

Multi-Directional Multi-Level Dual-Cross Patterns for Robust Face Recognition

Changxing Ding, Jonghyun Choi, Dacheng Tao, *Senior Member, IEEE*, and Larry S. Davis, *Fellow, IEEE*

Abstract—To perform unconstrained face recognition robust to variations in illumination, pose, and expression, this paper presents a new scheme to extract “Multi-Directional Multi-Level Dual-Cross Patterns” (MDML-DCPs) from face images. Specifically, the MDML-DCPs scheme exploits the first derivative of Gaussian operator to reduce the impact of differences in illumination and then computes the DCP feature at both the holistic and component levels. DCP is a novel face image descriptor inspired by the unique textural structure of human faces. It is computationally efficient and only doubles the cost of computing local binary patterns, yet is extremely robust to pose and expression variations. MDML-DCPs comprehensively yet efficiently encodes the invariant characteristics of a face image from multiple levels into patterns that are highly discriminative of inter-personal differences but robust to intra-personal variations. Experimental results on the FERET, CAS-PERL-R1, FRGC 2.0, and LFW databases indicate that DCP outperforms the state-of-the-art local descriptors (e.g. LBP, LTP, LPQ, POEM, and LGXP) for both face identification and face verification tasks. More impressively, the best performance is achieved on the challenging LFW and FRGC 2.0 databases by deploying MDML-DCPs in a simple recognition scheme.

Index Terms—Face recognition, face image descriptors, face image representation



1 INTRODUCTION

FACE recognition has been an active area of research due to both the scientific challenge and its potential use in a wide range of practical applications. Satisfactory performance has been achieved but often only in controlled environments. More recently, there has been increased demand for recognition of unconstrained face images, such as those collected from the internet or captured by mobile devices and surveillance cameras. However, recognition of unconstrained face images is a difficult problem due to degradation of face image quality and the wide variations of illumination, pose, expression, and occlusion often encountered in images.

A face recognition system usually consists of a face representation stage and a face matching stage. For face matching, multi-class classifiers have been used for face identification, such as the nearest neighbor (NN) classifier and the sparse representation classifier (SRC) [1], with two-class classifiers, such as support vector machine (SVM) and Bayesian analysis, being used for verification. In face representation, good representations discriminate inter-personal differences while being robust to intra-personal variations. To date, two major categories of face representation methods have emerged, namely holistic subspace learning-based methods [2], [3], [4], [5] and face image descriptor-based methods [6], [7], [8], [9]; the latter has dominated recent research due to

robustness to real-life challenges such as illumination and expression differences. Consequently, the design of effective face image descriptors is regarded as fundamental for face recognition. Based on design methodology, we can group existing face image descriptors into two groups: hand-crafted descriptors and learning-based descriptors.

Most face image descriptors are hand-crafted, of which Local Binary Patterns (LBP) and Gabor wavelets are two representative methods; Ahonen et al. [6] showed that the texture descriptor LBP is extremely effective for face recognition. LBP works by encoding the gray-value differences between each central pixel and its neighboring pixels into binary codes; the face image is then represented as the concatenated spatial histograms of the binary codes. Several variants of LBP have been proposed, e.g., Local Ternary Patterns (LTP) [10], three-patch LBP (TP-LBP) [11] and multi-block LBP (MB-LBP) [12]. On the other hand, Gabor wavelets aim to encode multi-scale and multi-orientation information on Gabor filtered images [8], [13], [14], [15]. LBP-like descriptors are therefore better at encoding fine-scale information while Gabor-based descriptors extract information on larger scales. Other notable descriptors for face recognition include Local Phase Quantization (LPQ) [16] and Patterns of Oriented Edge Magnitudes (POEM) [17]. In LPQ, the blur-invariant information in face images is encoded and the method shows good performance in unconstrained conditions [9]. POEM works by computing the LBP feature on orientated edge magnitudes.

Of the learning-based descriptors, LE [7], Local Quantized Patterns (LQP) [18], and Discriminant Face Descriptor (DFD) [19] have emerged in recent years, which rely on unsupervised or supervised learning techniques

- C. Ding and D. Tao are with the Centre for Quantum Computation and Intelligent Systems, Faculty of Engineering and Information Technology, University of Technology, Sydney, Australia. E-mail: changxing.ding@student.uts.edu.au, dacheng.tao@uts.edu.au.
- J. Choi and L.S.Davis are with the Institute for Advanced Computer Studies, University of Maryland, College Park, MD 20742. E-mail: {jhchoi,lsd}@umiacs.umd.edu.

to optimize encoders. One important advantage of learning-based descriptors over hand-crafted descriptors is their greater diversity in sampling pattern shapes and the larger sampling size.

Despite the successful application of existing face image descriptors, the following three points are worth considering. First, the textual characteristics of human faces have mostly been overlooked in the design of existing descriptors. Second, it is generally prohibitive for hand-crafted descriptors to adopt a large sampling size due to the complication of the resulting encoding scheme and large feature size (i.e., the number of histogram bins) [18]. However, a large sampling size is desirable since it provides better discriminative power, as has been proved by learning-based descriptors; it is therefore reasonable to ask whether it is genuinely impossible for hand-crafted descriptors to exploit large sampling sizes. Third, the recently proposed descriptors achieve good performance but at the cost of using computationally expensive techniques such as Gabor filtering and codebook learning. It would therefore be desirable to obtain a face image descriptor with superior performance that retains a lower computational cost and feature size.

To address these three limitations of existing techniques, in this paper we present a novel face image descriptor named Dual-Cross Patterns (DCP). Inspired by the unique textural structure of human faces, DCP encodes discriminative information along the directions of major facial components: the horizontal direction for eyes, eyebrows, and lips; the vertical direction for the nose; and the diagonal directions ($\pi/4$ and $3\pi/4$) for the end parts of facial components. The sampling strategy we adopt samples twice as many pixels as LBP. By appropriately grouping the sampled pixels from the perspective of maximum joint Shannon entropy, we keep the DCP feature size reasonable. DCP is very efficient - only twice the computational cost of LBP. Significantly better performance is achieved even when a sub-DCP (denoted herein as DCP-1 and DCP-2) of exactly the same time and memory costs as LBP is used.

A powerful face representation scheme is equally important for unconstrained face recognition as a good face image descriptor. To improve the discrimination of face representations, the usual approach is to fuse the information extracted by different descriptors [10], [20] and at different scales [9], [21]. To enhance robustness to pose variation, Wright et al. [22] expanded image patch descriptors with their spatial locations and represented the face image as a histogram of quantized patch descriptors. Zhu et al. [23] learnt pose-invariant face representation using convolutional neural networks. Recently, face representation has benefited from rapid progress in face alignment techniques [24], [25], [26], [27]. For example, Chen et al. [28] built a high dimensional face representation by extracting LBP features from multi-scale image patches around dense facial feature points. Using this face representation and outside training data, Cao et al. [29] achieved top level performance on the

LFW [30] database.

In this paper we propose a highly robust and discriminative face representation scheme called Multi-Directional Multi-Level Dual-Cross Patterns (MDML-DCPs). Specifically, the MDML-DCPs scheme employs the first derivative of Gaussian operator to conduct multi-directional filtering to reduce the impact of differences in illumination. DCP features are then computed at two levels: 1) holistic-level features incorporating facial contours and facial components and their configuration, and 2) component-level features focusing on the description of a single facial component. Thus, MDML-DCPs comprehensively encodes multi-level invariant characteristics of face images.

Both the DCP descriptor and the MDML-DCPs scheme are extensively evaluated on four large-scale databases: FERET [31], CAS-PEAL-R1 [32], FRGC 2.0 [33], and LFW [30]. The proposed DCP descriptor consistently achieves superior performance for both face identification and face verification tasks. More impressively, the proposed MDML-DCPs exploits only a single descriptor but achieves the best performance on two challenging unconstrained databases, FRGC 2.0 and LFW.

The remainder of the paper is organized as follows: Section 2 details the DCP descriptor and the construction of the MDML-DCPs face representation scheme is discussed in Section 3. Face recognition pipelines using MDML-DCPs are introduced in Section 4. Experimental results are presented in Section 5, leading to conclusions in Section 6.

2 DUAL-CROSS PATTERNS

The design of a face image descriptor consists of three main parts: image filtering, local sampling, and pattern encoding. The implementation of image filtering is flexible: possible methods include Gabor wavelets [8], Difference of Gaussian (DoG), or the recently proposed discriminative image filter [34]. In this paper, we focus on local sampling and pattern encoding, which are the core components of a face image descriptor.

