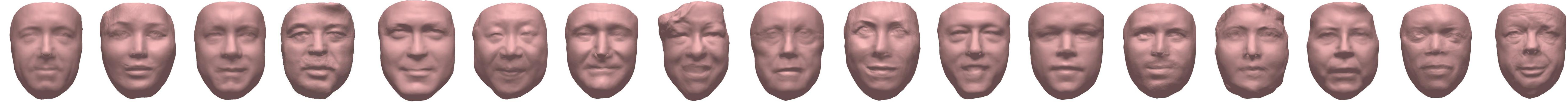


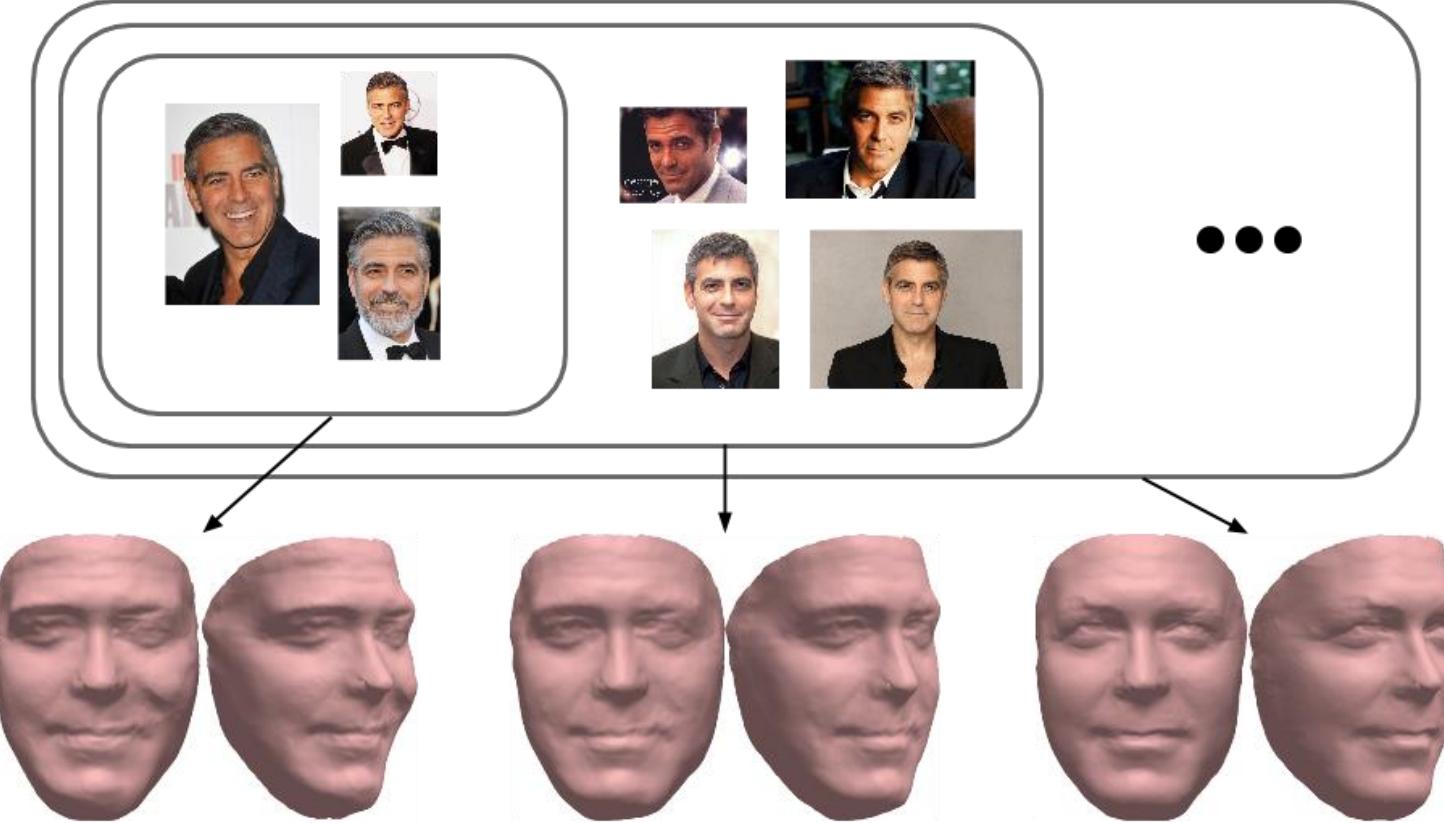


Adaptive 3D Face Reconstruction from Unconstrained Photo Collections

Joseph Roth, Yiyang Tong, and Xiaoming Liu
Department of Computer Science and Engineering, Michigan State University

