

# Modal Crash Types for Intermittent Computing

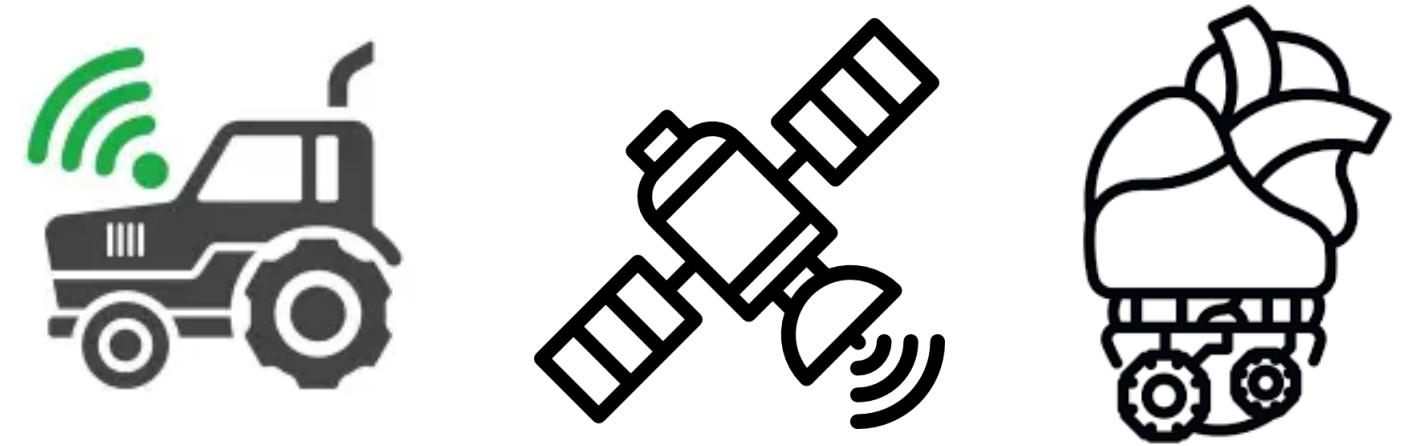
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**PhD student, CSD, CMU**

**Joint work with Farzaneh Derakhshan,  
Milijana Surbatovich, and Limin Jia**



# Intermittent Computing

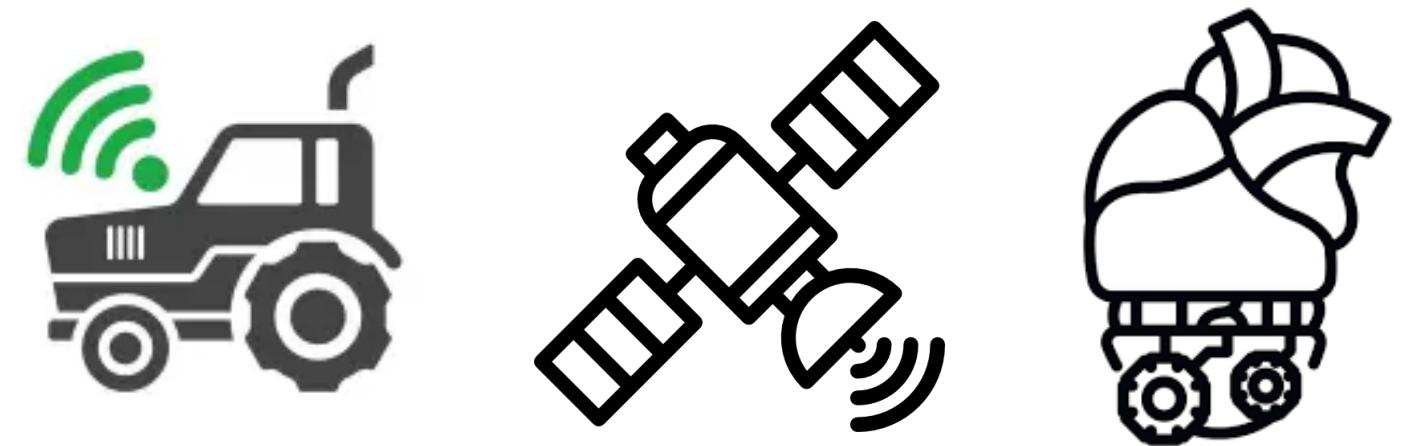
- tiny devices that compute in inaccessible environments



```
Ckpt  
x := y;  
y := z;  
w := x + y
```

# Intermittent Computing

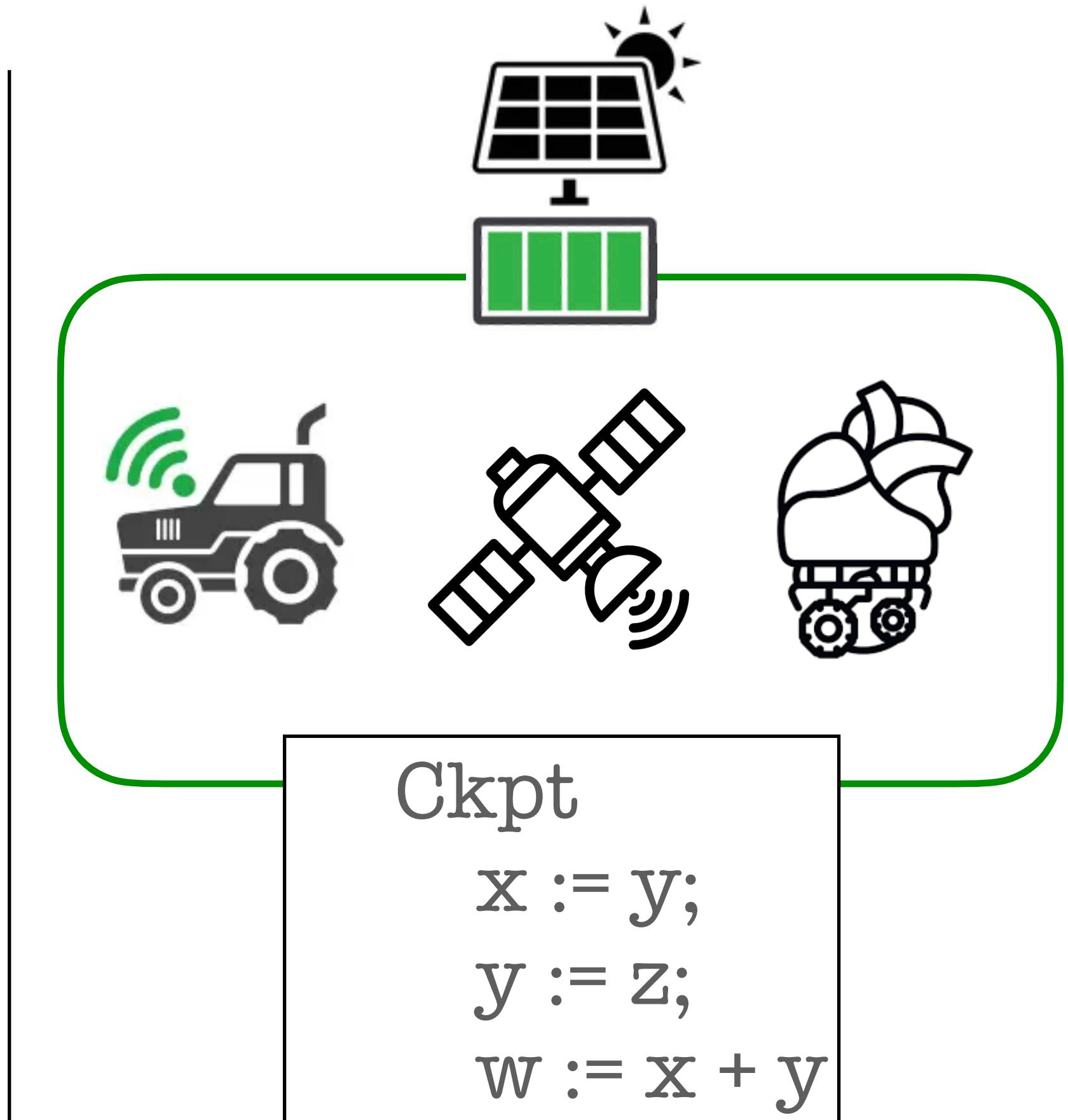
- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources



```
Ckpt  
x := y;  
y := z;  
w := x + y
```

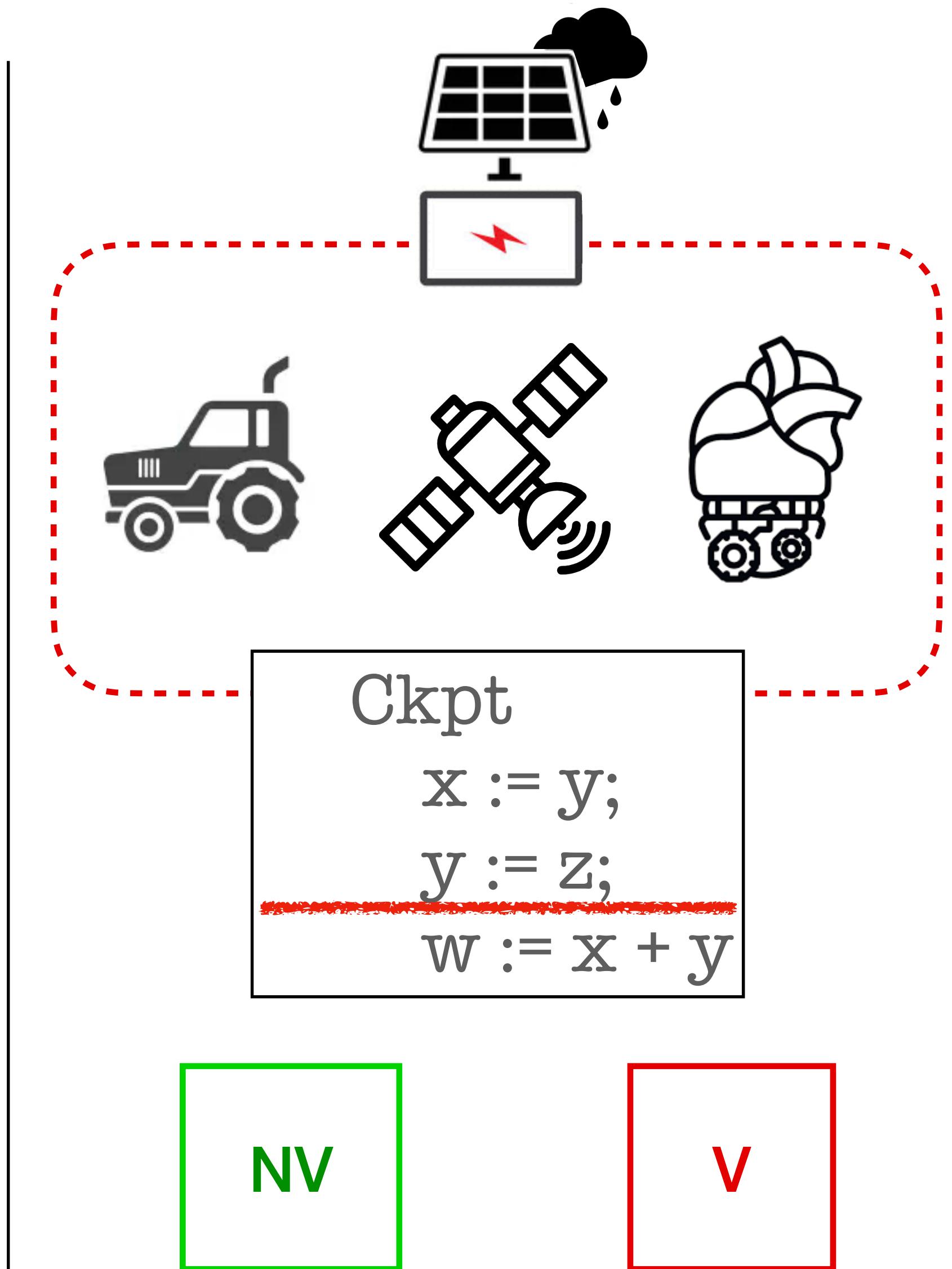
# Intermittent Computing

- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources
- charge, compute, and crash frequently



# Intermittent Computing

- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources
- charge, compute, and crash frequently
- rely on a combination of NV and V
- NV survives power failures, V does not
- runtime system support



# Checkpointing depends on execution mode

Ckpt

$x := y;$

$y := z;$

$w := x + y$



Atomic region

$\text{let } x = 5 \text{ in}$

$c := x + 1;$

$h := c$



JIT region

# Checkpointing depends on execution mode

```
Ckpt  
  x := y;  
  y := z;  
w := x + y
```

Atomic region

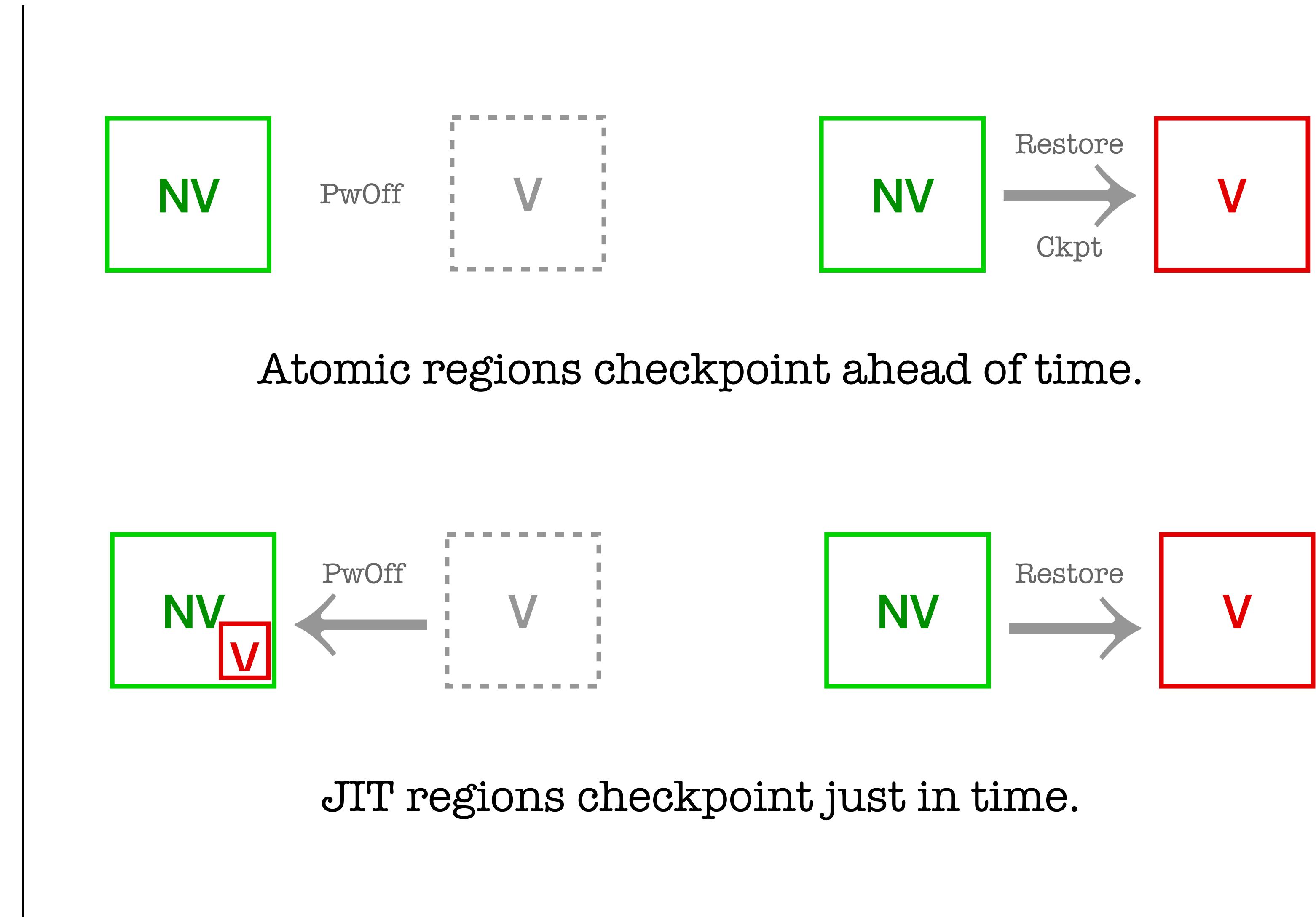
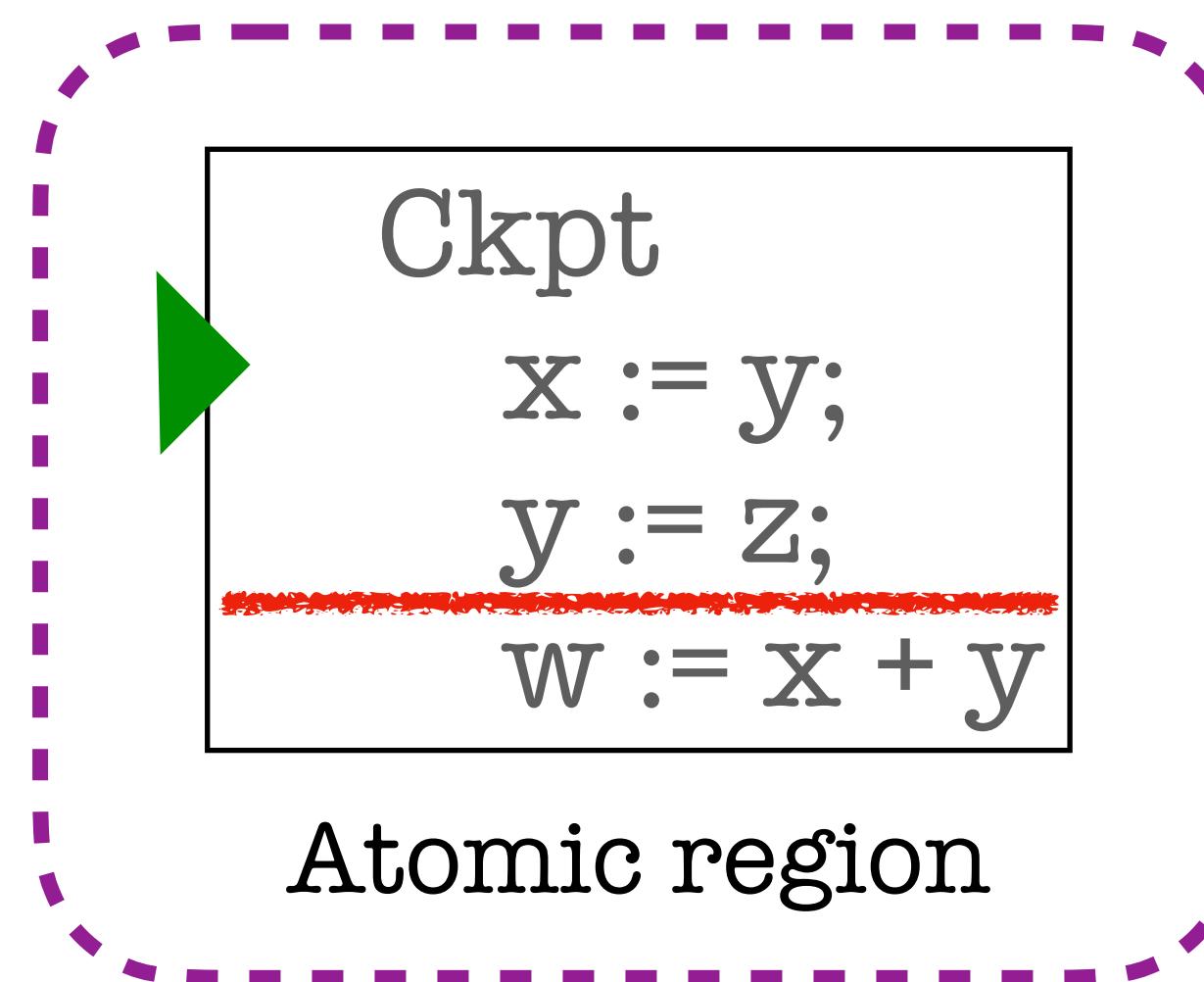
```
let x = 5 in  
  c:= x+1;  
h := c
```

JIT region

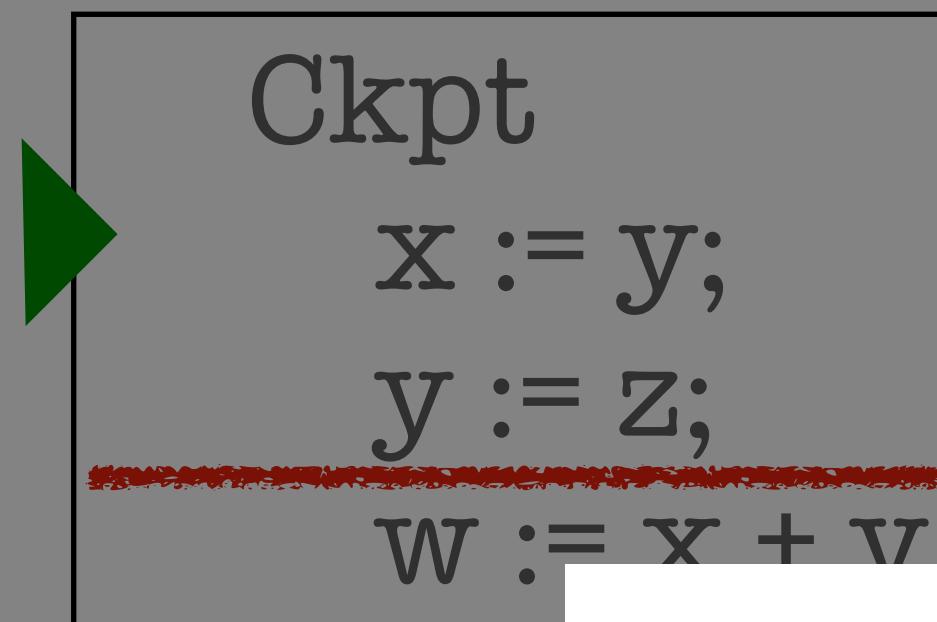


Atomic regions checkpoint ahead of time.

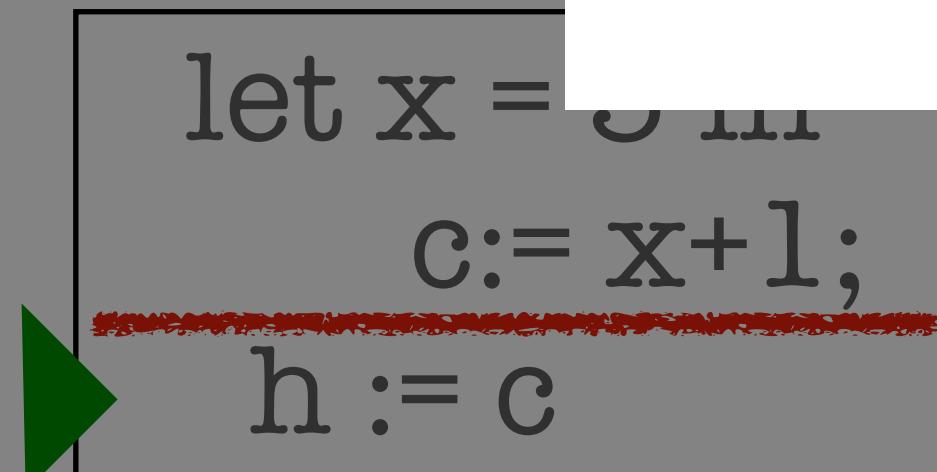
# Checkpointing depends on execution mode



# Checkpointing depends on execution mode



Atomic

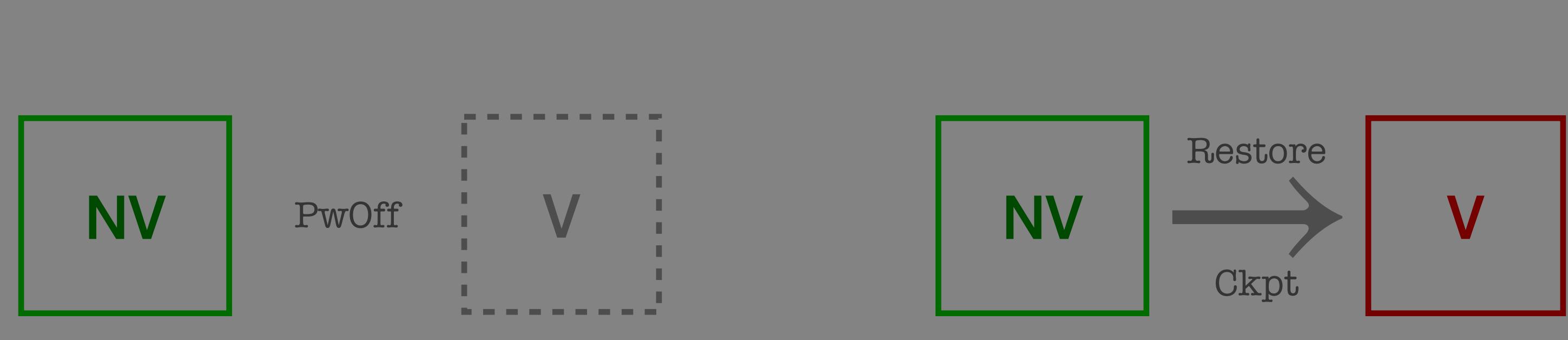


JIT region

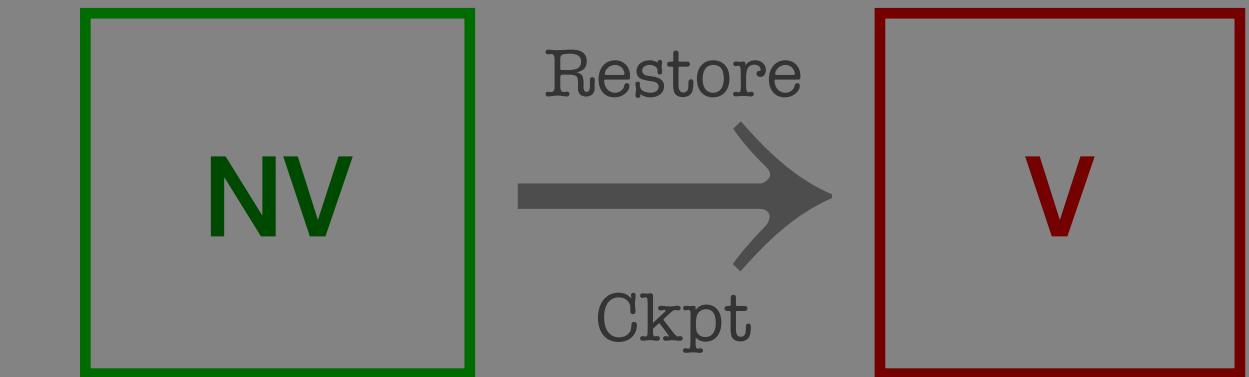
Question:

How can we **prove** that programs execute correctly despite these power failures?

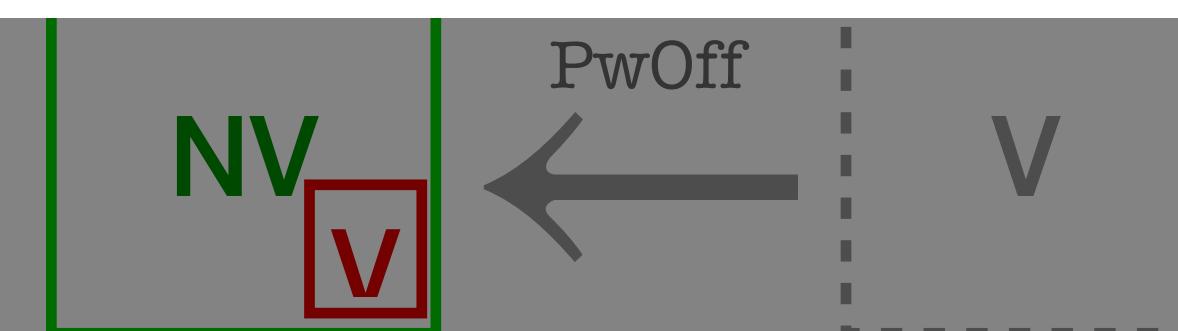
JIT regions checkpoint just in time.



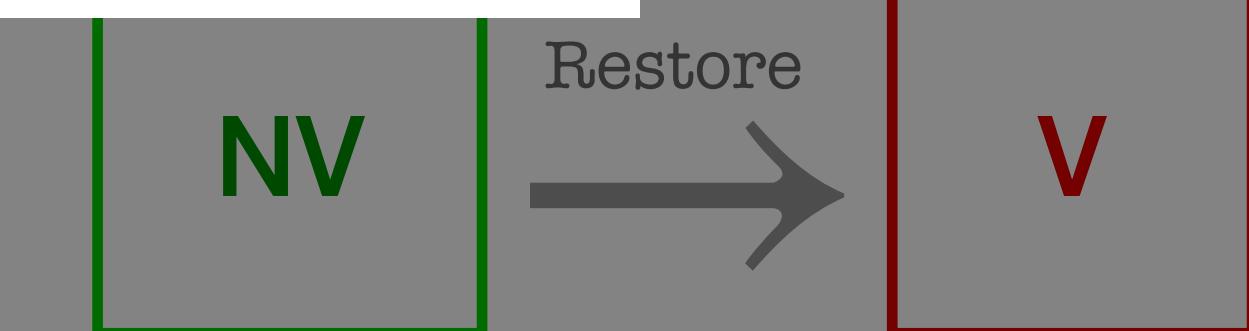
PwOff



time.



PwOff



time.

V

V

V

V

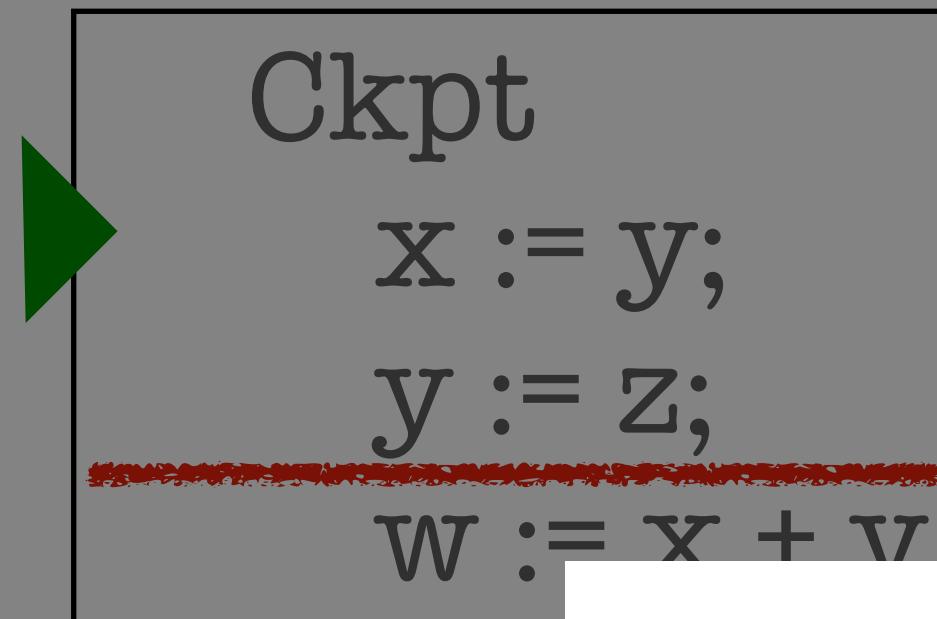
V

V

V

V

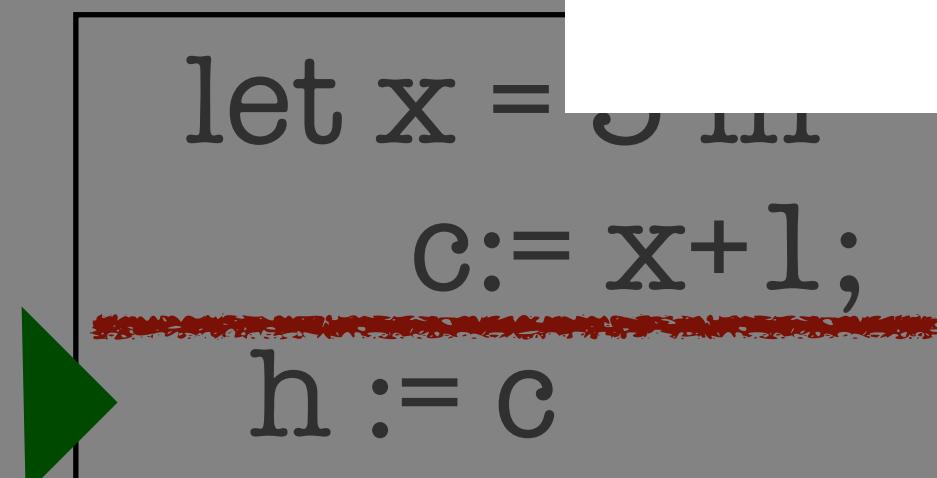
# Checkpointing depends on execution mode



Atomic

Answer:

time.

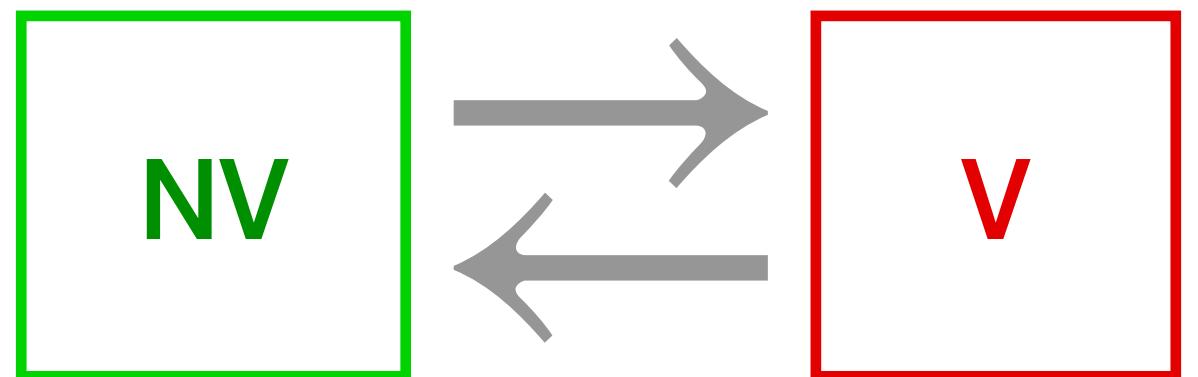


JIT region

JIT regions checkpoint just in time.

# What do we need to checkpoint?

```
Ckpt  
x := y;  
y := z;  
w := x + y
```

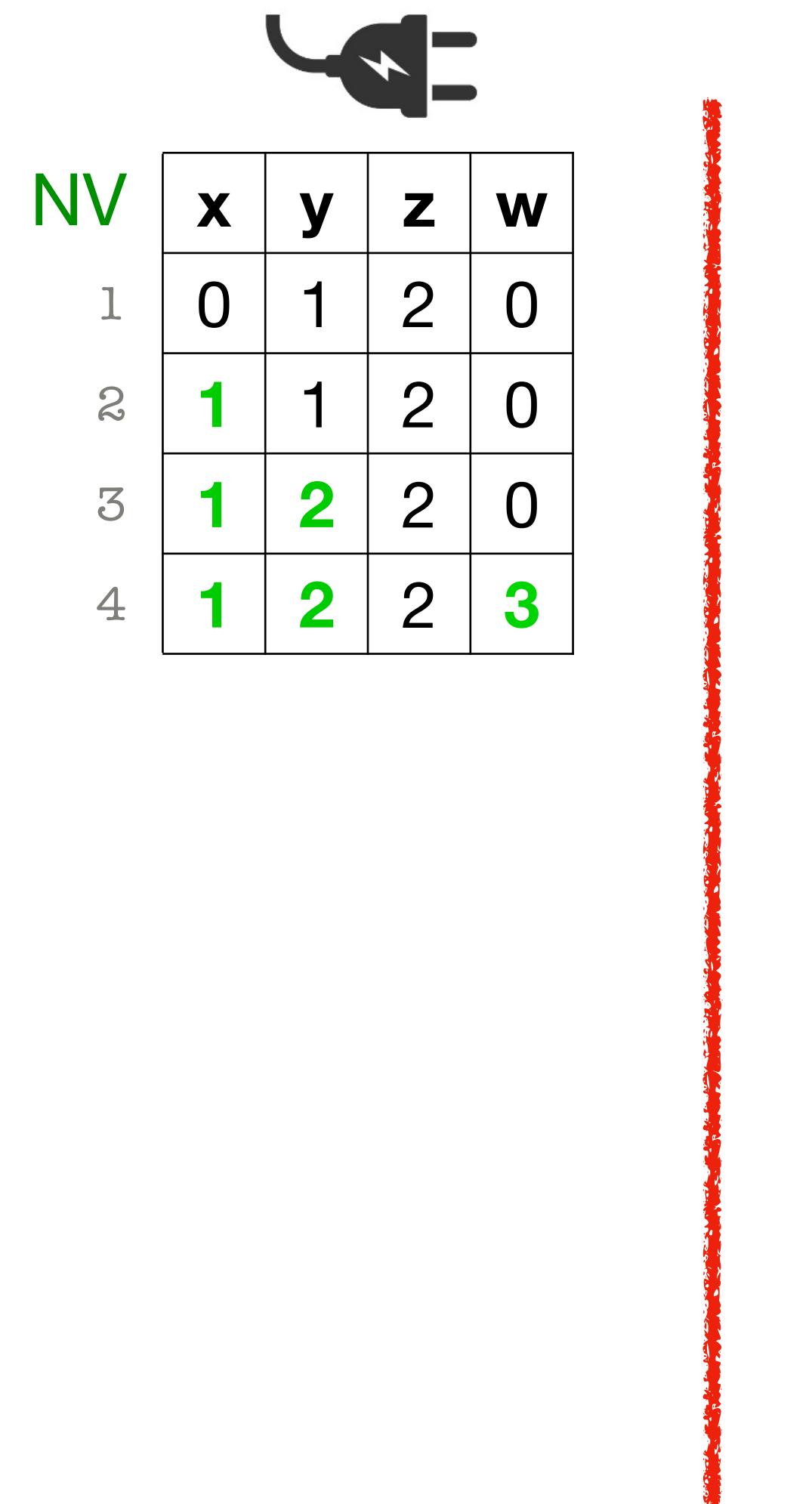


# Checkpoint nothing

```
1 Ckpt()  
2     x := y;  
3     y := z;  
4     w := x + y
```



| NV | x | y | z | w |
|----|---|---|---|---|
| 1  | 0 | 1 | 2 | 0 |
| 2  | 1 | 1 | 2 | 0 |
| 3  | 1 | 2 | 2 | 0 |



nothing

# Checkpoint nothing

```
1 Ckpt()  
2     x := y;  
3     y := z;  
4     w := x + y
```

NV

|         | x | y | z | w |
|---------|---|---|---|---|
| 1       | 0 | 1 | 2 | 0 |
| 2       | 1 | 1 | 2 | 0 |
| 3       | 1 | 2 | 2 | 0 |
| Restore | 1 | 2 | 2 | 0 |
| 2       | 2 | 2 | 2 | 0 |
| 3       | 2 | 2 | 2 | 0 |
| 4       | 2 | 2 | 2 | 4 |

NV

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

inconsistent  
memory!

nothing  
↗ consistency bugs!

# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```

NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |



NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |
| 1 | 2 | 2 | 0 |
| 1 | 2 | 2 | 3 |

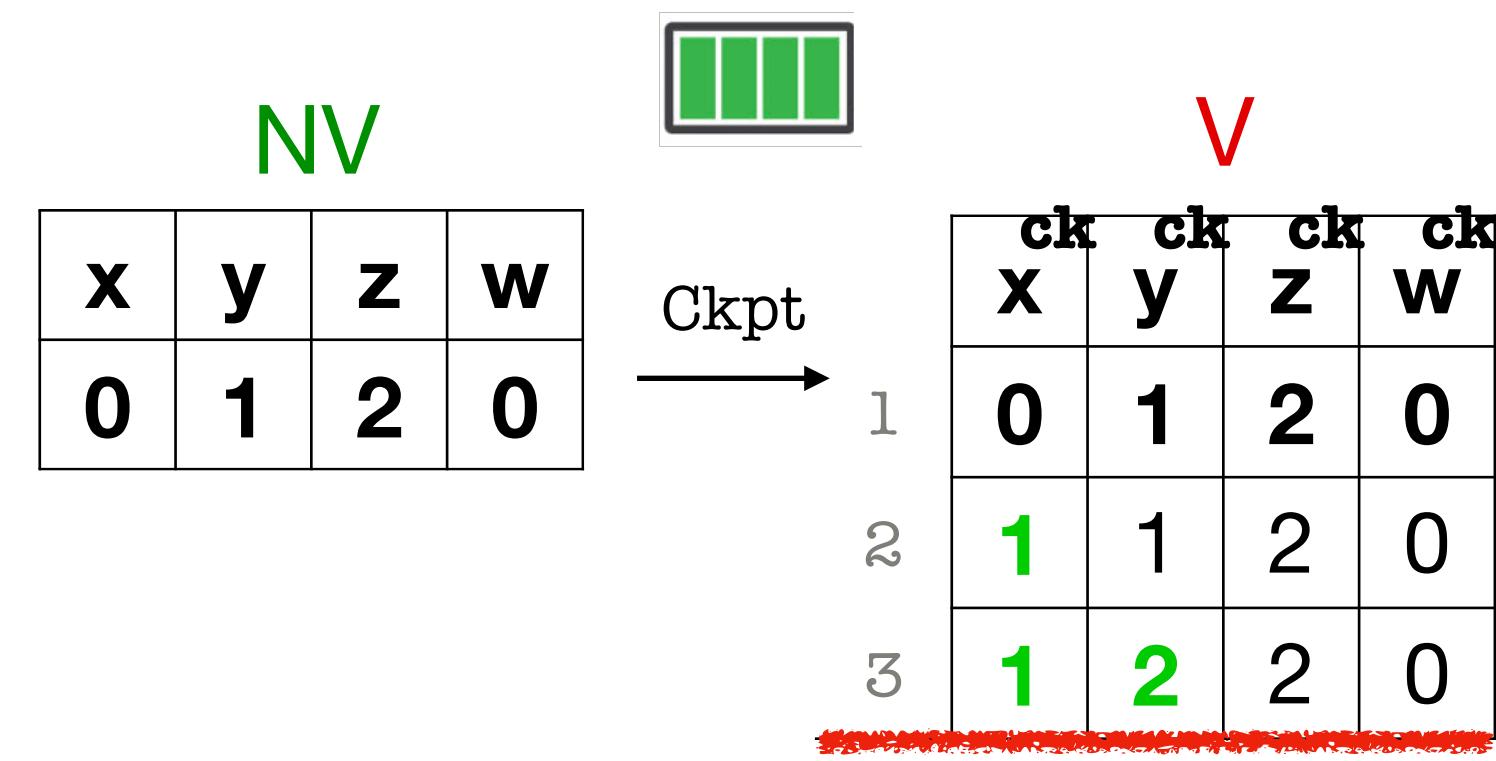
nothing

↗ consistency bugs!

everything

# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```



# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```

NV

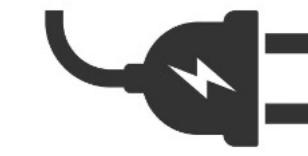
| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |



V

| ck |   | ck | ck | ck |
|----|---|----|----|----|
| x  | y | z  | w  |    |
|    |   |    |    |    |

pwOff



NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |
| 1 | 2 | 2 | 0 |
| 1 | 2 | 2 | 3 |

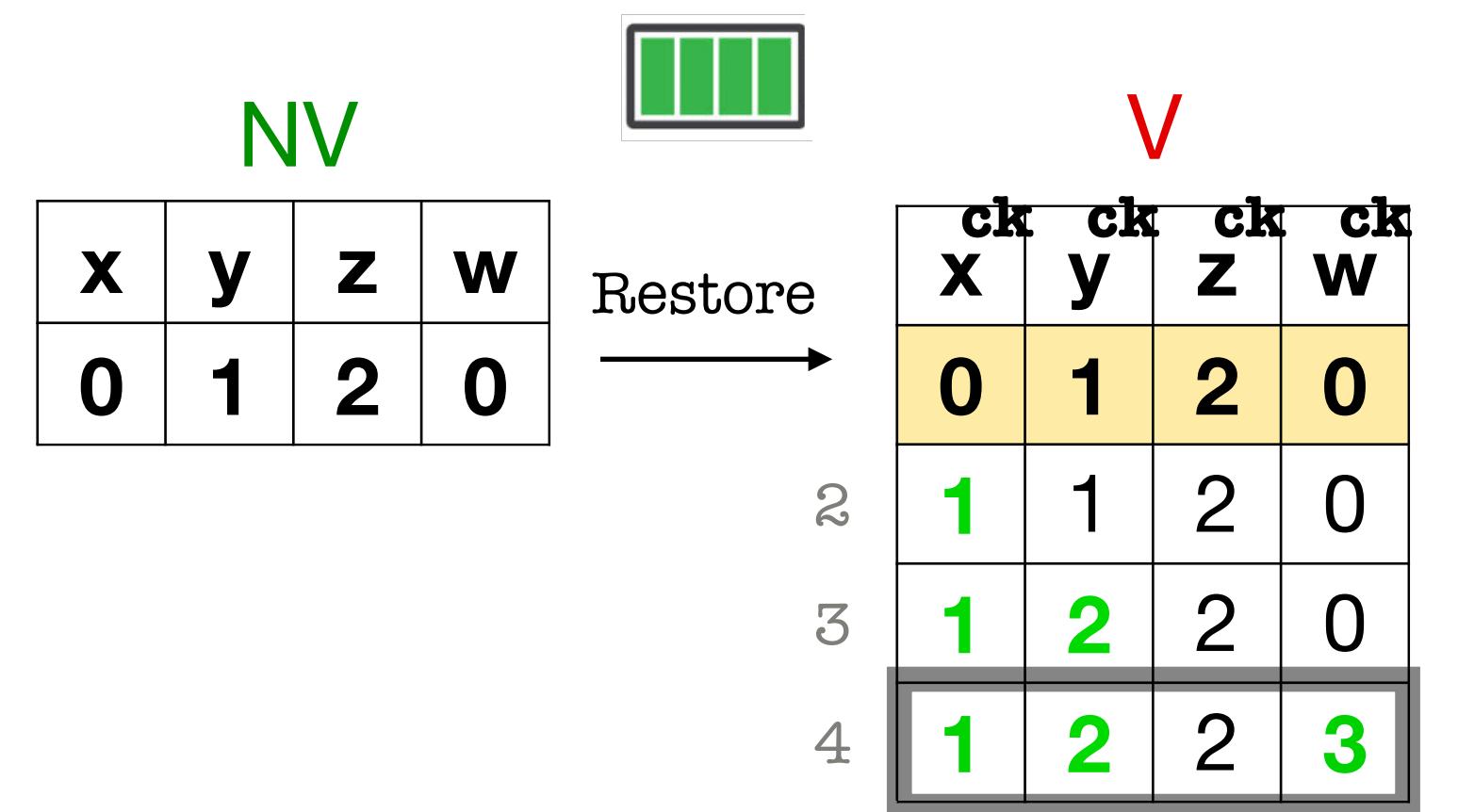
nothing

↗ consistency bugs!

everything

# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
➡ consistency bugs!

everything  
➡ inefficient!

# Do we really need to checkpoint everything?

The diagram shows a sequence of four statements enclosed in a rectangular box:

- 1 Ckpt(???)
- 2  $x := y;$
- 3  $y := z;$
- 4  $w := x + y$

Annotations in red text with arrows point to specific parts of the code:

- An arrow from the text "written before read" points to the assignment  $x := y;$ .
- An arrow from the text "safe to read here" points to the addition statement  $w := x + y$ .
- An arrow from the text "z is never updated" points to the assignment  $y := z;$ .

# No, only the write-after-read variables [Lucia et al. '15]

```
1 Ckpt(y)
2   x := y;           read
3   y := z;
4   w := x + y
```

write → read

y is a write-after-read (WAR) variable.

# Checkpoint write-after-read variables

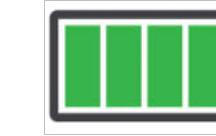
```
1 Ckpt(y)  
2     x := y;  
3     y := z;  
4     w := x + y
```

NV

|  | x | y | z | w |
|--|---|---|---|---|
|  | 0 | 1 | 2 | 0 |

NV

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |



nothing

✗ consistency bugs!

everything

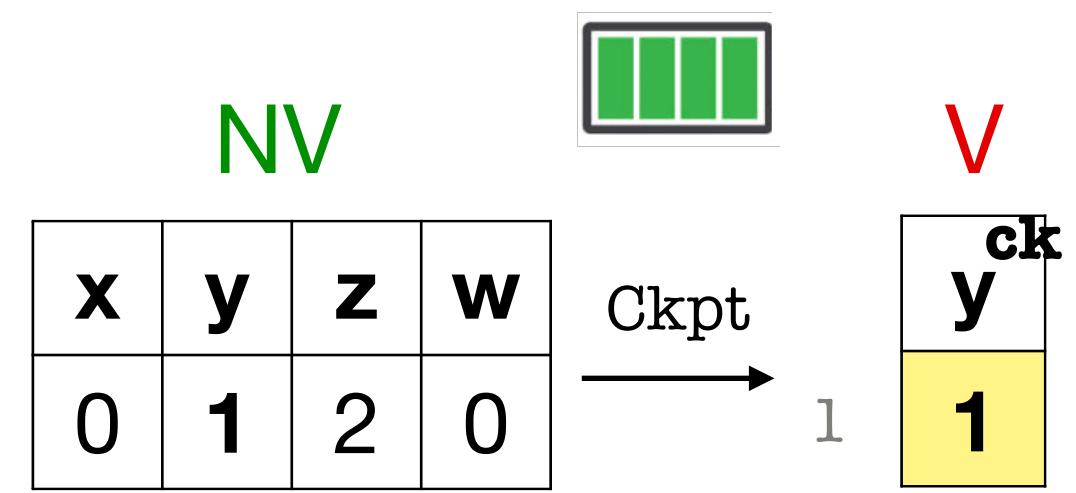
✗ inefficient!

write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
↗ consistency bugs!

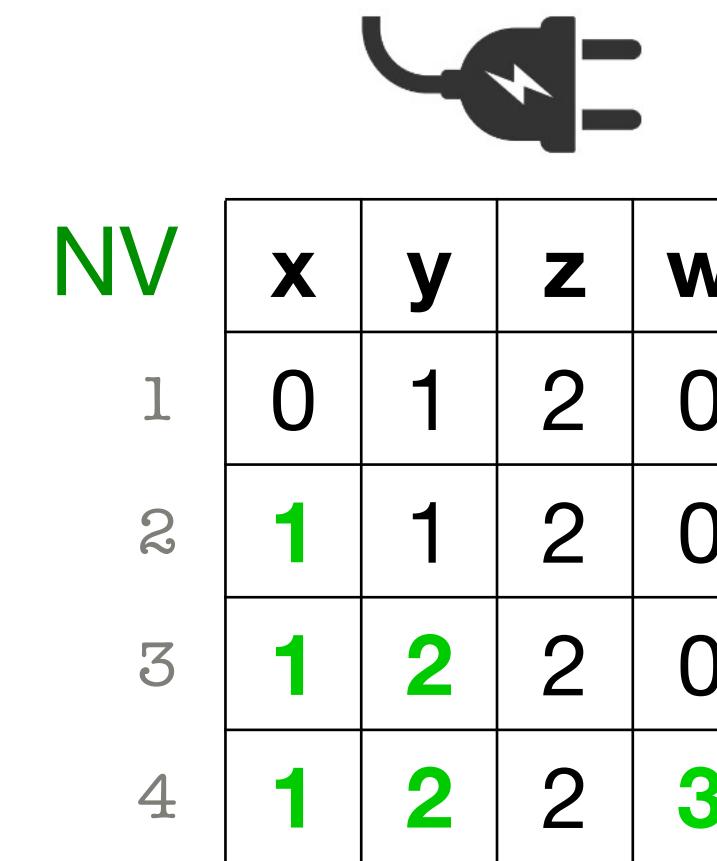
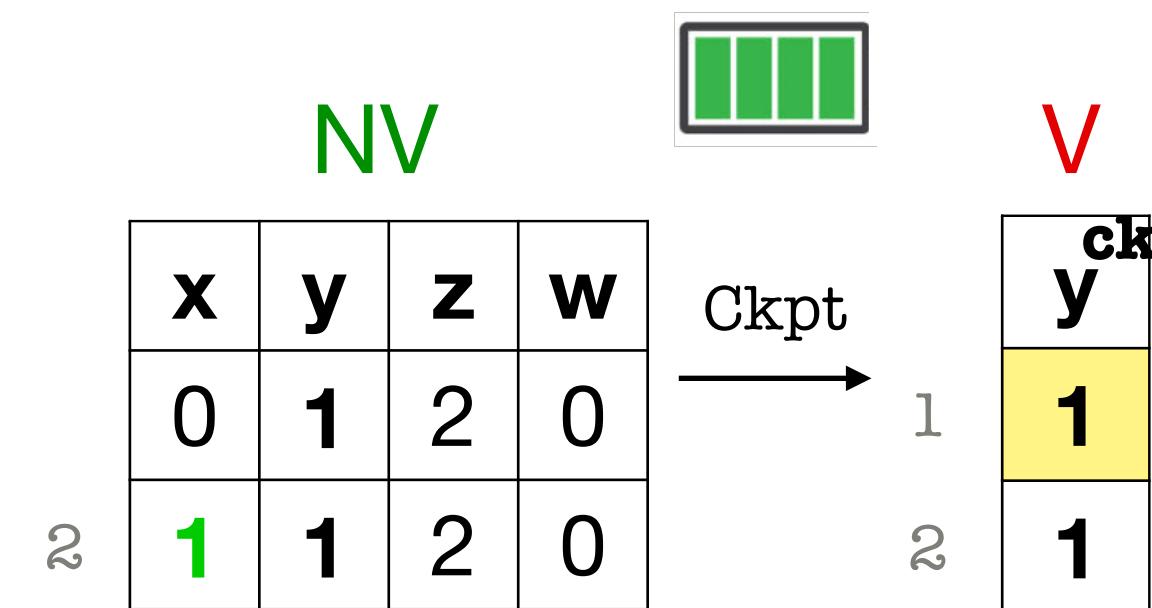
everything  
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write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
➡ consistency bugs!

everything  
➡ inefficient!

write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```

NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |



V

| ck | y |
|----|---|
| 1  | 1 |
| 2  | 1 |
| 3  | 2 |



NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |
| 1 | 2 | 2 | 0 |
| 1 | 2 | 2 | 3 |

nothing

↖ consistency bugs!

everything

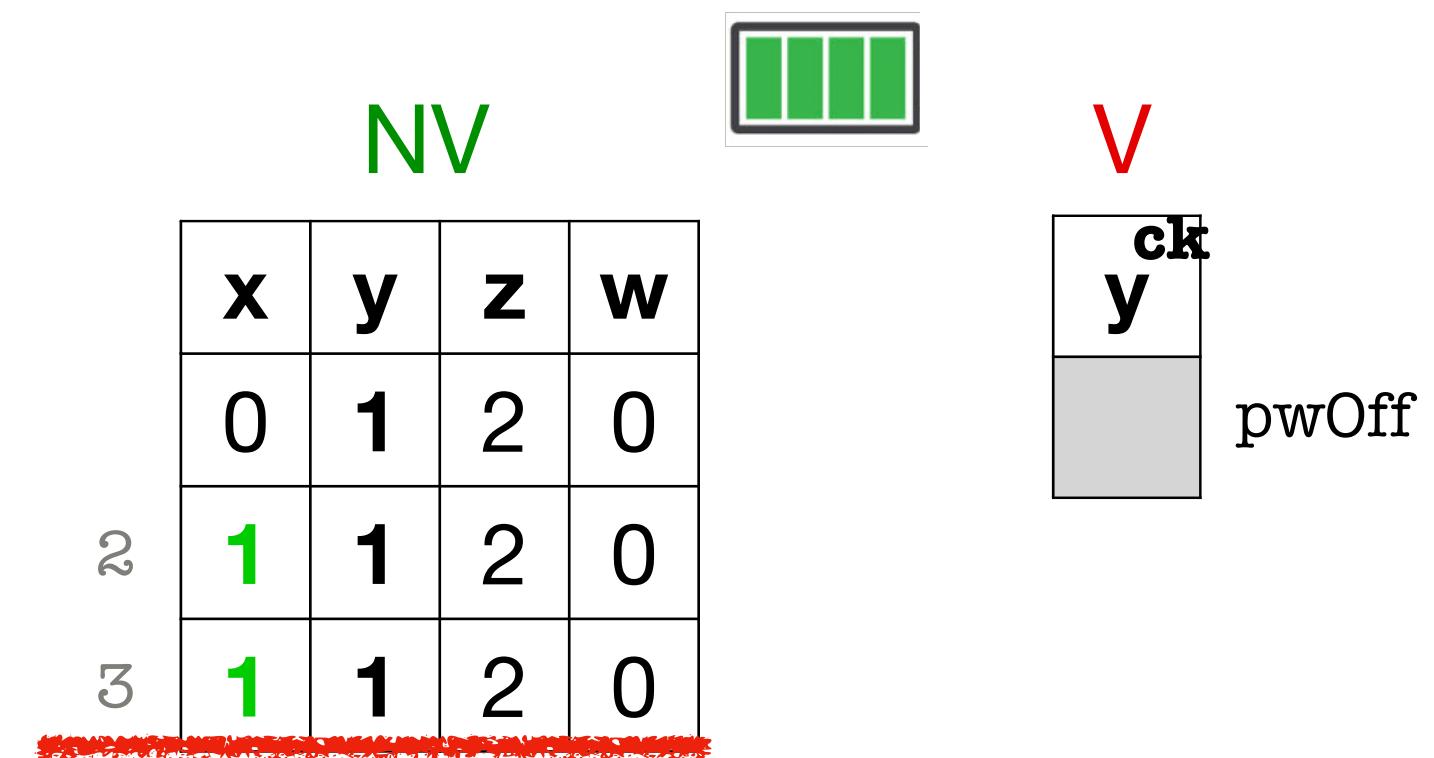
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write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

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1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
↗ consistency bugs!

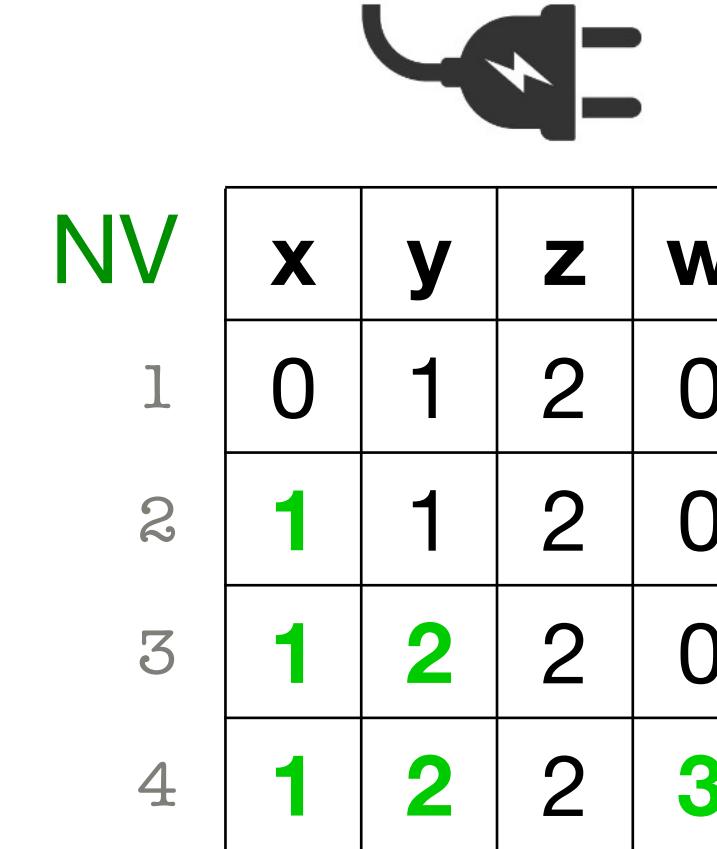
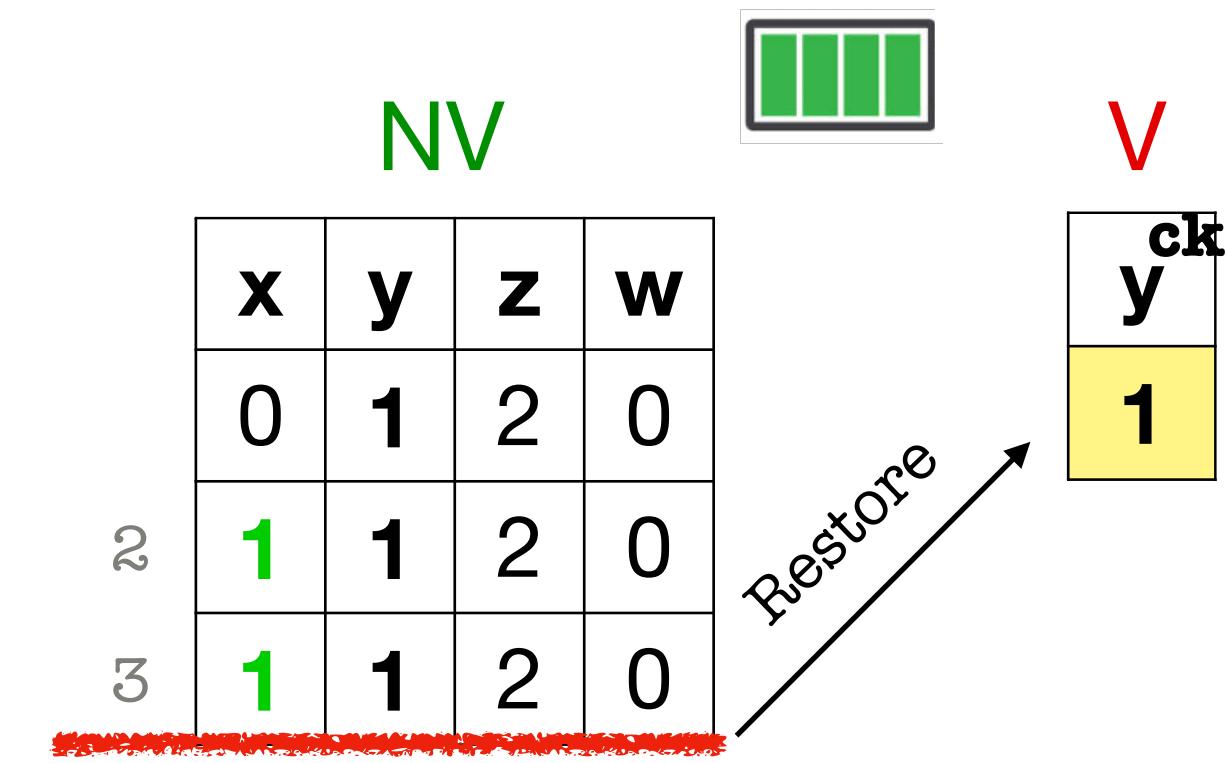
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write-after-read  
variables

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nothing  
➡ consistency bugs!

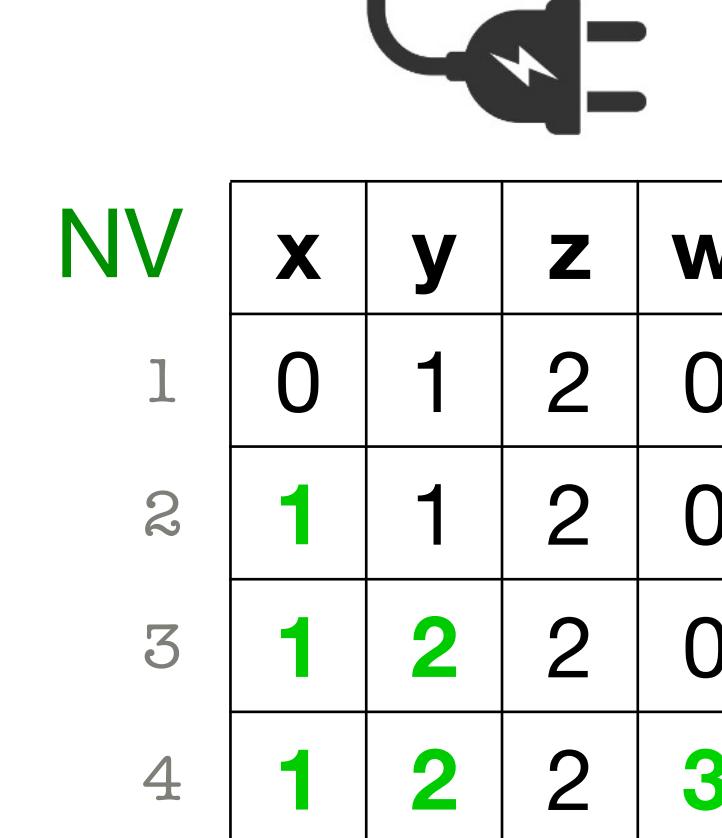
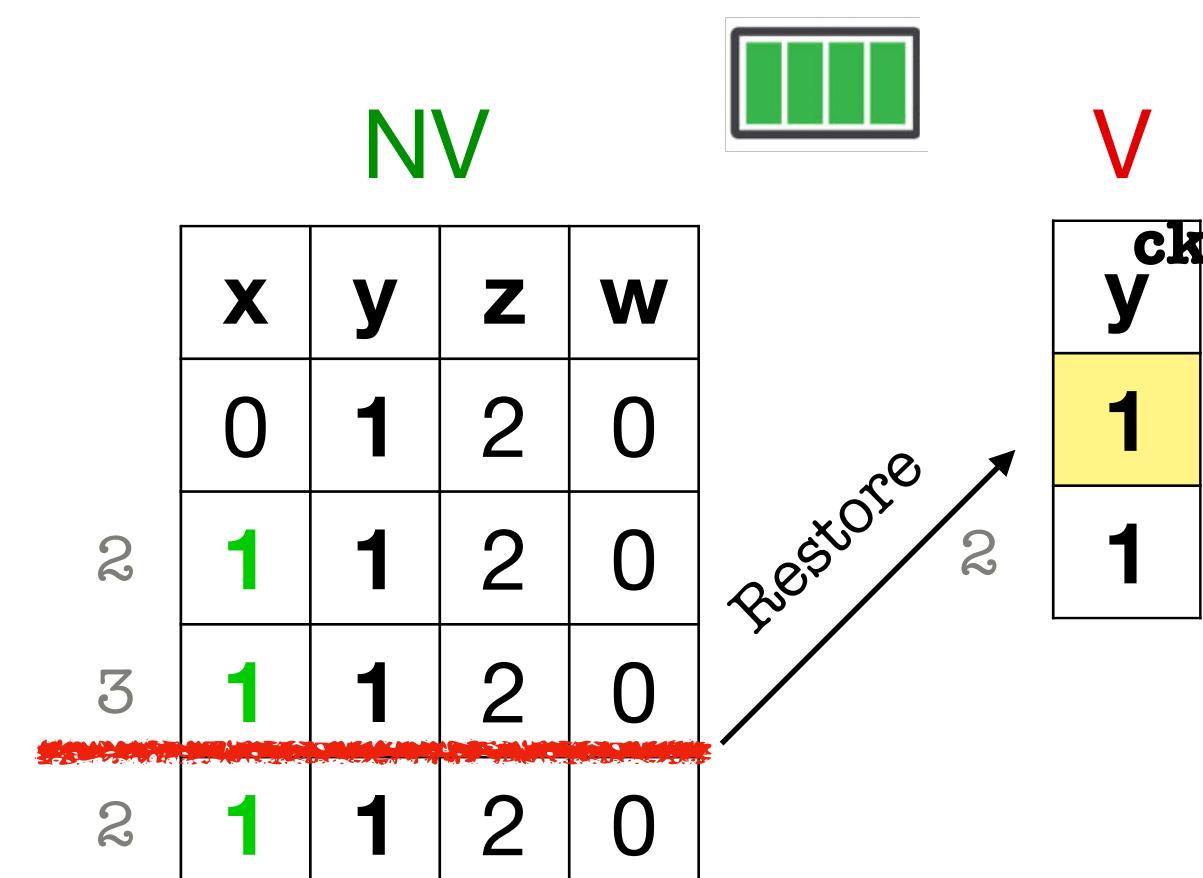
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write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

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4   w := x + y
```



nothing  
➡ consistency bugs!

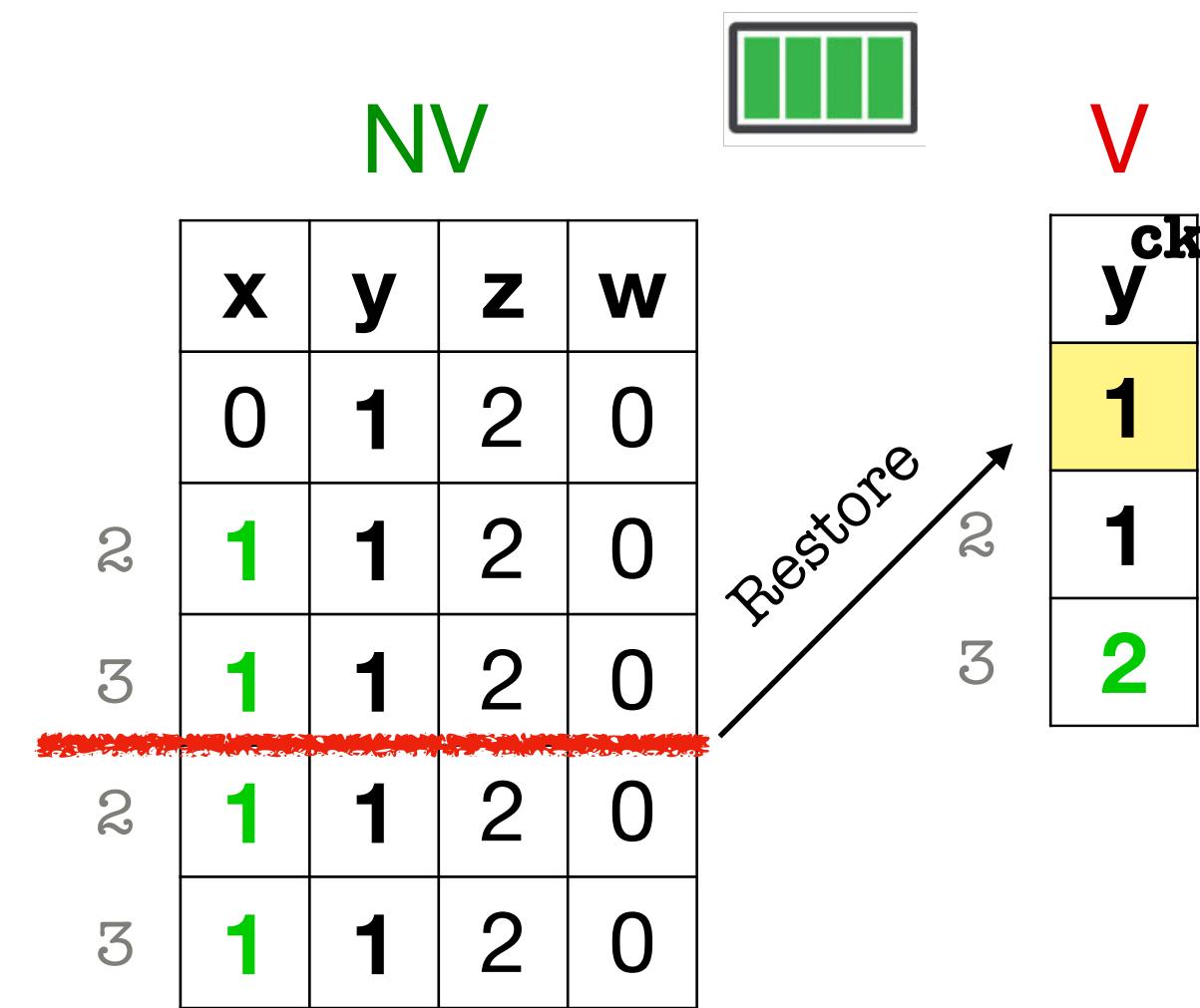
everything  
➡ inefficient!

write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
➡ consistency bugs!

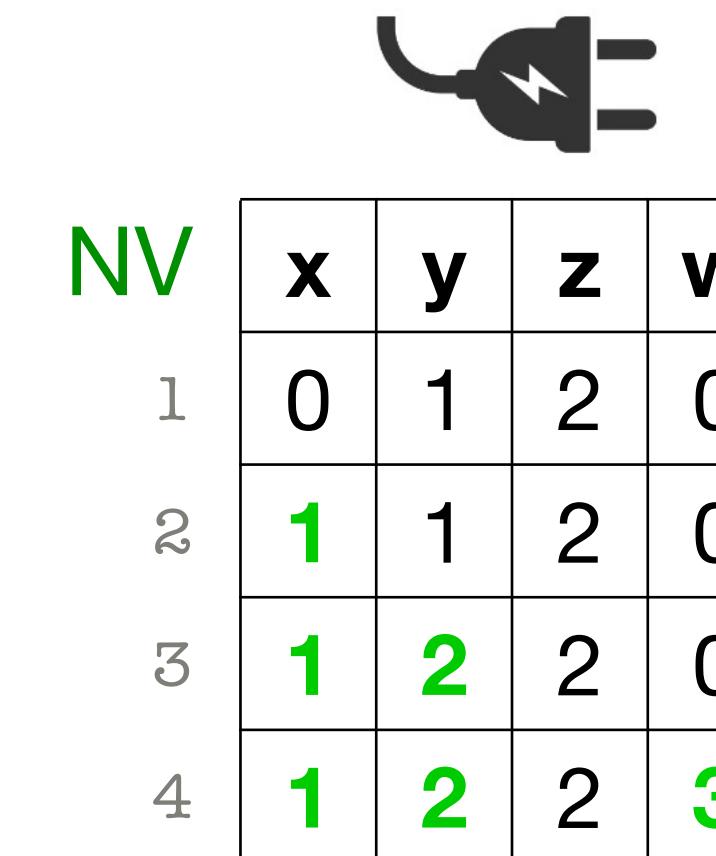
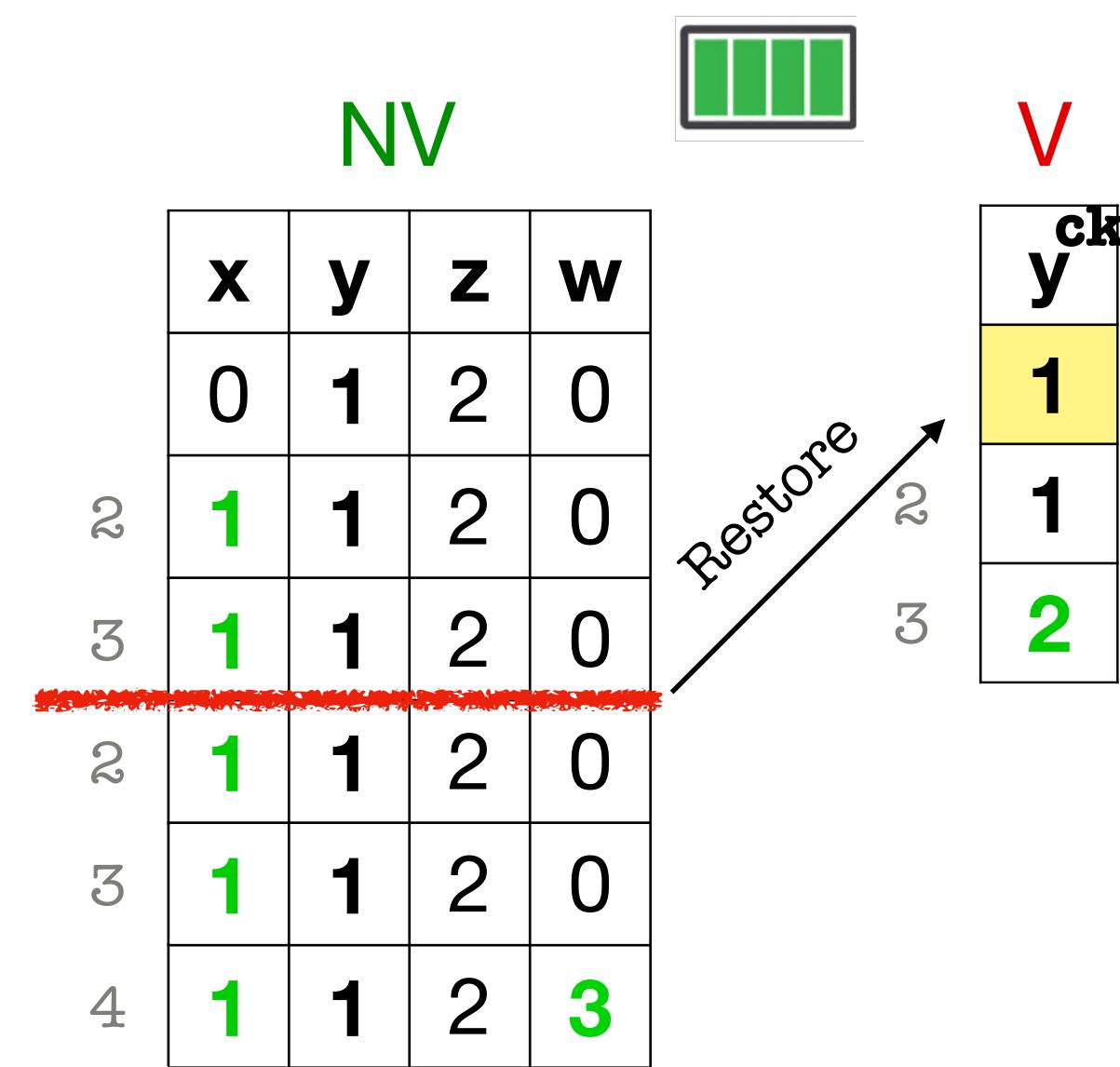
everything  
➡ inefficient!

write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

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1 Ckpt(y)
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nothing  
➡ consistency bugs!

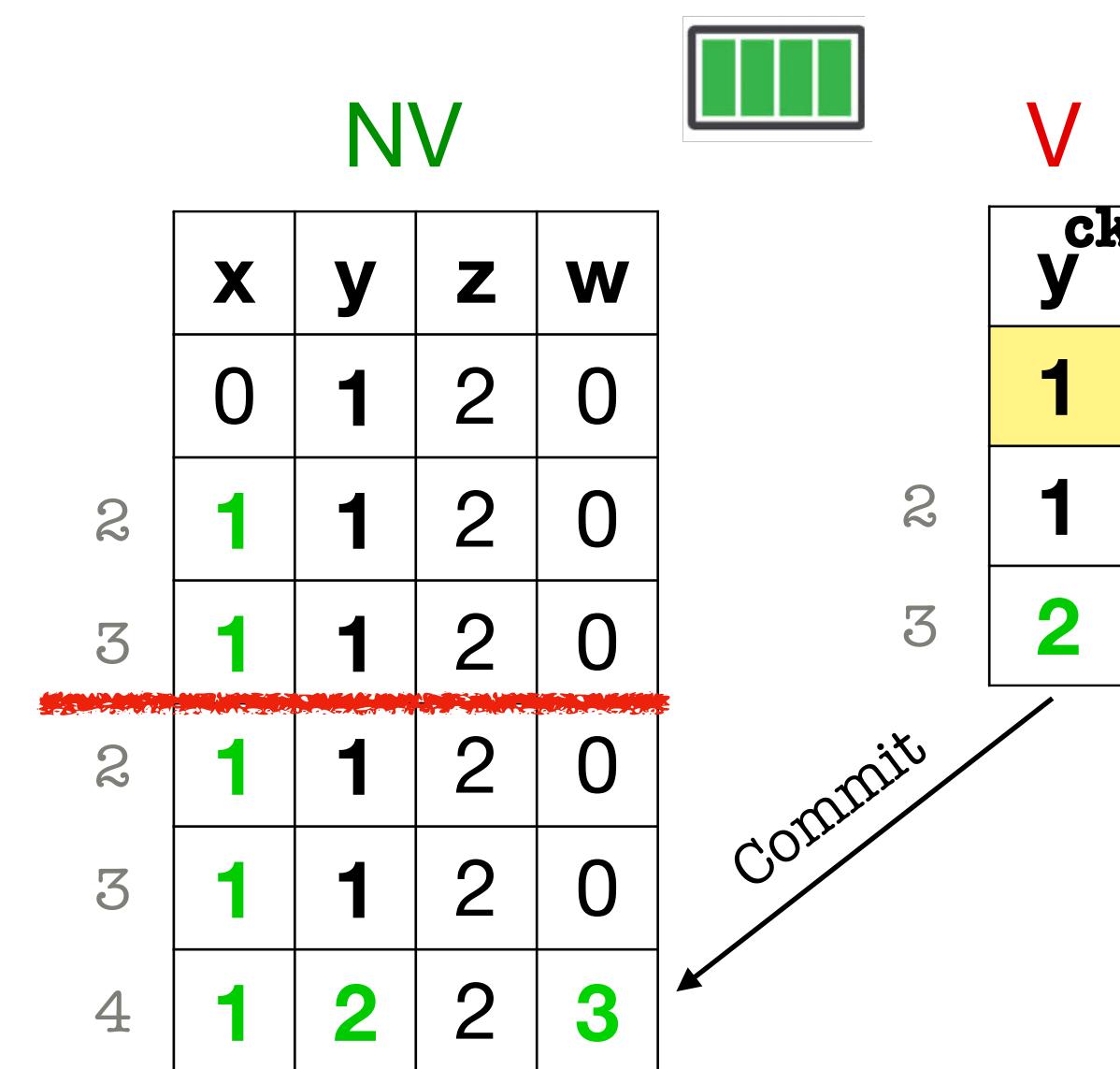
everything  
➡ inefficient!

write-after-read  
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✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
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4   w := x + y
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nothing  
↗ consistency bugs!

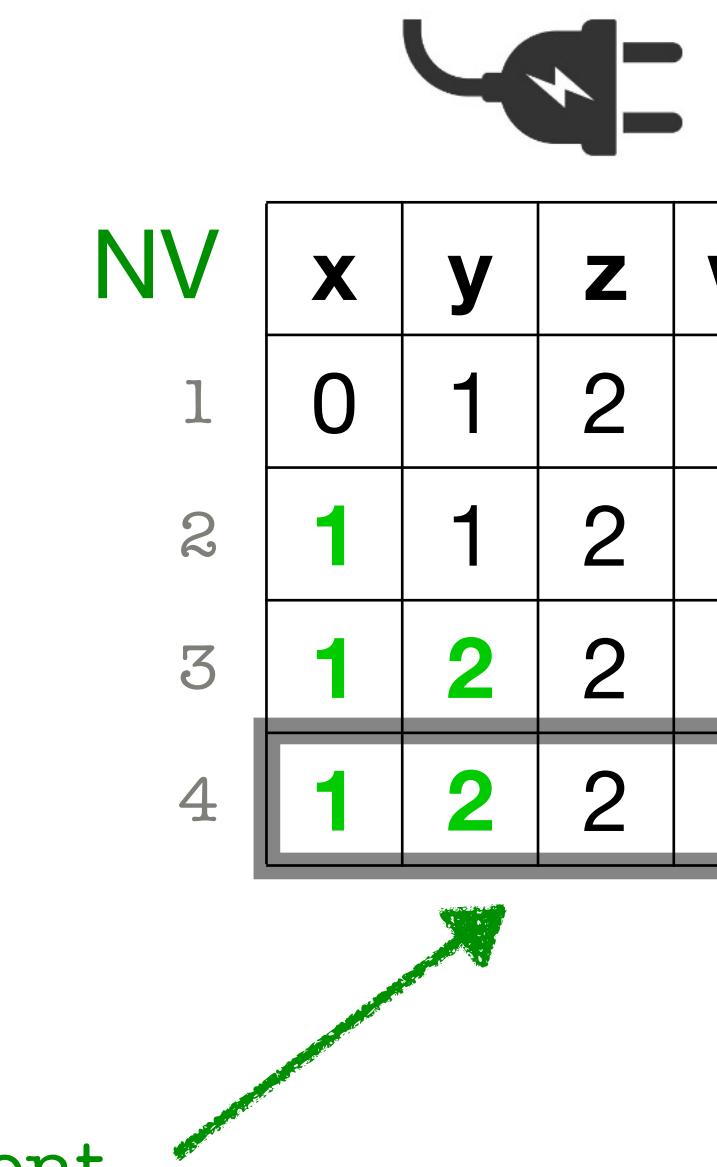
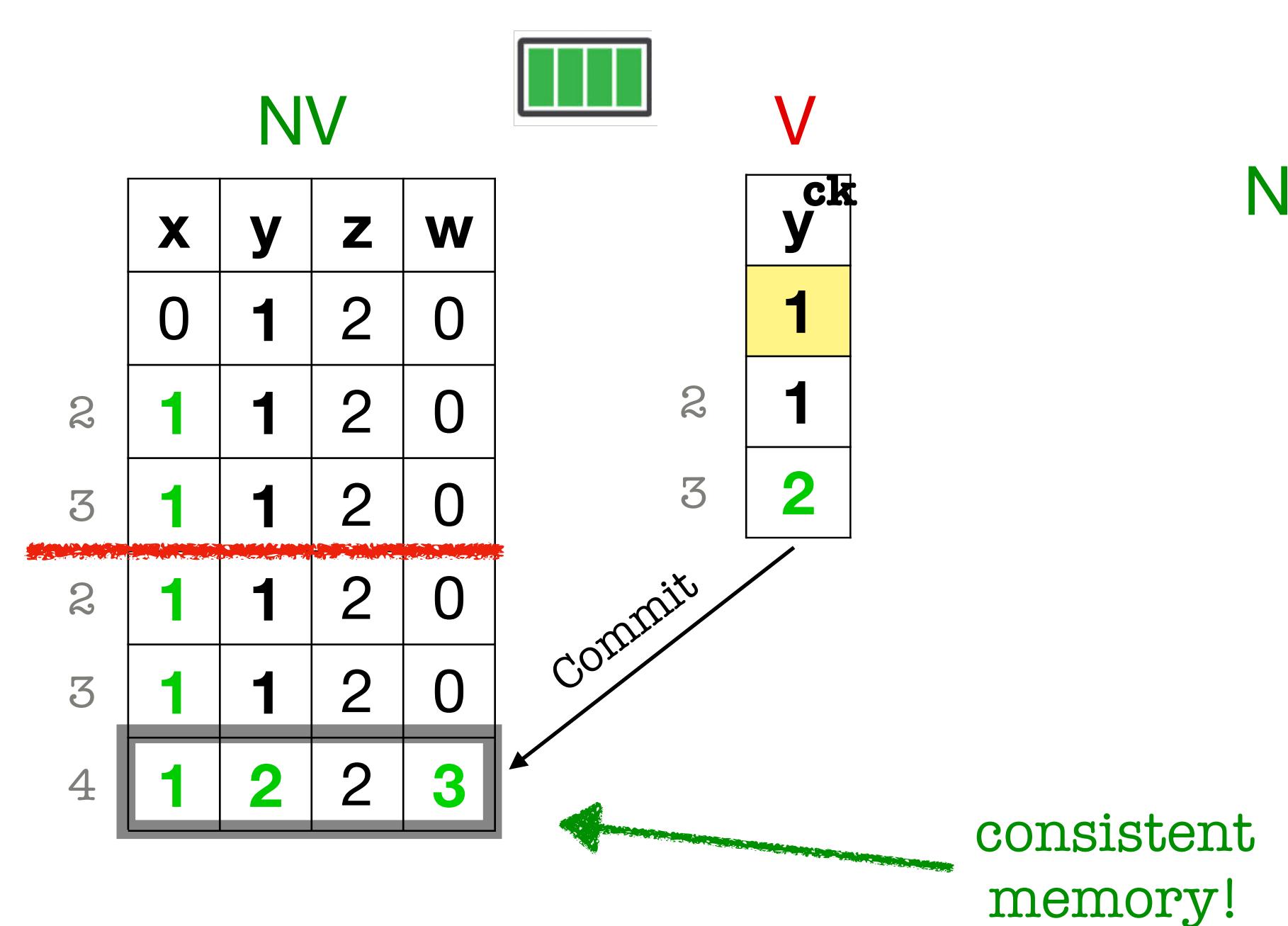
everything  
↗ inefficient!

write-after-read  
variables

✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



- nothing ↗ consistency bugs!
- everything ↗ inefficient!
- write-after-read variables ✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)  
2   x := y;  
3   y := z;  
4   w :=
```

NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |



V

| y | ck |
|---|----|
| 1 |    |
| 1 |    |



NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |



nothing

→ consistency bugs!

thing

inefficient!

-after-read

variables

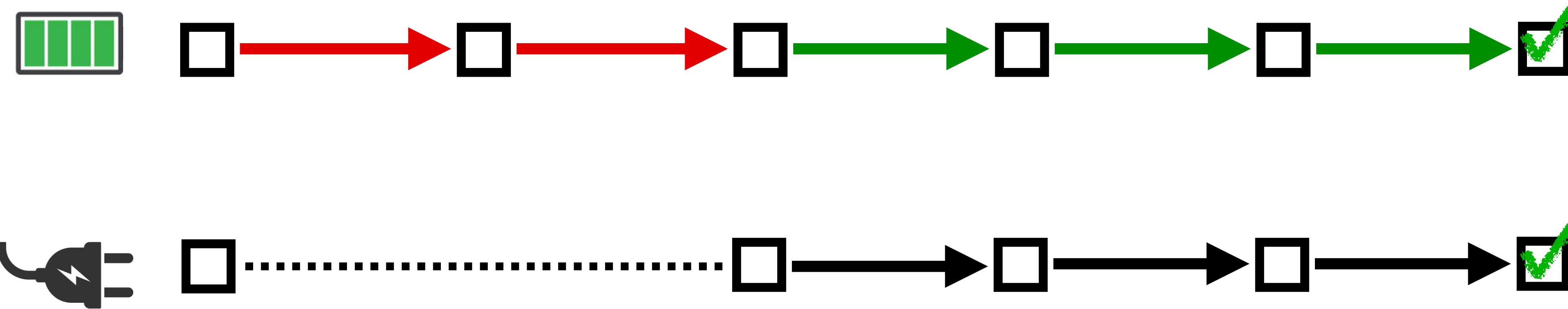
✓ real systems

More precisely:

How can we **prove** that programs execute correctly intermittently when checkpointing only WAR variables?

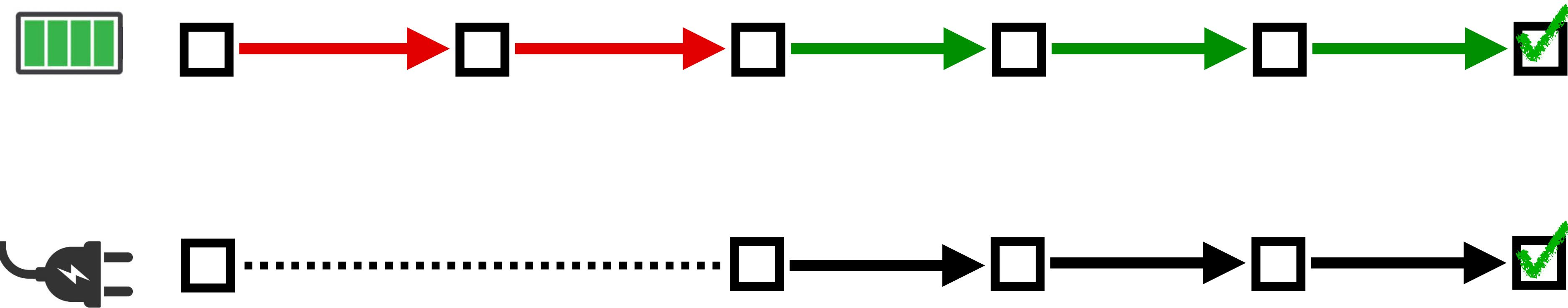
memory.

# Ensuring correctness



- first formal framework for reasoning about intermittent execution  
[Surbatovich et al. '20]

# Ensuring correctness



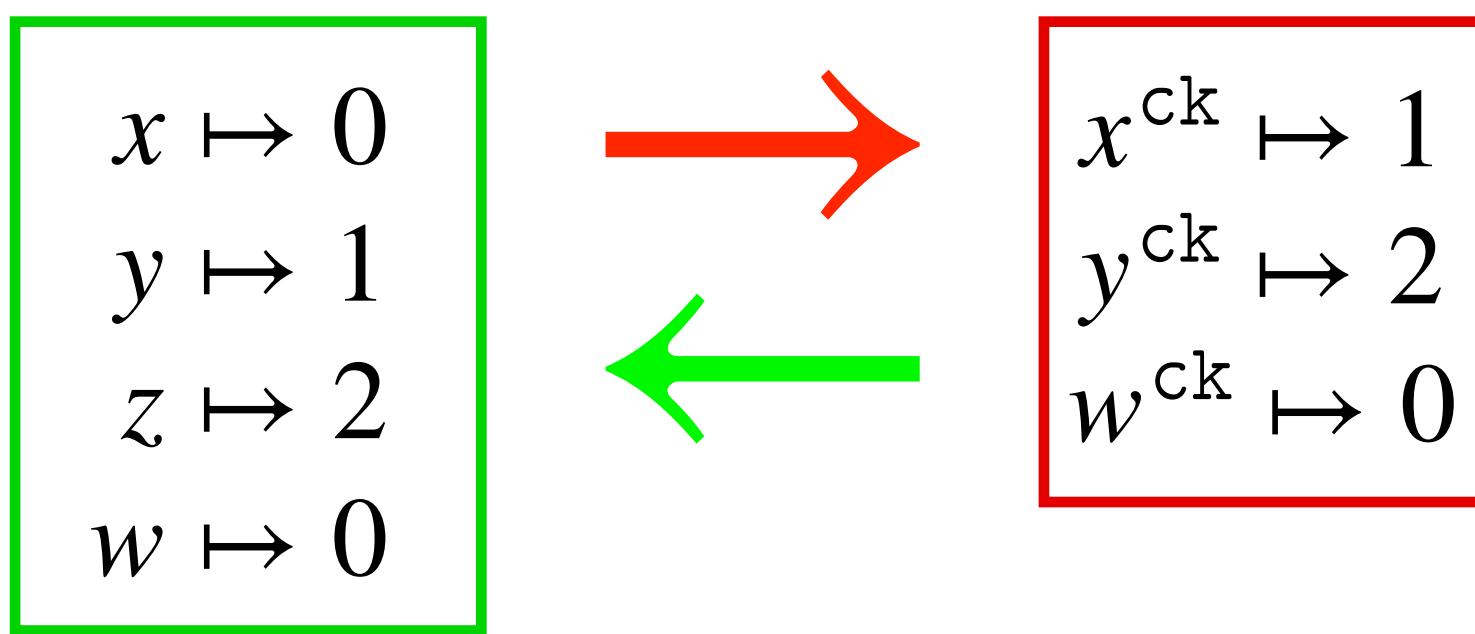
- first formal framework for reasoning about intermittent execution  
[Surbatovich et al. '20]
- type system focused on correct variable accesses [Surbatovich et al. '23]

# **First logical interpretation of intermittent computing power off, restore, commit.**

# First logical interpretation of intermittent computing

## power off, restore, commit.

One approach: checkpoint everything not read-only  
[Derakhshan et al. '23]



```
Ckpt(x,y,w)
  x := y;
  y := z;

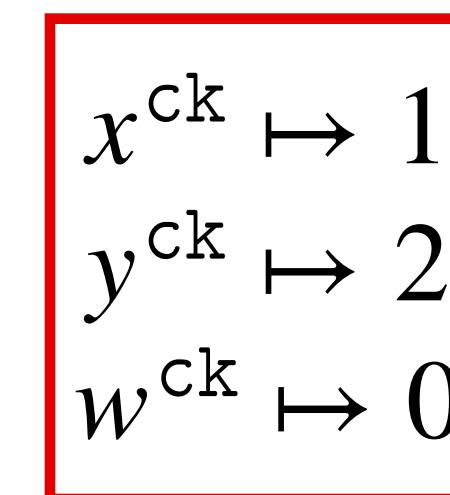
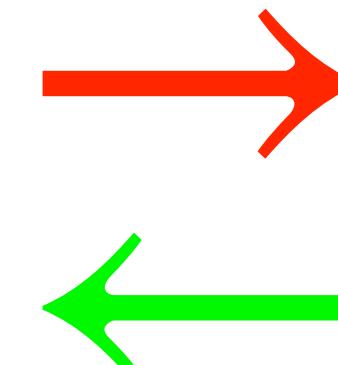
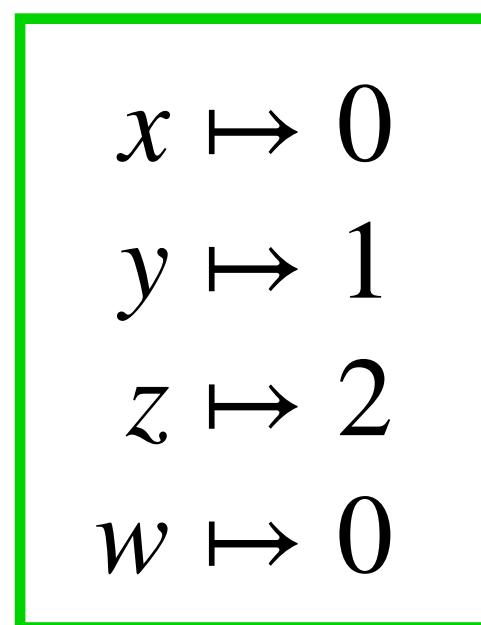

---


  w := x + y
```

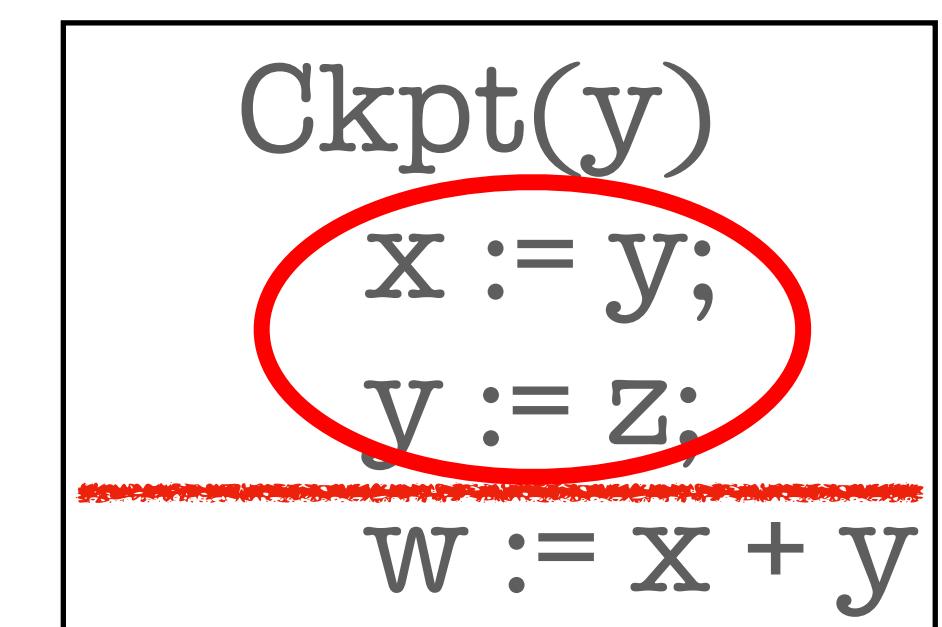
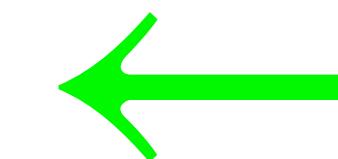
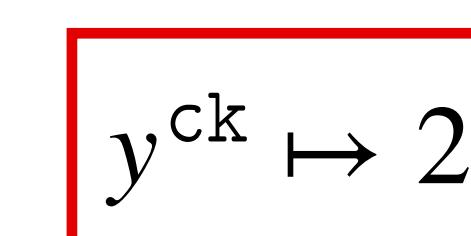
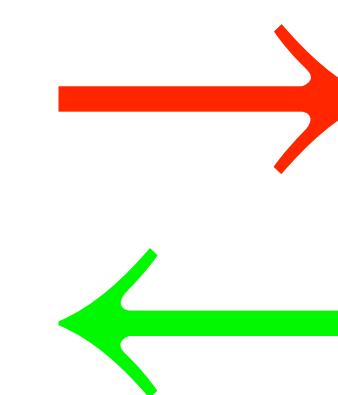
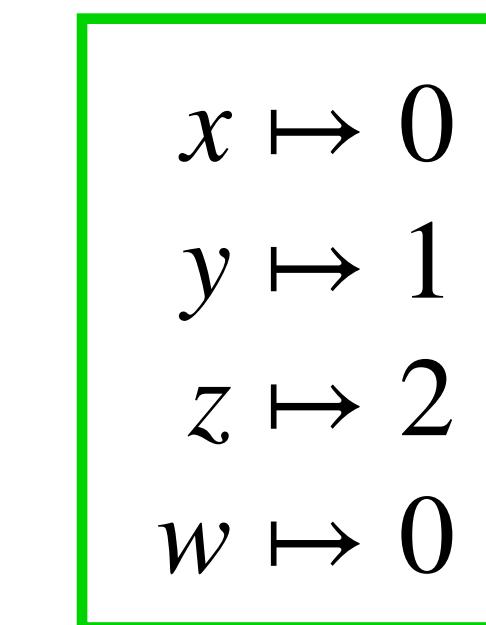
# First logical interpretation of intermittent computing

## power off, restore, commit.

One approach: checkpoint everything not read-only  
[Derakhshan et al. '23]



More efficient: checkpoint only write-after-read variables



Types allow us to automatically check that programs can execute **correctly intermittently**.

# Outline

- Intermittent computing
- Overview
- **Type system**
- Logical relation
- JIT mode
- Key theorems
- Conclusion

# Basic types and access qualifiers

basic types

$$T := \text{int} \mid \text{bool} \mid \text{unit}$$

access qualifiers

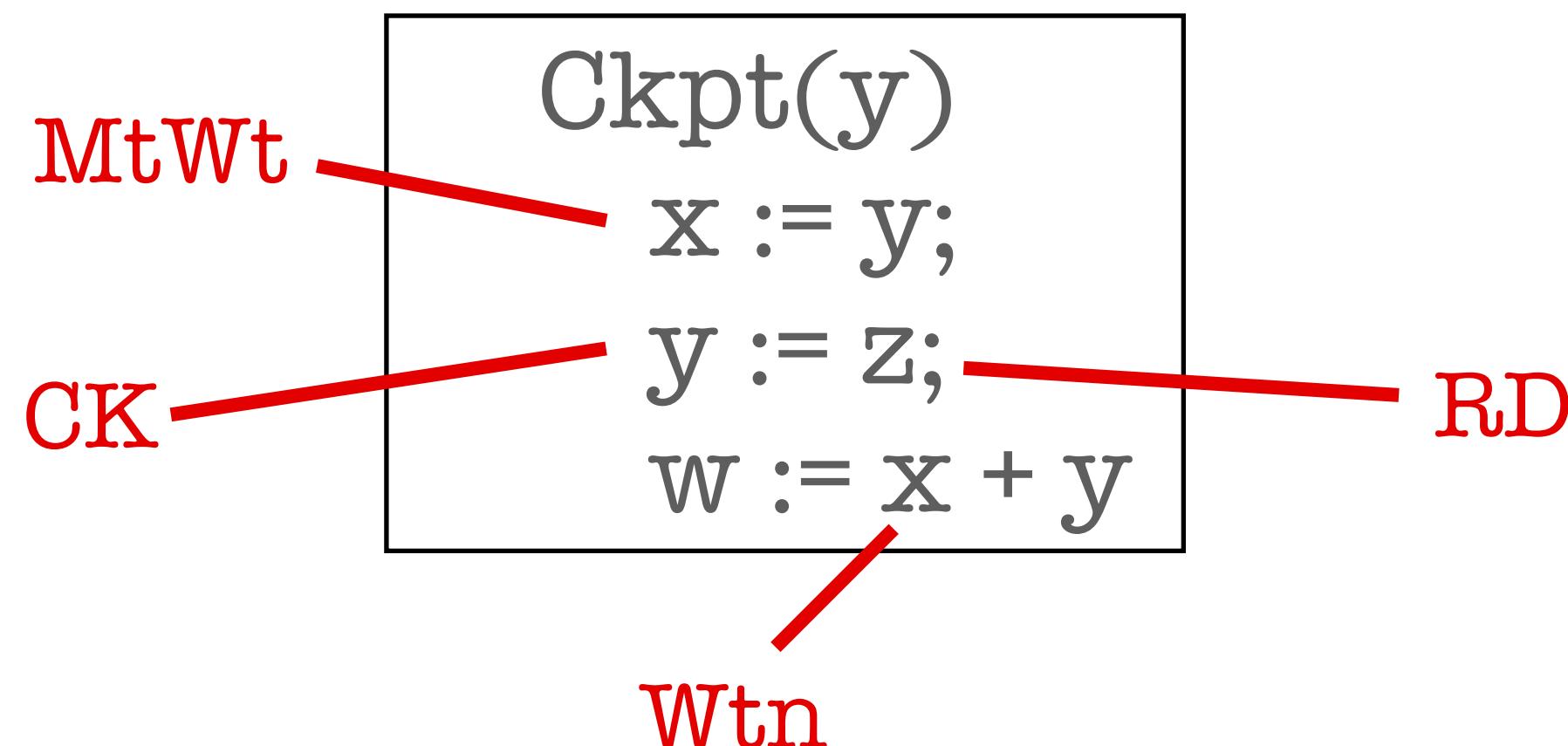
$$q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$$

unstable types

$$\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$$

stable types

$$\tau^s := \uparrow \tau^u \mid \text{[Battery Icon]} \rightsquigarrow \tau^s$$



CK – checkpointer

RD – read only

MtWt – must-first-write

Wtn – written

# Stable and unstable types

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

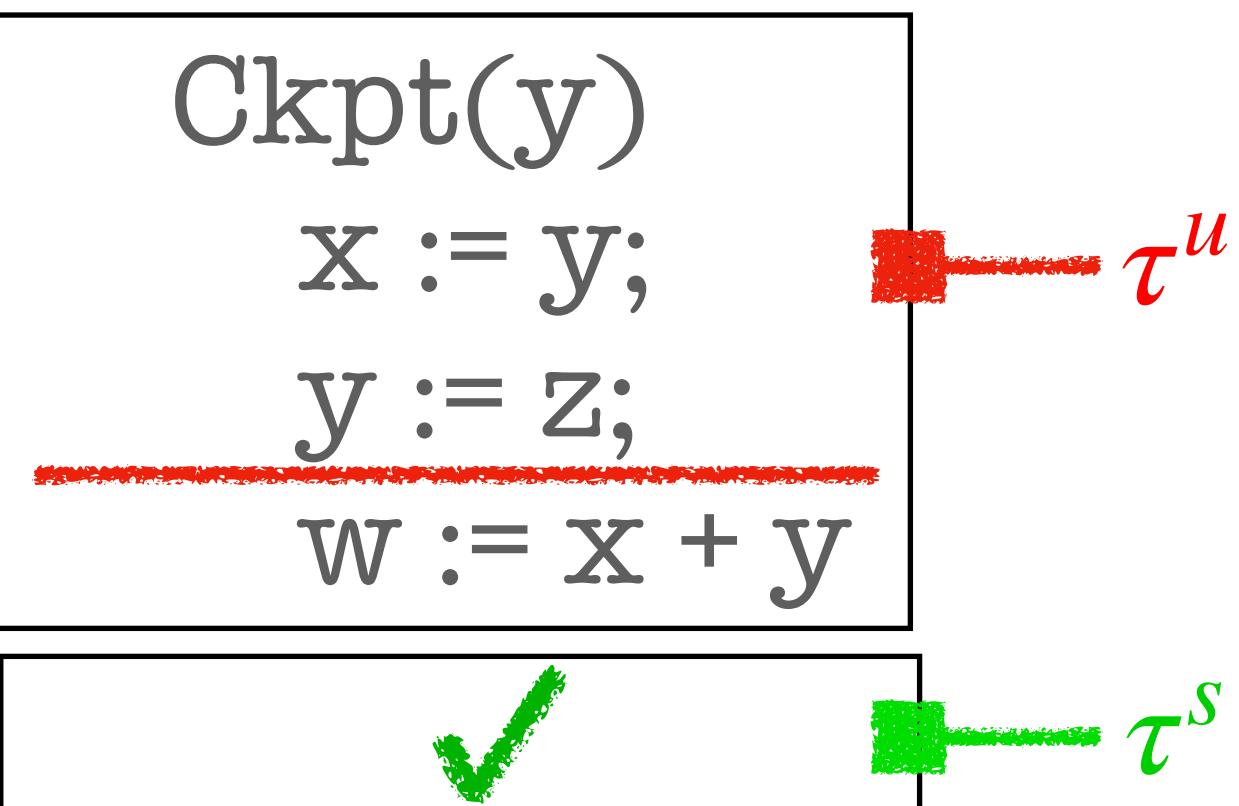
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$

$\tau^u$  code inside of checkpoints

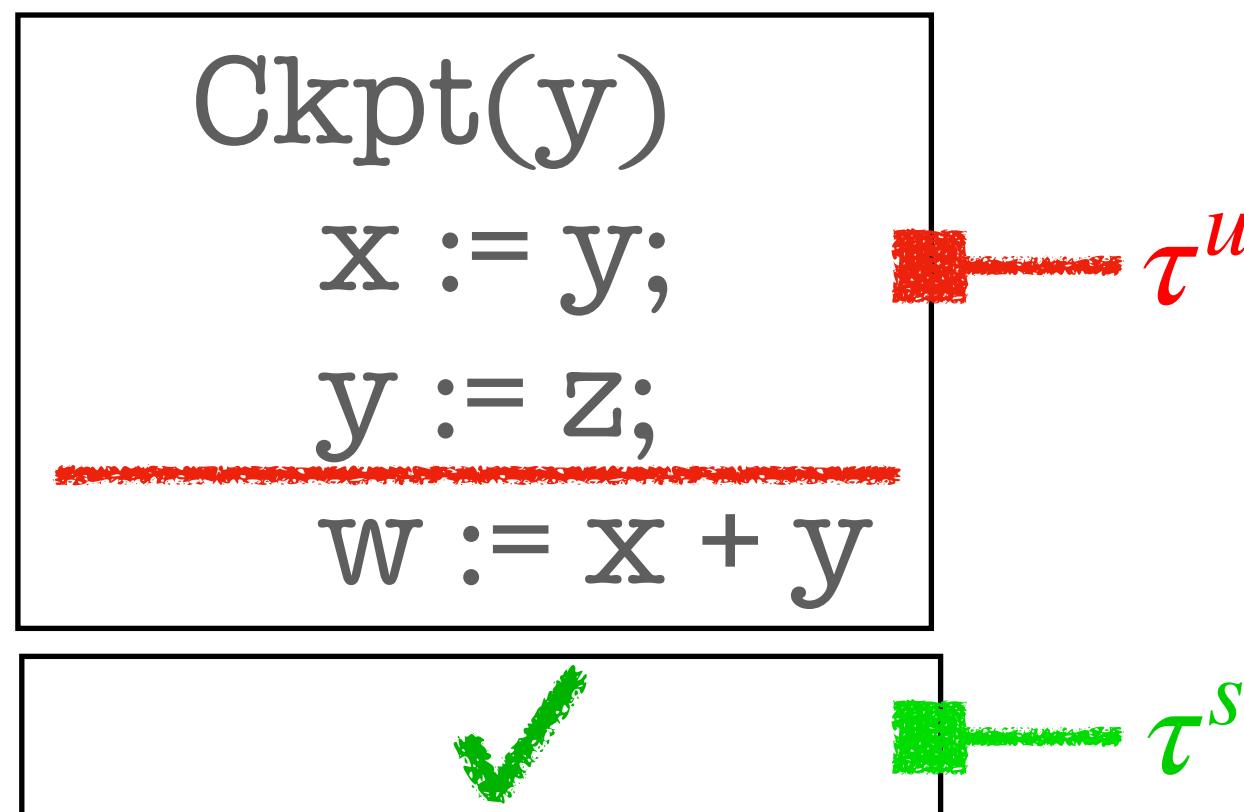
$\tau^s$  programs after commit



# Adjoint Logic\*

|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                      |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$         |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$    |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\text{}} \rightsquigarrow \tau^s$ |

**Independence principle:** universal truth does not depend on ephemeral truth.



\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

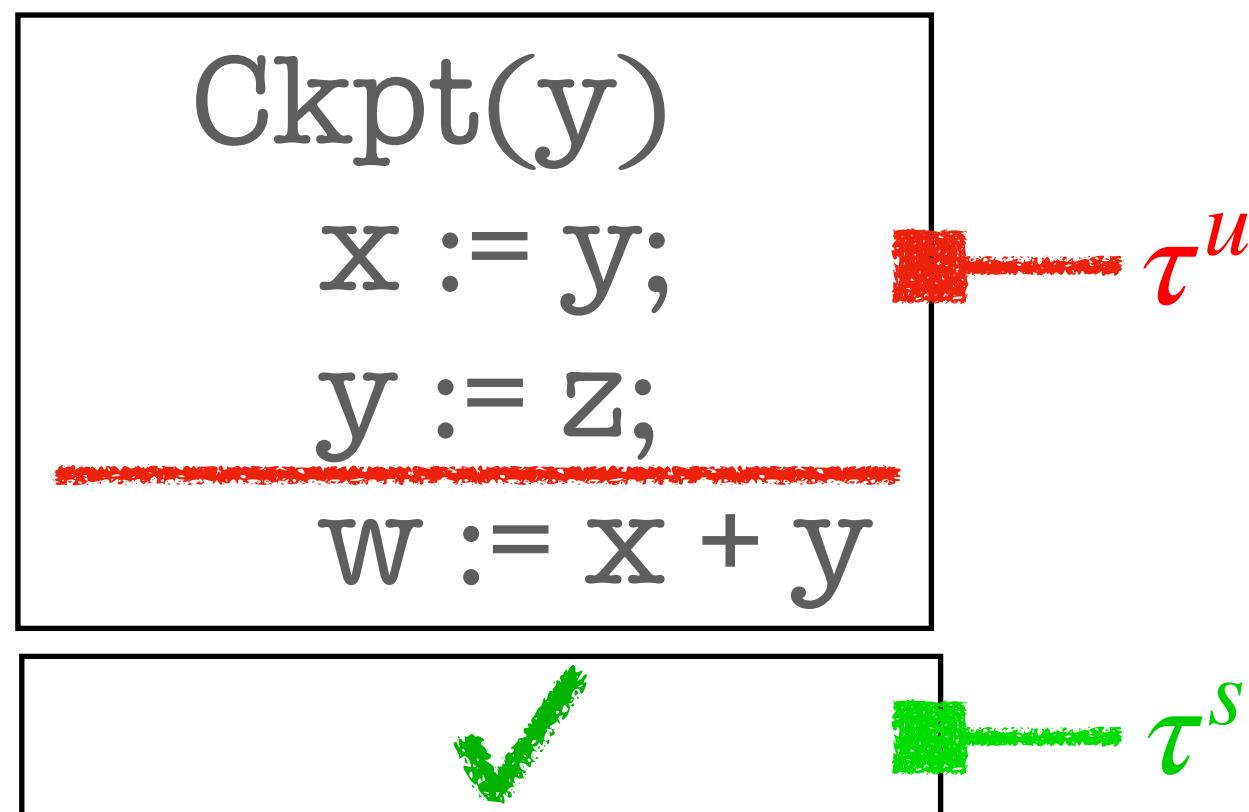
# Adjoint Logic\*

|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                          |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$             |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$        |
| stable types      | $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$ |

**Independence principle:** universal truth does not depend on ephemeral truth.

“It is *always* cold”

“It is cold *today*”



\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Adjoint Logic\*

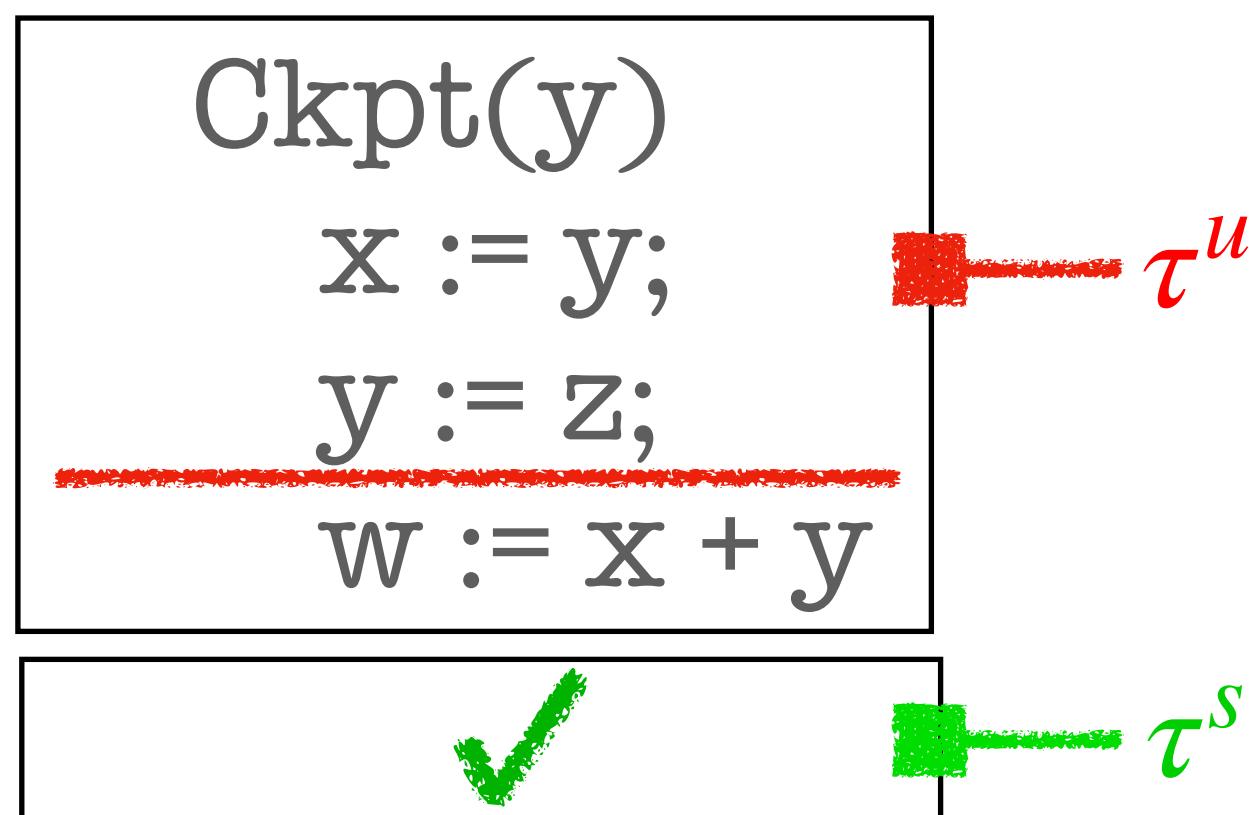
|                   |   |
|-------------------|---|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                   |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$      |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$ |
| stable types      | $\tau^s := \uparrow \tau^u \mid \square \rightsquigarrow \tau^s$      |

**Independence principle:** universal truth does not depend on ephemeral truth.

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\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Adjoint Logic\*

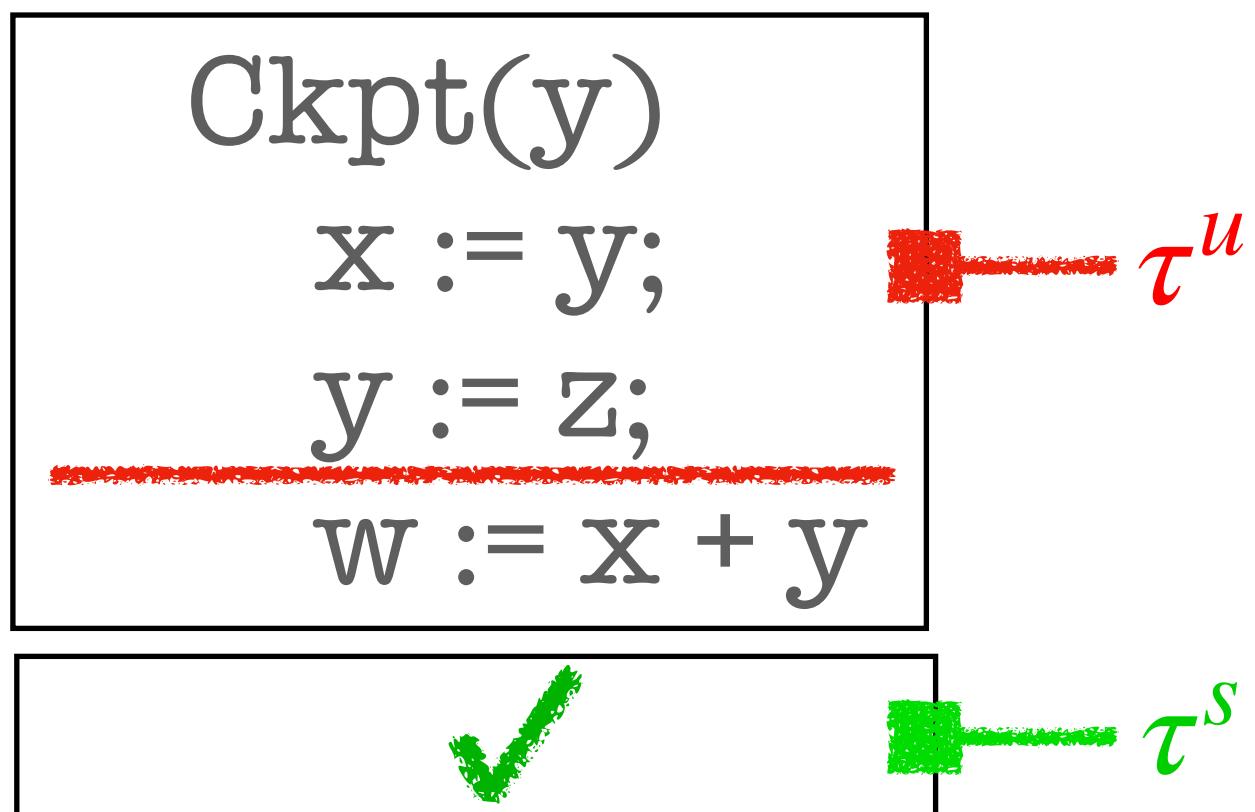
|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                          |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$             |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$        |
| stable types      | $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$ |