2.1 Local Sampling

The essence of DCP is to perform local sampling and pattern encoding in the most informative directions contained within face images. For face recognition, useful face image information consists of two parts: the configuration of facial components and the shape of each facial component. The shape of facial components is, in fact, rather regular. In particular, after geometric normalization of the face image, the central parts of several facial components, i.e., the eyebrows, eyes, nose, and mouth, extend either horizontally or vertically, while their ends converge along approximately diagonal directions ($\pi/4$ and $3\pi/4$). In addition, wrinkles in the forehead lie flat, while those in the cheeks are either raised or inclined.

Based on the above observations, local sampling of DCP is conducted as shown in Fig. 1. For each pixel

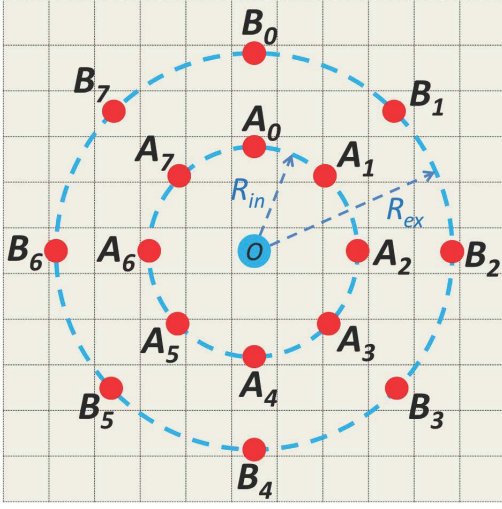


Fig. 1. Local sampling of Dual-Cross Patterns. Sixteen points are sampled around the central pixel O . The sampled points A_0 to A_7 are uniformly spaced on an inner circle of radius R_{in} , while B_0 to B_7 are evenly distributed on the exterior circle with radius R_{ex} .

O in the image, we symmetrically sample in the local neighborhood along the $0, \pi/4, \pi/2, 3\pi/4, \pi, 5\pi/4, 3\pi/2$, and $7\pi/4$ directions, which are sufficient to summarize the extension directions of major facial textures. Two pixels are sampled in each direction. The resulting sampled points are denoted as $\{A_0, B_0; A_1, B_1; \dots; A_7, B_7\}$. As illustrated in Fig. 1, A_0, A_1, \dots, A_7 are uniformly spaced on an inner circle of radius R_{in} , while B_0, B_1, \dots, B_7 are evenly distributed on the exterior circle with radius R_{ex} .

2.2 Pattern Encoding

Encoding of the sampled points is realized in two steps. First, textural information along each of the eight directions is independently encoded. Second, patterns in all eight directions are combined to form the final DCP codes.

To quantize the textural information in each sampling direction, we assign each a unique decimal number:

$$DCP_i = S(I_{A_i} - I_O) \times 2 + S(I_{B_i} - I_{A_i}), 0 \leq i \leq 7, \quad (1)$$

where

$$S(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0 \end{cases}, \quad (2)$$

and I_O, I_{A_i} , and I_{B_i} are the gray value of points O, A_i , and B_i , respectively. Therefore, four patterns are defined in each direction and each of the four patterns denotes one type of textural structure.

By simultaneously considering all eight directions, the total number of DCP codes is $4^8 = 65536$. This number is too large for practical face recognition applications; therefore, to reduce the number of codes, we adopt the following strategy. The eight directions are grouped into two subsets and each subset is further formulated as an

encoder. In this way, the total number of local patterns is reduced to $4^4 \times 2 = 512$, which is computationally efficient. Although this strategy results in information loss, compactness and robustness of the descriptor are promoted. In the following subsection, we define the optimal grouping mode.

2.3 Dual-Cross Grouping

The grouping strategy introduced in the previous subsection produces $\frac{1}{2} \binom{8}{4} = 35$ combinations in total to partition all eight directions. To minimize information loss, we look for the optimal combination from the perspective of maximum joint Shannon entropy.

With the above analysis, DCP_i ($0 \leq i \leq 7$) are discrete variables with four possible values: 0, 1, 2, and 3. Without loss of generality, the joint Shannon entropy for the subset $\{DCP_0, DCP_1, DCP_2, DCP_3\}$ is represented as

$$\begin{aligned} H(DCP_0, DCP_1, DCP_2, DCP_3) \\ = - \sum_{dcp_0} \dots \sum_{dcp_3} P(dcp_0, \dots, dcp_3) \log_2 P(dcp_0, \dots, dcp_3), \end{aligned} \quad (3)$$

where dcp_0, dcp_1, dcp_2 , and dcp_3 are particular values of DCP_0, DCP_1, DCP_2 , and DCP_3 , respectively. And $P(dcp_0, \dots, dcp_3)$ is the probability of these values occurring simultaneously. The maximum joint Shannon entropy of the four variables is achieved when they are statistically independent.

In real images, the more sparsely the pixels are scattered, the more independent they are. Therefore, the maximum joint Shannon entropy for each subset is achieved when the distance between the sampled points is at its maximum. As a result, we define $\{DCP_0, DCP_2, DCP_4, DCP_6\}$ as the first subset and $\{DCP_1, DCP_3, DCP_5, DCP_7\}$ as the second subset. The resulting two subsets are illustrated in Fig. 2. Since each of the two subsets constructs the shape of a cross, the proposed descriptor is named Dual-Cross Patterns. In Section 5.1, we empirically validate that the dual-cross grouping mode achieves the maximum joint Shannon entropy among all grouping modes on the FERET databases.

2.4 DCP Face Image Descriptor

We name the two cross encoders DCP-1 and DCP-2, respectively. The codes produced by the two encoders at each pixel O are represented as

$$DCP-1 = \sum_{i=0}^3 DCP_{2i} \times 4^i, \quad (4)$$

$$DCP-2 = \sum_{i=0}^3 DCP_{2i+1} \times 4^i. \quad (5)$$

The DCP descriptor for each pixel O in an image is the concatenation of the two codes generated by the two cross encoders:

$$DCP = \left\{ \sum_{i=0}^3 DCP_{2i} \times 4^i, \sum_{i=0}^3 DCP_{2i+1} \times 4^i \right\}. \quad (6)$$

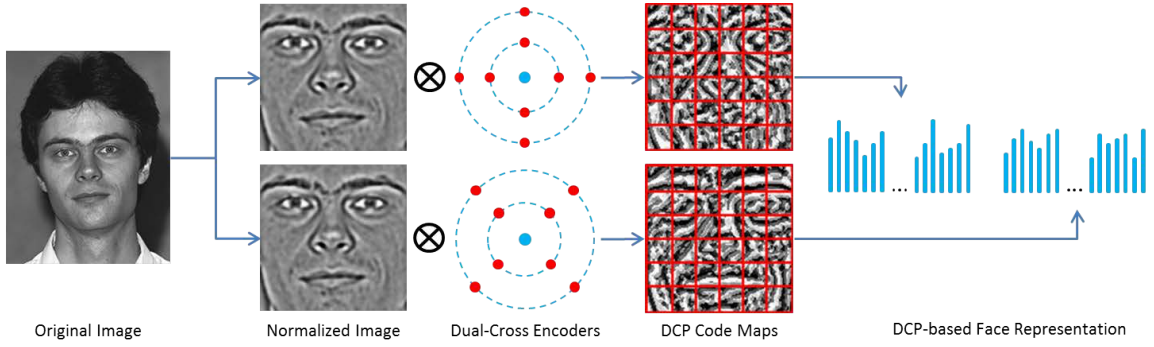


Fig. 2. Face representation using Dual-Cross Patterns. The normalized face image is encoded by the two cross encoders, respectively. Concatenation of the regional DCP code histograms forms the DCP-based face representation.

After encoding each pixel in the face image using the dual-cross encoders, two code maps are produced that are respectively divided into a grid of non-overlapping regions. Histograms of DCP codes are computed in each region and all histograms are concatenated to form the holistic face representation. The overall framework of the above face representation approach is illustrated in Fig. 2. This face representation can be directly used to measure the similarity between a pair of face images using metrics such as the chi-squared distance or histogram intersection.

The computation of the DCP descriptor, which doubles the feature size of LBP, is very efficient by only doubling the time cost of LBP.

We notice that two recently proposed descriptors DFD [19] and Center Symmetric-Pairs of Pixels (CCS-POP) [35] adopt similar sampling modes to DCP. However, they are essentially different from DCP. First, there is no clear motivation for the two descriptors that why such a sampling mode is suitable for face images. Second, the pattern encoding strategies are different: both the two descriptors rely on learning algorithms to handle the large sampling size problem mentioned in Section 1.

3 MULTI-DIRECTIONAL MULTI-LEVEL DUAL-CROSS PATTERNS

We now present a face representation scheme based on DCP named Multi-Directional Multi-Level Dual-Cross Patterns (MDML-DCPs) to explicitly handle the challenges encountered in unconstrained face recognition.

