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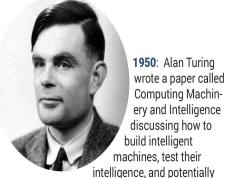
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Infographic: Al Timeline and Famous Applications

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make them indistinguishable from humans — proposing the famous Turing Test, which would become one of the measurements for Artificial Intelligence programs.

1961: Unimate is the first industrial robot to replace a human on an assembly line at a GM automobile

1950

1956: The Dartmouth
Summer Research
Project on Artificial
Intelligence is widely
thought to be the event
that founded Al as a
field at Dartmouth
College in Hanover, New
Hampshire, over eight weeks
with approximately 20 people in
attendance including Arthur Samuel, Oliver Selfridge,
Claude Shannon, Ray Solomonoff, Marvin Minsky,

John McCarthy, and Nathanial Rochester.

1960

1970

1980

1990

2000

manufacturing plant in New Jersey.



▶ The Unimate robot arm transported die casting and welded parts on cars at GM.

1970s through 1980s: Two "Al Winters" covered much of these two decades as government funding, technological gains, and interest in artificial intelligence fell off. Researchers and scientists still worked to improve programs and computing power (one of the things holding a lot of Al theory back) and eventually this work precipitated the growing tech of the 90s, which brought on the boom of the 2000s.

1998: KISMET, a robot head that recognized and mirrored human emotion developed by Dr. Cynthia Breazeal. It took programmers 2.5 years to develop and run the code for this project.





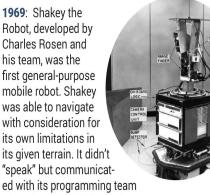
2000: Honda releases ASIMO, a humanoid robot made to move and react autonomously and serve as a mobility assistant. ASIMO became a bit of an ambassador for household robots by making appearances on television shows, the ringing the bell on



1965: ELIZA is a natural language program created by Joseph Weizenbaum to handle dialogue—the precursor to chatbots-specifically in the role of a Rogerian

psychotherapist, pairing and imitating possible responses.

1969: Shakey the Robot, developed by Charles Rosen and his team, was the first general-purpose mobile robot. Shakev was able to navigate with consideration for its own limitations in its given terrain. It didn't "speak" but communicatwith teletype and CRT display.



1997: New Al program development slowed at the start of the decade but finished strong with the introduction of IBM's Deep Blue Computer, which beat the world's reigning chess champion, Gary Kasparov.

IBM's Deep Blue chess-playing computer.



1999: Sony releases the AIBO (Artificial Intelligence RoBOt) a robotic dog made to learn by interacting with people and its environment. It could understand and respond to over a thousand voice commands and recognize its owner.



2002: iRobot releases the first version of the Roomba, a robot vacuum that travels around areas to clean



the New York Stock Exchange, going on a world tour and meeting heads of state, and conducting the Detroit Symphony Orchestra.

2010



while avoiding obstacles and

returning itself to its charging station when done, bringing autonomous robot into daily households.



2011: IBM's supercomputer, Watson, can understand natural language and was able to best the top two Jeopardy Contes-

tants in the world, Ken Jennings and Brad Rutter, in a televised game.



2011: Apple's Siri debuts, bringing in the age of personal virtual assistantsin our pockets.



▶ The ImageNet project crowd-sourced images to create gigantic data sets.

2010: Researchers like Dr. Fei Fei Li worked to expand data sets, train models, and create neural networks as part of the ImageNet project that have become the basis for the image recognition apps that exist today.



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