**Independence principle:** universal truth does not depend on ephemeral truth.

“It is *always* cold”



“It is cold *today*”



**Here:** stable values ( $s$ ) do not depend on unstable values ( $u$ ).

\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Adjoint Logic\*

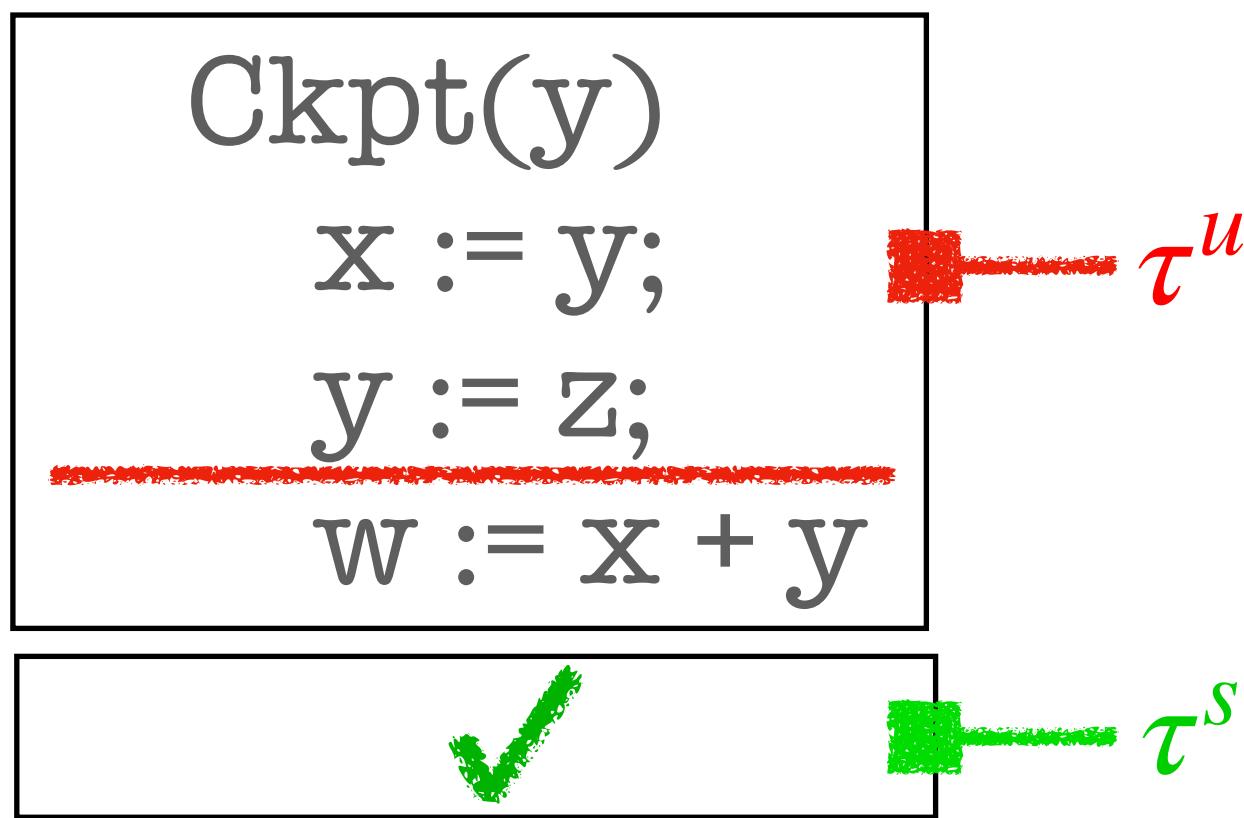
|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                          |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$             |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$        |
| stable types      | $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$ |

**Independence principle:** universal truth does not depend on ephemeral truth.

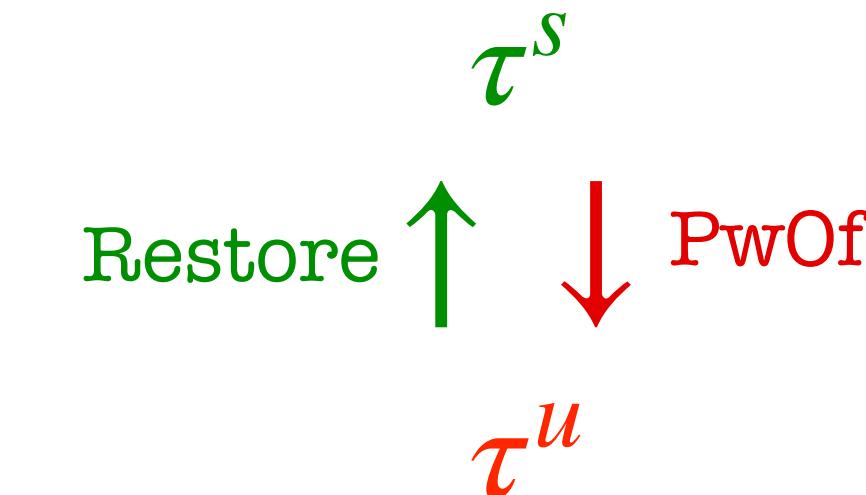
“It is *always* cold”



“It is cold *today*”



**Here:** stable values ( $s$ ) do not depend on unstable values ( $u$ ).



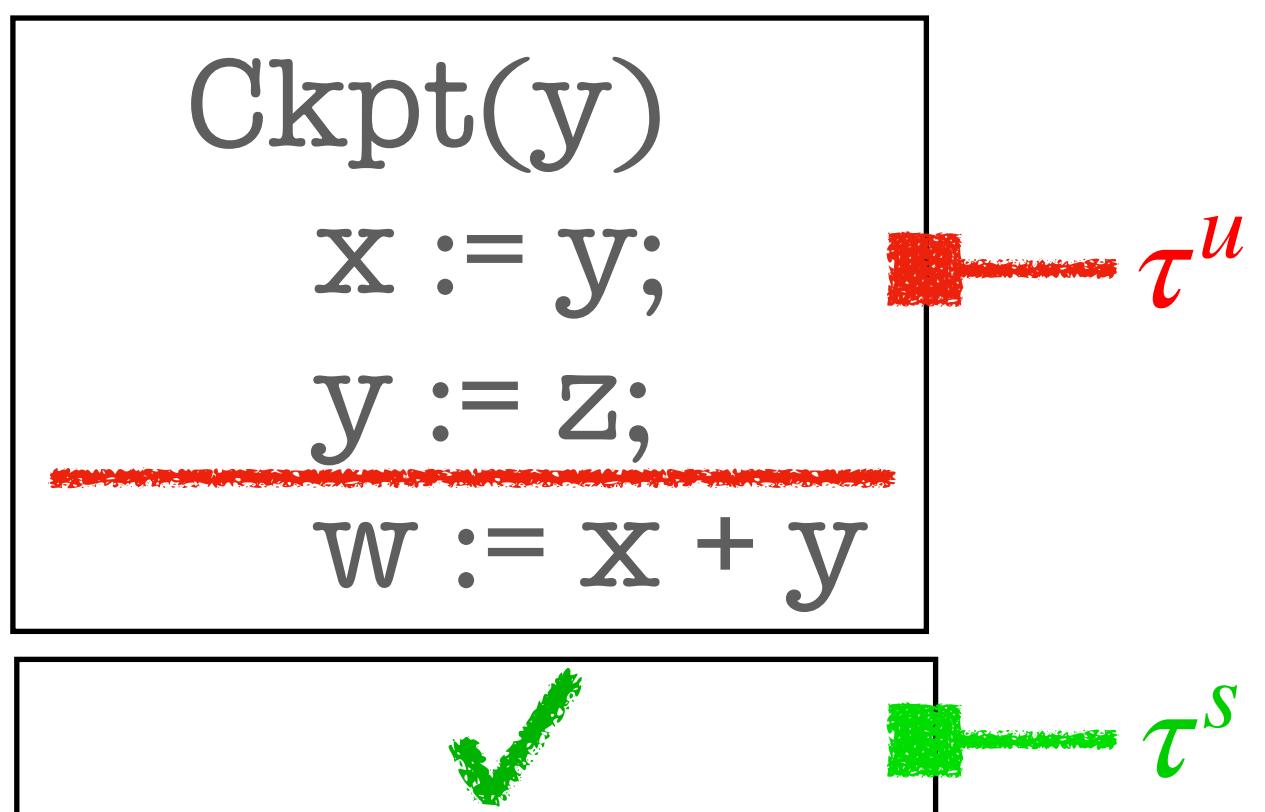
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$



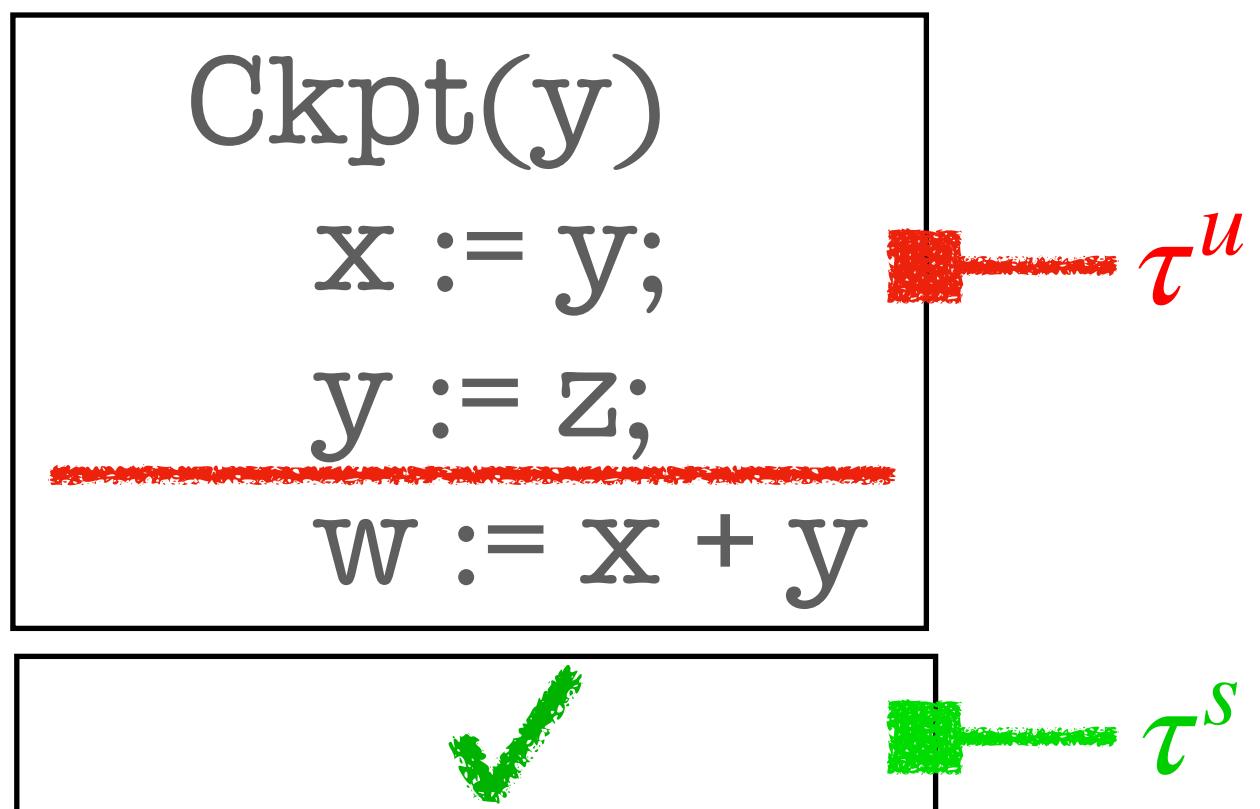
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

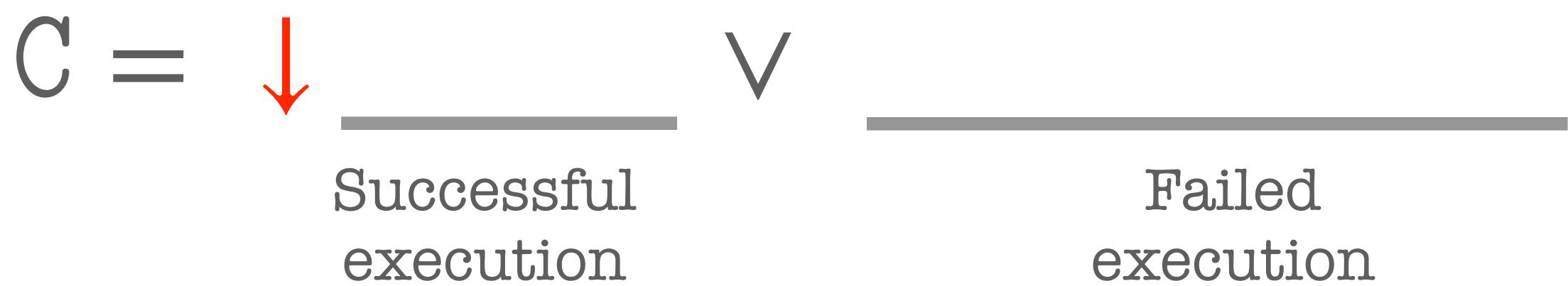
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{Battery icon} \rightsquigarrow \tau^s$



Commit



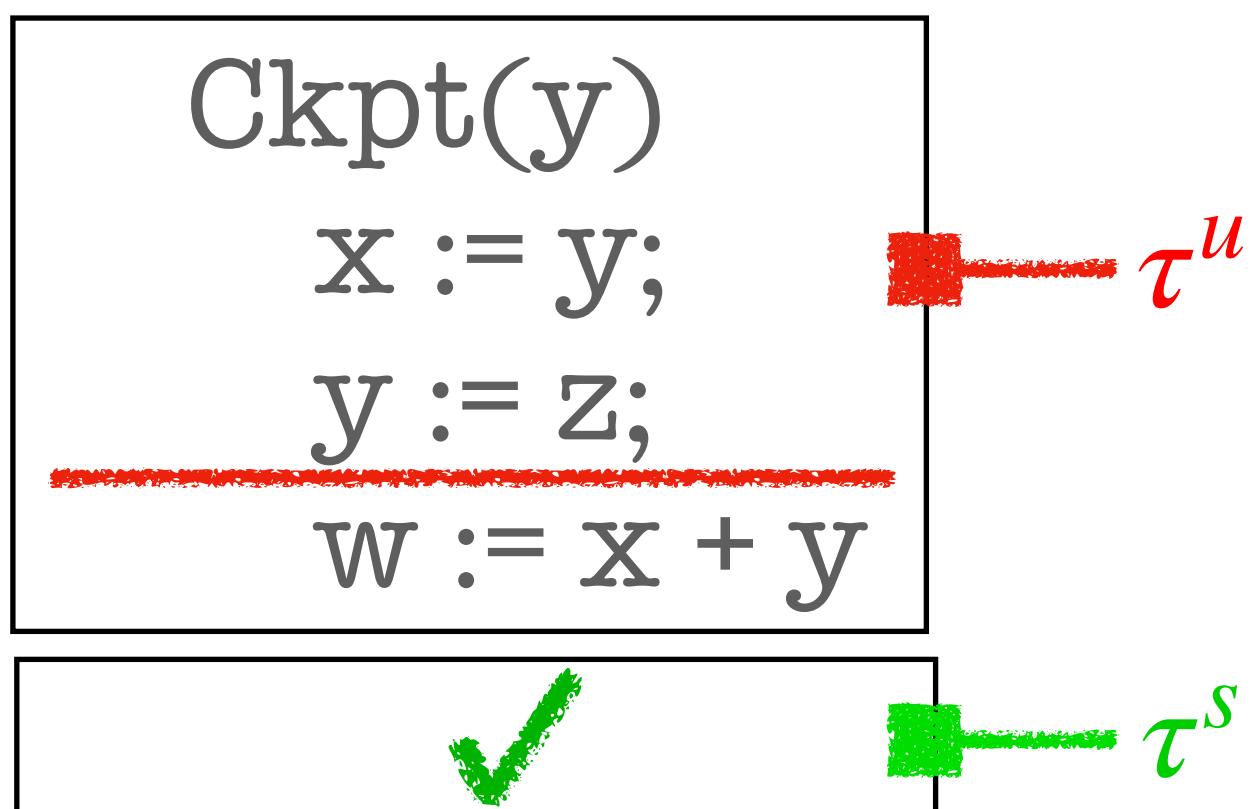
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$



$C = \downarrow \uparrow \text{unit} \vee$

Successful  
execution

Failed  
execution

Success!

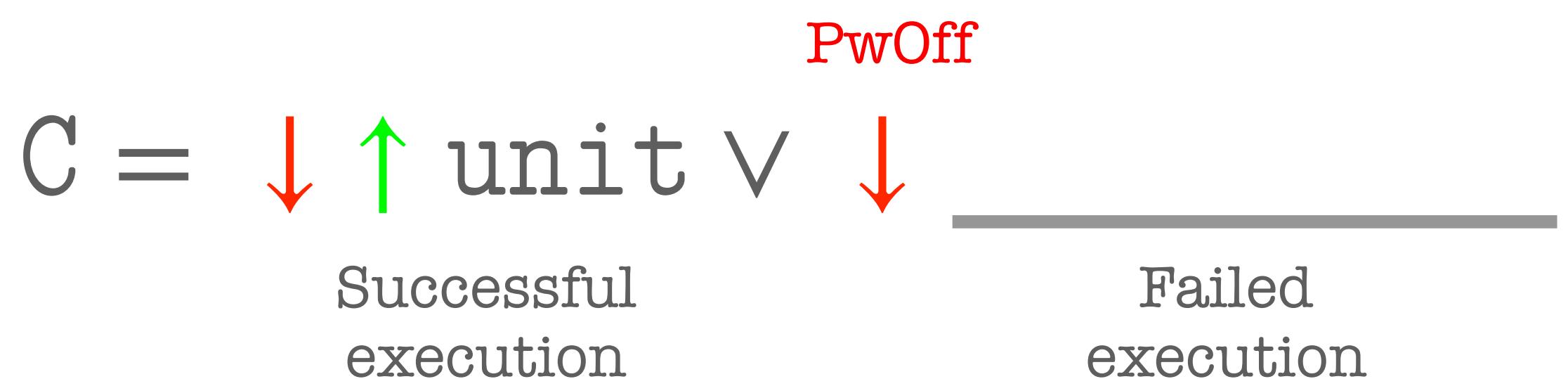
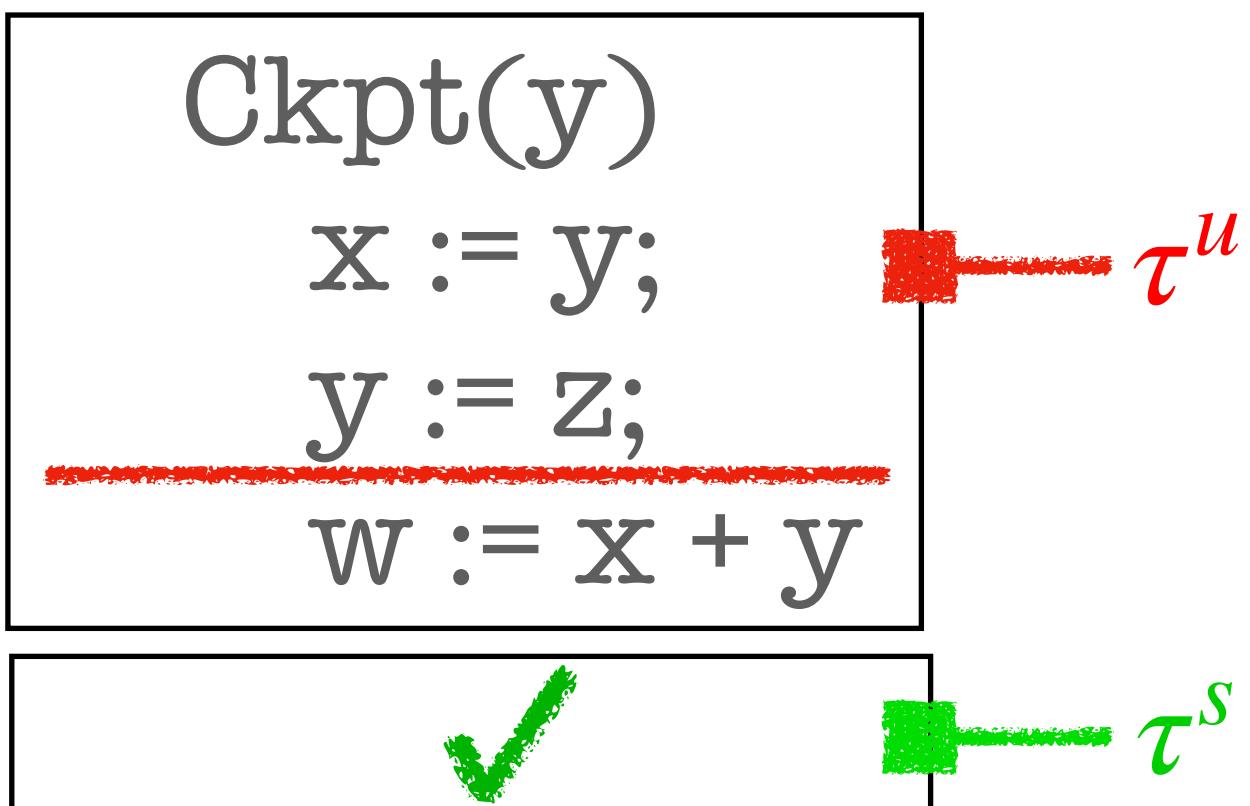
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{Battery icon} \rightsquigarrow \tau^s$



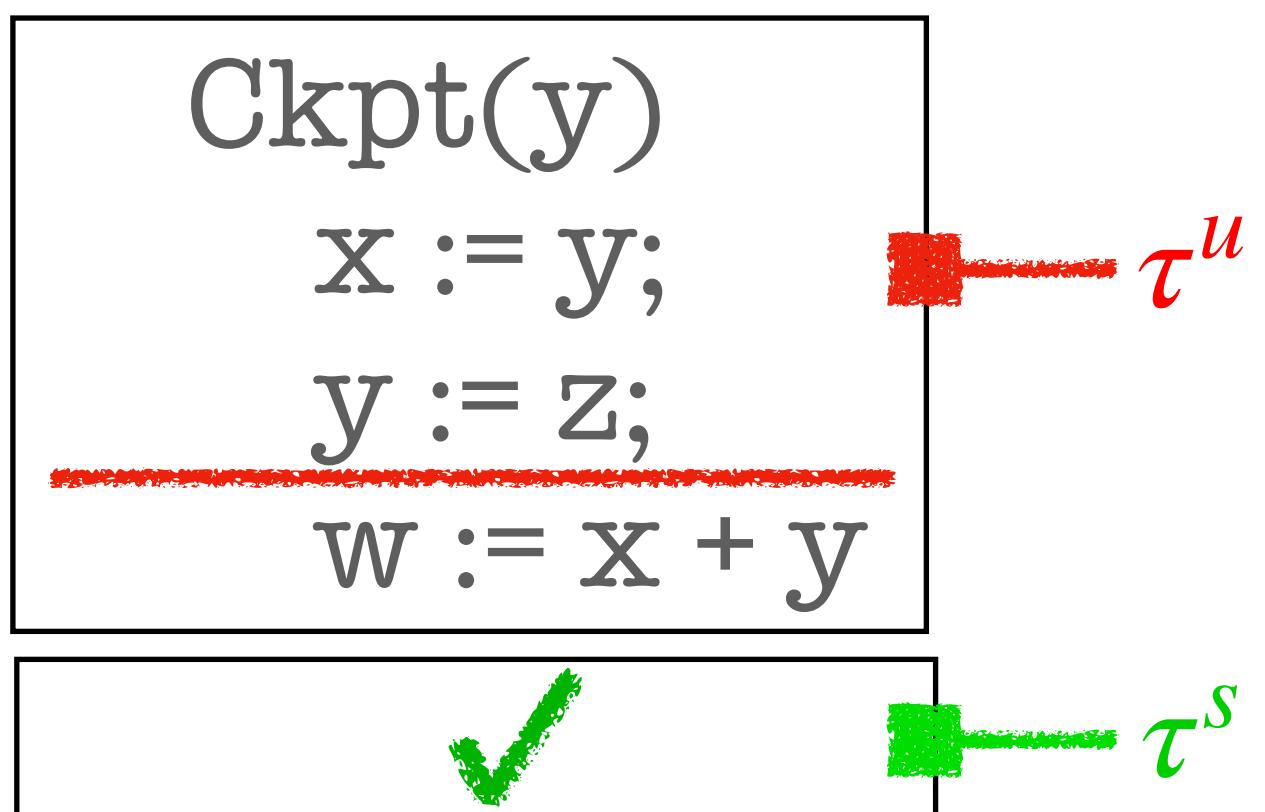
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{battery}} \rightsquigarrow \tau^s$



$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\boxed{\text{battery}} \rightsquigarrow \underline{\quad})$$

Harvest

Successful execution

Failed execution

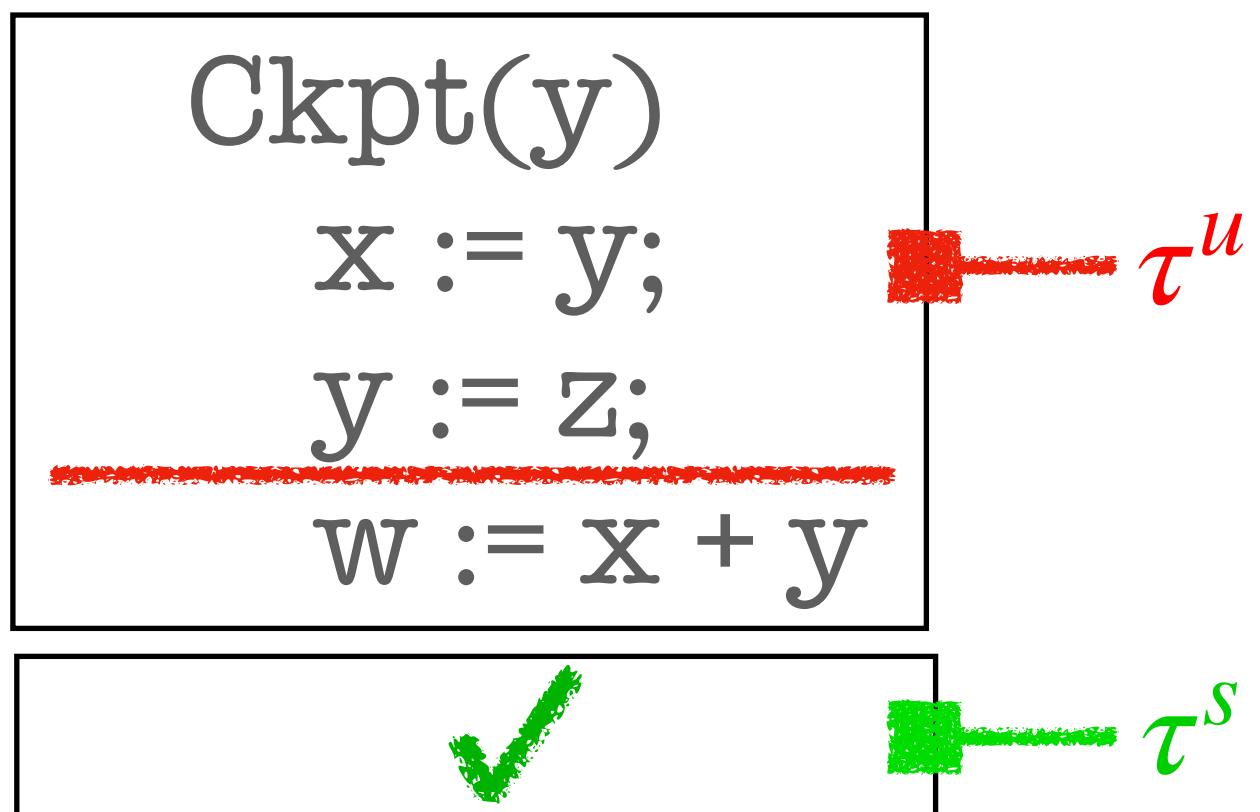
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{battery}} \rightsquigarrow \tau^s$



$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\boxed{\text{battery}} \rightsquigarrow \uparrow \_)$$

↓ ↑ Successful execution      Failed execution  
Restore

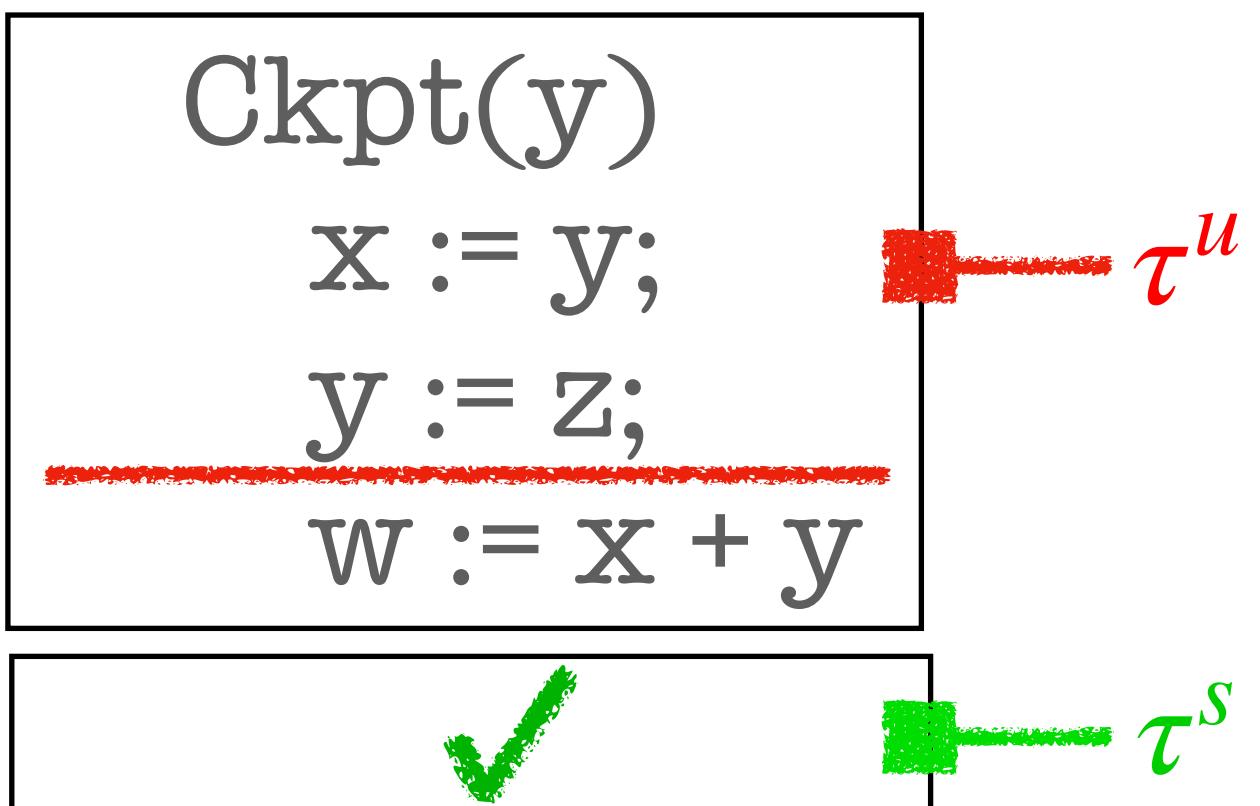
# Crash Type

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{battery}} \rightsquigarrow \tau^s$



$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\boxed{\text{battery}} \rightsquigarrow \uparrow C)$$

Successful execution                                    Failed execution

Re-execute

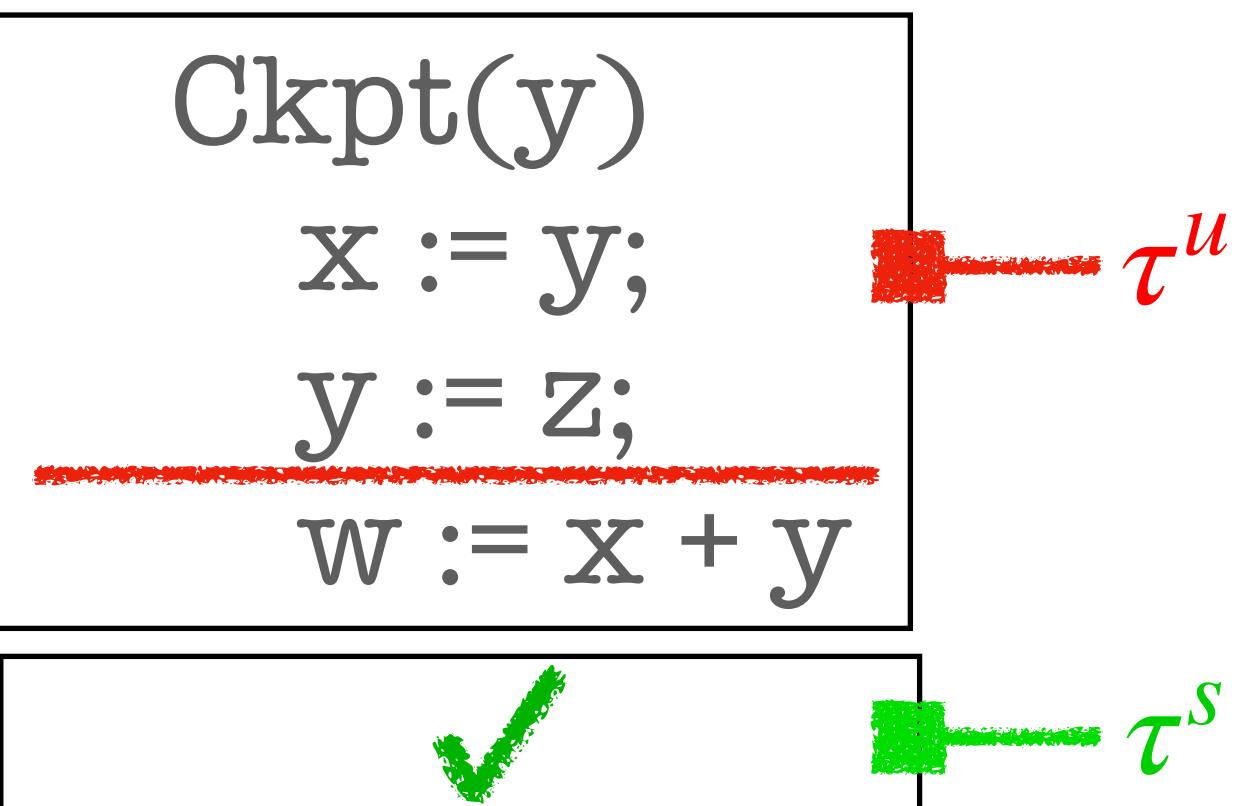
# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$



# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

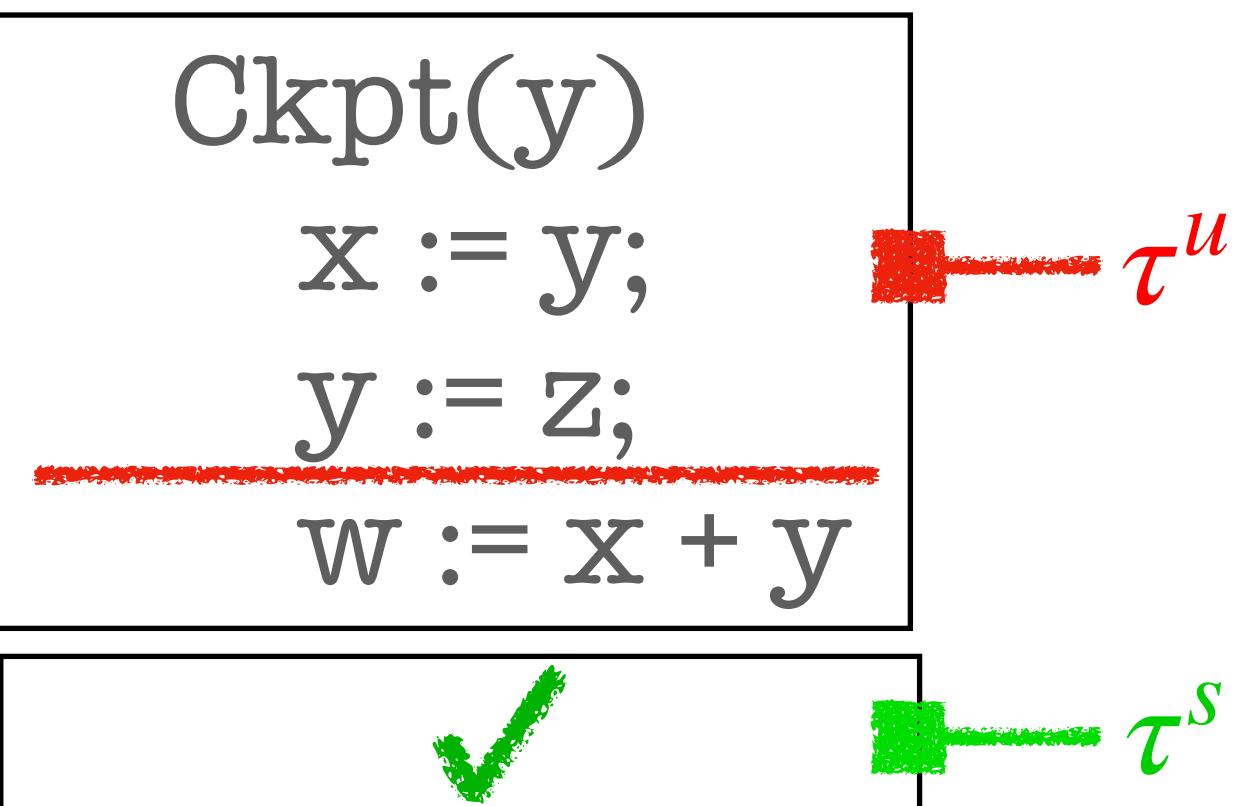
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$

**Unstable** typing judgment

$\vdash$



**Stable** typing judgment

$\vdash$

# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

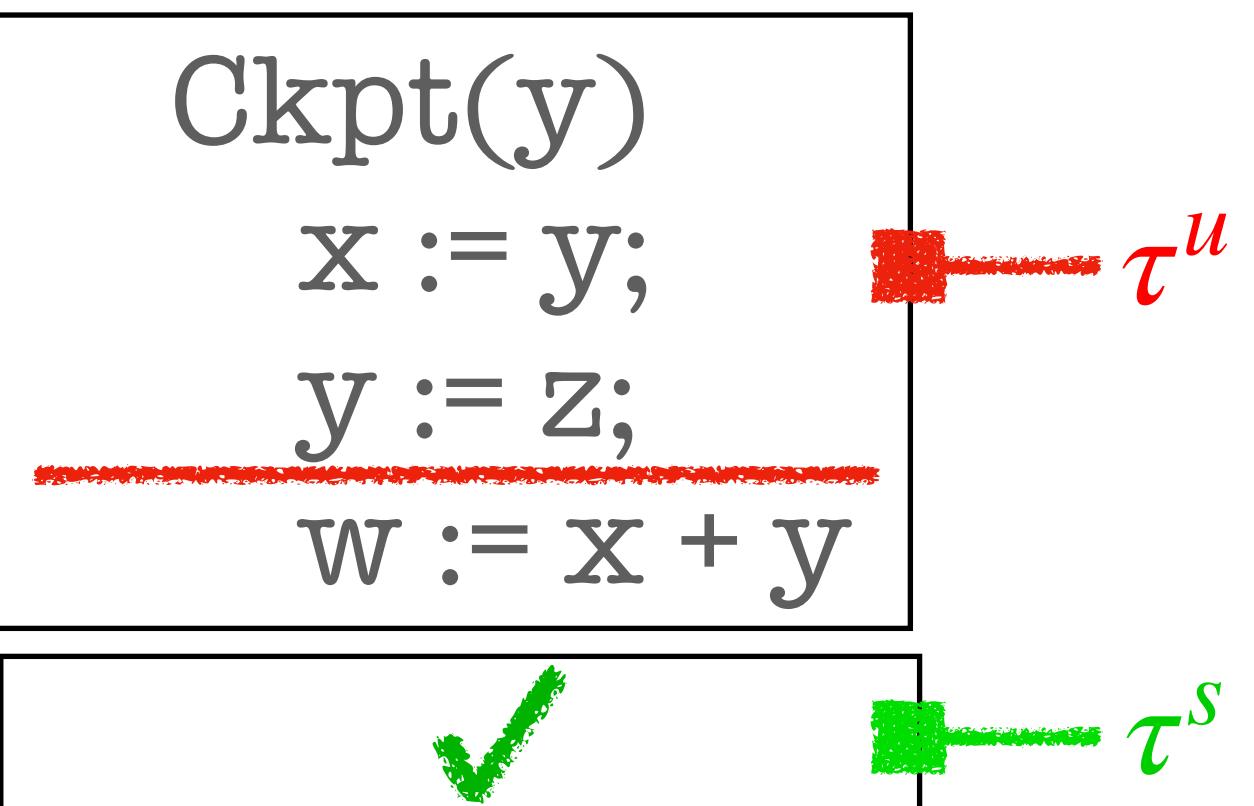
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$