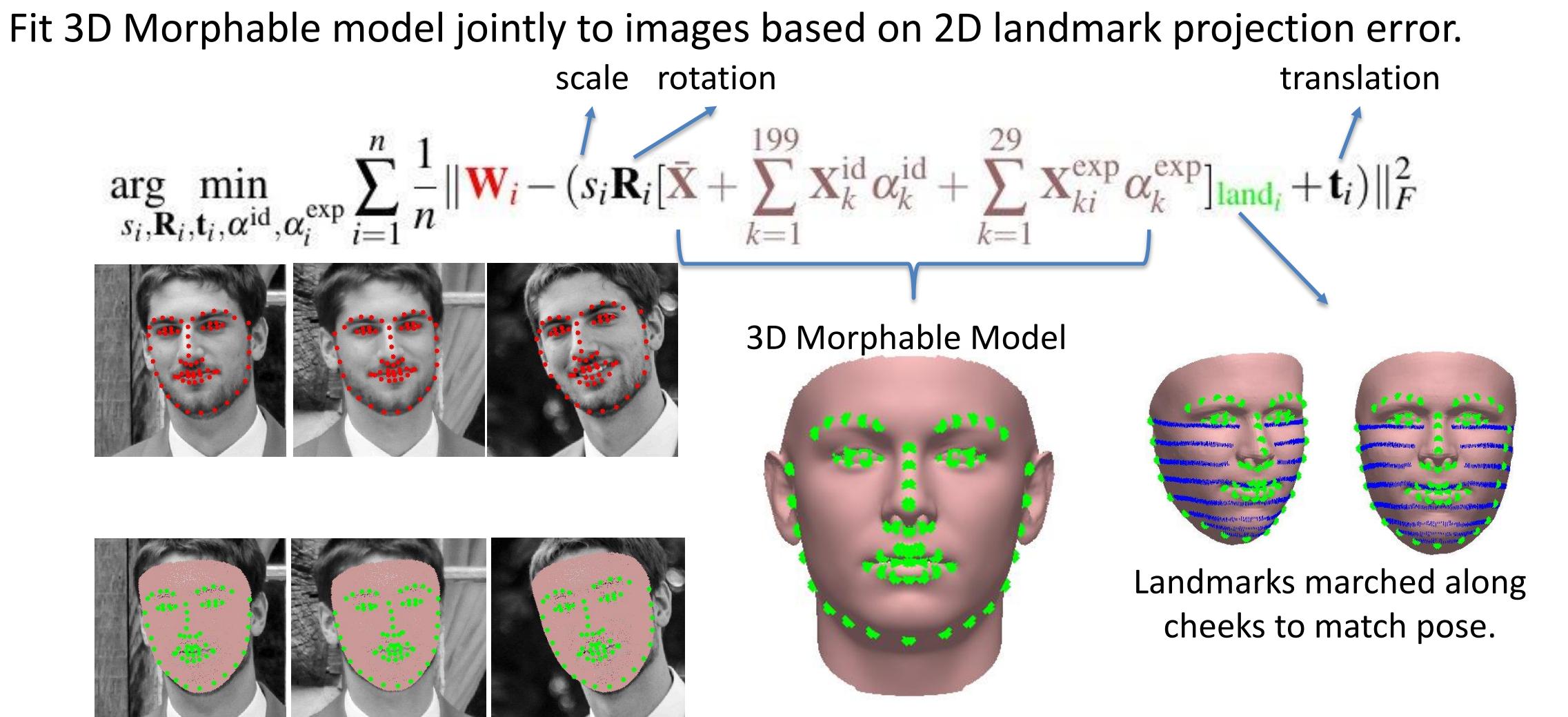


Problem Statement

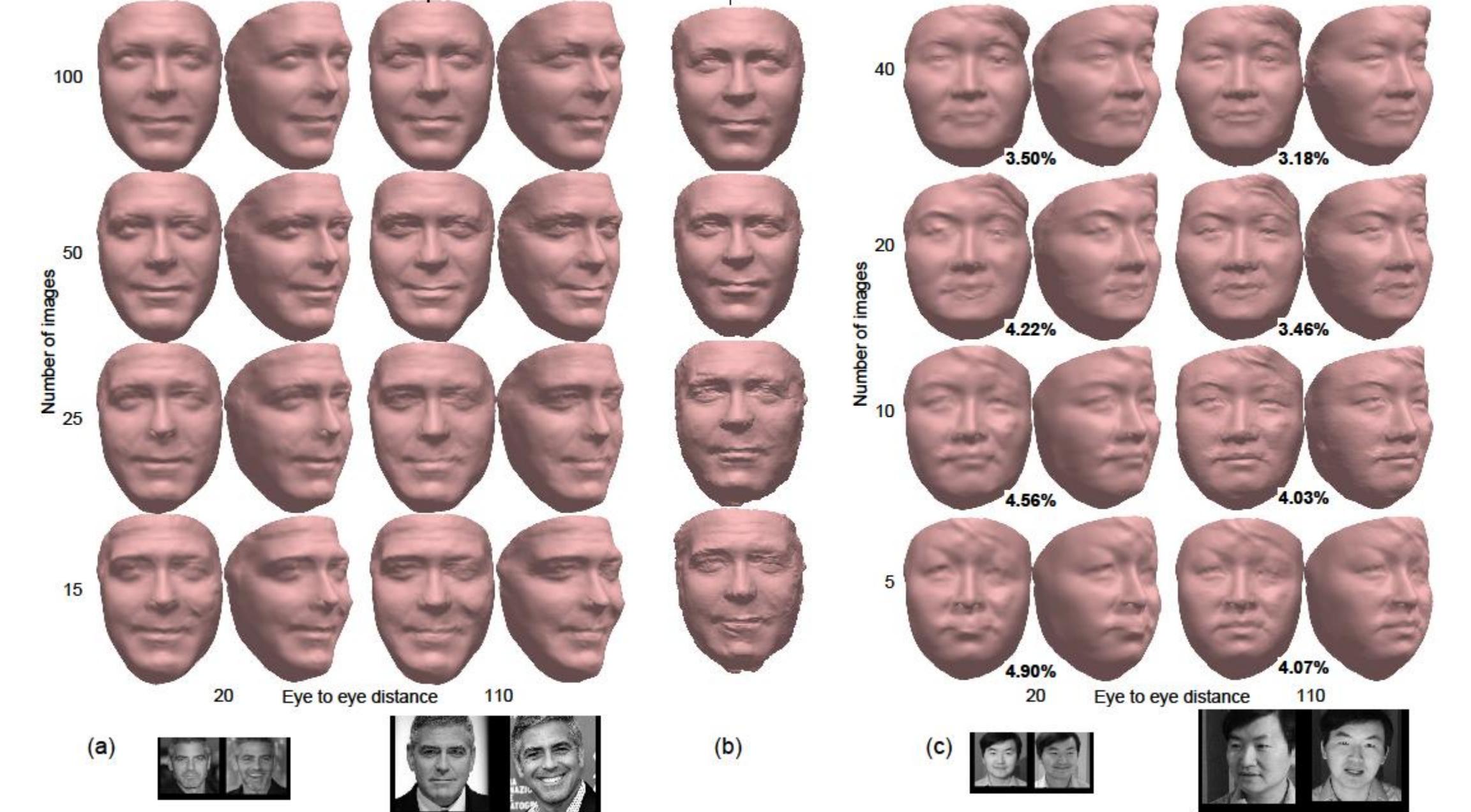


Reconstruct a detailed 3D face model from a photo collection of images with unknown pose, expression, and illumination.
The reconstruction adapts to the number and quality of images.