3.1 The MDML-DCPs Scheme

A major difficulty in unconstrained face recognition is that many factors produce significant intra-personal differences in the appearance of face images, in particular variations in illumination, image blur, occlusion, and pose and expression changes. We mitigate the influence of these factors using multi-directional gradient filtering and multi-level face representation.

In MDML-DCPs, the first derivative of Gaussian operator (FDG) is exploited to convert a gray-scale face image

into multi-directional gradient images that are more robust to variations in illumination. The FDG gradient filter of orientation θ can be expressed as follows:

$$FDG(\theta) = \frac{\partial G}{\partial \mathbf{n}} = \mathbf{n} \cdot \nabla G, \quad (7)$$

where $\mathbf{n} = (\cos\theta, \sin\theta)$ is the normal vector standing for the filtering direction and $G = \exp\left(-\frac{x^2+y^2}{\sigma^2}\right)$ is a two-dimensional Gaussian filter. The application of FDG is inspired by the classical work of Canny [36], which proved that FDG is the optimal gradient filter according to three criteria, namely signal-to-noise ratio (SNR) maximization, edge location accuracy preservation, and single response to single edge. These three criteria are also relevant for face recognition, where it is desirable to enhance the facial textural information while suppressing noise. FDG significantly saves computational cost compared to other gradient-like filters, such as Gabor wavelets [8]. We denote the concatenation of DCP descriptors extracted from the FDG-filtered images as MD-DCPs.

To build pose-robust face representation, MDML-DCPs normalizes the face image by two geometric rectifications based on a similarity transformation and an affine transformation, respectively. The similarity transformation retains the original information of facial contours and facial components and their configuration. The affine transformation reduces differences in intra-personal appearance caused by pose variation.

MDML-DCPs combines both holistic-level and component-level features, which are computed on the normalized images by the two transformations. Holistic-level features capture comprehensive information on both facial components and facial contour. However, it is also sensitive to changes in appearance of each component caused by occlusion, pose, and variations in expression. In contrast, component-level features focus on the description of a single facial component, and thus are independent of changes in appearance of the other components. In this way the information generated by these two feature levels is complementary and appropriate fusion of the two promotes robustness

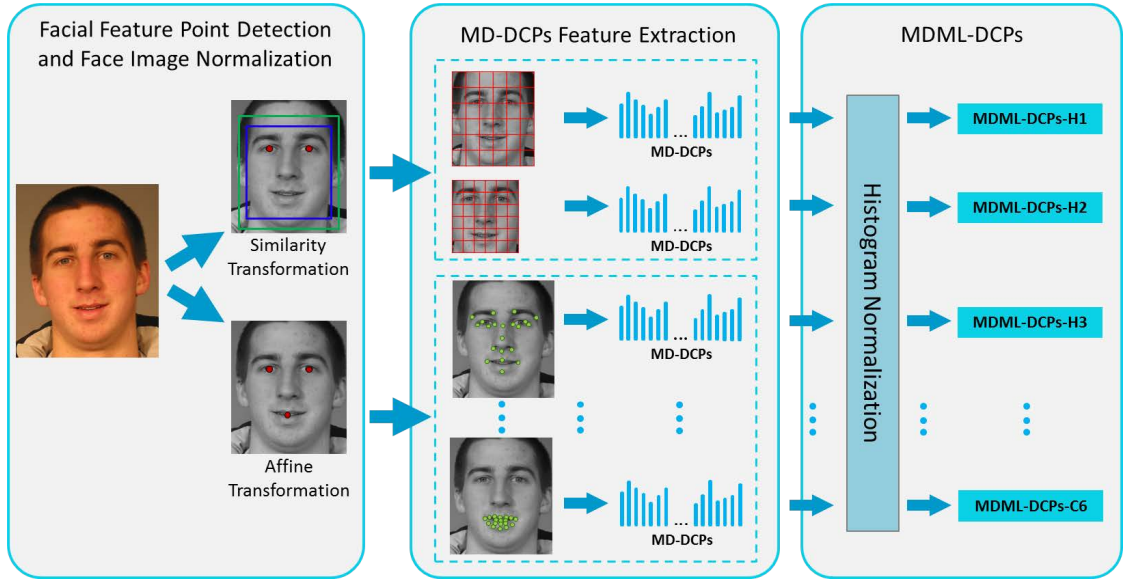


Fig. 3. Framework of the MDML-DCPs face representation scheme. The original face image is normalized by a similarity transformation and an affine transformation. MDML-DCPs-H1 and MDML-DCPs-H2 are extracted from the rectified image by the similarity transformation. MDML-DCPs-H3, MDML-DCPs-C1 to C6 are extracted from the affine-transformed image. The MDML-DCPs face representation is the set of the above nine feature vectors.

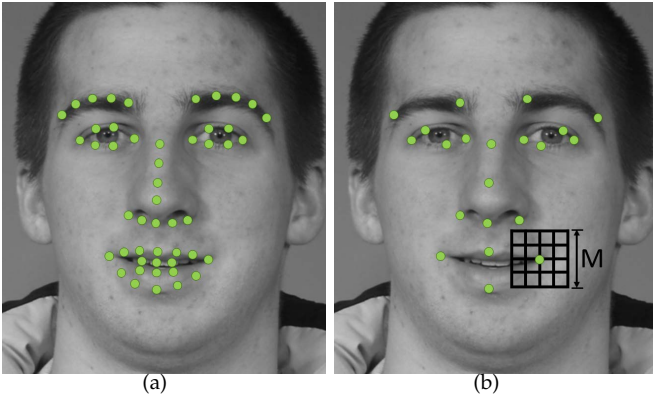


Fig. 4. (a) The 49 facial feature points detected by the face alignment algorithm. (b) MDML-DCPs-H3 employs 21 facial feature points over all facial components. MDML-DCPs-C1 to C6 respectively select 10 facial feature points on both eyebrows, 12 points on both eyes, 11 points on the left eye and left eyebrow, 11 points on the right eye and right eyebrow, 9 points on nose, and 18 points on mouth. Around each facial feature point, MD-DCPs are extracted from $J \times J$ (in this figure, $J = 4$) non-overlapping regions within the patch of size $M \times M$ pixels.

to interference.

3.2 Implementation Details

Similar to most state-of-the-art face representation schemes, e.g., [26], [28], [29], [37], [38], MDML-DCPs also benefits from recent progress in face alignment algorithms [24], [25] that accurately locate dense facial feature points in real-time. The MDML-DCPs face

representation scheme is shown in Fig. 3. In MDML-DCPs, a high performance face alignment algorithm based on [24] is first employed to locate 49 facial feature points (as shown in Fig. 4a), before applying the two geometric rectifications.

The similarity transformation is based on the two detected eye centers. In the rectified image, we compute MD-DCPs at two holistic levels: 1) MD-DCPs of non-overlapping regions of the external cropped face image (including facial contour), and 2) MD-DCPs of non-overlapping regions of the internal cropped face image (without facial contour). The first feature encodes both facial contour and facial components while the second feature focuses on encoding facial components only, which are free from background interference. For clarity, we denote the two features as MDML-DCPs-H1 and MDML-DCPs-H2.

The affine transformation is determined by the three detected facial feature points: the centers of the two eyes and the center of the mouth. In the rectified image, one holistic-level feature denoted as MDML-DCPs-H3, and six component-level features referred to MDML-DCPs-C1 to MDML-DCPs-C6, are computed based on the detected dense facial feature points. As shown in Fig. 4b, the method for feature extraction around each facial feature point is similar to the approaches used in [28], [39]: centered on each facial feature point, a patch of size $M \times M$ pixels is located and further divided into $J \times J$ non-overlapping regions. The concatenated MD-DCPs feature of the J^2 regions forms the description of the feature point.

MDML-DCPs-H3 and MDML-DCPs-C1 to C6 are formed by respectively concatenating the descriptions

of different facial feature points. As shown in Fig. 4, MDML-DCPs-H3 selects 21 facial feature points over all facial components, while MDML-DCPs-C1 to C6 select feature points on only one particular facial component. Elements of the three holistic-level features and six component-level features are normalized by the square root. Together, the set of the nine normalized feature vectors form the MDML-DCPs face representation.

4 FACE RECOGNITION ALGORITHM

In this section, the face matching problem is addressed using the proposed MDML-DCPs face representation scheme. First, one classifier is built for each of the nine feature vectors. Then, the similarity scores computed by the nine classifiers are fused by linear SVM or simple averaging.

Two algorithms are considered: Whiten Principal Component Analysis (WPCA; an unsupervised learning algorithm) and Probabilistic Linear Discriminant Analysis (PLDA; a supervised learning algorithm) [40], [41]. The choice of which of the two algorithms to use is dataset dependent: for datasets that have a training set with multiple face images for each subject, we choose PLDA; otherwise, WPCA is used.