**Unstable** typing judgment

$\vdash x := y : C$

Command is  
well-typed



**Stable** typing judgment

$\vdash$

# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

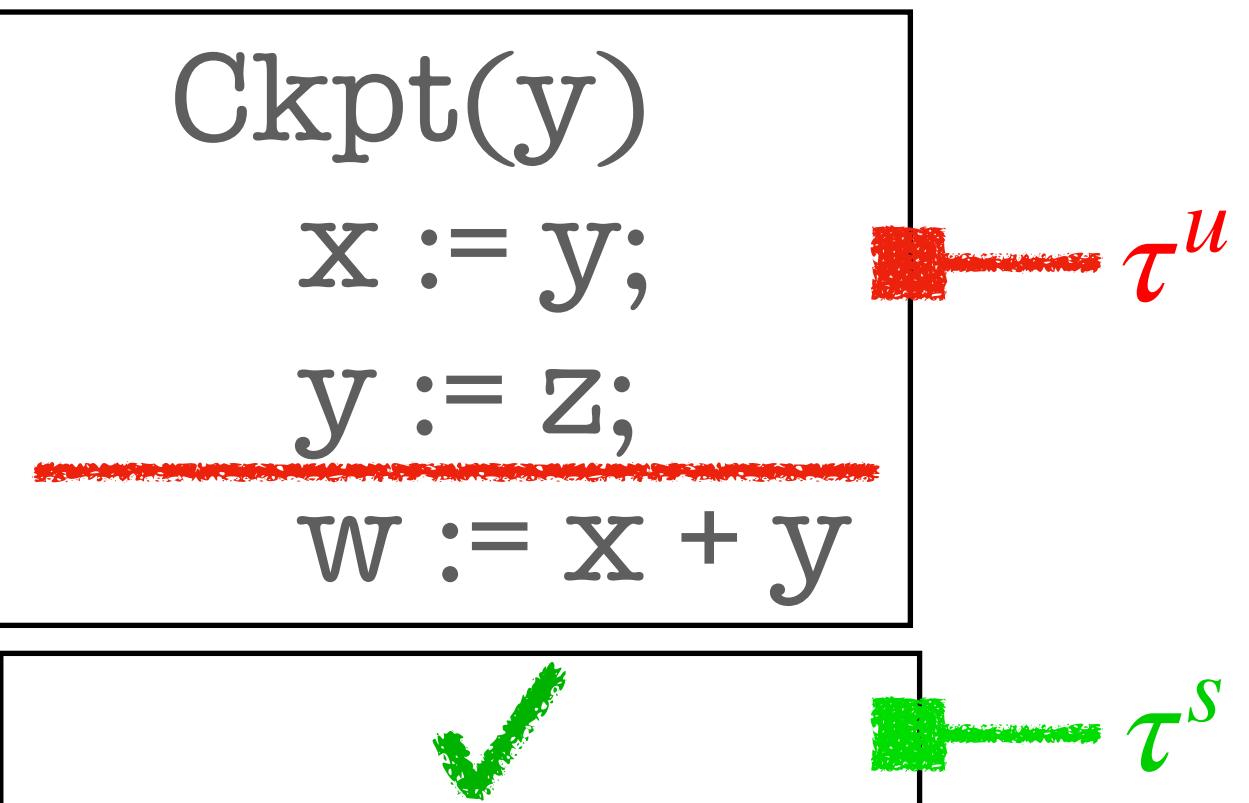
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \text{battery icon} \rightsquigarrow \tau^s$

**Unstable** typing judgment



Energy  
buffer

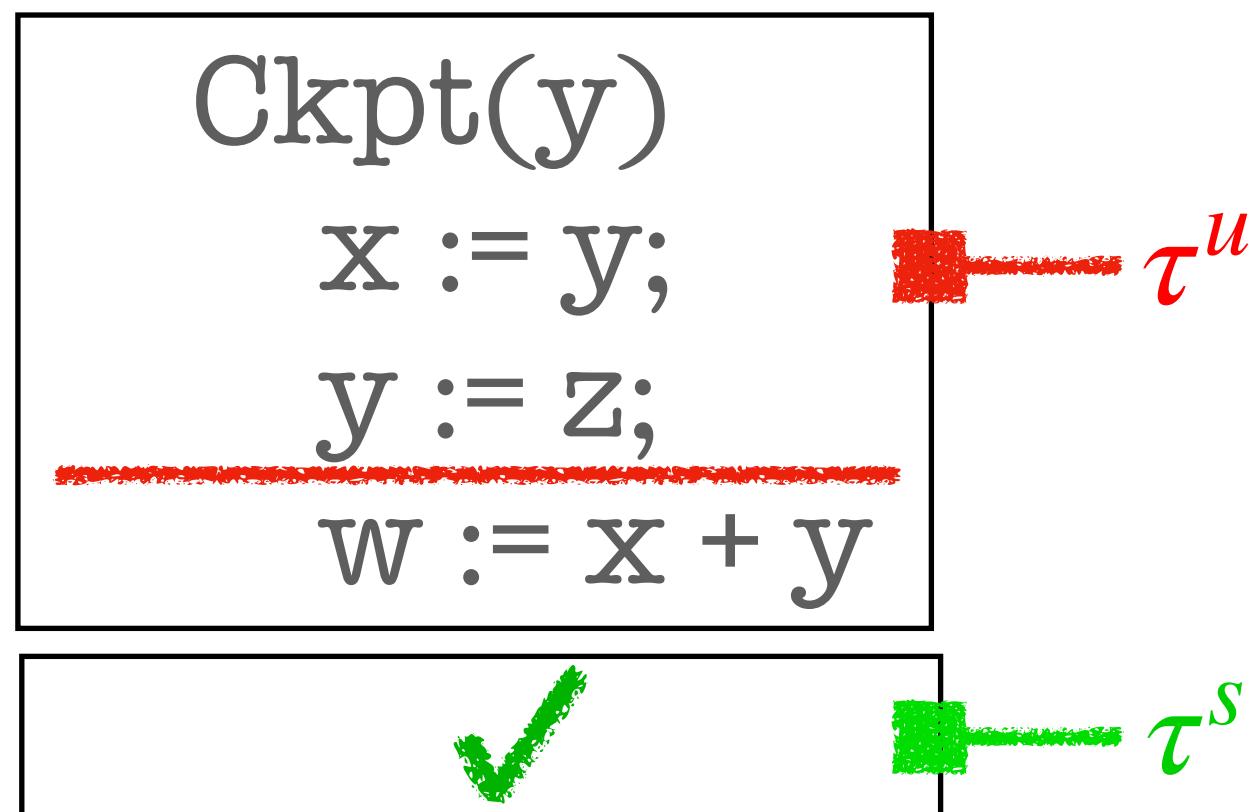


**Stable** typing judgment



# Typing judgments

|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                          |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$             |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$        |
| stable types      | $\tau^s := \uparrow \tau^u \mid \text{Battery icon} \rightsquigarrow \tau^s$ |



## Unstable typing judgment

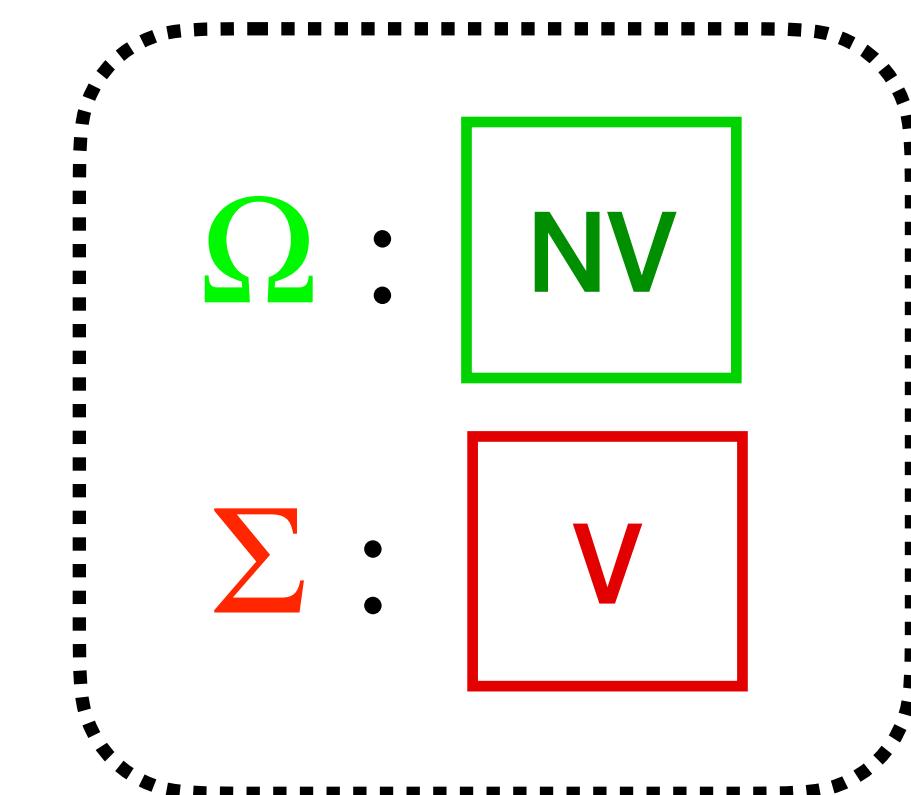
$$\text{Battery icon} \mid \Omega \mid \Sigma \vdash x := y : C$$

Energy  
buffer

NV+V  
typing  
contexts

## Stable typing judgment

$\vdash$



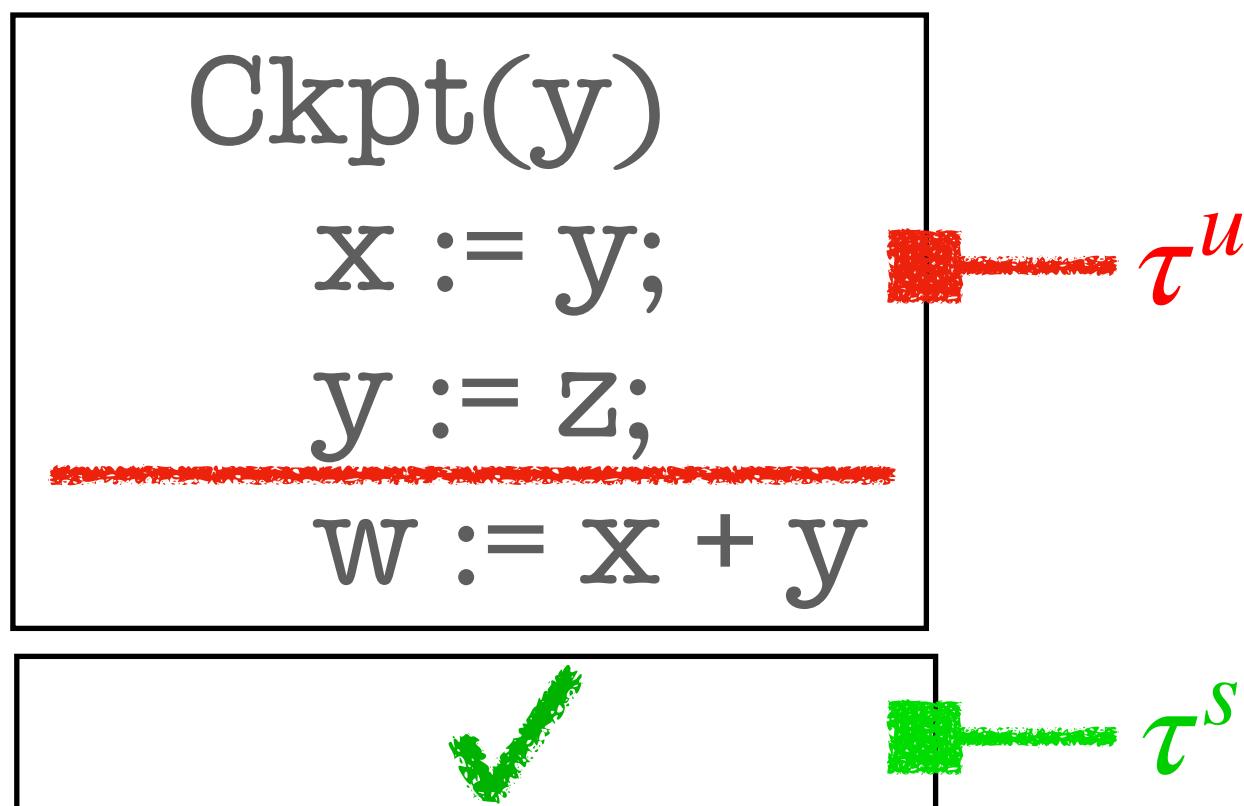
# Typing judgments

basic types       $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types       $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types       $\tau^s := \uparrow \tau^u$  |   $\rightsquigarrow \tau^s$



# Unstable typing judgment

$x : \tau^s$      $y : \tau^u$



# Energy buffer

# NV+V typing contexts

## Post- context

# Stable typing judgment

1

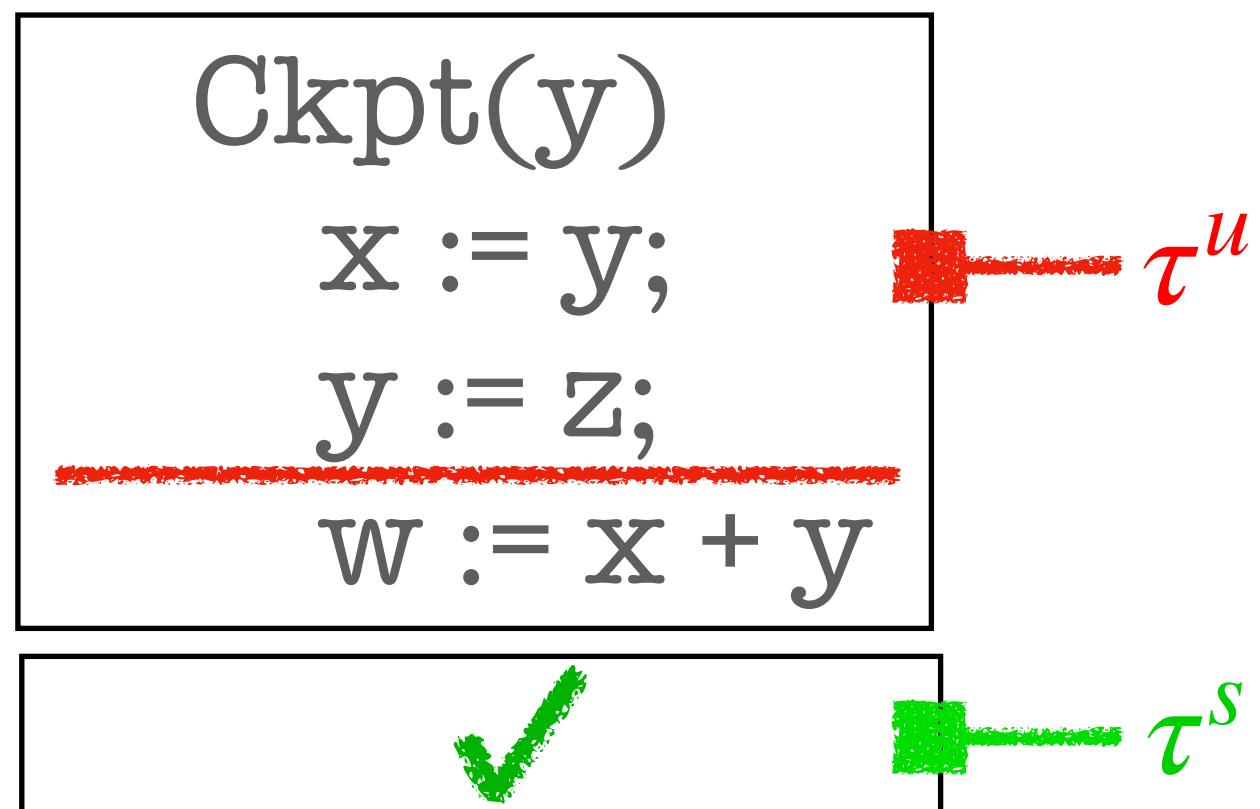
# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{battery}} \rightsquigarrow \tau^s$



**Unstable** typing judgment

$$\boxed{x : \tau^s} \quad \boxed{y : \tau^u} \\ \boxed{\text{battery}} \mid \Omega \mid \Sigma \vdash x := y : C \dashv \Omega'$$

Energy  
buffer

NV+V  
typing  
contexts

Post-  
context

**Stable** typing judgment

$$\boxed{x : \tau^s} \\ \boxed{\text{battery}} \mid \Omega \vdash \text{Ckpt} \boxed{x := y;  
y := z;  
w := x + y;} : \uparrow C$$

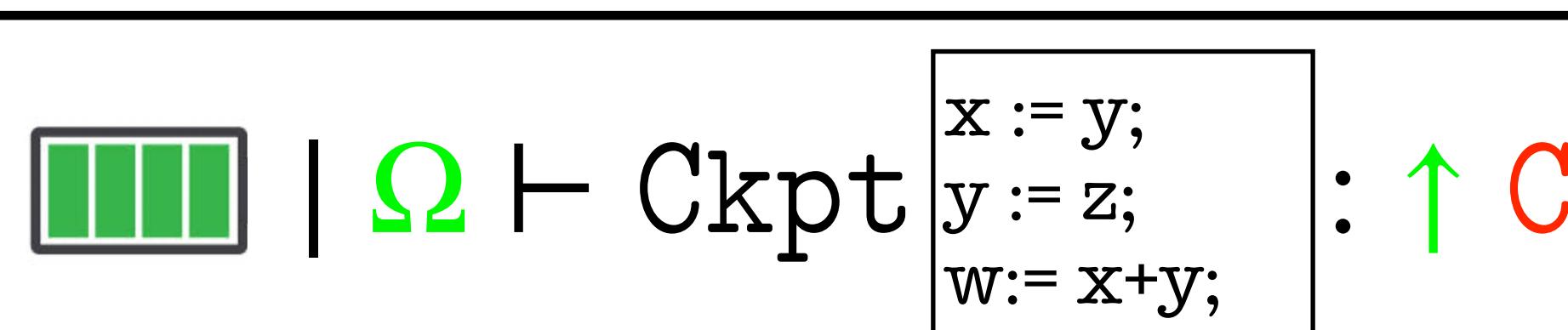
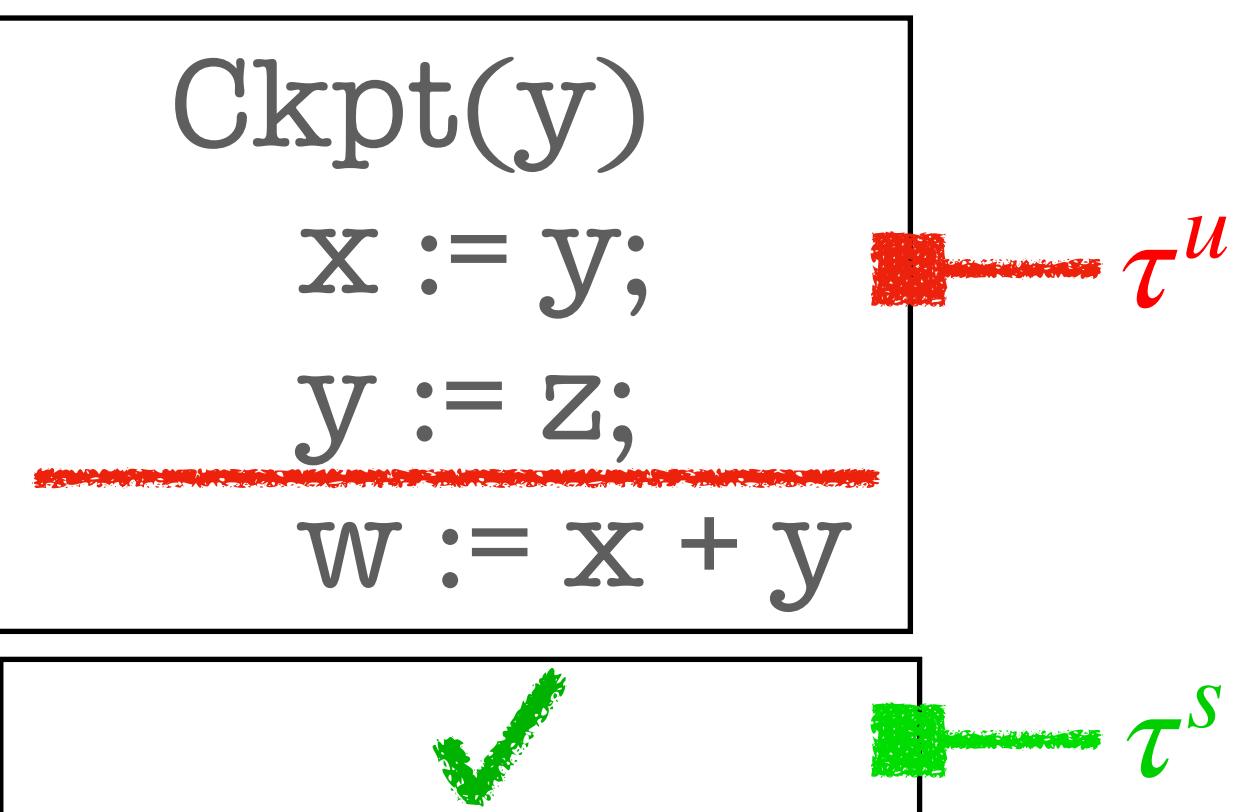
# Typing a program bottom-up

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{}} \rightsquigarrow \tau^s$



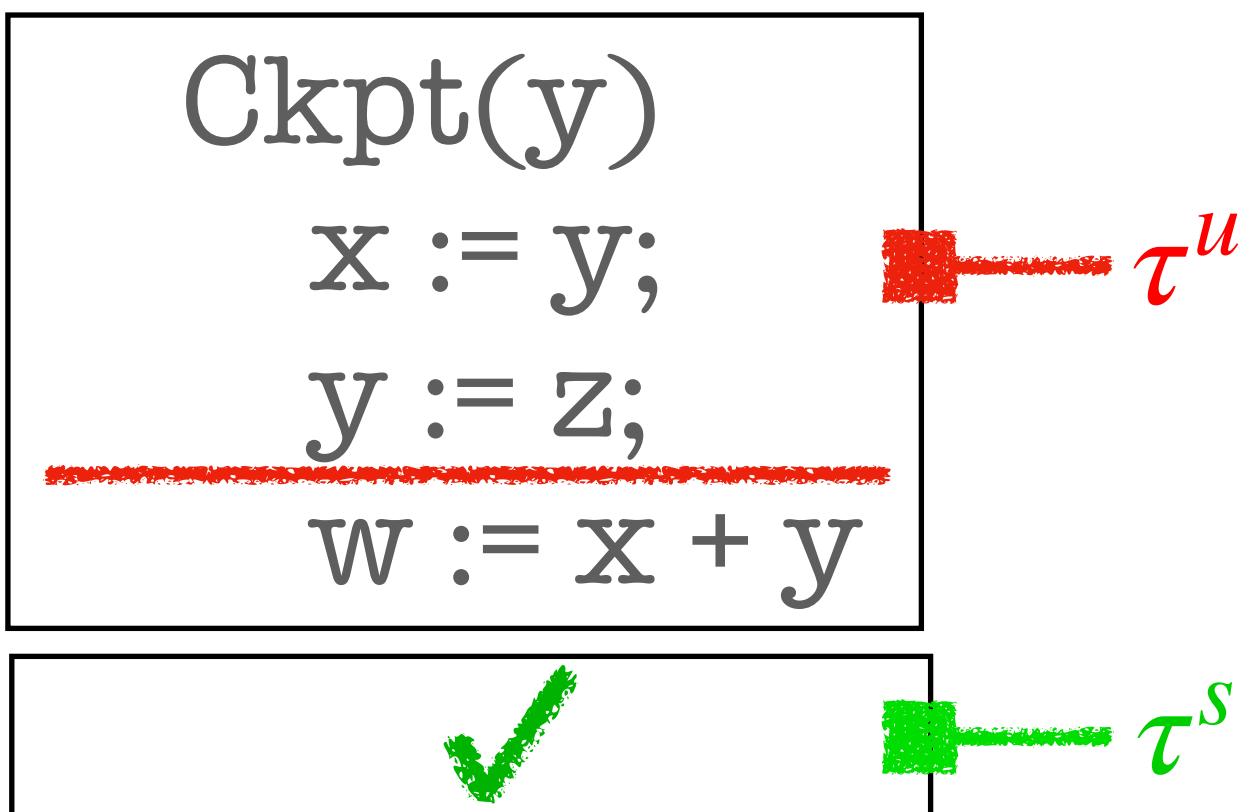
# Typing a command

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{}} \rightsquigarrow \tau^s$



$$\boxed{\text{}} \mid \Omega \mid \Sigma \vdash x := y; \\ y := z; \\ w := x + y : C \dashv \Omega''$$

$$\boxed{\text{}} \mid \Omega \vdash \text{Ckpt} \boxed{x := y; \\ y := z; \\ w := x + y;} : \uparrow C$$

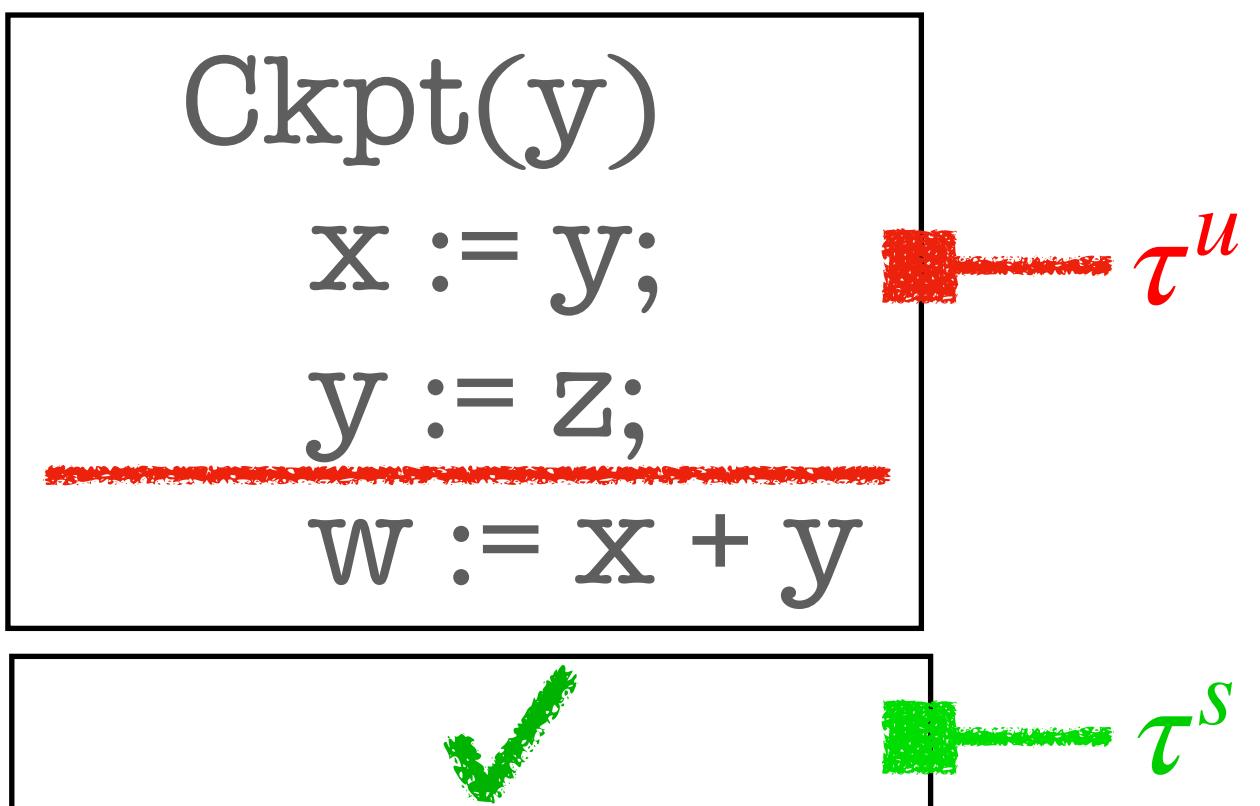
# Typing a smaller command

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{████}} \rightsquigarrow \tau^s$



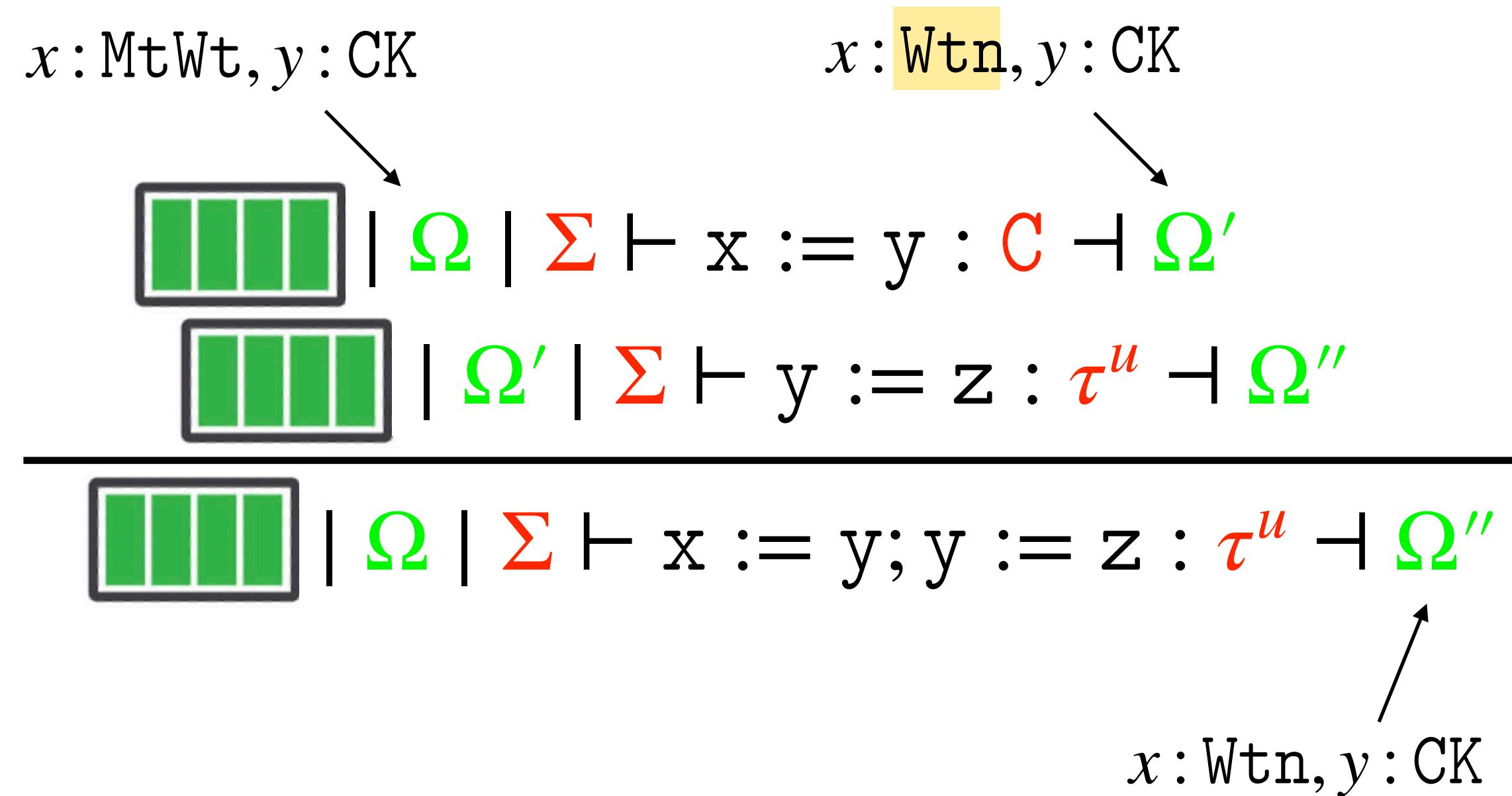
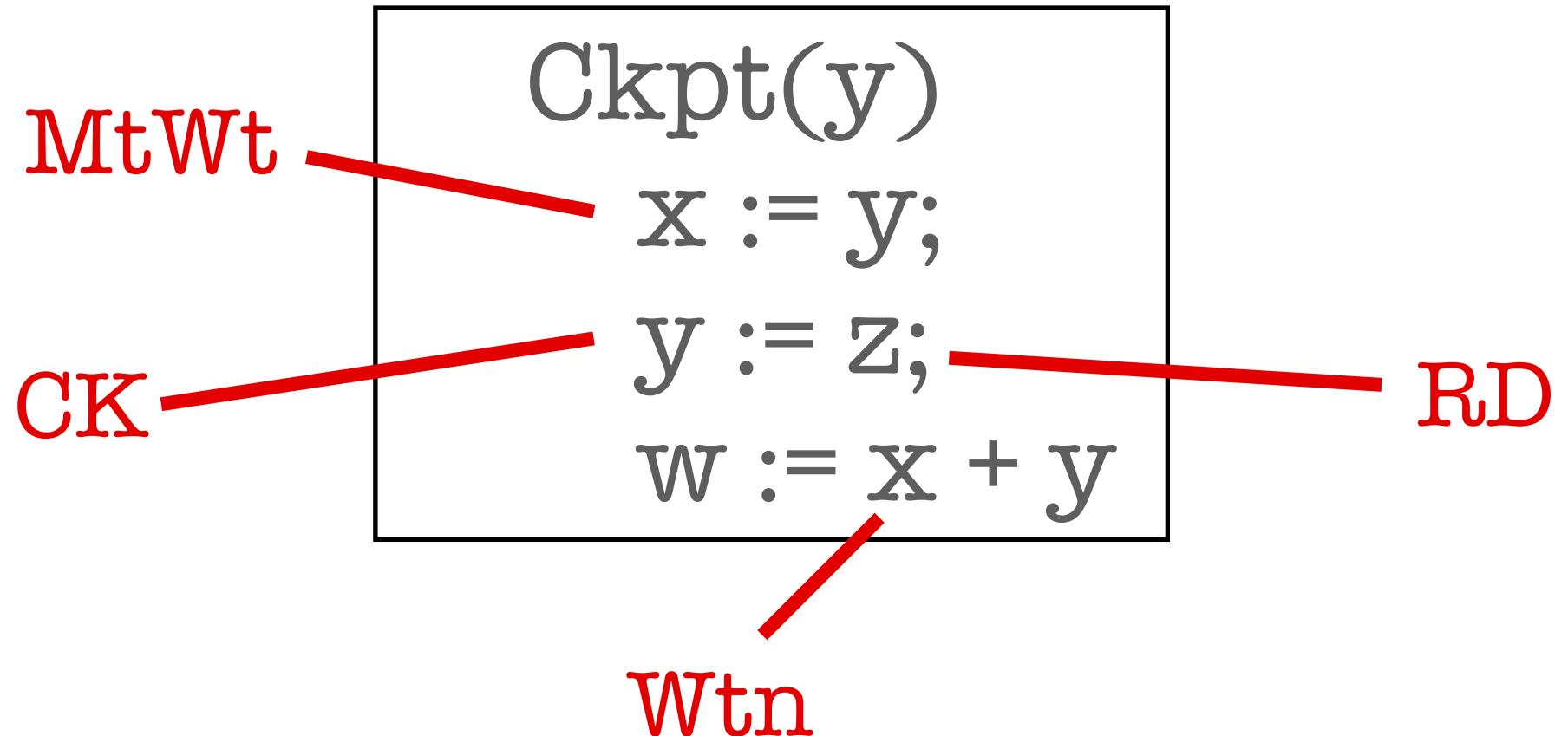
$$\boxed{\text{████}} \mid \Omega \mid \Sigma \vdash x := y; \\ y := z : \text{C} \dashv \Omega'' \\ \dots$$

$$\boxed{\text{████}} \mid \Omega \mid \Sigma \vdash x := y; \\ y := z; \\ w := x + y : \text{C} \dashv \Omega'''$$

$$\boxed{\text{████}} \mid \Omega \vdash \text{Ckpt} \boxed{x := y; \\ y := z; \\ w := x + y} : \uparrow \text{C}$$

# Type checking $x := y; y := z$

|                   |  |
|-------------------|--|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                      |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$         |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$    |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\text{}} \rightsquigarrow \tau^s$ |

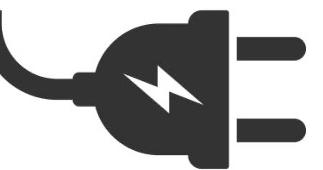


# Example

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



| NV   | x  | y  | z    | w |
|------|----|----|------|---|
| MtWt | CK | RD | MtWt |   |
|      | 0  | 1  | 2    | 0 |



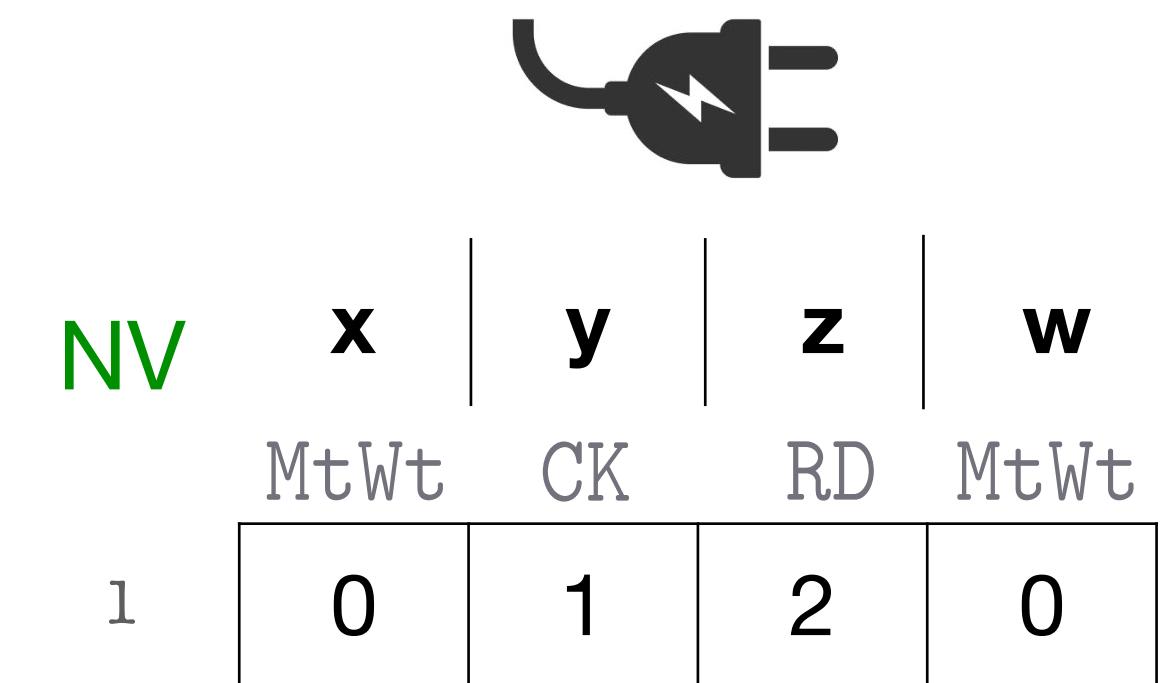
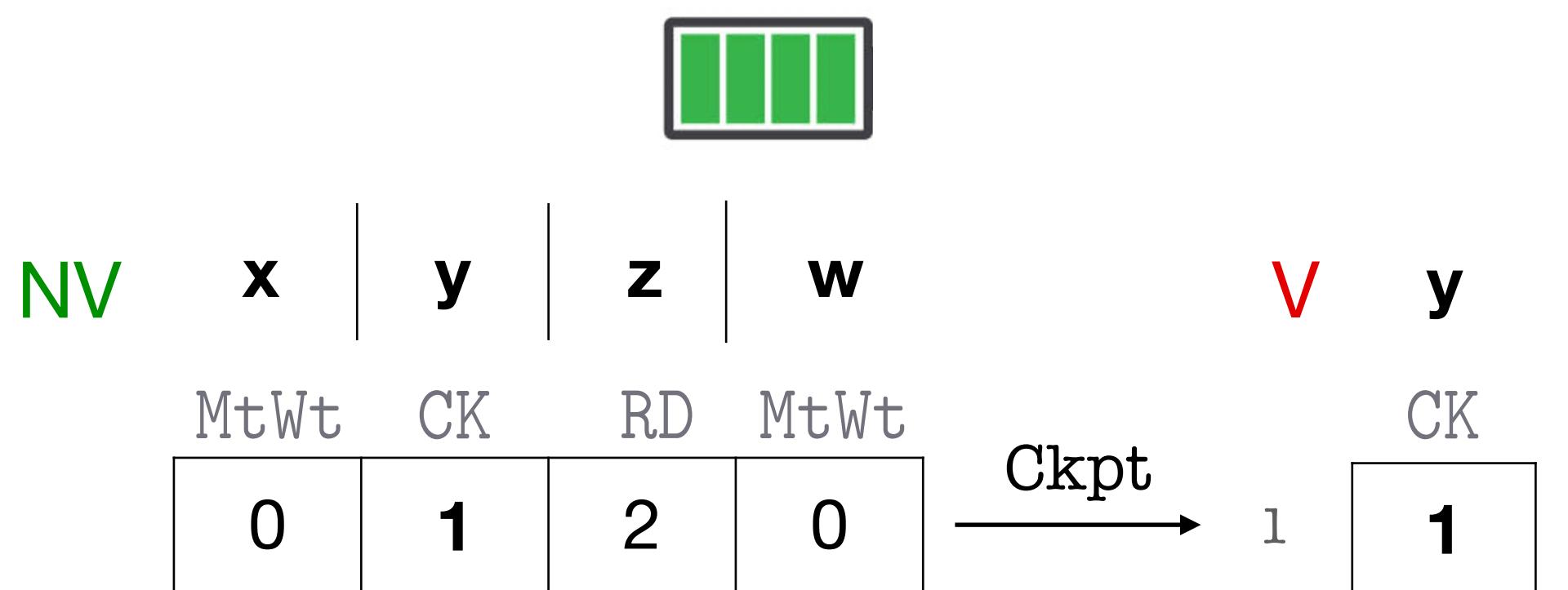
| NV   | x  | y  | z    | w |
|------|----|----|------|---|
| MtWt | CK | RD | MtWt |   |
| 1    | 0  | 1  | 2    | 0 |

# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

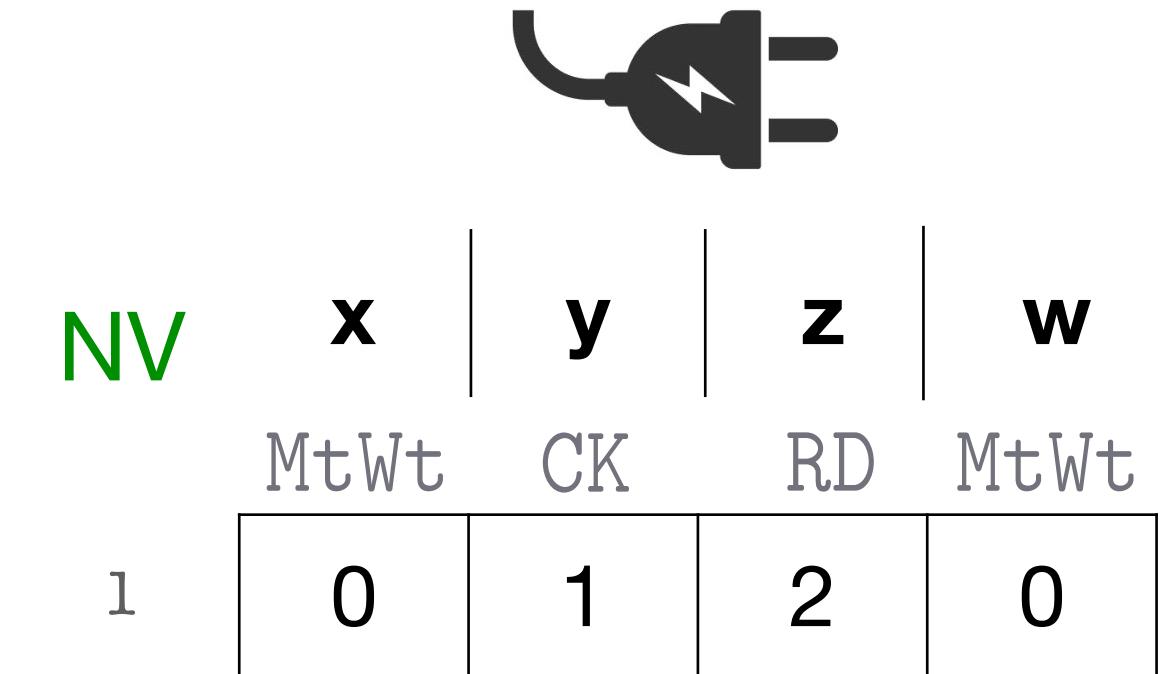
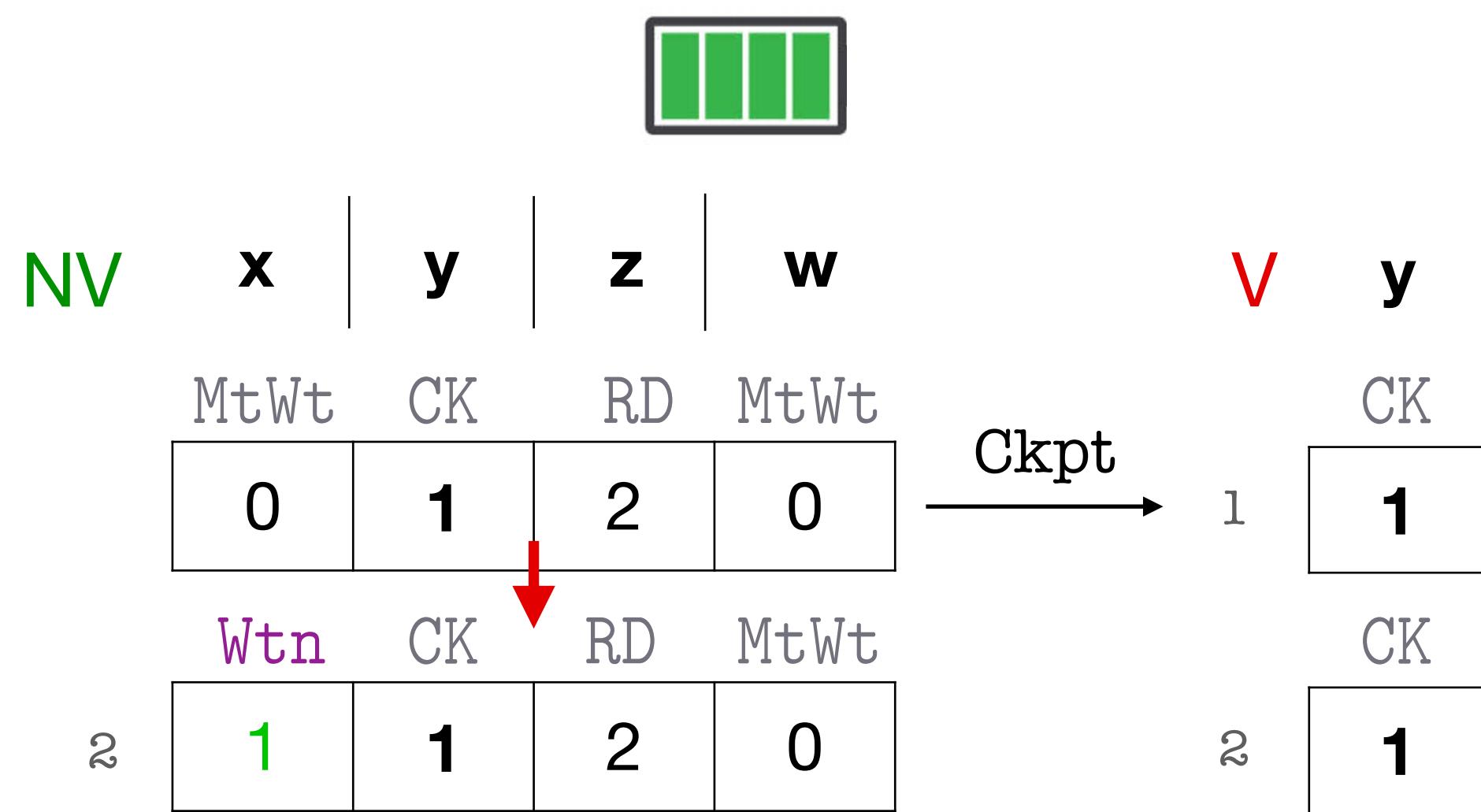


# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

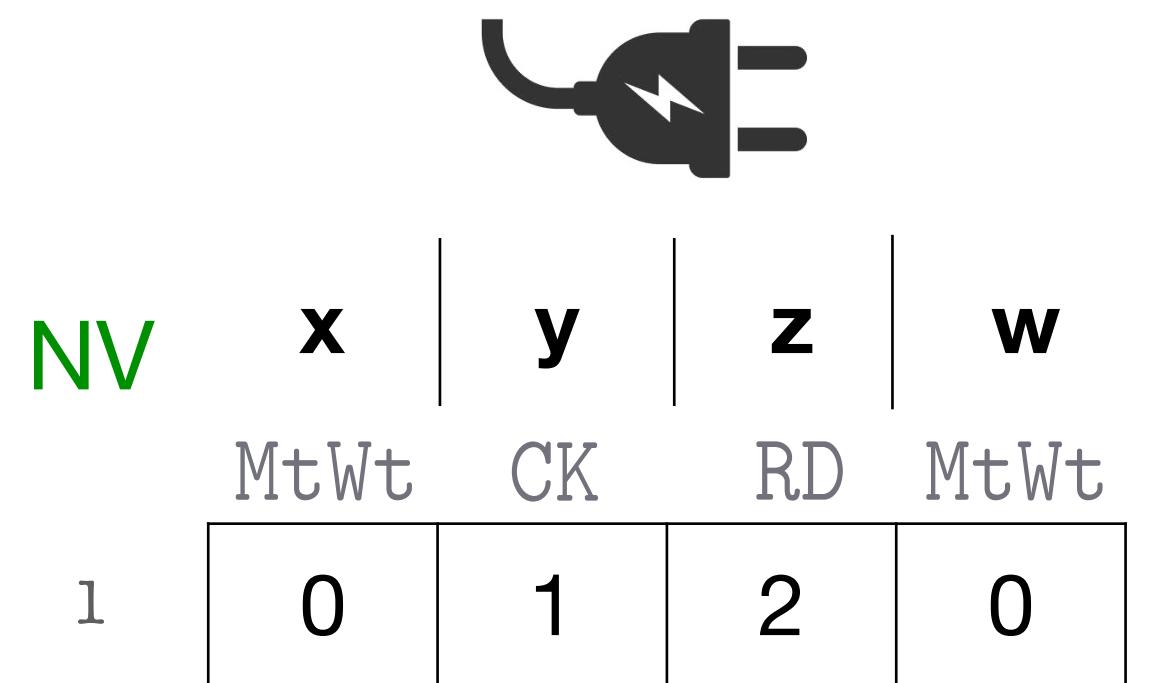
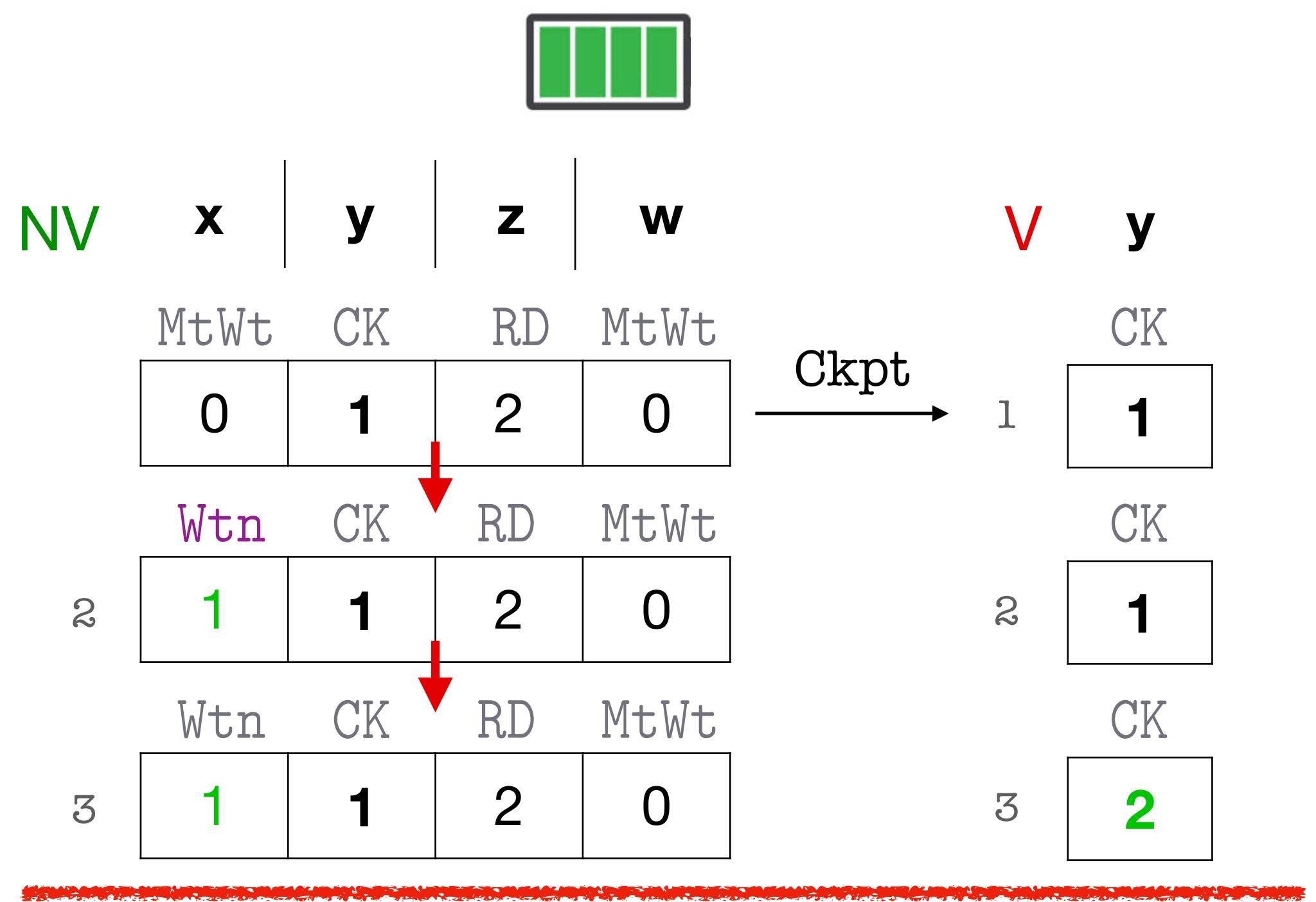


# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

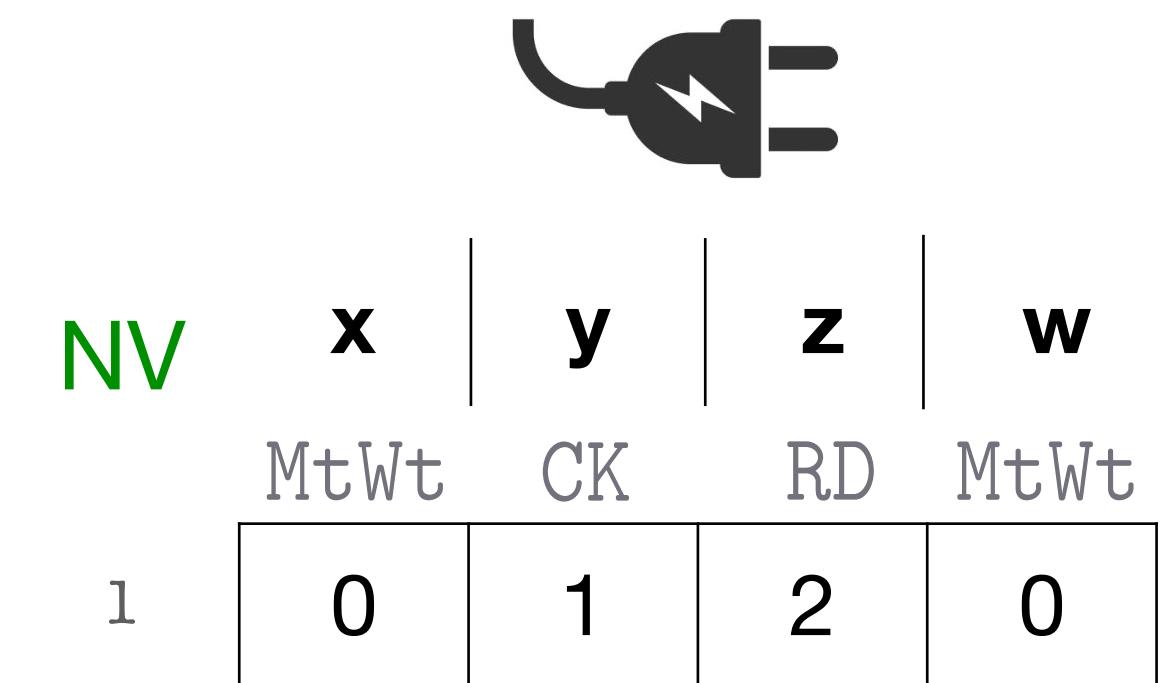
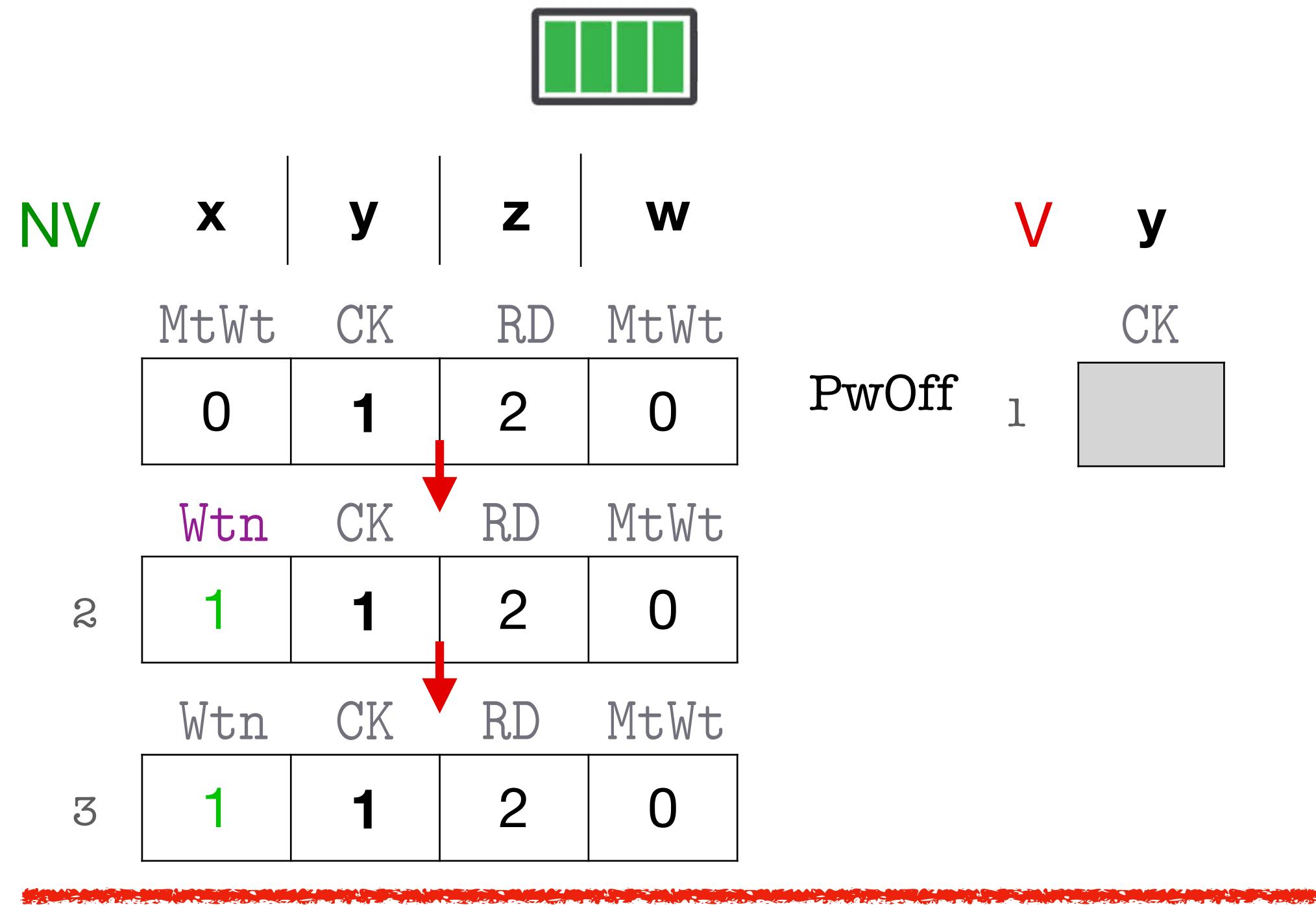


# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

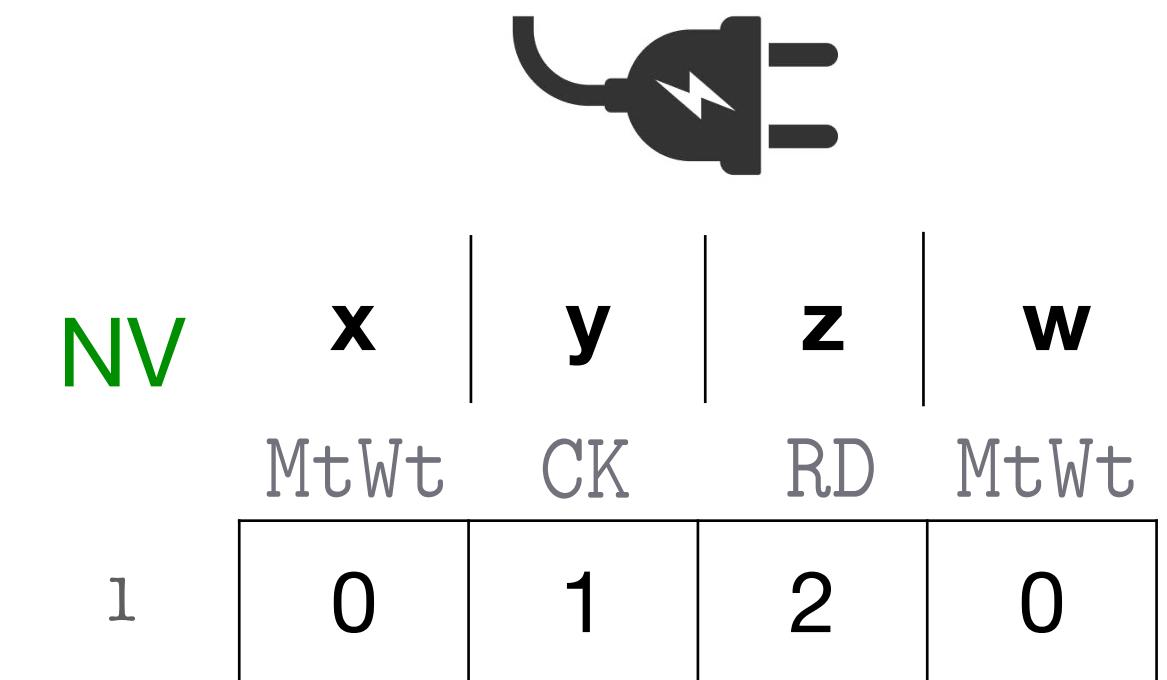
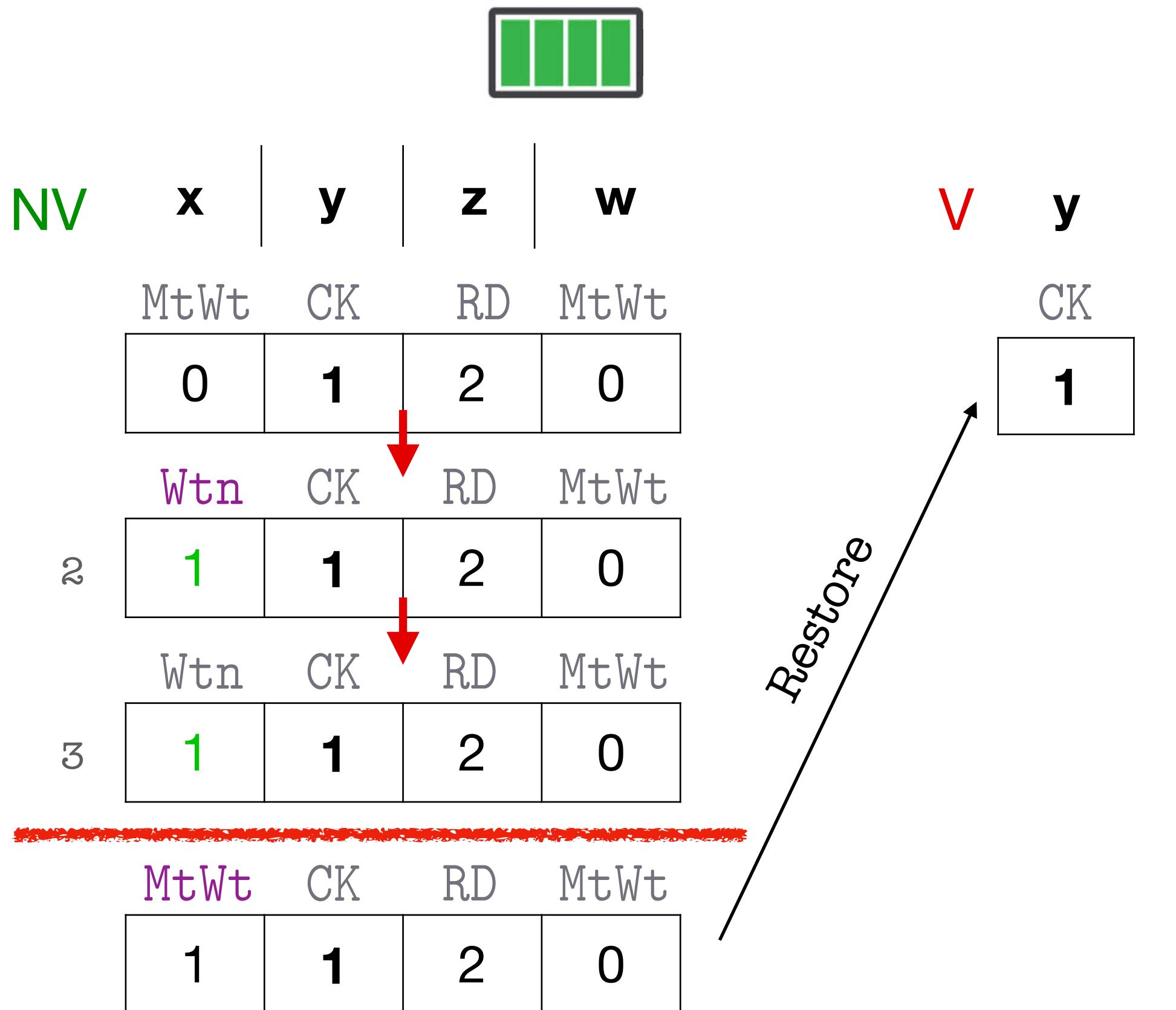


# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

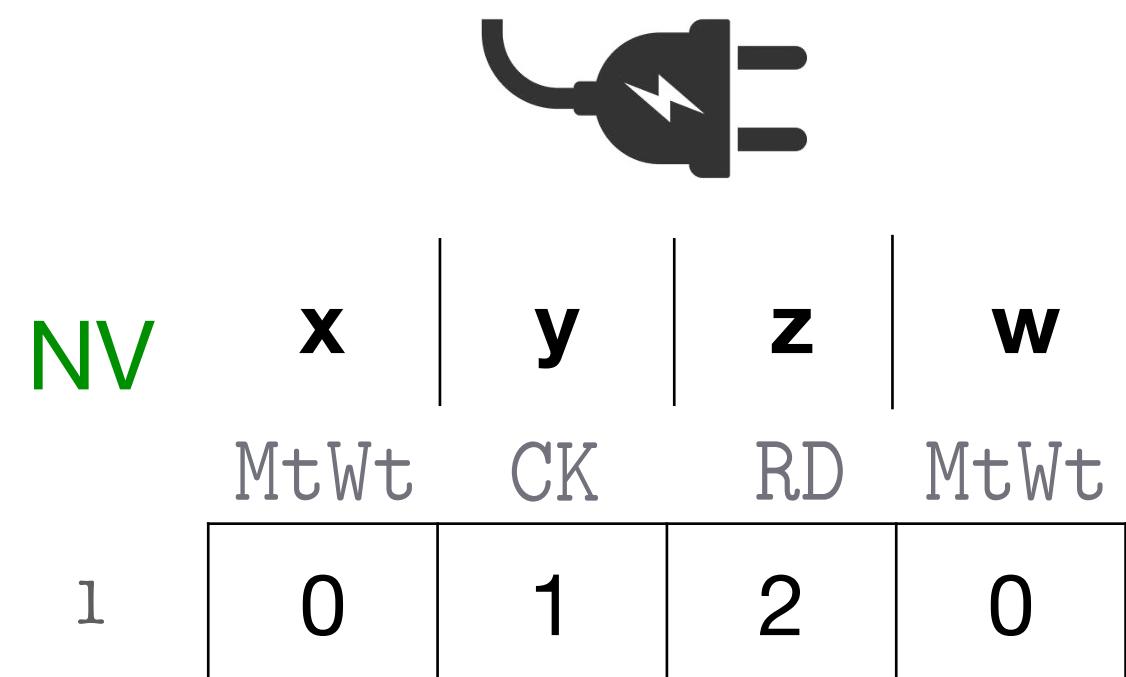
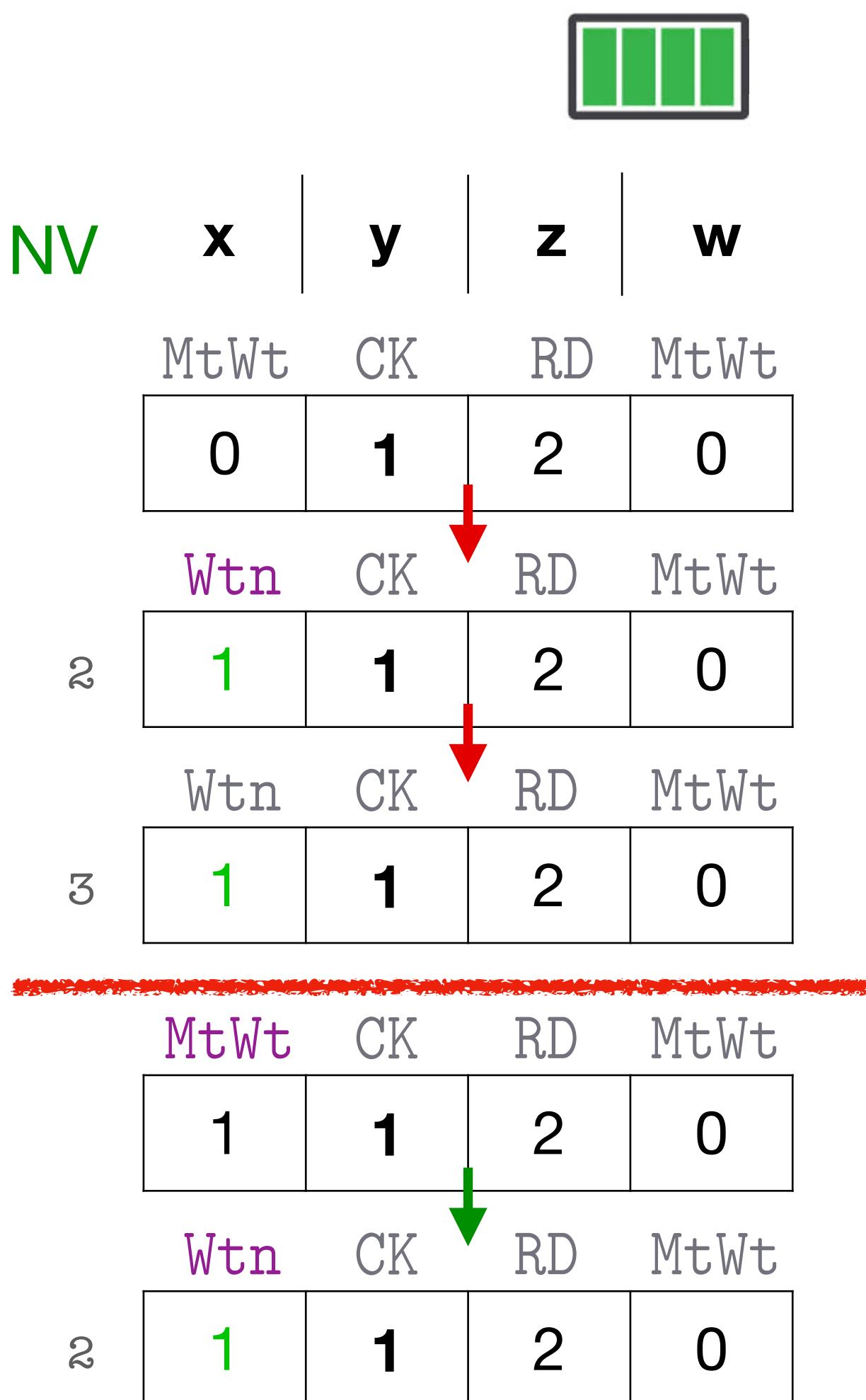


# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```



# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

NV

|   | x    | y  | z  | w    |
|---|------|----|----|------|
|   | MtWt | CK | RD | MtWt |
| 0 | 0    | 1  | 2  | 0    |
| 1 | Wtn  | CK | RD | MtWt |
| 2 | 1    | 1  | 2  | 0    |
| 3 | Wtn  | CK | RD | MtWt |
| 4 | 1    | 1  | 2  | 0    |

V

| y       |
|---------|
| CK<br>1 |

NV

|   | x    | y  | z  | w    |
|---|------|----|----|------|
|   | MtWt | CK | RD | MtWt |
| 1 | 0    | 1  | 2  | 0    |

---

|   | MtWt | CK | RD | MtWt |
|---|------|----|----|------|
|   | Wtn  | CK | RD | MtWt |
| 1 | 1    | 1  | 2  | 0    |
| 2 | Wtn  | CK | RD | MtWt |
| 3 | 1    | 1  | 2  | 0    |
| 4 | Wtn  | CK | RD | MtWt |
| 5 | 1    | 1  | 2  | 0    |

| CK |
|----|
| 1  |
| 2  |
| 3  |
| 4  |
| 5  |

# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

NV

|      | x  | y  | z    | w |
|------|----|----|------|---|
| MtWt | CK | RD | MtWt |   |
| 0    | 1  | 2  | 0    |   |
| 1    | 1  | 2  | 0    |   |
| 2    | 1  | 2  | 0    |   |
| 3    | 1  | 2  | 0    |   |

Wtn CK RD MtWt

| MtWt | CK | RD | MtWt |     |
|------|----|----|------|-----|
| 1    | 1  | 2  | 0    |     |
| 2    | 1  | 2  | 0    |     |
| 3    | 1  | 2  | 0    |     |
| 4    | 1  | 2  | 3    | Wtn |

V

| y       |
|---------|
| CK<br>1 |

CK

| 2       |
|---------|
| CK<br>1 |
| CK<br>2 |
| CK<br>2 |

NV

| x    | y  | z  | w    |  |
|------|----|----|------|--|
| MtWt | CK | RD | MtWt |  |
| 0    | 1  | 2  | 0    |  |

# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

NV

| x    | y  | z  | w    |
|------|----|----|------|
| MtWt | CK | RD | MtWt |
| 0    | 1  | 2  | 0    |

V

| y  |
|----|
| CK |
| 1  |

| Wtn | CK | RD | MtWt |
|-----|----|----|------|
| 2   |    |    |      |
| 1   | 1  | 2  | 0    |

| Wtn | CK | RD | MtWt |
|-----|----|----|------|
| 3   |    |    |      |
| 1   | 1  | 2  | 0    |

---

| MtWt | CK | RD | MtWt |
|------|----|----|------|
| 1    |    |    |      |
| 1    | 1  | 2  | 0    |

| Wtn | CK | RD | MtWt |
|-----|----|----|------|
| 2   |    |    |      |
| 1   | 1  | 2  | 0    |

| Wtn | CK | RD | MtWt |
|-----|----|----|------|
| 3   |    |    |      |
| 1   | 1  | 2  | 0    |

| Wtn | CK | RD | Wtn |
|-----|----|----|-----|
| 4   |    |    |     |
| 1   | 2  | 2  | 3   |

V

| y  |
|----|
| CK |
| 1  |

2

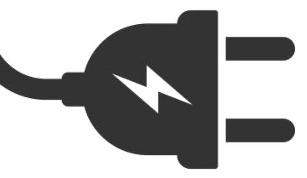
| CK |
|----|
| 1  |

3

| CK |
|----|
| 2  |

4

| CK |
|----|
| 2  |



NV

| x    | y  | z  | w    |
|------|----|----|------|
| MtWt | CK | RD | MtWt |
| 0    | 1  | 2  | 0    |

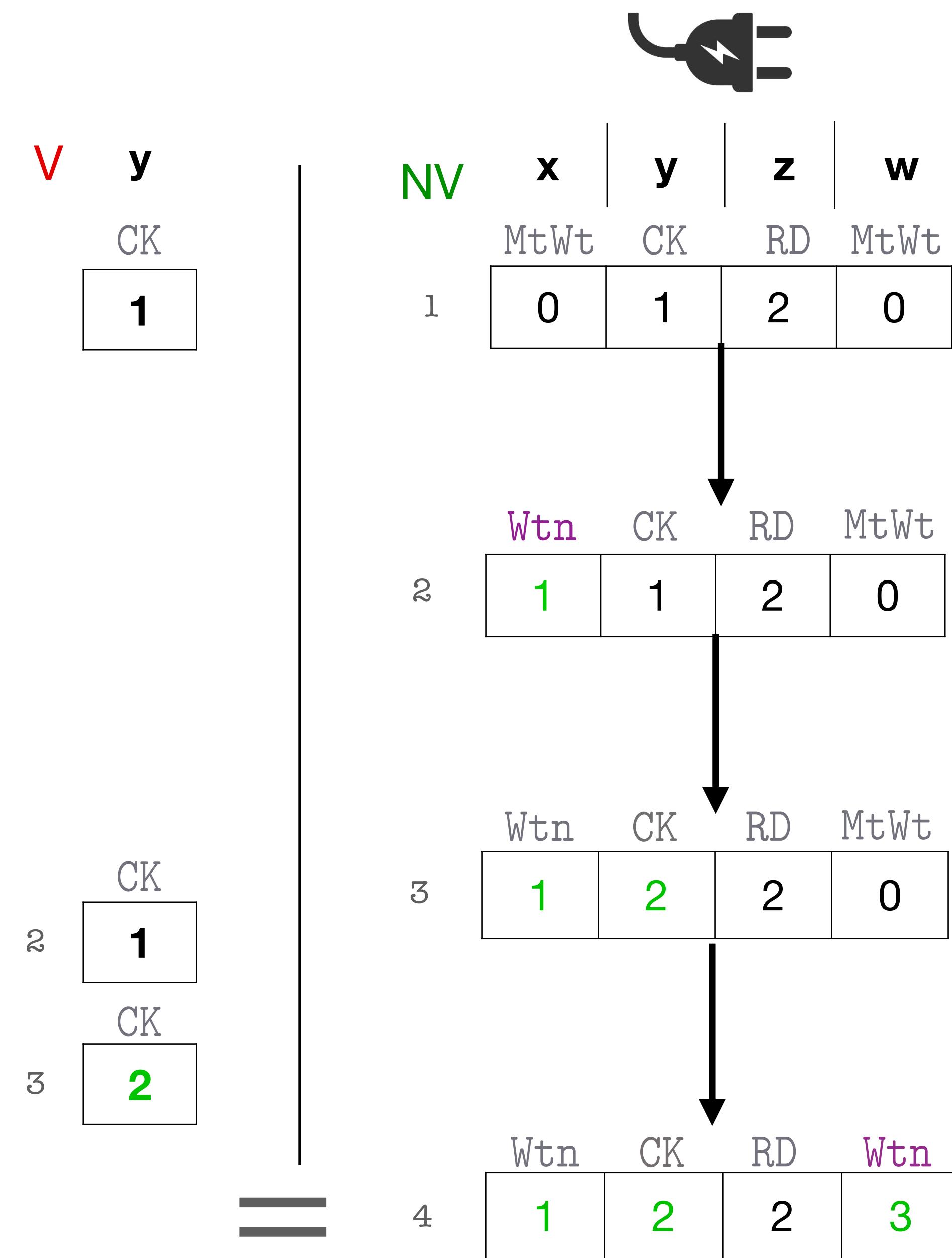
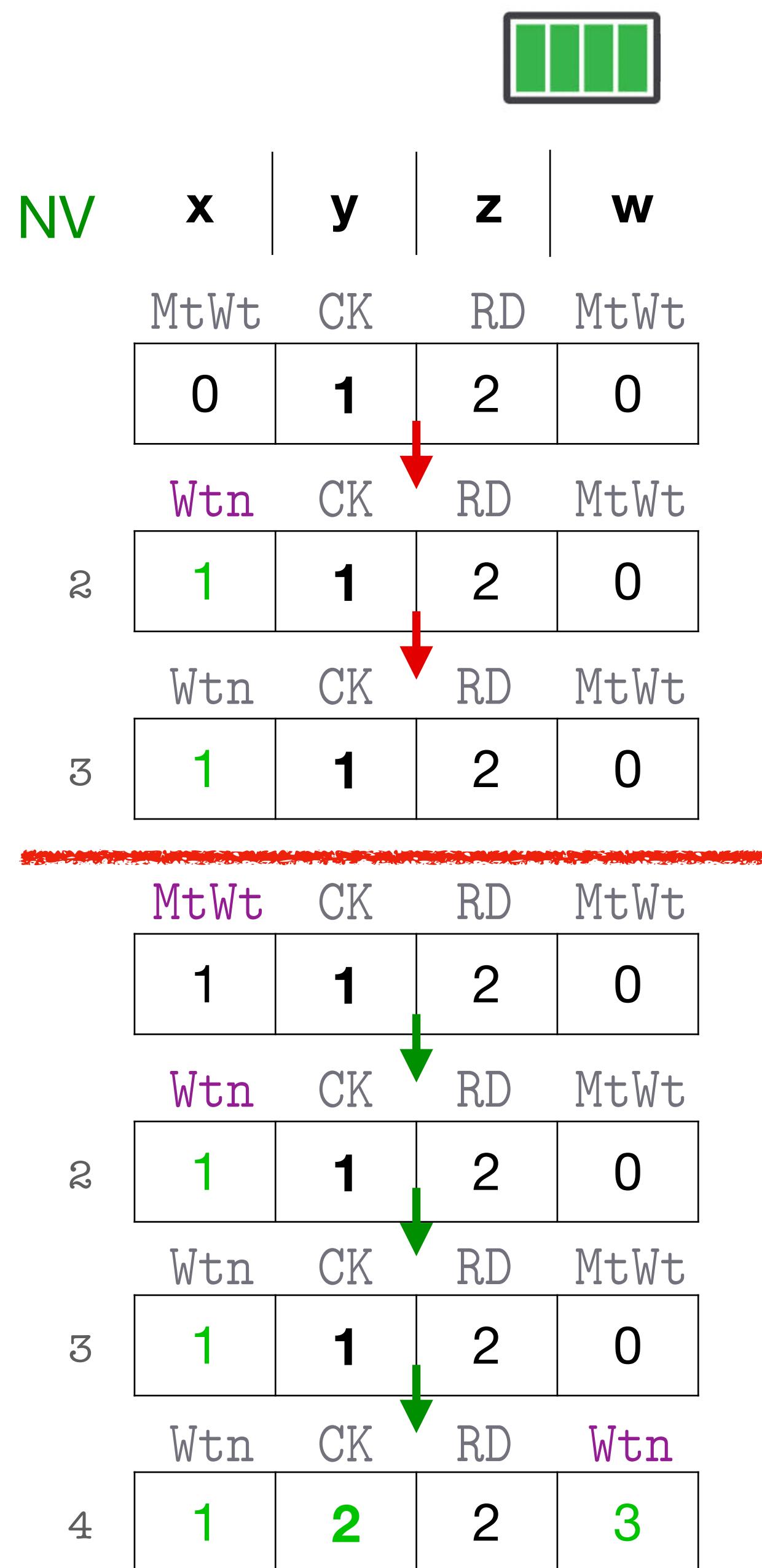
Commit

# Example

```

1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y

```

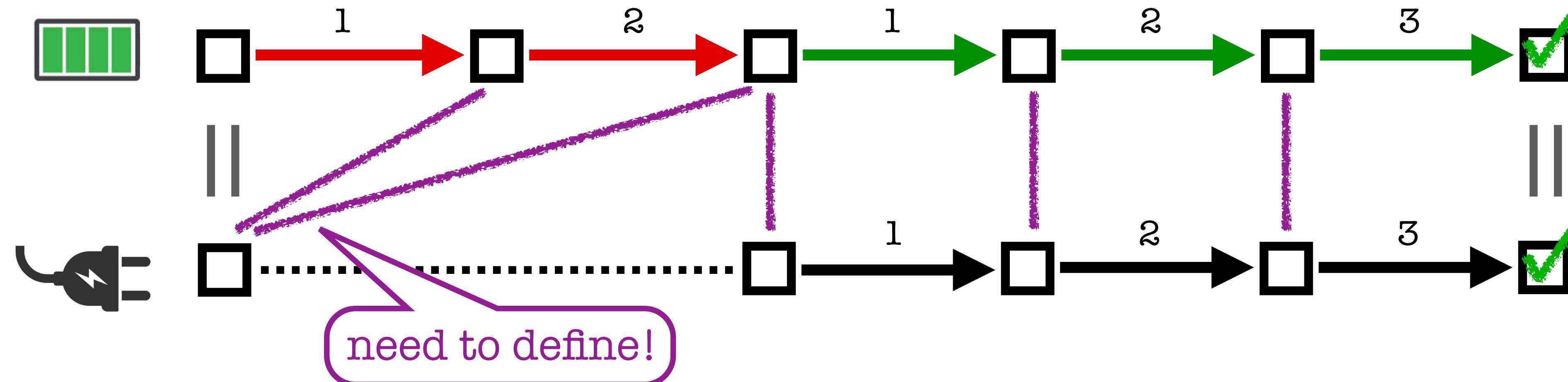


# Outline

- Intermittent computing
- Overview
- Type system
- **Logical relation**
- JIT mode
- Key theorems
- Conclusion

# Proving Correctness

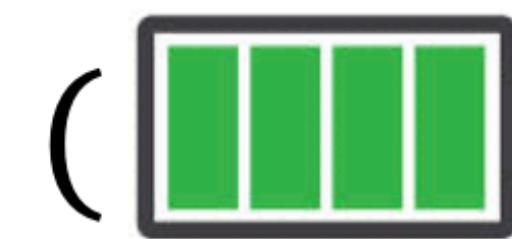
Every intermittent execution of a **well-typed** program can be simulated by its continuous execution.