Template Personalization



Results

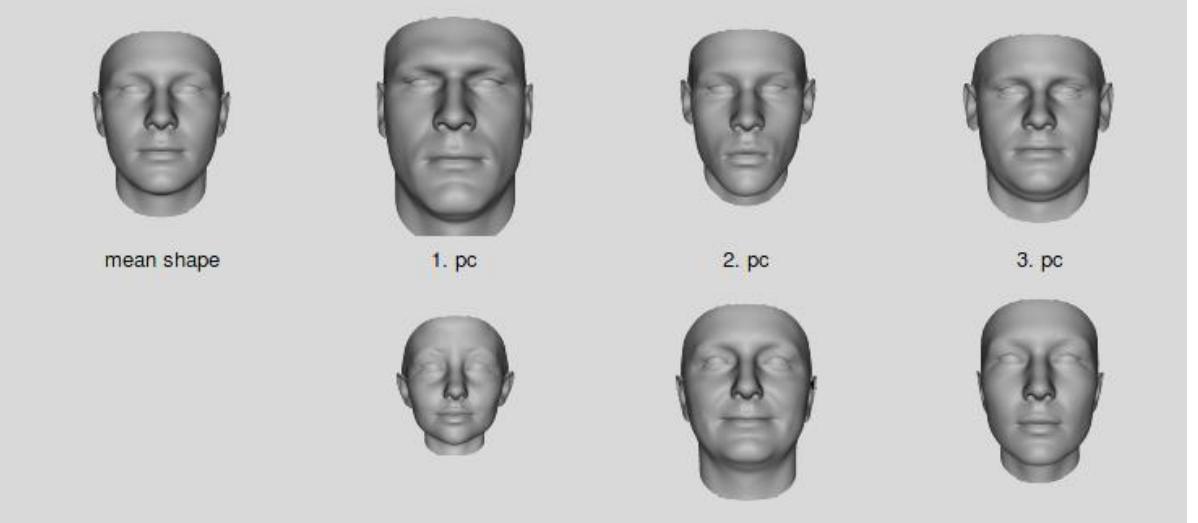


Applications

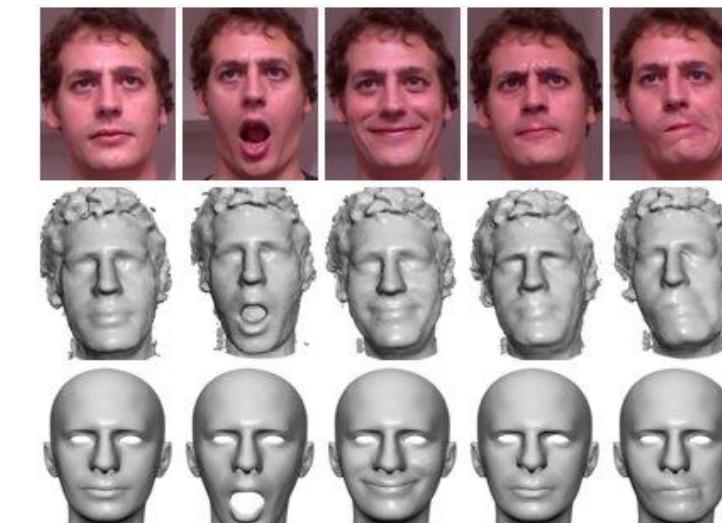
- 3D-assisted face recognition (Blanz & Vetter '03, Hu *et al.* '04).
- Facial animation (Cao *et al.* '14).
- 3D expression recognition (Wang *et al.* '06).
- Consumer entertainment, e.g., personalized bobbleheads.

3D Morphable Model

Basel Face Model:
Identity variations.