4.1 WPCA

Principal Component Analysis (PCA) learns an orthogonal projection matrix U from training data and projects high-dimensional feature vector x to the low-dimensional vector y ,

$$y = U^T x. \quad (8)$$

The columns of U are composed of the leading eigenvectors of the covariance matrix of the training data. However, the first few eigenvectors in U encode mostly variations in illumination and expression, rather than information that discriminates identity. The whitening transformation tackles this problem by normalizing the contribution of each principal component

$$y = \left(U \Lambda^{-1/2} \right)^T x, \quad (9)$$

where $\Lambda = \text{diag} \{ \lambda_1, \lambda_2, \dots \}$ with λ_i being the i th leading eigenvalue. After projecting the facial feature vectors to the low-dimensional subspace using WPCA, the similarity score between two feature vectors y_1 and y_2 is measured by the cosine metric

$$\text{Sim}(y_1, y_2) = \frac{y_1^T y_2}{\|y_1\| \|y_2\|}. \quad (10)$$

4.2 PCA combined with PLDA

The feature vectors in MDML-DCPs are high-dimensional. To effectively apply PLDA, the dimensionality of the nine feature vectors is first reduced by PCA.



Fig. 6. Sample images from LFW. Images in the two rows are aligned by a similarity transformation and an affine transformation, respectively.

PLDA models the face data generation process

$$x_{ij} = \mu + Fh_i + Gw_{ij} + \varepsilon_{ij}, \quad (11)$$

where x_{ij} denotes the j th face data of the i th individual. μ is the mean of all face data. F and G are factor matrices whose columns are the basis vectors of the between-individual subspace and the within-individual subspace, respectively. h_i is the latent identity variable that is constant for all images of the i th subject. w_{ij} and ε_{ij} are noise terms explaining intra-personal variance.

It is shown in [40] that the identification and verification problems can be solved by computing the log-likelihood that two observed images share the same identity variable h ; that is, the probability that the images belong to the same subject. In this paper, we refer to the log-likelihood value as similarity score for consistency with the case of the WPCA classifier.

5 EXPERIMENTS

In this section, the proposed DCP and MDML-DCPs are extensively evaluated in both controlled and uncontrolled environments for both face identification and face verification tasks. To ensure reproducibility and fair comparison with existing methods, all experiments in this section are conducted on four publicly available large-scale face databases: FERET, CAS-PEAL-R1, FRGC 2.0, and LFW. Example images of the four databases are shown in Figs. 5 and 6.

The FERET [31] database is designed to evaluate the performance of face identification algorithms under controlled conditions. FERET frontal images are divided into one gallery set Fa (1,196 images of 1,196 subjects) and four probe sets, i.e., Fb (1,195 images with different facial expressions), Fc (194 images captured under different illumination conditions), Dup1 (722 images captured a week later), and Dup2 (234 images captured a year later). In this paper, the standard evaluation protocol specified in [31] is employed and the rank-1 identification rates on the four probe sets are reported.

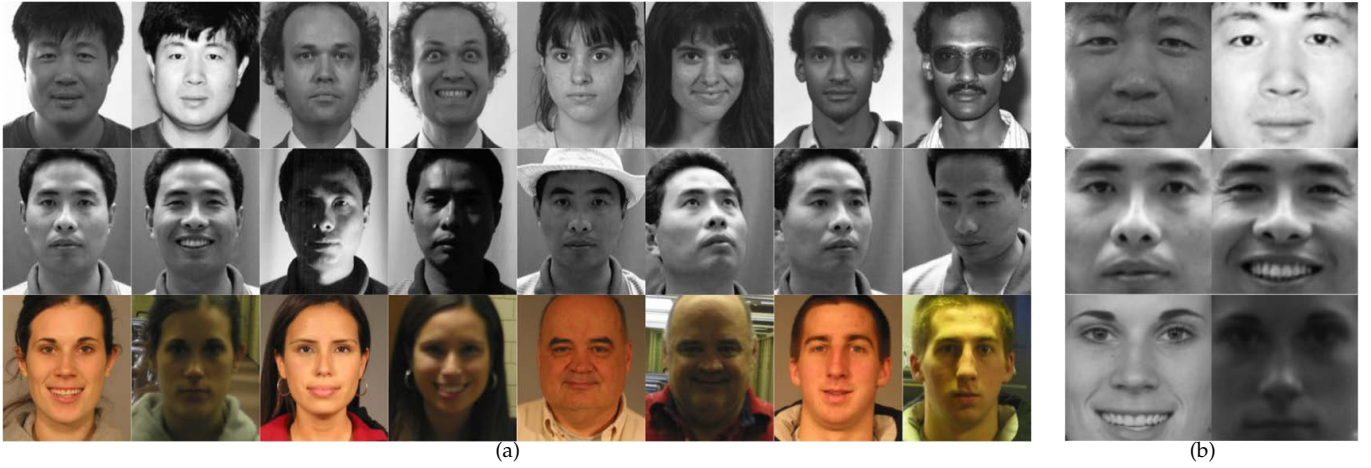


Fig. 5. (a) Sample images from FERET (first row), CAS-PEAL-R1 (second row) and FRGC 2.0 (third row) containing representative variations in each database. (b) Samples of normalized images for experiments from Section 5.1 to 5.4.

The CAS-PEAL-R1 [32] database is built under systematically controlled laboratory conditions, and allows researchers to test the robustness of their algorithms to particular sources of variation. Images in CAS-PEAL-R1 are divided into one training set (1,200 frontal images of 300 subjects), one gallery set (1,040 images of the 1,040 subjects), and nine probe sets. Each of the nine probe sets is restricted to one main variation. In detail, the first six probe sets PE, PA, PL, PT, PB, and PS correspond to variations in expression, accessory, lighting, time, background, and distance of frontal face images, respectively. The remaining three probe sets PU, PM, and PD correspond to one type of pose variation. In this work, the rank-1 face identification rates on the nine probe sets are reported according to the face identification protocol defined in [32].

The FRGC 2.0 [33] database is constructed to evaluate the performance of face verification algorithms in both controlled and uncontrolled environments. Images in FRGC 2.0 are partitioned into a training set and a test set. The training set is composed of 12,776 images from 222 subjects, with one half controlled still images and the other half uncontrolled still images. The test set is made up of 24,042 images of 466 subjects, with 16,028 controlled still images and 8,014 uncontrolled still images. Six experiments are defined in [33]; here we focus on Experiments 1 and 4. The shared target set of Experiments 1 and 4 are collected from frontal facial images taken under controlled illumination, while images in their query sets are captured under controlled and uncontrolled conditions, respectively. For each of the experiments, a large similarity matrix containing similarity scores of each pair of target and query images is generated. Three ROC curves of verification rate (True Acceptance Rate) versus False Acceptance Rate (FAR) are plotted according to the similarity matrix, wherein ROC I, ROC II, and ROC III correspond to image pairs within a semester, within a year, and between semesters, respec-

tively. Verification rates at 0.1% FAR are also reported.

The LFW [30] database is created for research on unconstrained face verification. It contains 13,233 images of 5,749 subjects that feature dramatic intrapersonal variations of pose, illumination, and expression. These images are organized into two “Views”. View 1 is for model selection and parameter tuning while View 2 is for performance reporting. The images in View 2 are divided into ten distinct subsets. Algorithms are evaluated based on a 10-fold cross-validation scheme, where for each cross-validation, 9 subsets are combined to form a training set while the remaining subset is used for testing. Two paradigms are used to exploit the combined training set, an image-restricted paradigm and an image-unrestricted paradigm. In the first paradigm, only inter-personal and intra-personal image pairs defined by the database are available for training, and the experimenters are not allowed to utilize the identity information of the training images. In the second paradigm, the identity information of the training images can be used. Following the evaluation protocol described in [30], we report the mean accuracy and standard error of the mean and also present the ROC curve averaged over the 10-fold cross validations of the View 2 data.

Five experiments are conducted on the above databases for the evaluation of DCP and MDML-DCPs. First, the dual-cross grouping mode adopted by DCP is empirically proved to achieve the maximum joint Shannon entropy among all grouping modes. Second, the influence of the free parameters of DCP on its performance is evaluated. Third, the performance of DCP is compared with eight state-of-the-art face image descriptors. Fourth, the performance of MD-DCPs is evaluated to determine the contribution of multi-directional filtering by FDG. Finally, the power of the MDML-DCPs face representation scheme is presented.

