minimum in the case of convex, non-convex surfaces and surfaces with saddle point.
2. **Recurrent Deep-Q Learning**
  - In Partially Observable Markov Decision process (POMDPs), agent can't directly observe the underlying state, which violates the major assumption of most of the Reinforcement Learning algorithm i.e. state is Markovian. [\[POMDP Environment\]](#)
  - Recurrent networks can learn the latent representation which encodes the useful information of what agent has seen in the past. [\[Trained Policy\]](#)
  - Latent representation is then used as the state input to learn control policies. [\[Results\]](#)
3. **A Deep Reinforcement Learning Framework** [\[Demo\]](#)
  - This framework implements the various state of the art Value based Deep Reinforcement Learning algorithms, supports OpenAI gym environments out of the box.
  - Implementation include [Deep-Q learning](#), Deep-Q learning with target freezing, [Prioritized experience replay](#), [Double Q-learning](#).
4. **Asynchronous Actor-Critic (A3C) - Policy Gradients Methods**
  - High quality implementation of A3C algorithm with Generalized Advantage Estimation. Supports different neural network based policies out of the box. [\[Source Code\]](#)
  - Performance of the algorithm scales linearly with the number of cores. [\[Trained Policies\]](#)
5. **Accelerating Convolutional and Recurrent neural networks Inference on GPU and FPGA using OpenCL**
  - Accelerated VGG19, a Deep neural networks for vision tasks, inference on GPU using OpenCL. [\[Source Code\]](#), [\[Report\]](#).
  - Implemented a Recurrent neural network to accelerate text deciphering inference on FPGA using OpenCL. Xilinx ZC706 platform was used for the implementation. [\[Source Code\]](#), [\[Report\]](#)

# Publications

1. **A Reinforcement Learning Approach to Jointly Adapt Vehicular Communications and Planning for Optimized Driving.** *Mayank K. Pal, Rupali Bhati, Anil Sharma, Sanjit K. Kaul, Saket Anand, P.B. Sujit*, IEEE International Conference on Intelligent Transportation Systems (IEEE-ITSC), November 2018. [\[Paper\]](#), [\[Video\]](#)

# Work in Progress

1. **Autonomous Driving Using Age Optimal Updates**, *Mayank K. Pal, Shivangi Agarwal, Sanjit K. Kaul, Saket Anand and P. B. Sujit* [\[Paper\]](#)

# Tools and Technologies

1. **Programming Languages** - Python (Expert), C/C++(Expert), MATLAB (Intermediate Level)
2. **Deep Learning Frameworks** - PyTorch, Keras, TensorFlow
3. **Machine Learning Frameworks/Tools** - scikit-learn, numpy, pandas, matplotlib
4. **Reinforcement Learning Frameworks/Tools** - [ray](#), [rllib](#), OpenAI gym, MoJoCo
5. **Technologies** - Google Cloud Platform, Kubernetes, Docker, Git

## Teaching

1. Teaching Assistant for **Reinforcement Learning** course taught by Prof. [Sanjit Kaul](#) at IIIT-Delhi (Winter Semester 2018 & Monsoon Semester 2019)
2. Teaching Assistant for **Intelligent Applications Implementation on Heterogeneous Platforms** course taught by Prof. [Sumit Mediratta](#) at IIIT-Delhi (Monsoon Semester 2019)

## Talks/Tutorials

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| 1. Recurrent Neural Networks for Deep Reinforcement Learning to handle Partial Observability in states, <a href="#">[Slides]</a>   | June 2018 |
| 2. Value based Reinforcement Learning - RL Thursdays, <a href="#">[Slides]</a>   | Jan 2019  |
| 3. A Hands-On Tutorial on implementing <a href="#">[Q-Learning]</a> (Off-Policy), <a href="#">[SARSA]</a> (On-Policy) and Policy Gradients algorithms at <b>AI-Winter School</b> , IIIT-Delhi, India | Jan 2019  |
| 4. A Hands-On tutorial on implementing algorithms for Heterogeneous Devices using Open Compute Language (OpenCL). <a href="#">[Slides]</a>   | Aug 2019  |