FaceWarehouse: Expression information.



$$\bar{\mathbf{X}} + \sum_{k=1}^{199} \mathbf{X}_k^{\text{id}} \alpha_k^{\text{id}} + \sum_{k=1}^{29} \mathbf{X}_{ki}^{\text{exp}} \alpha_k^{\text{exp}}$$

Photometric Normal Estimation

Lambertian reflectance model. Intensity in image is a linear combination of the surface normals weighted by the lighting.

image albedo ambient diffuse

$$\mathbf{I} = \rho(k_a + k_d(l^x, l^y, l^z)^T \mathbf{n})$$

Lighting and Albedo Estimation

Project template onto each face to find vertex correspondence across all images.
Some parts of the face may be obscured in a given image.

$$\arg \min_{\rho_j, \mathbf{l}_t, \mathbf{n}_j} \sum_{i=1}^n \sum_{j=1}^p \| f_{ij} d_{ij} - \rho_j \mathbf{l}_t^T \mathbf{n}_j d_{ij} \|^2 + \lambda_n \|\mathbf{n}_j - \mathbf{n}_j^t\|^2$$

dependability Adaptive template regularization

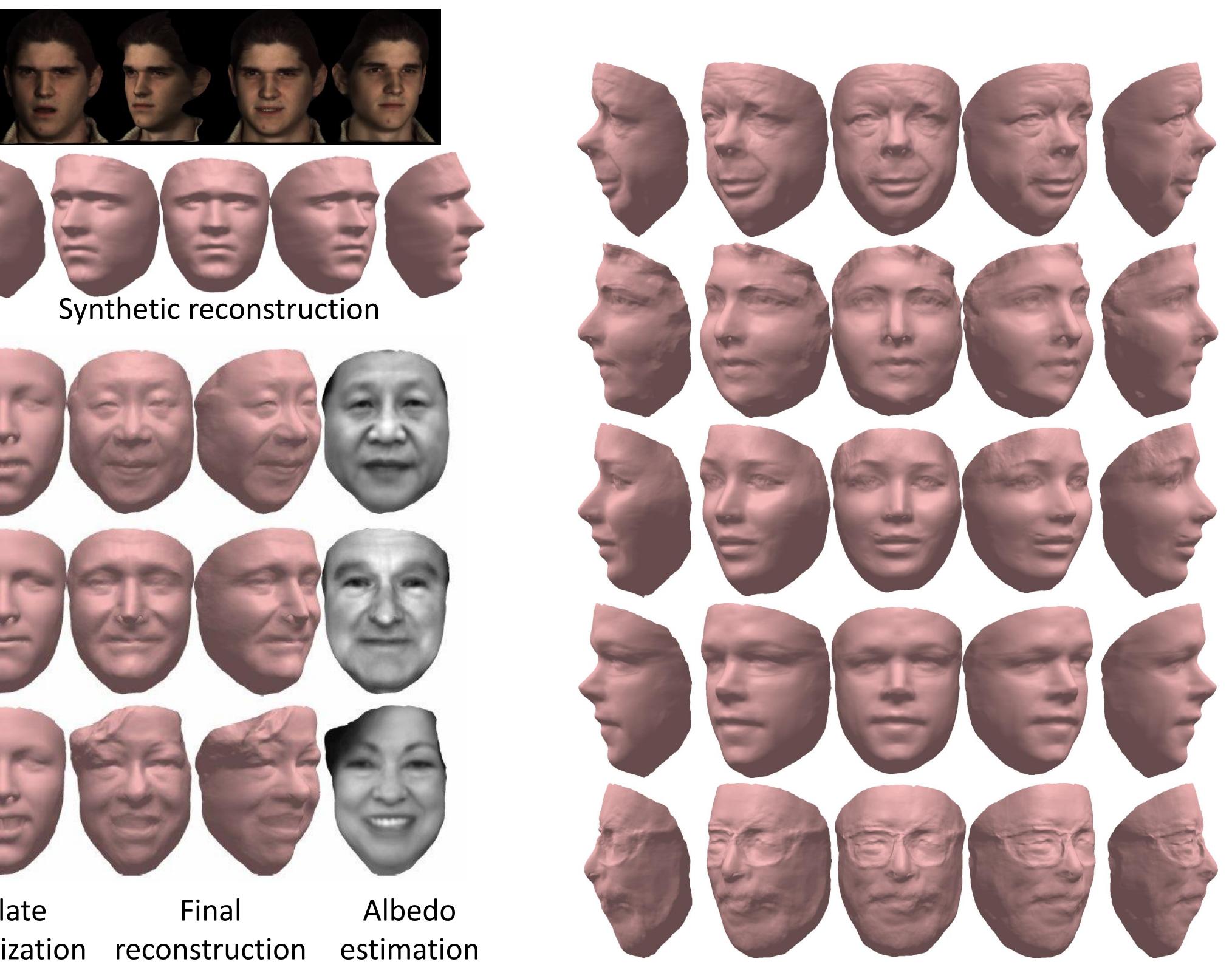
Table: Error comparison for synthetic data.