In the first four experiments, we focus on the evaluation of face image descriptors. In these four experiments,

all face images are cropped and resized to 128×128 (*rows* \times *columns*) pixels with the eye centers located at (34, 31) and (34, 98). For LFW, we use the aligned version (LFW-A) [11], while for the other three databases, images are cropped according to the eye coordinates provided by the databases. As shown in Fig. 5b, facial contours are cropped to avoid interference from the background. The cropped images are photometrically normalized using a simple operator (denoted as TT) developed by Tan & Triggs [10] and then encoded by one face image descriptor. Each encoded face image is divided into $N \times N$ non-overlapping regions. Concatenating the code histograms of these regions forms the face representation for the face image.

In the fifth experiment, we aim to demonstrate that the proposed MDML-DCPs face representation scheme has excellent performance characteristics. In this experiment, all face images are normalized by two geometric transformations, a similarity transformation and an affine transformation, as illustrated in Fig. 6. In both transformations, face images are resampled to 180×162 pixels with the eye centers mapped to (66, 59) and (66, 103). For the affine-transformed face images, the centers of the mouths are unified to (116, 81). Similar to the first three experiments, TT is applied to the resampled images for photometric normalization.

5.1 Empirical Justification for Dual-Cross Grouping

Section 2.3 intuitively suggests that the dual-cross grouping mode is optimal from the perspective of the joint Shannon entropy maximization. In this experiment, we empirically validate this point on the FERET database. For each of the 35 possible grouping modes, DCP_i ($0 \leq i \leq 7$) are divided into two subsets. Then, the joint Shannon entropy for each of the two subsets are calculated on one image using (3) and are summed together. The above process is repeated on the 1,196 gallery images of the FERET database. The mean of the summed joint Shannon entropy over the 1,196 images is recorded.

Experimental results show that dual-cross grouping mode achieves the highest joint Shannon entropy among all 35 grouping modes. Fig. 8 characterizes the joint Shannon entropy as a function of R_{in} and R_{ex} and illustrate the superiority of dual-cross grouping mode by comparing it with two representative grouping modes, exemplified in Fig. 7. Note that the joint Shannon entropy is related to the sampling radii of DCP: smaller sampling radii mean stronger dependence among the sampled points, which results in a smaller joint Shannon entropy. The dual-cross grouping mode achieves the highest entropy under all sets of the radii values. Therefore, the dual-cross grouping mode is empirically optimal.

5.2 Parameter Selection of DCP

In this experiment, the influence of the DCP parameters on performance are evaluated using the FERET database.

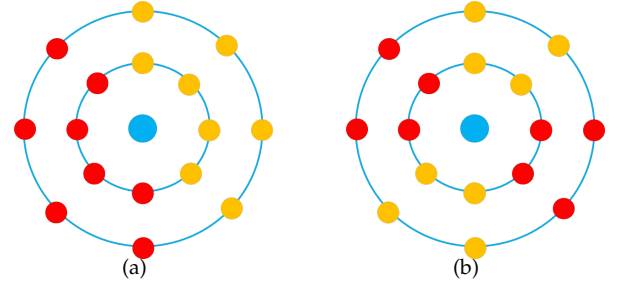


Fig. 7. Another two representative grouping modes for the eight sampling directions of DCP. Sampled points of the same colour belong to the same subset.

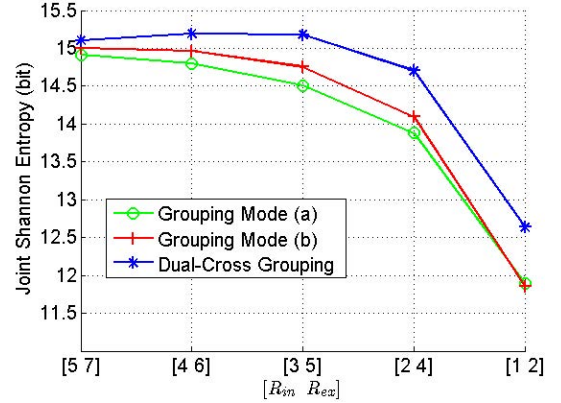


Fig. 8. Joint Shannon entropy as a function of R_{in} and R_{ex} . Three grouping modes are evaluated in this figure: modes (a) and (b) in Fig. 7 and the dual-cross grouping.

There are only two parameters for DCP, the radii R_{in} and R_{ex} (with different values of R_{in} and R_{ex} capturing information on different scales) and the region number N . A larger value of N helps to preserve spatial information but makes the descriptor more sensitive to misalignment errors. LBP is also evaluated in this experiment for comparison with a sampled points number of eight and exploiting all 256 LBP codes.

The mean rank-1 identification rates against N for the four FERET probe sets using DCP and LBP are plotted in Fig. 9. Optimal performance of DCP is achieved when $N = 9$, $R_{in} = 4$ and $R_{ex} = 6$. DCP consistently achieves better performance than LBP with all sets of parameters. In particular, DCP outperforms LBP by 10% to 30% when $N \leq 2$, which suggests that DCP has better discriminative power.

The chi-squared metric has been used to measure the similarity of two face images, but it is noted that DCP works equally well when assessed using the histogram intersection metric. The mean identification rates using DCP measured with the chi-squared and histogram intersection metrics are 92.80% and 92.66%, respectively.

5.3 Evaluation of the Performance of DCP

In this section the performance of DCP for both face identification and face verification tasks are evaluated.

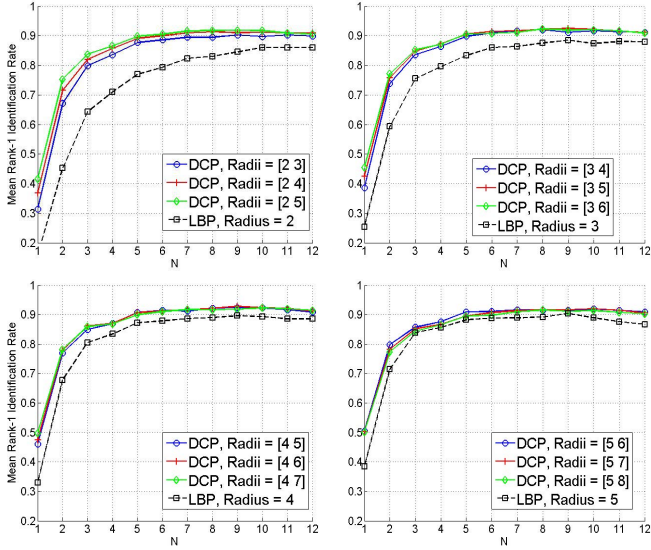


Fig. 9. The mean rank-1 identification rates of DCP and LBP on four FERET probe sets as a function of N .

To better illustrate the advantages of DCP, the performance of DCP-1, DCP-2, and eight state-of-the-art face image descriptors, (LBP [6], LTP [10], LPQ [16], POEM [17], Local Gabor XOR Patterns (LGXP) [8], LQP [42], DFD [19], and CHG [35]) are also presented. Note that CHG is a hybrid descriptor of CCS-POP, Histogram of Oriented Gradients (HOG), and Gabor wavelets.

The first five state-of-the-art descriptors are hand-crafted and they are easy to implement. We therefore test them together with DCP. It is worth noting that the cropped face image data for these descriptors are exactly the same. All of them extract features from photometrically normalized images by TT. The parameters for each of the descriptors are carefully tuned and different distance metrics (chi-squared or histogram intersection) are tested. Finally, the best results for each descriptor are reported. Therefore, the experimental results directly compare the recognition capabilities of the descriptors.

On the other hand, LQP, DFD, and CHG are learning-based descriptors, which are complicated to implement. In this paper, their performance on FERET and LFW is directly cited from the original papers, even though the experimental settings are different from that of DCP. For LQP, we cite its performance with the image filtering step by Gabor wavelets, which is more robust to illumination variation.

Before presenting the detailed experimental results, the feature size (number of histogram bins) for each descriptor except CHG (CHG is not a histogram-based descriptor) is listed in Table 1. In the following experiments, LBP-based descriptors are implemented without using uniform coding [43] (using uniform coding actually degrades the performance of LBP, LTP, and POEM), which means that all 256 codes for LBP are utilized. For POEM, we compute LBP codes on four-orientation gradient magnitude maps, so its feature size is 1024 in

TABLE 1
Feature Size of the Investigated Face Image Descriptors

	Feature Size		Feature Size
LBP* [6]	256	LQP [42]	300
LTP* [10]	512	DFD [19]	1024
LPQ [16]	256	DCP-1	256
POEM* [17]	1024	DCP-2	256
LGXP [8]	640	DCP	512

*Note: All 256 LBP codes are employed for LBP-based descriptors.

this paper.