# Binary Logical Relation

Every intermittent execution of a **well-typed** program can be simulated by its continuous execution.

---



Intermittent execution



Continuous execution

# crashes 

$$(\text{Battery icon} \mid \text{INV} \mid \text{V} \mid c_1, \text{Plug icon} \mid \text{NV} \mid \text{V} \mid c_2) \in \underline{\text{[C}_Unit\text{]}}^m$$

Crash type

# Term Relation

$$(\text{[Battery]} \mid \text{INV} \mid \text{V} \mid \underline{c_1}, \text{[Plug]} \mid \text{NV} \mid \text{V} \mid c_2) \in \underline{\mathcal{E}} \llbracket \mathbf{C}_{Unit} \rrbracket^m$$

---

where  $c_1$  is...

$x := y$

$c_1; c_2$

$\text{if } v \text{ then } c_1 \text{ else } c_2$

$\text{let } x = e \text{ in } c$

# Value Relation

$$(\text{Battery icon} \mid \text{INV} \mid \text{V} \mid \underline{\nu_1}, \text{Plug icon} \mid \text{NV} \mid \text{V} \mid c_2) \in \underline{\mathcal{V}}[\mathbb{C}_{Unit}]^m$$

---

where  $\nu_1$  is...



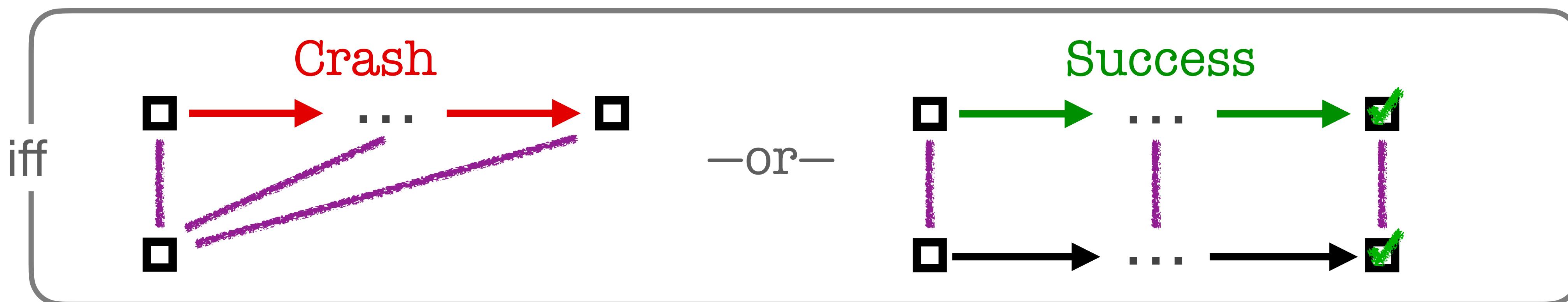
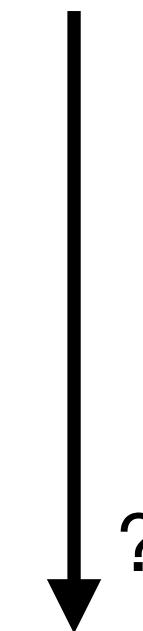
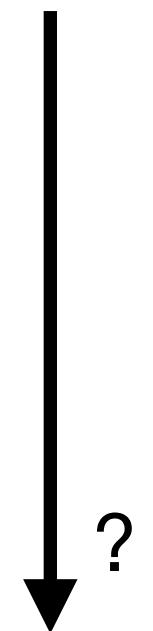
# No remaining power failures

(  | NV | V | c,  | NV | V | c)  $\in \mathcal{E}[\![\mathbf{C}_{Unit}]\!]^0$

# A power failure is possible!

$$(\text{Battery icon} \mid NV_1 \mid V \mid c, \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbf{C}_{Unit}]^{k+1}$$

$(NV_1 \setminus \text{MtWt} = NV_2 \setminus \text{MtWt})$



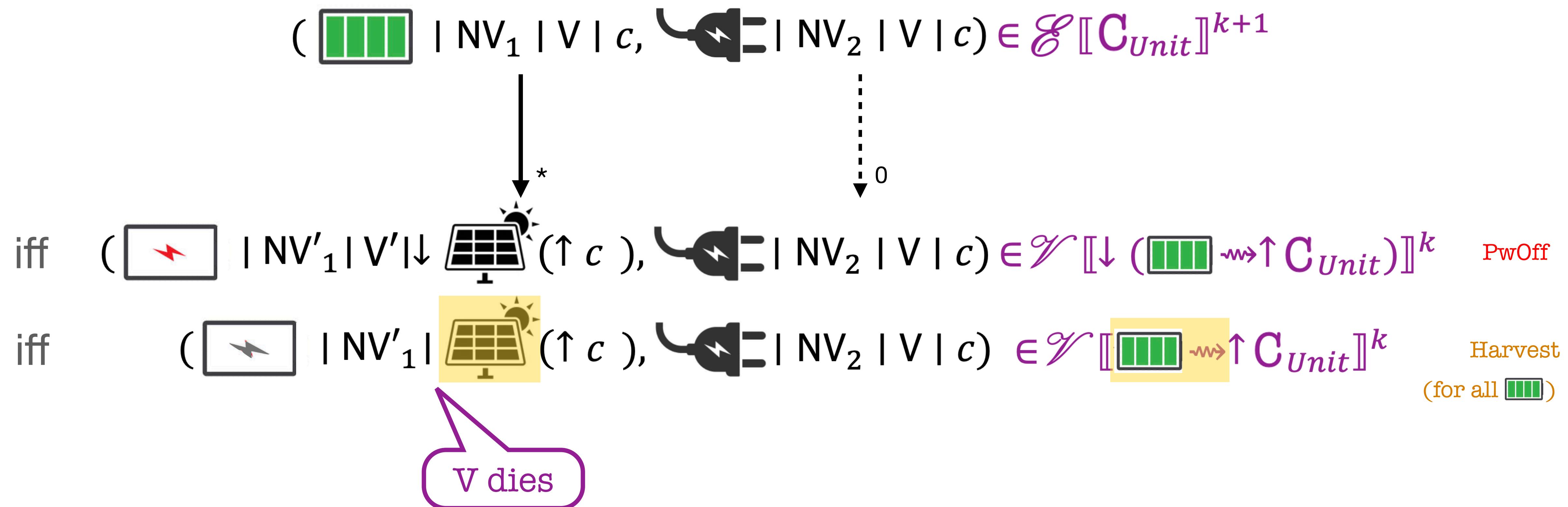
# If there is a power failure...

(  | NV<sub>1</sub> | V | c,  | NV<sub>2</sub> | V | c) ∈ ℬ[[C<sub>Unit</sub>]]<sup>k+1</sup>

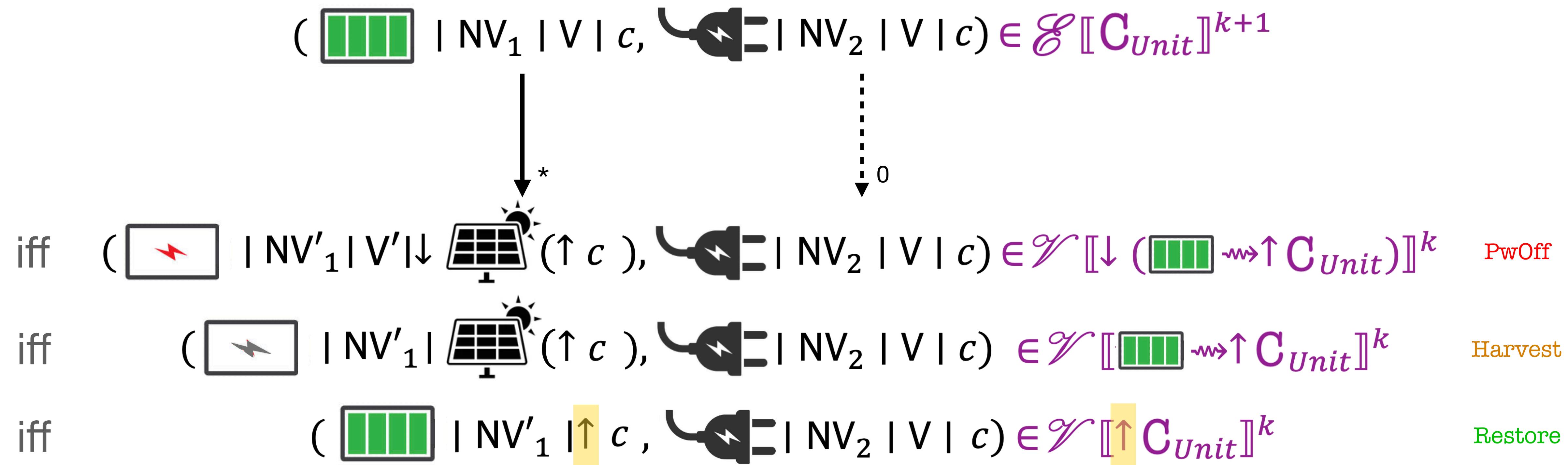
# Device powers off

$$\begin{array}{c} (\text{Battery icon} \mid NV_1 \mid V \mid c, \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1} \\ \downarrow * \\ \text{iff } (\text{Device icon with lightning} \mid NV'_1 \mid V' \mid \text{Solar panel icon} \downarrow (\uparrow c), \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{V}[\downarrow (\text{Battery icon} \rightsquigarrow \uparrow \mathbb{C}_{Unit})]^k \quad \text{PwOff} \end{array}$$

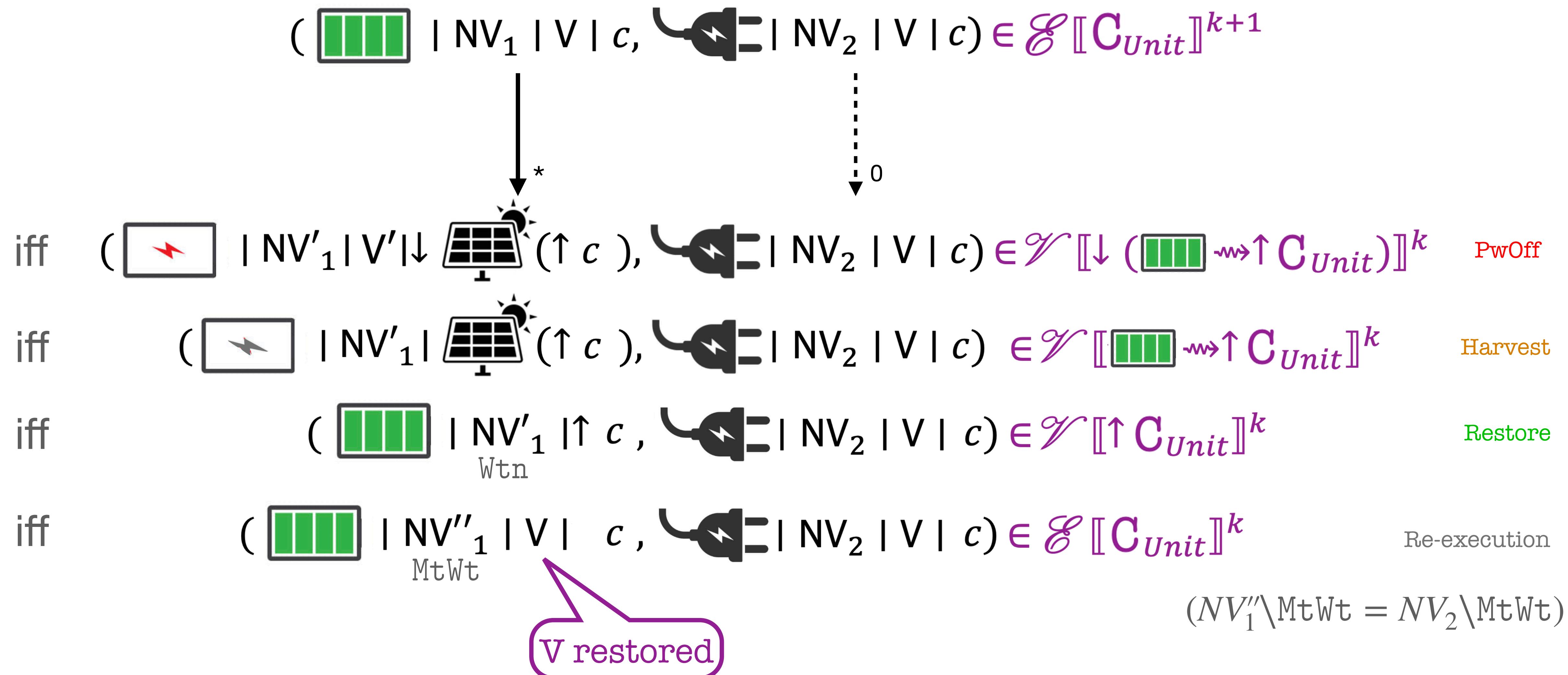
# Harvest energy from the environment



# Execution state is restored



# Prepare for re-execution



# If there is no power failure...

$$(\text{Battery icon} | NV_1 | V | c, \text{Plug icon} | NV_2 | V | c) \in \mathcal{E}[\![C_{Unit}]\!]^{k+1}$$

# Stable values are committed

$$(\text{battery icon} | NV_1 | V | c, \text{plug icon} | NV_2 | V | c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

$\downarrow n$

$\downarrow n$

iff

$$(\text{battery icon} | NV'_1 | V' | \text{skip}, \text{plug icon} | NV'_2 | V' | \text{skip}) \in \mathcal{V}[\uparrow \downarrow unit]^k$$

Commit

# We are done!

$$(\text{battery icon} | NV_1 | V | c, \text{plug icon} | NV_2 | V | c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

$\downarrow n$

$\downarrow n$

iff

$$(\text{battery icon} | NV'_1 | V' | \text{skip}, \text{plug icon} | NV'_2 | V' | \text{skip}) \in \mathcal{V}[\downarrow\uparrow unit]^k$$

Commit

iff

$$(\text{battery icon} | NV''_1 | V' | \text{skip}, \text{plug icon} | NV''_2 | V' | \text{skip}) \in \mathcal{V}[\uparrow unit]^k$$

Success!

$(NV''_1 = NV''_2)$

# Outline

- Intermittent computing
- Overview
- Type system
- Logical relation
- **JIT mode**
- Key theorems
- Conclusion

# Real programs don't always use Ckpt

- intermittent systems default to JIT mode
- checkpoints everything “just-in-time”
- no re-execution
- hybrid JIT+Ckpt programs

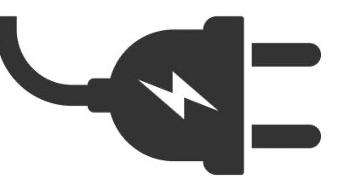
```
Ckpt(y)
  x := y;
  y := z;
  w := x + y;
```

```
let x = 5 in
  c:= x+1;
  h := c
```

# Example

```
5 let x = 5 in  
6   c := x+1;  
7   h := c
```

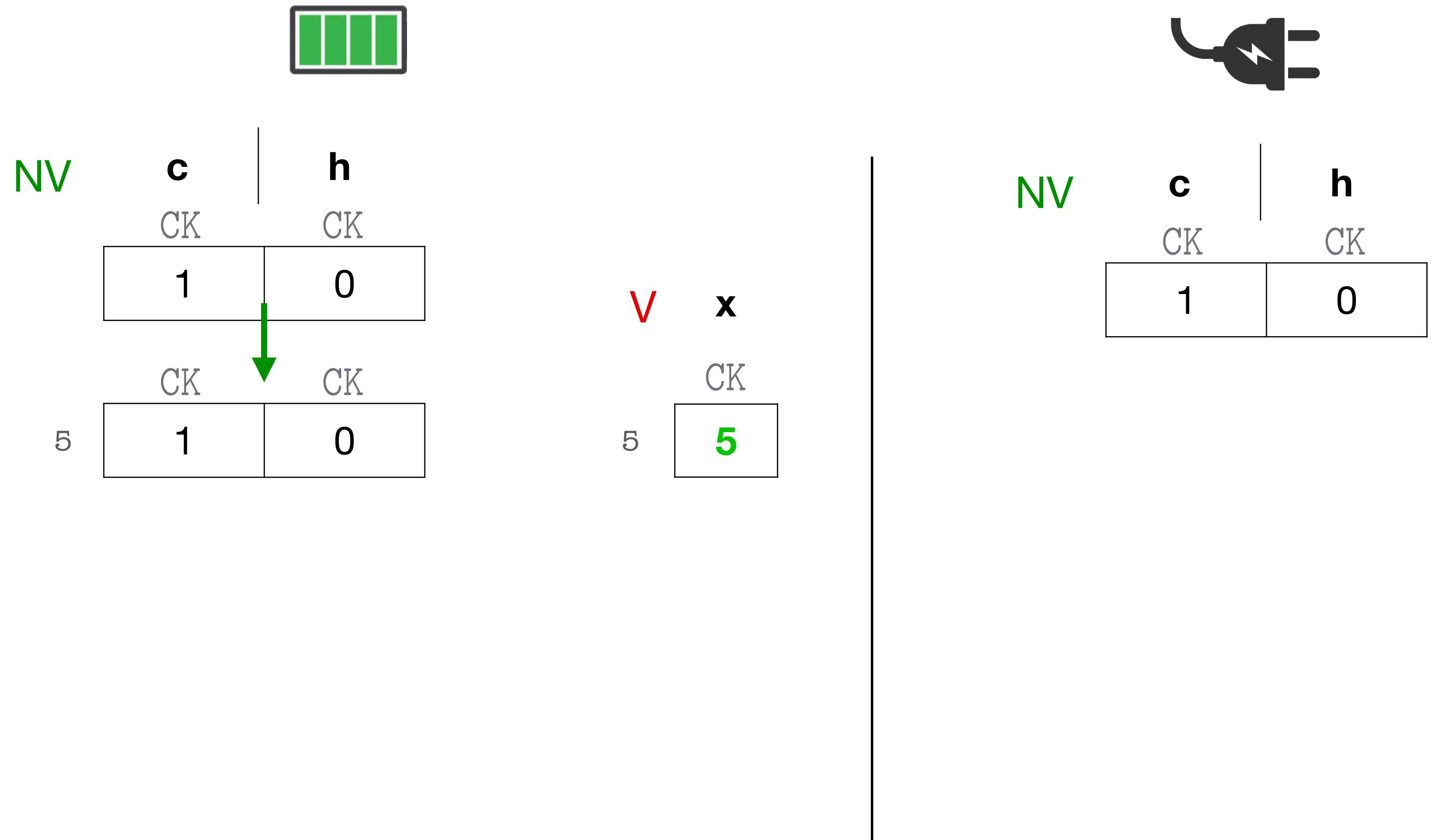
| NV | c  | h  |
|----|----|----|
| CK | CK | CK |
|    | 1  | 0  |



| NV | c  | h  |
|----|----|----|
| CK | CK | CK |
|    | 1  | 0  |

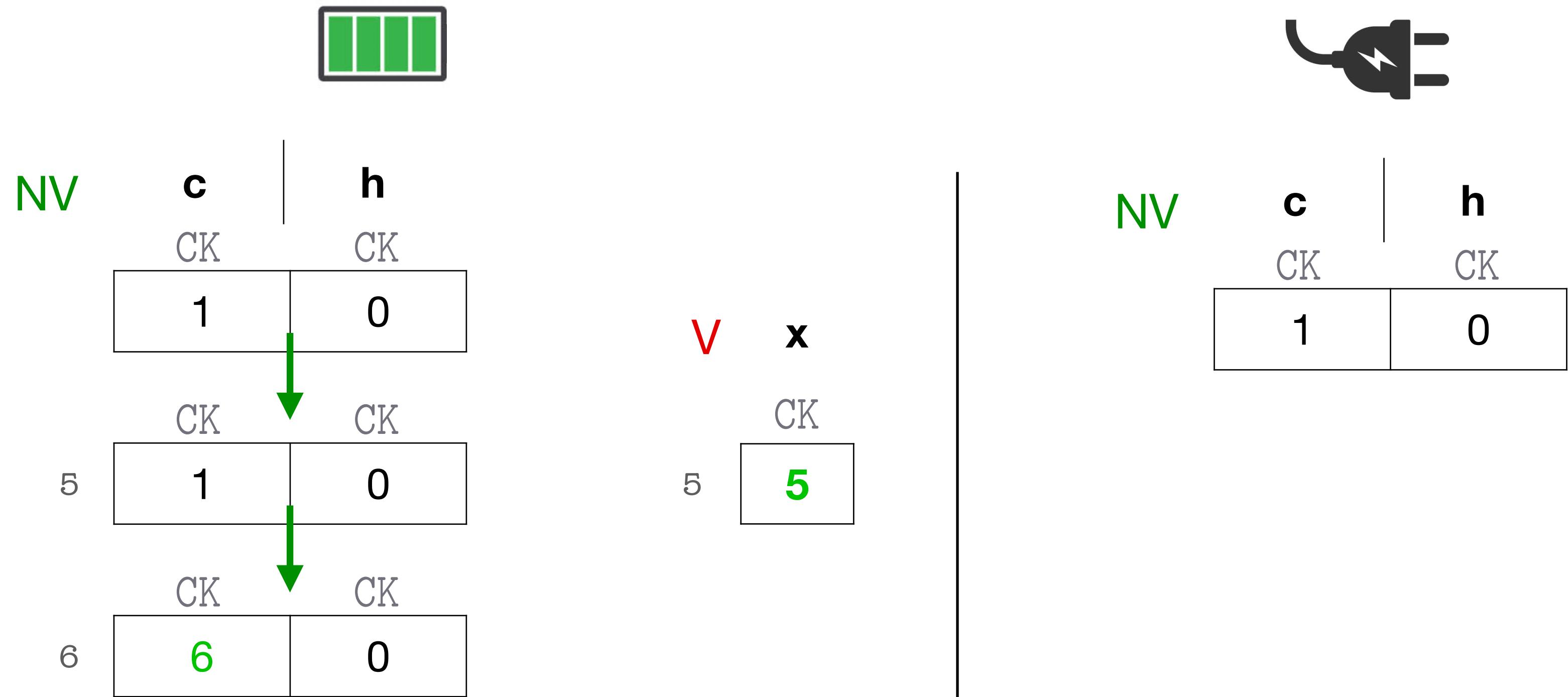
# Example

```
5 let x = 5 in  
6   c := x+1;  
7   h := c
```



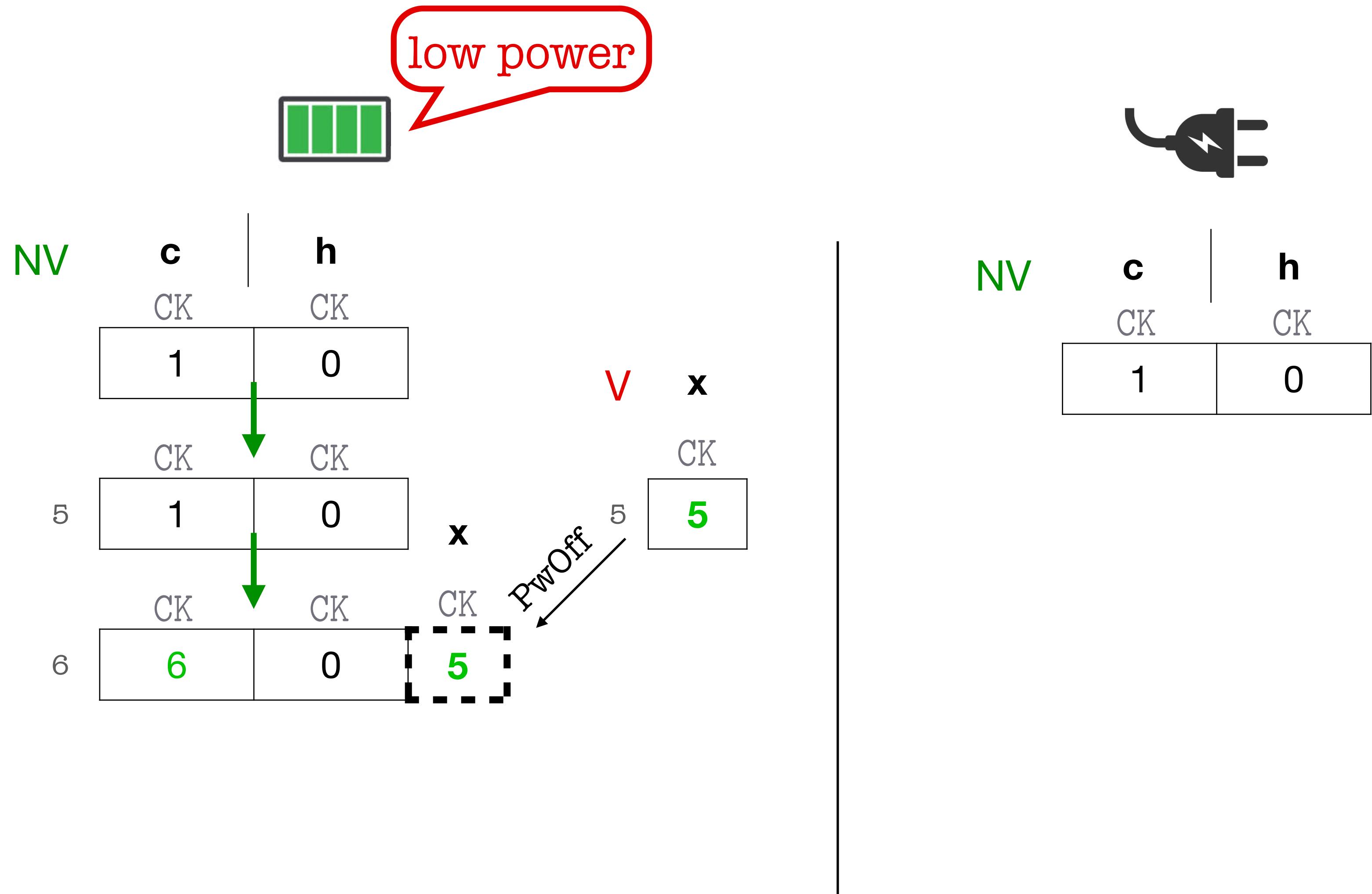
# Example

```
5 let x = 5 in  
6   c := x+1;  
7   h := c
```



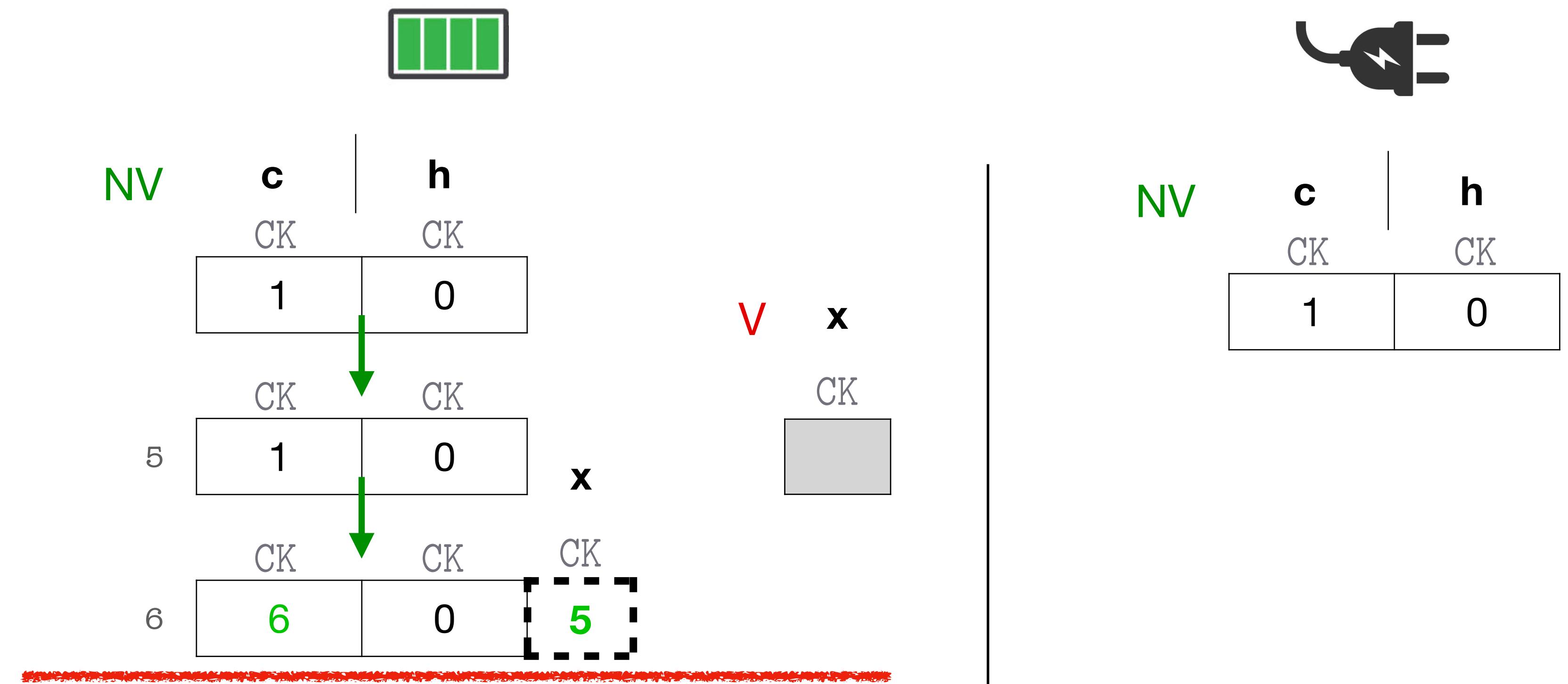
# Example

```
5 let x = 5 in  
6   c := x+1;  
7   h := c
```



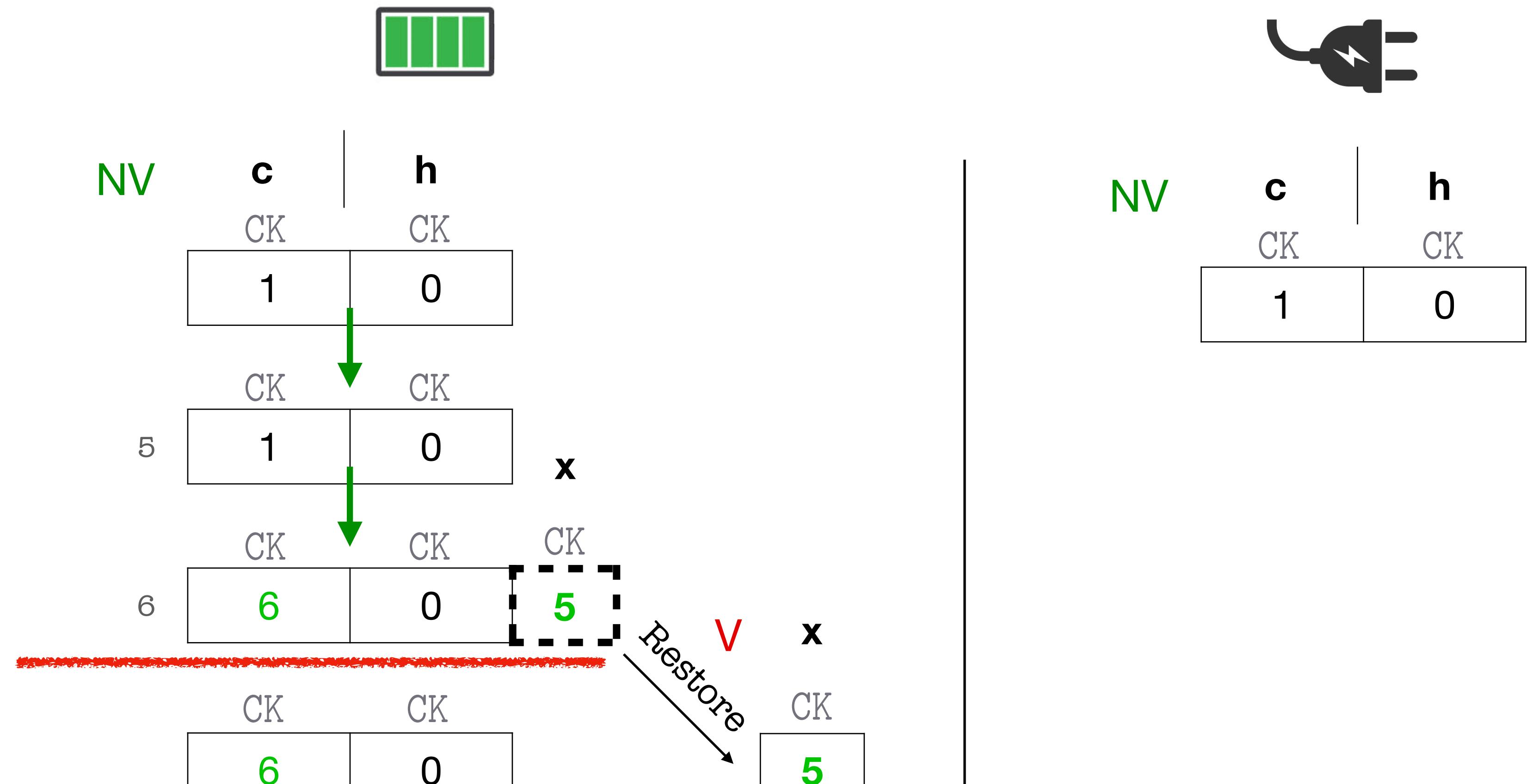
# Example

```
5 let x = 5 in  
6   c := x + 1;  
7   h := c
```



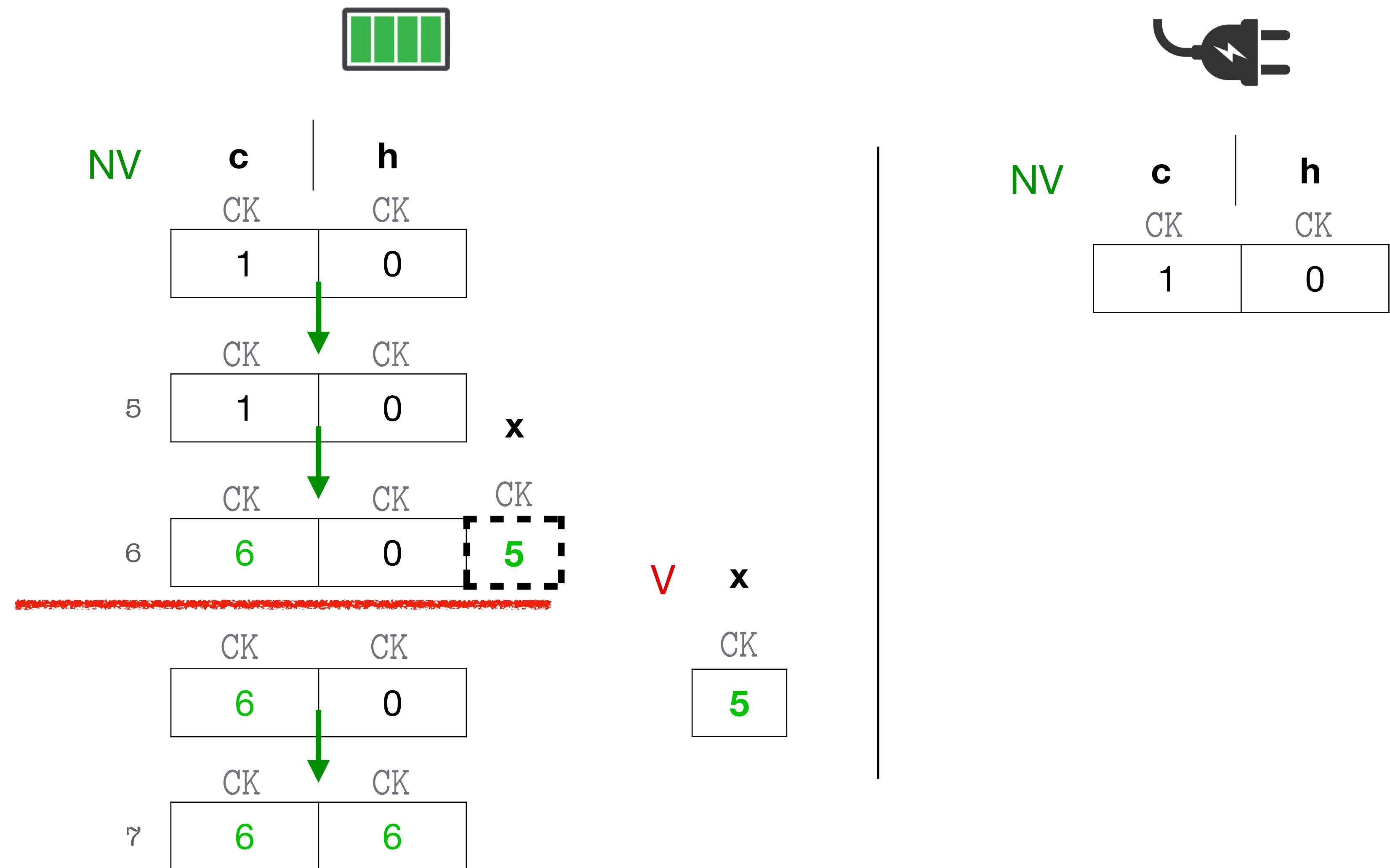
# Example

```
5 let x = 5 in  
6   c := x + 1;  
7   h := c
```