Method	Neutral	30 Yaw	Expression
Ours	3.22%	3.82%	4.40%
Roth et al. 2015	6.13%	7.48%	6.59%

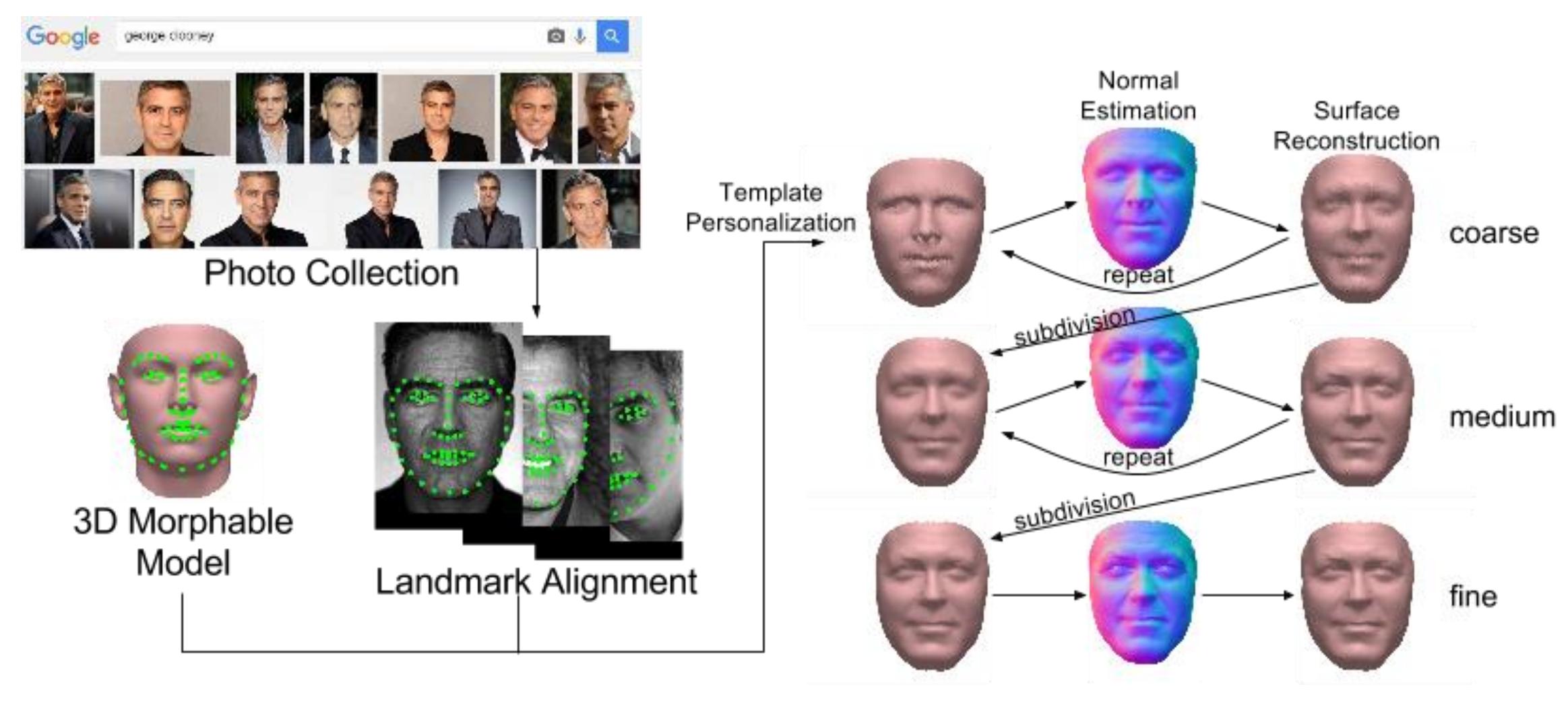
Table: Error comparison of personal collection.