5.3.1 Face Identification: FERET

Face identification experiments are conducted on the FERET and CAS-PEAL-R1 databases. The rank-1 identification rates on the four probe sets of FERET are presented in Table 2. We make four observations:

- 1) In general, the performance of all the descriptors is good on images photometrically normalized by the simple operator TT. While high performance is achieved by all descriptors on the well controlled Fb and Fc probe sets, DCP still outperforms LBP by over 1%. In particular, DCP achieves a perfect identification rate on the Fc set.
- 2) There is a substantial performance drop for all descriptors on the Dup1 and Dup2 probe sets, whose images contain moderate expression and illumination variations. However, DCP performs significantly better than other descriptors on both sets, indicating that it is more robust to expression and illumination variations. The performance of LGXP ranks second on Dup1 and Dup2, but at the cost of 80 expensive convolutions and a larger feature size.
- 3) Both DCP-1 and DCP-2 perform better than most of the other descriptors and at lower computational cost. Their time and memory costs are exactly the same as those of LBP, suggesting that the sampling and encoding strategies of DCP are highly effective.
- 4) As expected, the performance of DCP is better than both DCP-1 and DCP-2, which means that DCP-1 and DCP-2 contain complementary information. When DCP-1 and DCP-2 are combined, the mean identification rate increases by over 1%.

5.3.2 Face Identification: CAS-PEAL-R1

Identification results on the six frontal probe sets of CAS-PEAL-R1 are shown in Table 3 and on the three non-frontal probe sets in Table 4. For each descriptor, results are reported with the set of parameters that achieves the highest mean identification rate over all nine probe sets. We make the following three observations:

- 1) In general, the performance of all the descriptors is good on the PE, PA, PT, PB, and PS probe sets, with DCP producing the highest mean identification

TABLE 2

Identification Rates for Different Face Image Descriptors on the Probe Sets Fb, Fc, Dup1, and Dup2 of FERET

	Fb	Fc	Dup1	Dup2	Mean
LBP	96.90	98.45	83.93	82.48	90.44
LTP	96.90	98.97	83.93	83.76	90.89
LPQ	97.41	99.48	82.69	81.62	90.30
POEM	98.24	99.48	82.83	82.05	90.65
LGXP	97.32	99.48	85.46	85.47	91.93
LQP-Flip*	99.50	99.50	81.20	79.90	90.03
DFD*	99.20	98.50	85.00	82.90	91.40
CHG*	97.50	98.50	85.60	84.60	91.55
DCP-1	97.91	98.45	84.49	84.19	91.26
DCP-2	97.99	99.48	84.35	85.04	91.72
DCP	98.16	100.0	86.29	86.75	92.80

*Note that the results are cited from the original papers. A suffix ‘-Flip’ means that the descriptor adopts the ‘flip’ trick [42].

TABLE 3

Identification Rates for Different Face Image Descriptors on the Frontal Probe Sets of PEAL

	PE	PA	PL	PT	PB	PS	Mean
LBP	94.27	91.82	46.90	100.0	99.46	99.64	88.68
LTP	94.39	91.77	47.17	100.0	99.46	99.64	88.74
LPQ	93.95	92.39	57.16	100.0	99.28	99.27	90.34
POEM	95.54	92.39	54.66	100.0	99.46	99.64	90.28
LGXP	94.97	91.33	63.26	100.0	99.28	99.64	91.41
DCP-1	95.99	92.60	46.37	100.0	98.73	99.27	88.83
DCP-2	95.54	91.90	43.91	100.0	98.92	99.64	88.32
DCP	96.11	92.82	50.25	100.0	99.10	99.64	89.65

rate and POEM the second highest. The performance of all descriptors is poor on the remaining PL, PU, PM, and PD probe sets due to serious illumination and pose variations.

- 2) DCP outperforms LBP and LTP by 3.35% and 3.08% on the PL set, respectively. However, the performance of DCP is lower than LPQ, POEM, and LGXP; careful examination of the PL images reveals that these images contain not only rich illumination variation, but also serious image blur, which explains the superior performance of the blur-invariant descriptor LPQ. LGXP and POEM benefit from image filtering steps that turn the gray-scale image into gradient images. We show in Section 5.4 that by introducing multi-directional gradient filtering by FDG, the performance of DCP is significantly improved.
- 3) DCP exhibits excellent robustness to pose variations on the PU, PM, and PD probe sets, with superior mean recognition rate by as much as 4.55%. This result is encouraging, since pose variation is a major challenge in unconstrained face recognition.

TABLE 4

Identification Rates for Different Face Image Descriptors on the Non-frontal Probe Sets of PEAL

	PU	PM	PD	Mean
LBP	60.32	83.66	44.60	62.86
LTP	61.32	84.46	44.68	63.49
LPQ	57.78	86.46	44.76	63.00
POEM	58.14	85.12	42.52	61.93
LGXP	39.46	66.83	22.91	43.07
DCP-1	60.68	85.74	48.14	64.85
DCP-2	60.64	83.08	43.62	62.45
DCP	65.39	87.44	51.30	68.04

TABLE 5

Verification Rates at 0.1% FAR for Different Face Image Descriptors on the FRGC 2.0 Experiment 1

	ROC I	ROC II	ROC III
LBP	89.93	87.53	84.83
LTP	90.98	88.63	86.07
LPQ	89.96	87.38	84.48
POEM	90.60	88.26	85.63
LGXP	91.89	88.80	85.33
DCP-1	91.40	89.14	86.65
DCP-2	92.73	90.56	88.16
DCP	93.09	91.11	88.93

5.3.3 Face Verification: FRGC 2.0

Face verification experiments are conducted on the FRGC 2.0 and LFW databases. Verification rates at 0.1% FAR on Experiments 1 and 4 of FRGC 2.0 are listed in Tables 5 and 6, respectively. As mentioned above, the query sets of the two experiments are composed of controlled and uncontrolled images, respectively. The query images in Experiment 4 are degraded by serious image blur and significant illumination variation, making this dataset very challenging. We make the following observations:

- 1) In Experiment 1, DCP shows the best performance. Both DCP-1 and DCP-2 achieve better performance than existing descriptors. These observations are consistent with the experimental results on FERET.
- 2) In Experiment 4, the mean verification rate of DCP is higher than LBP and LTP by 3.35% and 1.09%, respectively. Due to the lack of an image filtering step in DCP, its performance is lower than that of LGXP and POEM. This result is consistent with that seen for the PL set of CAS-PEAL-R1, whose images also feature serious illumination variation and image blur.

5.3.4 Face Verification: LFW

As mentioned above, LFW is a very challenging dataset since its images contain large pose, expression, and illumination variations. Experiments in this section follow the image-restricted paradigm. For each descriptor, its

TABLE 6

Verification Rates at 0.1% FAR for Different Face Image Descriptors on the FRGC 2.0 Experiment 4

	ROC I	ROC II	ROC III
LBP	18.62	19.12	20.07
LTP	20.21	21.39	22.99
LPQ	22.53	23.25	24.39
POEM	29.99	30.60	31.46
LGXP	32.44	31.81	31.13
DCP-1	20.10	20.57	21.51
DCP-2	18.22	18.74	19.58
DCP	21.78	22.49	23.59

parameters are tuned on the View 1 data, and performance on the View 2 data is reported in Table 7. We observe that:

- 1) Among the manually-designed descriptors, DCP achieves the best performance while DCP-1 ranks second. This result is consistent with the results on FERET and Experiment 1 on FRGC 2.0, whose illumination variations are moderate. The robustness of DCP to pose variations is consistent with the results from experimentation on the CAS-PEAL-R1 database.
- 2) LGXP does not perform well on LFW because LFW images contain significant pose variations. Although LGXP is robust to serious illumination variations, it is sensitive to pose variations, consistent with the results seen from experimentation on the three challenging non-frontal probe sets PU, PM, and PD of CAS-PEAL-R1.
- 3) Compared with the two learning-based descriptors, the performance of DCP is better than that of LQP, but is worse than that of DFD. However, DCP has clear advantage in both time and memory costs. In particular, the feature size of DFD is twice as large as DCP. What is more, both the image filtering and local sampling steps of DFD adopt supervised learning algorithms to enhance the discriminative power of the descriptor, while DCP is independent of any learning algorithms. We show in Section 5.5 that by applying supervised learning algorithms to the extracted DCP feature, superior performance can be achieved.

5.4 The Contribution of Multi-directional Filtering

In Section 5.3, DCP is shown to have strong discriminative power and excellent robustness to expression, pose, and moderate illumination variations. It has also been shown that when there is serious illumination variation and image blur, the performance of DCP is degraded due to the lack of an image filtering step. In this section, we show that MD-DCPs that extracts the DCP feature on FDG-filtered images is robust to illumination variation. The contributions of FDG are two-fold: first, it converts

TABLE 7

Mean Accuracy and the Standard Error of the Mean on the LFW View 2 Data

	Accuracy($\pm S_E$)		Accuracy($\pm S_E$)
LBP	72.43 ± 0.49	DFD-Flip*	80.02 ± 0.50
LTP	72.65 ± 0.52	DCP-1	74.50 ± 0.48
LPQ	72.68 ± 0.46	DCP-2	73.28 ± 0.48
POEM	73.98 ± 0.56	DCP	75.00 ± 0.64
LGXP	70.58 ± 0.43	DCP-Flip	76.37 ± 0.71
LQP-Flip*	75.30 ± 0.26		

*Note that the results are cited from the original papers. A suffix ‘Flip’ means that the descriptor adopts the ‘flip’ trick [42].

TABLE 8

Verification Rates at 0.1% FAR for DCP and MD-DCPs on the FRGC 2.0 Experiment 4

	ROC I	ROC II	ROC III
DCP	21.78	22.49	23.59
MD-DCPs	29.68	30.61	31.93

the gray-scale face image into gradient images, which are more robust to illumination variation, and second, FDG is proven to achieve high SNR [36], which is vital for the performance of face image descriptors for low quality images.

Throughout this paper, the number of filtering orientations by FDG is fixed to 4 ($\theta = 0, \pi/4, \pi/2$, and $3\pi/4$) and the parameter σ of the Gaussian kernel is set at 1.0. Experiments in this section are conducted on three challenging datasets:

- A new FERET probe set is constructed by collecting the 146 most challenging FERET probe images. The original FERET Fa set is still utilized as the gallery set. The identification rate of DCP on this probe set is only 17.12%. In contrast, the identification rate when MD-DCPs is used increases to 33.56%.
- For the PL probe set of CAS-PEAL-R1, the identification rates of DCP and MD-DCPs are 50.25% and 65.23%, respectively. When considered along with the results shown in Table 3, it is clear that the performance of MD-DCPs is superior to that of LPQ, POEM, and LGXP on this dataset.
- For the face verification task on FRGC 2.0 Experiment 4, the verification rates of DCP and MD-DCPs at 0.1% FAR are listed in Table 8. Together with the results in Table 6, it is shown that the performance of MD-DCPs is better than LPQ and POEM. LGXP performs better than MD-DCPs, but at the cost of 80 expensive convolution operations.

In conclusion, MD-DCPs consistently achieves excellent performance, which means that multi-directional filtering by FDG is indeed helpful for removing illumination variation and enhancing the robustness of face image descriptors on low SNR images.

5.5 Performance Evaluation of MDML-DCPs

Before presenting the experimental results of MDML-DCPs, we first unify most of its parameters for testing the four databases. For the holistic-level feature MDML-DCPs-H1, we compute it within the area whose top left corner is located at (33, 27), while the bottom right corner is located at (154, 136) in the normalized image by similarity transformation. The holistic-level feature MDML-DCPs-H2 is computed within the area where the two corners are located at (36, 41) and (140, 122), respectively. Both areas are divided into 9×9 non-overlapping regions. For MDML-DCPs-H3 and MDML-DCPs-C1 to C6, we consistently use a patch size $M \times M$ of 40×40 and the number of regions $J \times J$ within the patch to be 4×4 .

The two parameters σ_1 and σ_2 for TT are set to 1.4 and 2.0 on FERET, CAS-PEAL-R1, and FGRC 2.0. Since TT in fact slightly degrades the performance of MDML-DCPs on the LFW View 1 data, the photometric normalization step is omitted for the experiment on LFW. The subspace dimensions of WPCA and PCA for all nine features are set to 600. The subspace dimension of PLDA is set to 100.

There are only two remaining sets of parameters to tune over the four databases: the first is the sampling radii R_{in} and R_{ex} of DCP, and the other is the cost parameter c of the linear SVM [44]. The optimal values of R_{in} and R_{ex} for FERET, CAS-PEAL-R1, and FGRC 2.0 are $R_{in} = 2$ and $R_{ex} = 3$. The cost parameter c is set at 10^{-4} for FGRC 2.0. For LFW, R_{in} , R_{ex} , and c are set to 4, 6, and 1.0, respectively, based on the results on the View 1 data.

5.5.1 Face Identification: FERET

Since there is no officially defined training set for FERET, we only report the performance of MDML-DCPs with the WPCA-based classifiers. The nine WPCA projection matrices are trained on the 1,196 FERET gallery images. For simplicity, the similarity scores computed by the nine classifiers are fused by averaging with equal weights. A better method for fusing the similarity scores using weighting can be found in [45].

The performance of MDML-DCPs on FERET, compared with the state-of-the-art approaches, is shown in Table 9. The first three approaches use supervised learning algorithms such as Linear Discriminant Analysis (LDA). All the other approaches utilize the unsupervised learning algorithm WPCA. The performance achieved by MDML-DCPs is superior even to those that employ a supervised learning algorithm. In particular, MDML-DCPs achieves the best results on the Fc, Dup1, and Dup2 probe sets. On the Fb set, three images are misclassified by MDML-DCPs, two of which are due to the mislabeling of subjects in the database itself.

5.5.2 Face Identification: CAS-PEAL-R1

For experiments on CAS-PEAL-R1, we present MDML-DCPs results with both WPCA and PLDA, with DCP set

TABLE 9
Identification Rates for Different Methods on FERET

	Fb	Fc	Dup1	Dup2
AMFG07' (L,G) + KDCV [46]	98.00	98.00	90.00	85.00
ICCV09' MLPQ + LDA [47]	99.20	100.0	92.00	88.00
TIP10' LGBP + LGXP + LDA [8]	99.00	99.00	94.00	93.00
BMVC12' G-LQP + WPCA [42]	99.90	100.0	93.20	91.00
PAMI13' DFD + WPCA [34]	99.40	100.0	91.80	92.30
MDML-DCPs + WPCA	99.75	100.0	96.12	95.73

as the baseline (with chi-squared metric: $DCP + \chi^2$). Both WPCA and PLDA are trained on all 1,200 training images. In both approaches, the similarity scores are fused by simple averaging without weighting. A comparison of the performance of MDML-DCPs with other state-of-the-art methods is presented in Table 10. We make the following observations:

- 1) "MDML-DCPs + WPCA" achieves the best performance for eight of the nine probe sets of CAS-PEAL-R1. In particular, it outperforms DCP by 32.67% on the challenging PL probe set.
- 2) Compared with the performance of DCP, there is only minor performance improvement made by "MDML-DCPs + WPCA" on the PU and PD probe sets. The reason for this is that the training set contains only frontal images while the PU and PD images possess large pose variations. Therefore, the two probe sets benefit little from training.
- 3) The identification rates by "MDML-DCPs + PLDA" are lower than "MDML-DCPs + WPCA", which suggests that there might be a gap between the distribution of training and testing data. In particular, the discriminative subspace learnt by PLDA on the frontal images does not generalize to the three non-frontal probe sets. Therefore, the performance of "MDML-DCPs + PLDA" on the PU, PM, and PD probe sets are quite low.

5.5.3 Face Verification: FRGC 2.0

In this section, the performance of MDML-DCPs on Experiments 1 and 4 of the FRGC 2.0 database is discussed. As shown in Section 5.3.3, the query images in Experiment 4 contain serious illumination variation and image blur, making this an interesting dataset to investigate. The FRGC 2.0 database provides a large training set, on which PLDA and linear SVM are trained. For each subject in the training set, 12 images are randomly selected and there are 2,664 images in total for SVM training, for which 13,320 intra-personal images pairs and 13,320 inter-personal image pairs are generated according to the method described in [30]. All the remaining images are used to train the PLDA model.

The performance of the proposed algorithm, together with other state-of-the-art approaches, is shown in Table 11. We observe that:

- 1) The MDML-DCPs approach consistently achieves

TABLE 10
Identification Rates for Different Methods on the Nine Probe Sets of PEAL

	PE	PA	PL	PT	PB	PS	PU	PM	PD
TIP07' LGBPHS [15], [14]	95.20	86.80	51.00	100.0	98.70	98.90	-	-	-
TIP07' HGPP [14]	96.80	92.50	62.90	98.40	99.80	99.60	-	-	-
SP09' Weighted LLGP [48]	98.00	92.00	55.00	-	-	-	-	-	-
PAMI13' DFD + WPCA [34]	99.00	96.90	63.90	-	-	-	-	-	-
DCP + χ^2	96.11	92.82	50.25	100.0	99.10	99.64	65.39	87.44	51.30
MDML-DCPs + PLDA	98.22	97.51	63.26	100.0	100.0	100.0	34.31	70.24	33.59
MDML-DCPs + WPCA	99.62	99.21	82.92	100.0	99.82	100.0	68.29	98.10	53.92

TABLE 11
Verification Rates at 0.1% FAR for Different Methods on the FRGC 2.0 Experiment 1 and 4