# Images	1	5	10	20	40
Ours	4.19%	4.07%	4.03%	3.46%	3.13%
Roth et al. 2015	-	8.77%	5.40%	4.73%	4.13%

Error is the surface to surface distance, defined as the mean closest distance from each vertex to the other surface. Expressed as a percentage of the interpupillary distance.



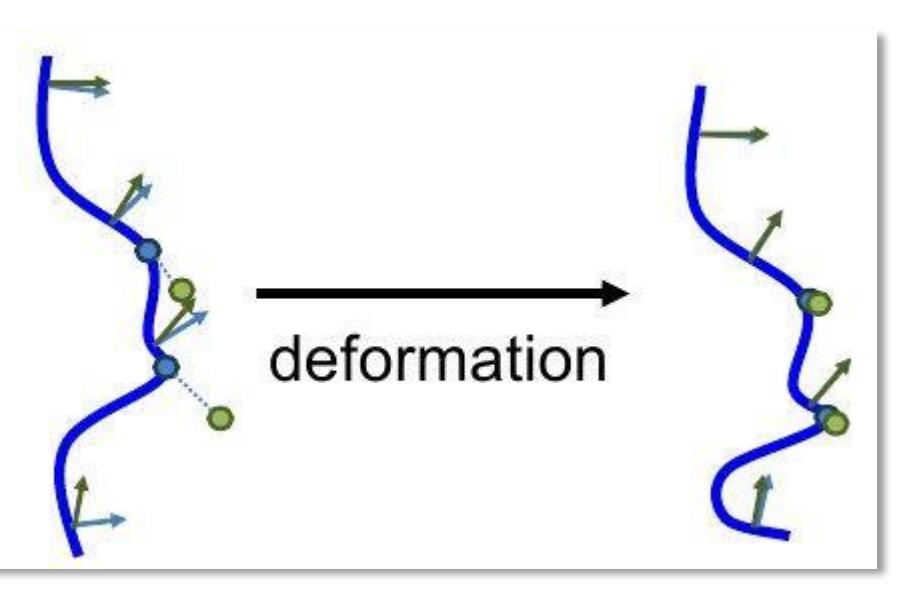
Approach Overview



Surface Reconstruction

Surface Reconstruction

- Deform the surface to better match the landmark constraints and the surface normal constraints.
- Additional boundary constraint to maintain consistency.



$$\mathbf{X}^{k+1} = \arg \min_{\mathbf{X}} \sum_{i=1}^n \| s_i \mathbf{R}_i [\mathbf{X}]_{\text{land}_i} + \mathbf{t}_i - \mathbf{W} \|_F^2 + \lambda_n \|\mathbf{X}\mathcal{L} - \mathbf{NH}\|_F^2 + \lambda_b \|\mathbf{X}\mathcal{L}_b - \mathbf{X}^k \mathcal{L}_b \|_F^2$$

Landmarks Surface Normals Boundary

Conclusions

- 3D Morphable Model fit jointly across entire collection.
- Adaptable regularization in joint Lambertian image rendering formulation allows it to work photo collections of *any* size and diverse ethnicities and gender.
- Coarse to fine scheme improves alignment as well as efficiency.