		Experiment 1			Experiment 4		
		ROC I	ROC II	ROC III	ROC I	ROC II	ROC III
Single Descriptor	TIP09' Gabor + LDA [45]	-	-	97.00	-	-	83.00
	TIP10' Gabor + Kernel LDA [10]	-	-	-	-	-	80.00
	PAMI13' Multiscale LPQ (MLPQ) + Kernel fusion [9]	98.99	98.68	98.37	89.26	89.80	90.36
	PAMI13' Multiscale LBP (MLBP) + Kernel fusion [9]	98.79	98.50	98.21	86.77	87.54	88.21
	MDML-DCPs + PLDA + Score averaging	99.59	99.41	99.22	93.40	93.18	92.89
	MDML-DCPs + PLDA + Linear SVM	99.61	99.43	99.25	93.91	93.64	93.39
Multiple Descriptor	AMFG07' Gabor + LBP + KDCV [46]	-	-	-	-	-	83.60
	TIP09' Gabor + DCT + LDA [45]	-	-	98.00	-	-	89.00
	ICB09' Hybrid RCrQ with Gabor + MLBP + DCT [21]	-	-	-	-	-	92.43
	TIP10' Gabor + LBP + Kernel LDA [10]	-	-	-	-	-	88.10
	TIP10' LGBP + LGXP + Block-based LDA [8]	98.60	98.00	97.30	83.90	84.70	85.20
	TIP11' Hybrid Fourier feature + LDA [51]	96.38	95.11	93.90	81.82	81.50	81.14
	PAMI13' MLPQ + MLBP + Kernel fusion [9]	99.04	98.77	98.49	90.30	90.94	91.59

superior performance on both Experiment 1 and 4 with the single descriptor DCP. Score fusion by linear SVM also works slightly better than score averaging.

- 2) On Experiment 1, the performance of MDML-DCPs is nearly perfect. On Experiment 4, it outperforms the current state-of-the-art method [21] by 0.9%. Moreover, MDML-DCPs utilizes only a single face image descriptor, while the method in [21] relies on color information and makes use of three descriptors: LBP, Gabor, and Fourier features.

Different from the approaches in Table 11, it is shown in [49], [50] that by conducting normalization on the similarity matrices which contain similarity scores of each pair of target and query images, verification rates can be improved significantly. However, this operation may not be suitable for the general face verification problems, where only a pair of target and query images is available each time. Therefore, we provide results of MDML-DCPs without score normalization in this paper.

5.5.4 Face Verification: LFW

Experiments in this section follow the image-unrestricted paradigm of the LFW database. For face matching, we use the PLDA-based classifiers. Both linear SVM and score averaging are tested for the score fusion of the nine

classifiers. For each of the 10-fold cross validations on the View 2 data, the remaining nine subsets are partitioned into two: the first eight subsets of subjects with at least two images are used for PCA and PLDA training, while the last subset is used to train the linear SVM or learn the optimal threshold of similarity scores fused by averaging. According to the description in [30], 2,500 intra-personal image pairs and 2,500 inter-personal image pairs are generated using the images in the last subset. No outside training data are employed for the training of either PLDA or SVM. In addition, following [11], [40], the facial pose for each image is estimated by projecting the vector of the coordinates of facial feature points to the first principal component. All images with right profile faces are flipped to the left profile faces.

A comparison of the classification accuracies is presented in Table 12. All the methods in Table 12 follow the image-unrestricted training paradigm and do not use outside training data. To better compare the proposed algorithms with the state-of-the-art methods, ROC curves averaged over the 10-fold cross validations of the View 2 data are plotted in Fig. 10. Based on Table 12 and Fig. 10, we make the following observations:

- 1) MDML-DCPs outperforms the current state-of-the-art method [28] by about 2%. It is worth noting that the face representation in [28] is also based on

TABLE 12
Mean Accuracy and the Standard Error of the Mean (S_E)
on the LFW View 2 Data

	Accuracy(%) $\pm S_E$
PAMI12' Combined PLDA [40]	90.07 \pm 0.51
ECCV12' Combined Joint Bayesian [52]	90.90 \pm 1.48
ICCV13' VMRS [53]	92.05 \pm 0.45
BMVC13' Fisher vector faces [37]	93.03 \pm 1.05
CVPR13' high-dim LBP [28]	93.18 \pm 1.07
MDML-DCPs + PLDA + Score averaging	94.57 \pm 0.30
MDML-DCPs + PLDA + Linear SVM	95.13 \pm 0.33

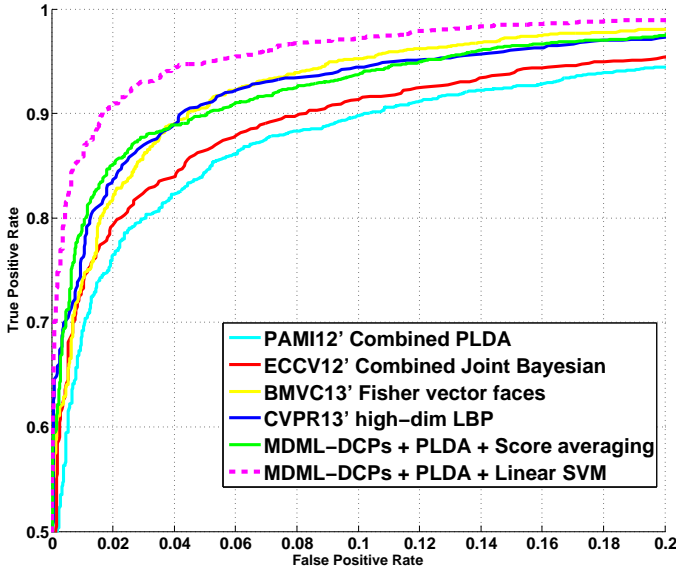


Fig. 10. ROC curves of the MDML-DCPs method and other state-of-the-art methods in the unrestricted paradigm.

dense facial feature points. MDML-DCPs outperforms [40], which also employs the PLDA-based classifier, by over 5%. The above facts suggest that the MDML-DCPs face representation scheme is more effective than previous approaches.

- 2) Score fusion by linear SVM results in better performance than using score averaging. Moreover, with either linear SVM or score averaging, MDML-DCPs is able to achieve better performance than existing methods, and using both fusion methods the standard error of classification accuracy is consistently smaller than the other approaches.

In summary, the proposed MDML-DCPs face representation scheme enhances the accuracy and robustness of face recognition. With MDML-DCPs, our algorithm achieves the best performance on the challenging LFW database under the image-unrestricted paradigm and without using outside training data.

6 CONCLUSION

Due to the degradation of face image quality and large variations of illumination, pose, and expression, the recognition of unconstrained face images remains a challenging task. Solving this problem demands work in at least two areas: development of an effective face image descriptor and a comprehensive face representation scheme. To achieve this goal, we presented a novel face image descriptor named Dual-Cross Patterns using the textural characteristics of human faces. Based on this descriptor, we build the MDML-DCPs face representation scheme and achieve superior results on four large-scale face databases: FERET, CAS-PEAL-R1, FRGC 2.0, and LFW.

The main contributions of this work are summarized as follows:

- 1) Inspired by the textural characteristics found in human faces, a simple but highly effective face image descriptor named Dual-Cross Patterns (DCP) is proposed. DCP samples and encodes along the most informative directions contained within a face image. It is computationally efficient at only double the cost of LBP. Extensive and systematic experimentation on four large-scale face databases shows that the proposed DCP face image descriptor has superior discriminative power and is robust to expression, pose, and moderate variations in illumination.
- 2) A comparison of DCP with other state-of-the-art face image descriptors is conducted on the four image databases. Detailed analysis is provided describing the performance of the face image descriptors. Conclusions about the advantages and disadvantages of the descriptors can be drawn from these results.
- 3) We employ the first derivative of Gaussian operator to conduct multi-directional filtering before extracting DCP features. This strategy turns the gray-scale image into more robust gradient images at low computational cost. It significantly improves the performance of DCP when encountering serious variations in illumination and image blur.
- 4) The proposed MDML-DCPs face representation scheme comprehensively incorporates both holistic-level DCP features and component-level DCP features. With MDML-DCPs, our algorithm consistently achieves the best results on the four image databases. In particular, exploiting the single descriptor DCP, MDML-DCPs improves the verification rate of ROC III in Experiment 4 of FRGC 2.0 to 93.39% and outperforms the state-of-the-art result on LFW by about 2%.

In summary, this paper tackles the problem of unconstrained face recognition by proposing an effective face image descriptor and constructing a comprehensive face representation scheme. Clear advantages in performance and efficiency are observed for the proposed DCP de-

scriptor for face identification and face verification tasks. With the proposed MDML-DCPs face representation scheme, consistently superior results are achieved on FERET, CAS-PEAL-R1, FRGC 2.0, and LFW. This work helps to expedite the design of useful and robust face image descriptors and face representation schemes.

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