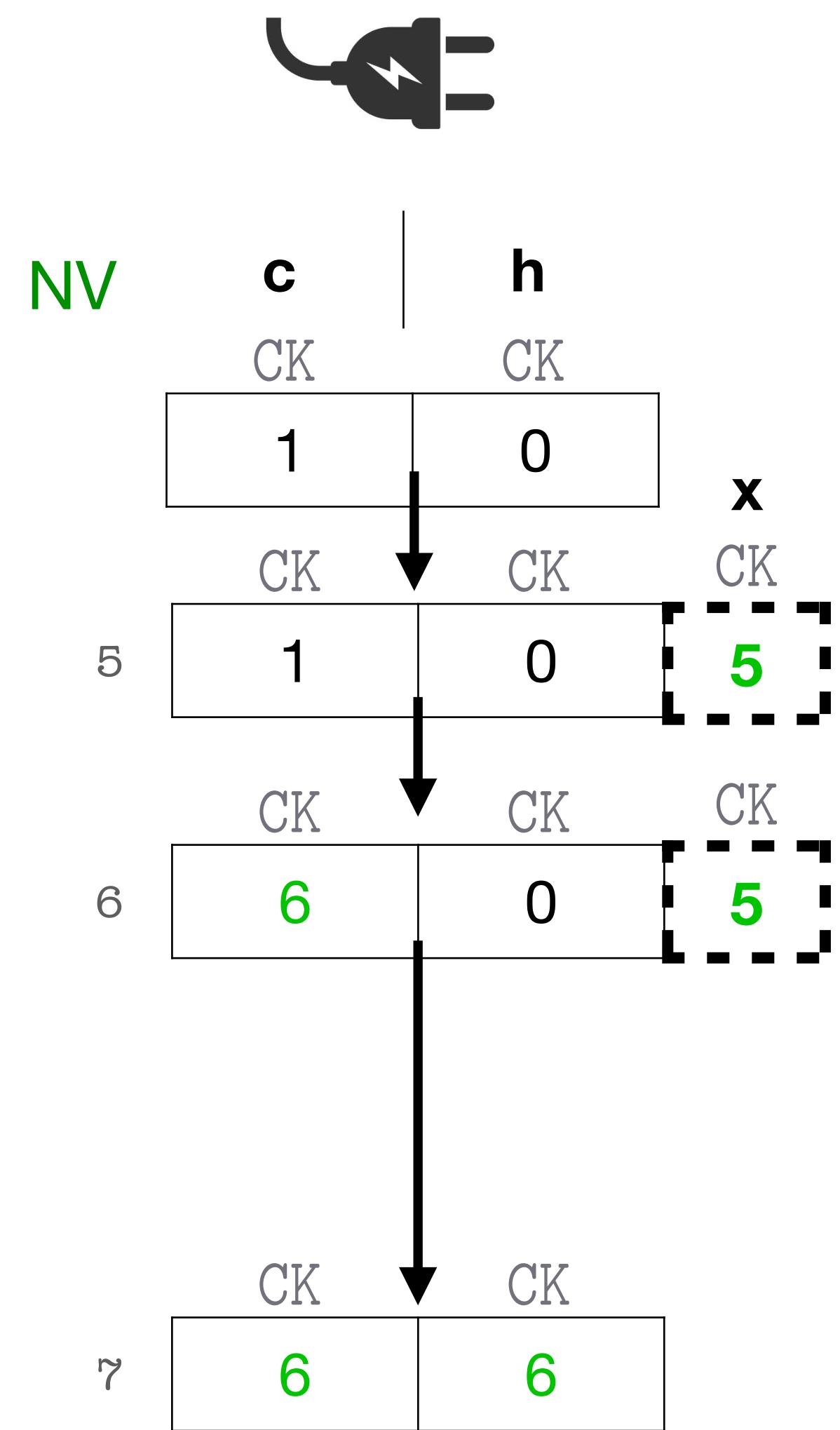
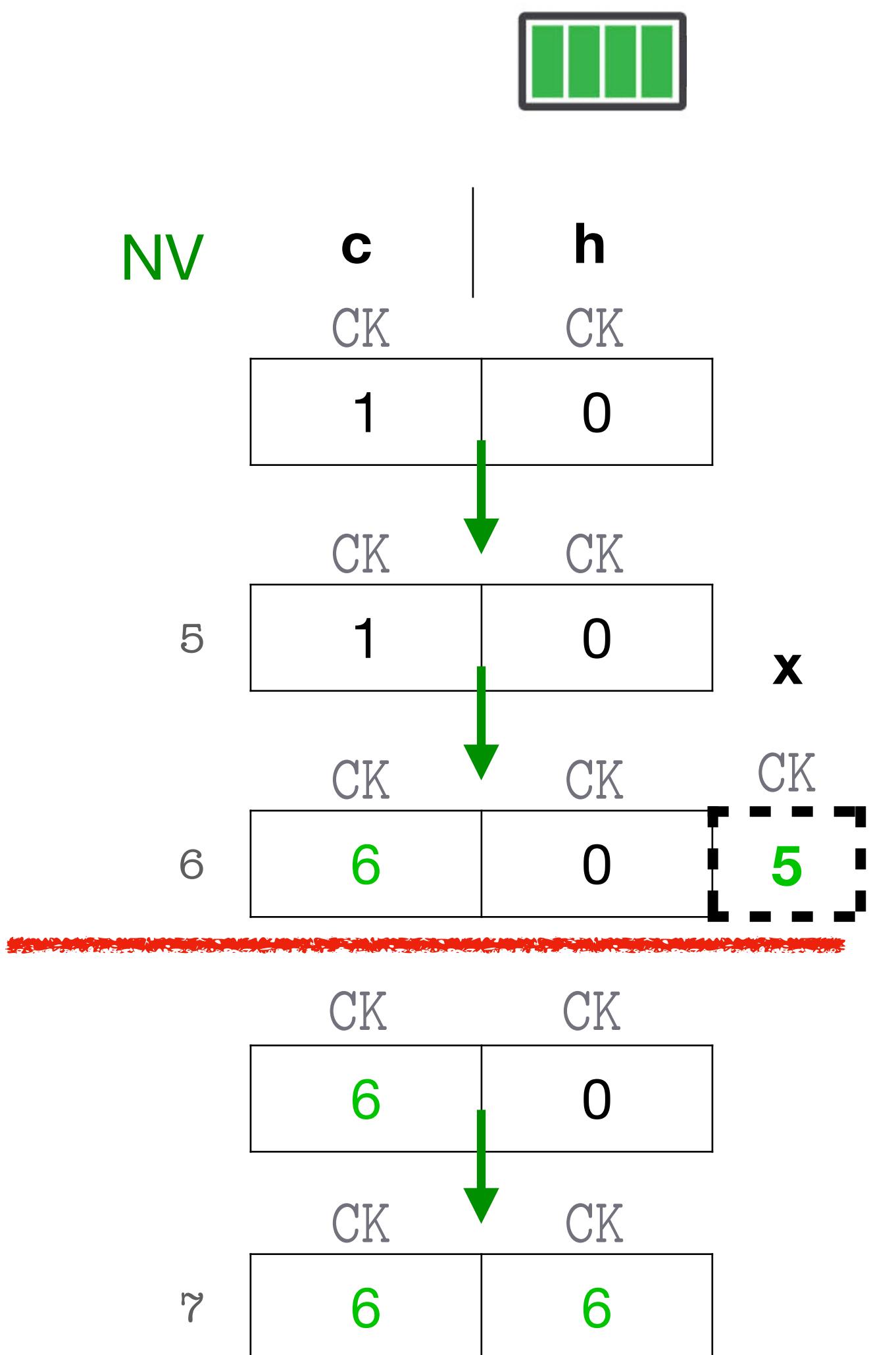
# Example

```
5 let x = 5 in  
6   c := x + 1;  
7   h := c
```



# Example

```
5 let x = 5 in  
6   c := x + 1;  
7   h := c
```

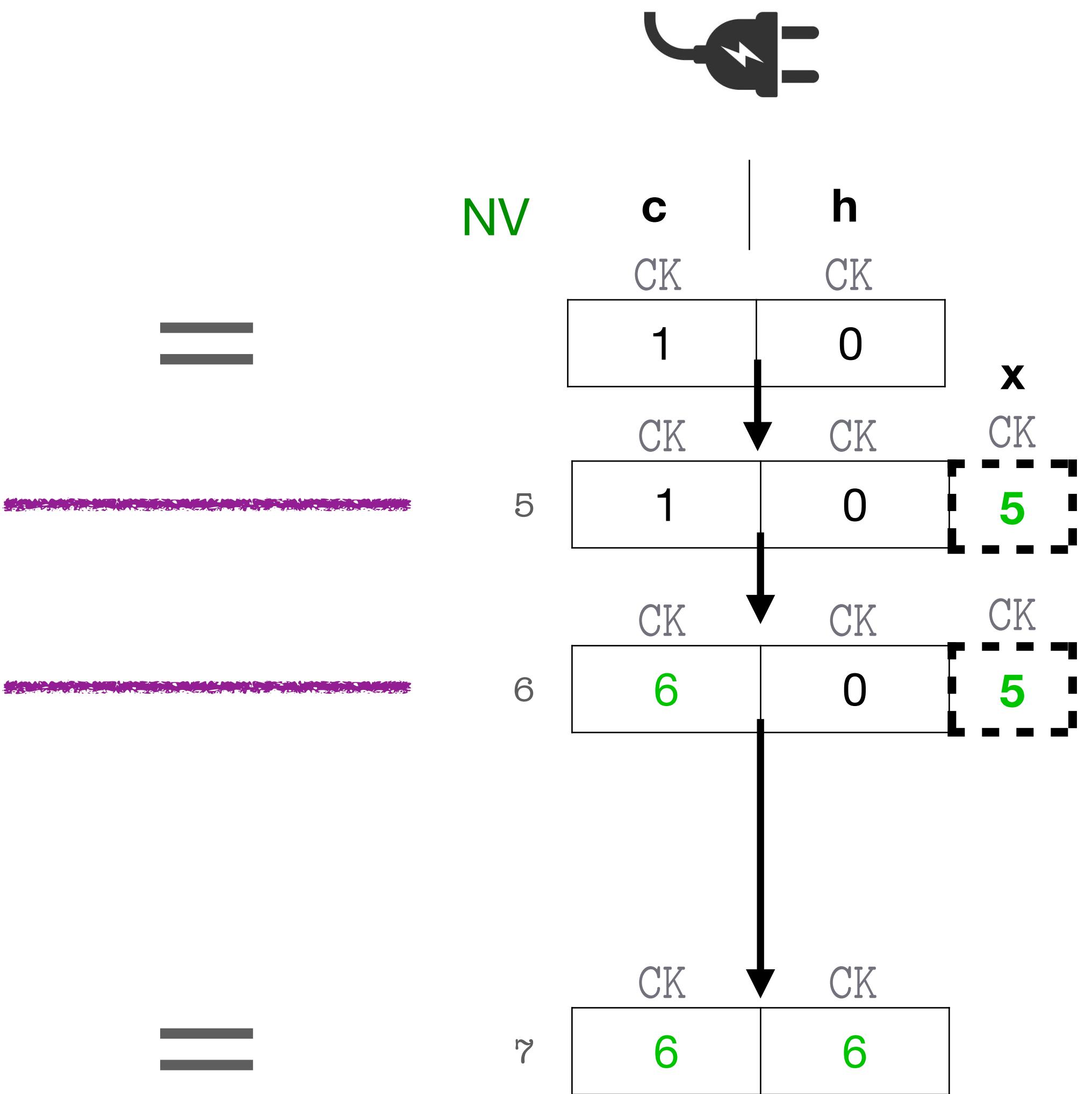
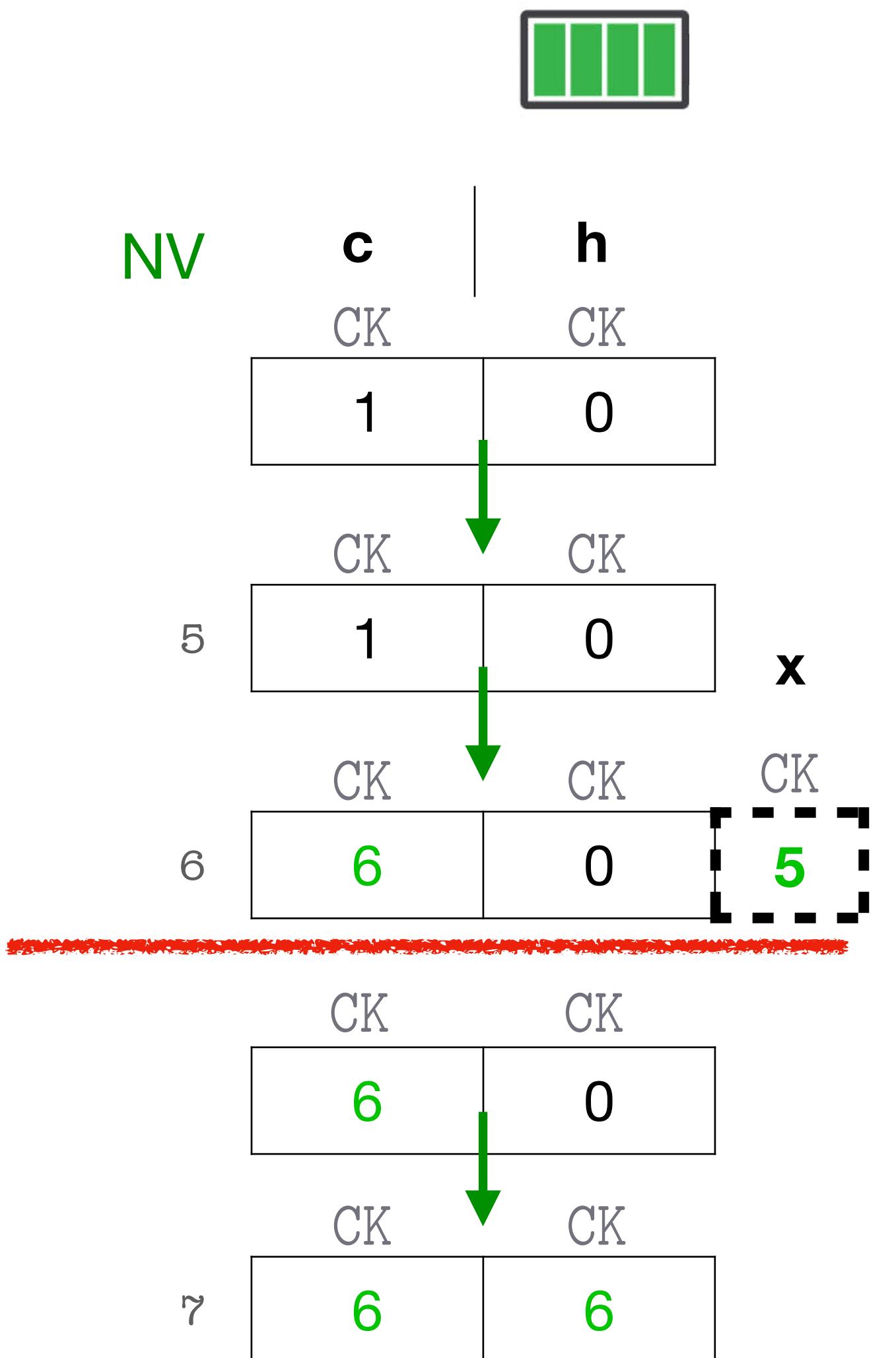


# Example

```

5 let x = 5 in
6   c := x + 1;
7   h := c

```

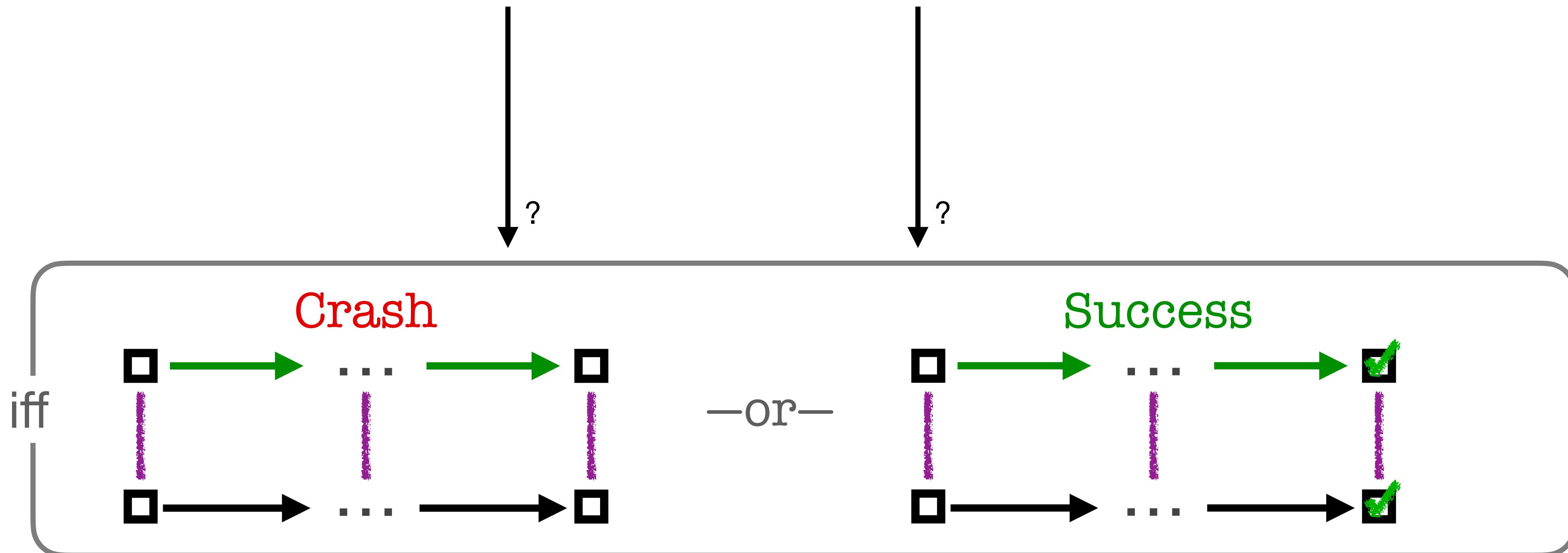


# Logical Relation for JIT

$$(\text{Battery icon} \mid NV_1 \mid V \mid c, \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\![C_{Unit}]\!]^{k+1}$$

Same great structure,  
different **PwOff** and **Restore**!

# Logical Relation for JIT

$$(\text{Battery icon} \mid NV_1 \mid V \mid c, \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbf{C}_{Unit}]^{k+1}$$


# If there is a power failure...

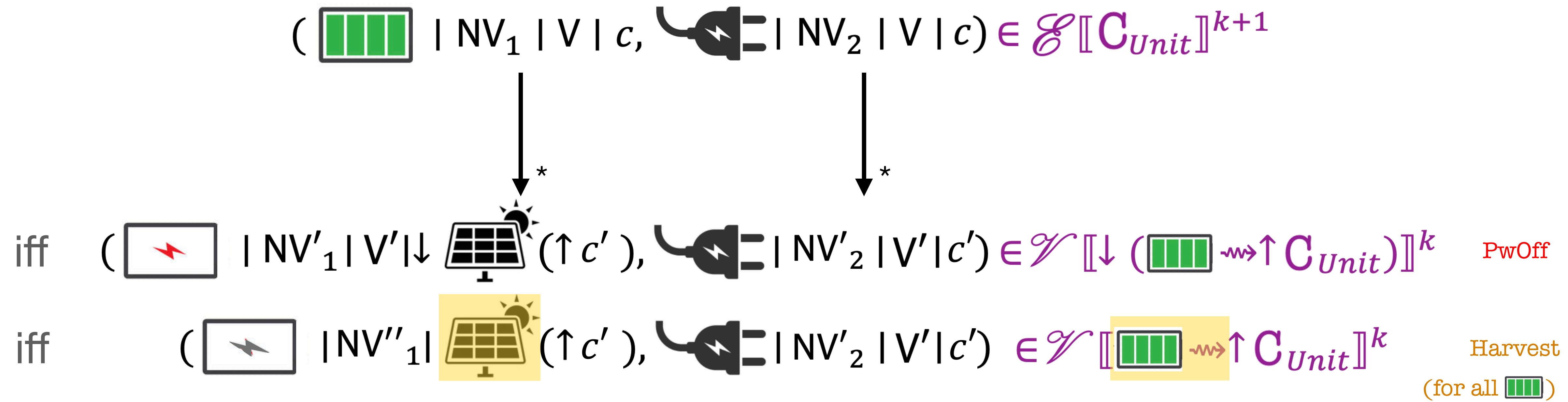
(  | NV<sub>1</sub> | V | c,  | NV<sub>2</sub> | V | c) ∈ ℬ[[C<sub>Unit</sub>]]<sup>k+1</sup>

# Device powers off

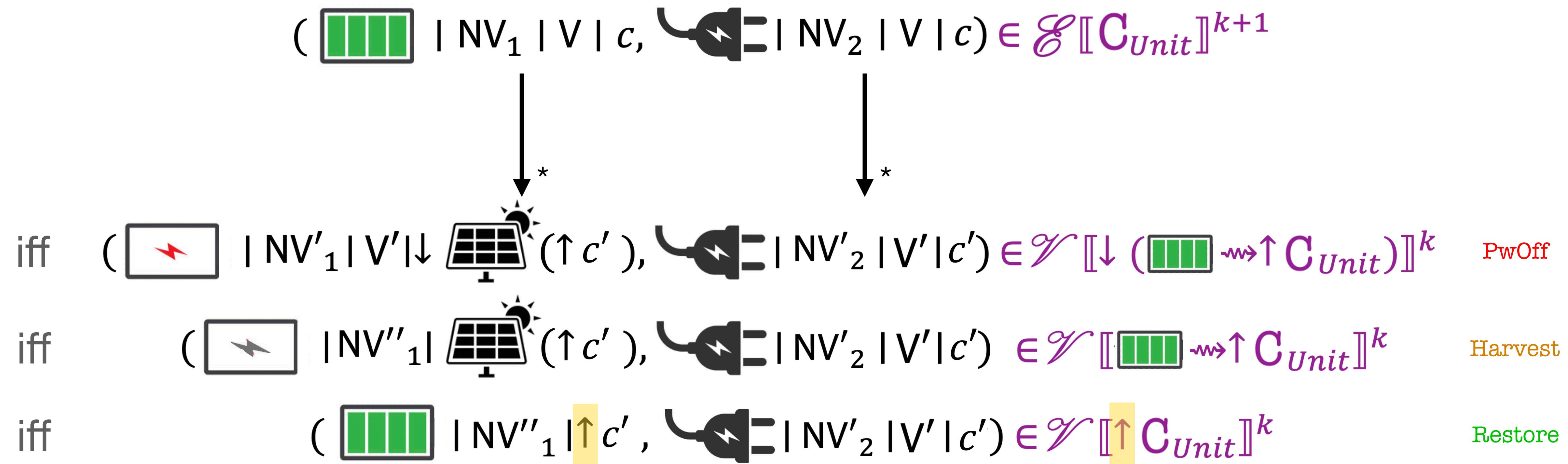
$$\begin{array}{c} (\text{Battery icon} \mid NV_1 \mid V \mid c, \text{Plug icon} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1} \\ \downarrow \quad \quad \quad \downarrow \\ \text{iff } (\text{Device icon with lightning} \mid NV'_1 \mid V' \mid \text{Down arrow icon} \mid \text{Solar panel icon} \mid (\uparrow c'), \text{Plug icon} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\text{Down arrow icon} \mid (\text{Battery icon} \rightsquigarrow \uparrow \mathbb{C}_{Unit})]^k \end{array}$$

PwOff

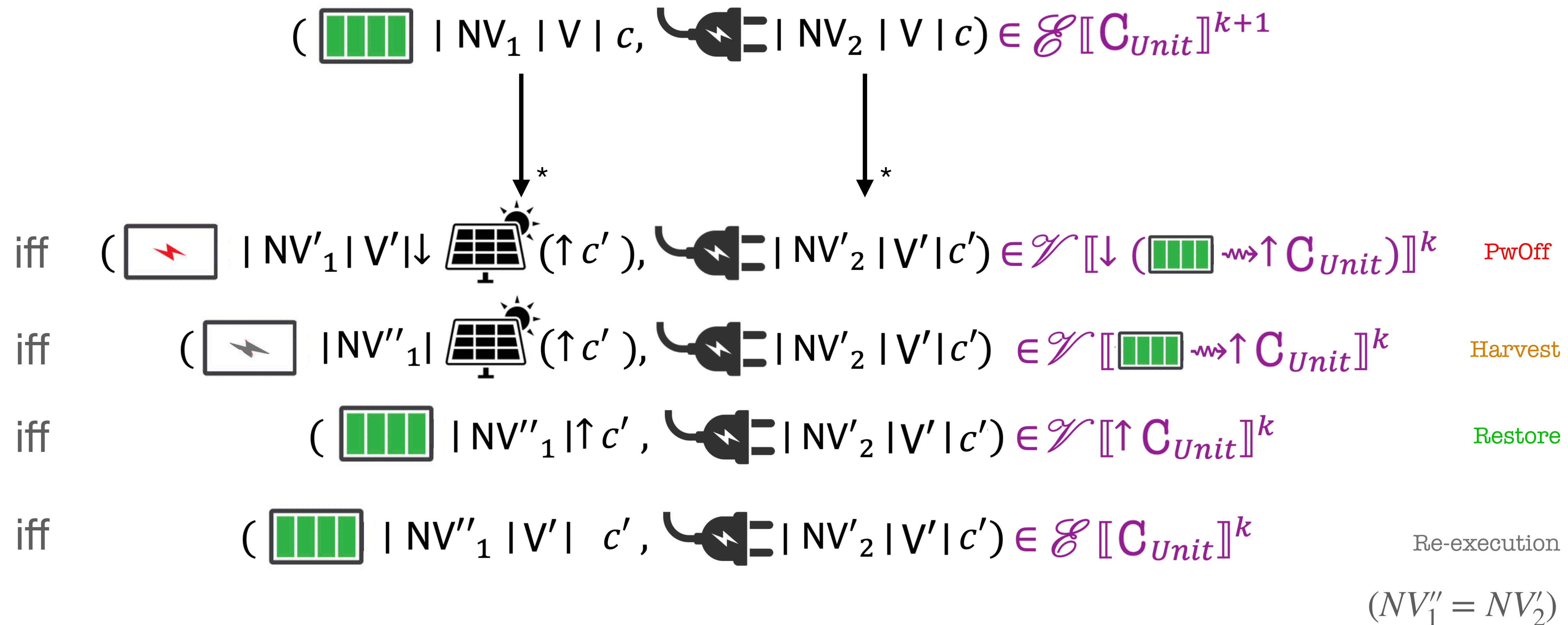
# Harvest energy from the environment



# Execution state is restored



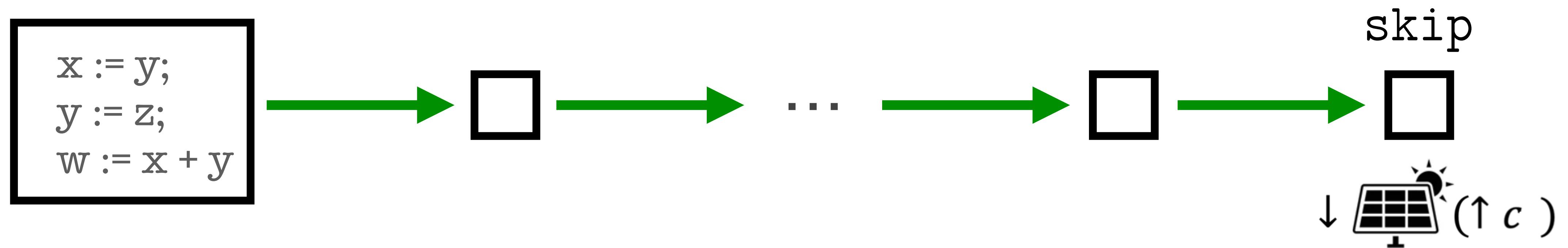
# Prepare for re-execution



# Outline

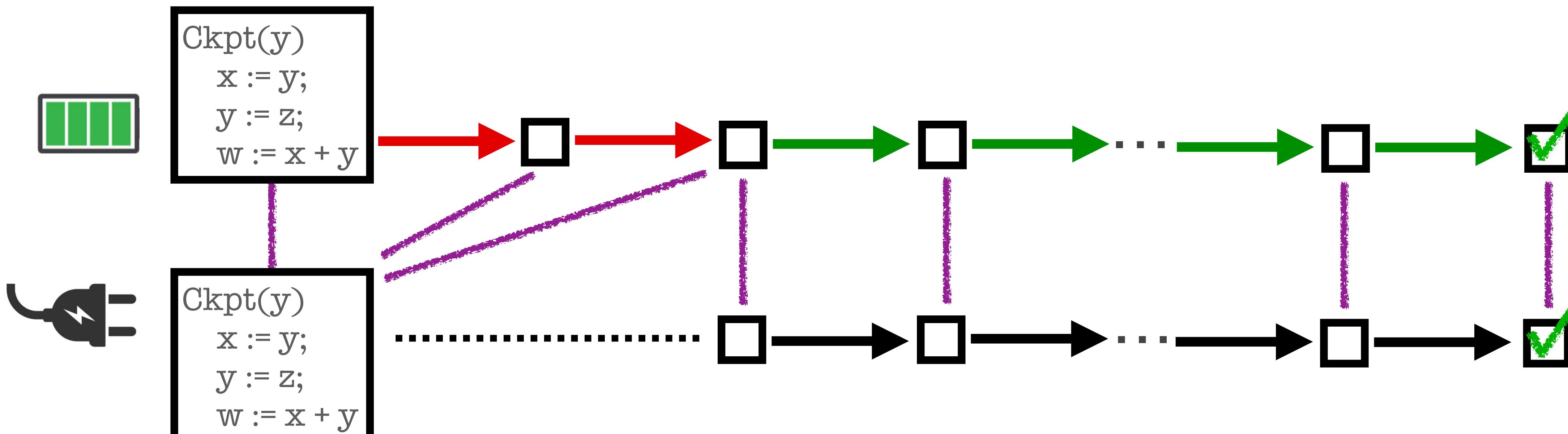
- Intermittent computing
- Overview
- Type system
- Logical relation
- JIT mode
- **Key theorems**
- Conclusion

# Progress and Preservation



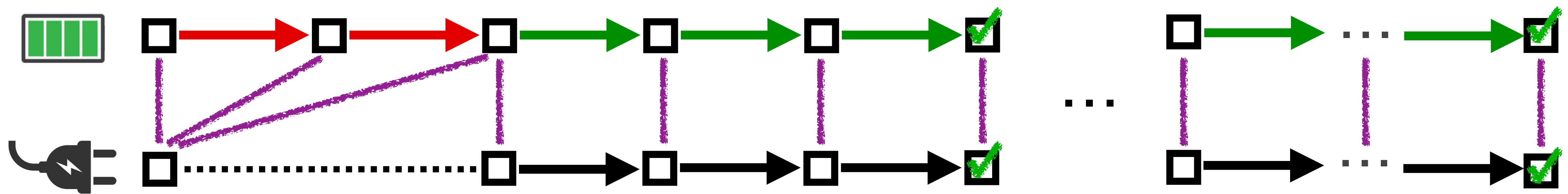
**Well-typed code doesn't get stuck and stays well-typed**

# Fundamental Theorem of Logical Relation



**Well-typed Atomic and JIT regions are self-related**

# Adequacy



**Every intermittent execution of a well-typed program can be simulated by its continuous execution**

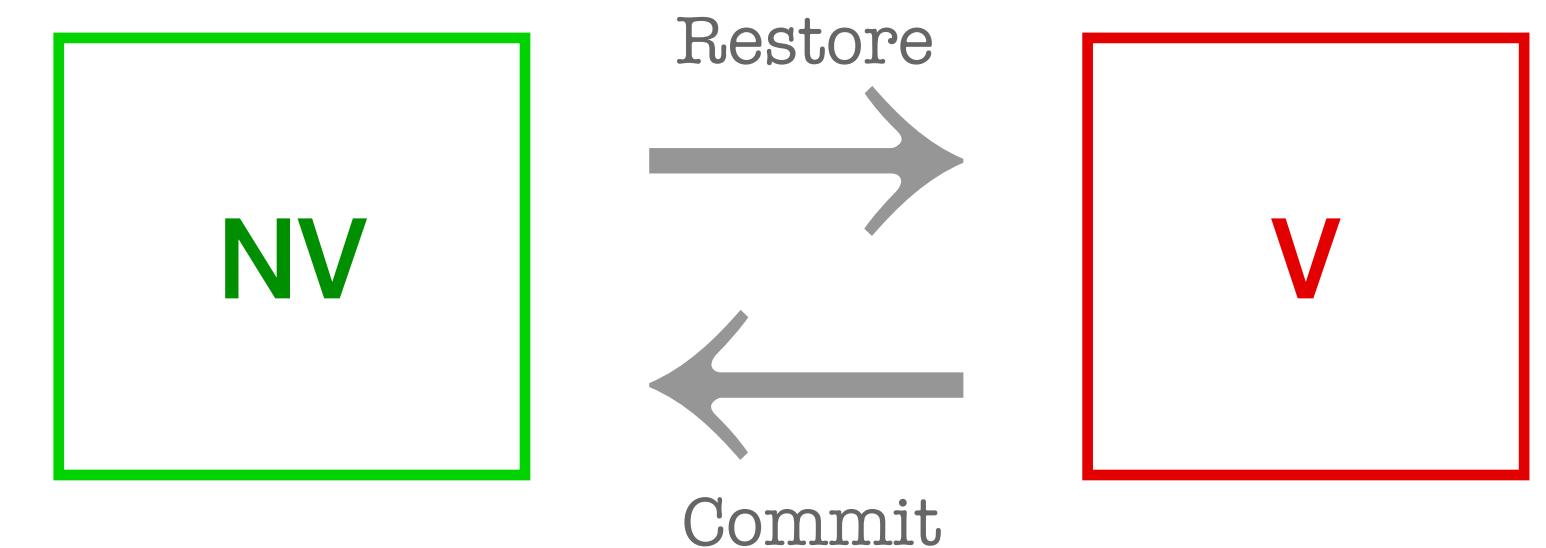


# Outline

- Intermittent computing
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- Key theorems
- **Conclusion**

# In this work, we developed...

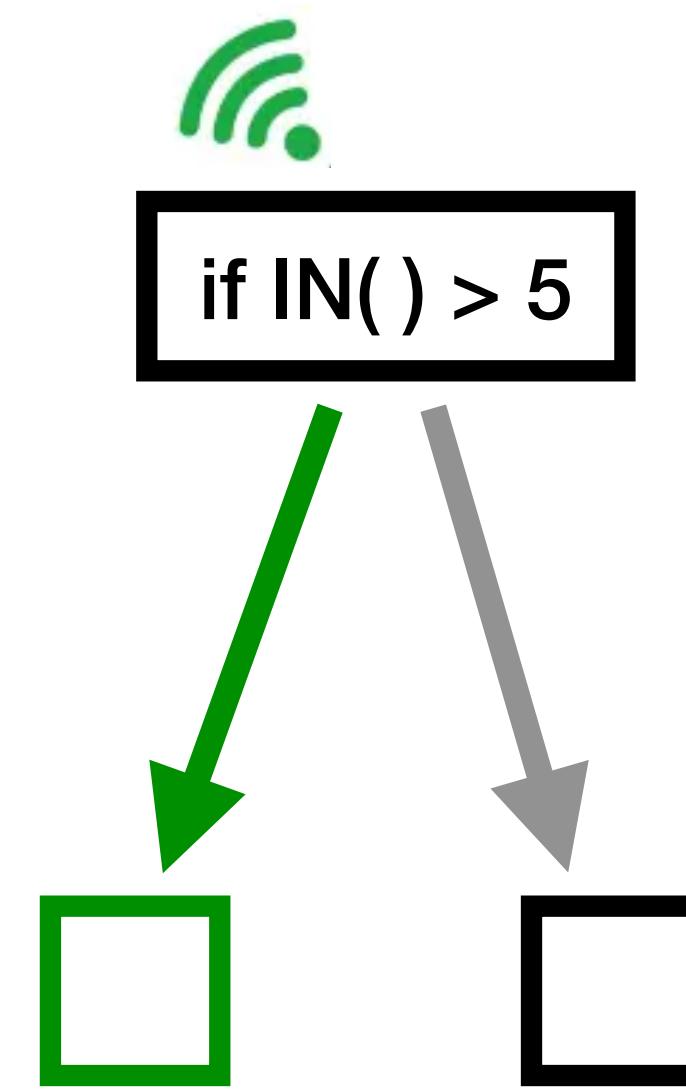
- One of the first type systems for intermittent computing
- First logical interpretation of key operations of intermittent execution
- A calculus for Crash types with type soundness
- A novel logical relation to characterize correctness



$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\text{nat} \rightsquigarrow \uparrow C)$$

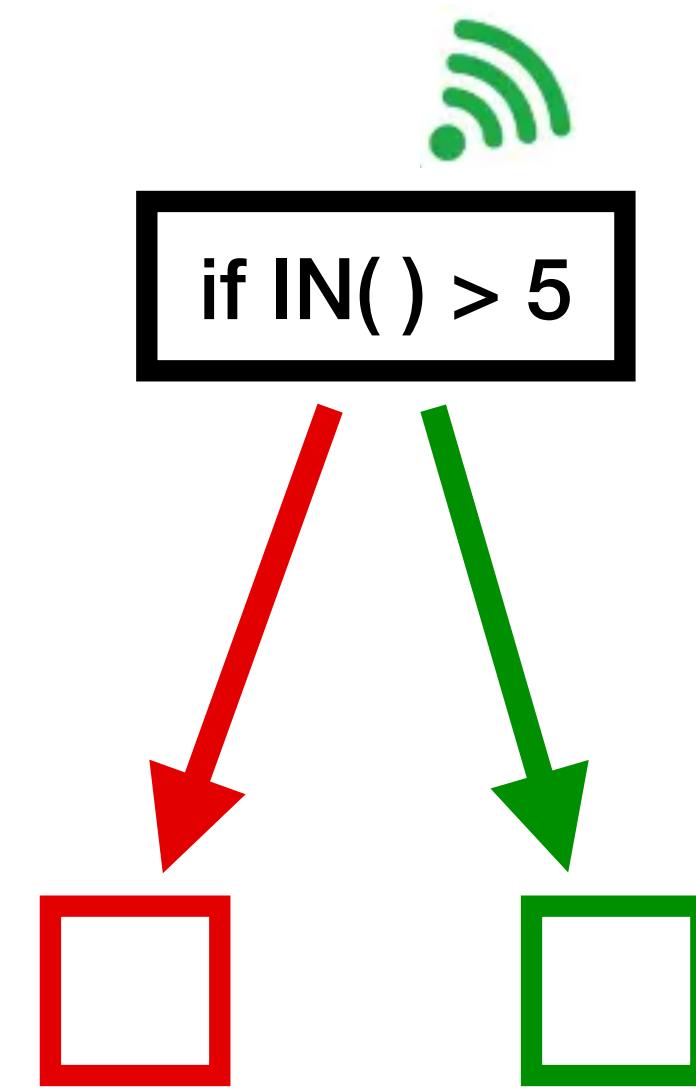
# Future work

- Repeated I/O bugs



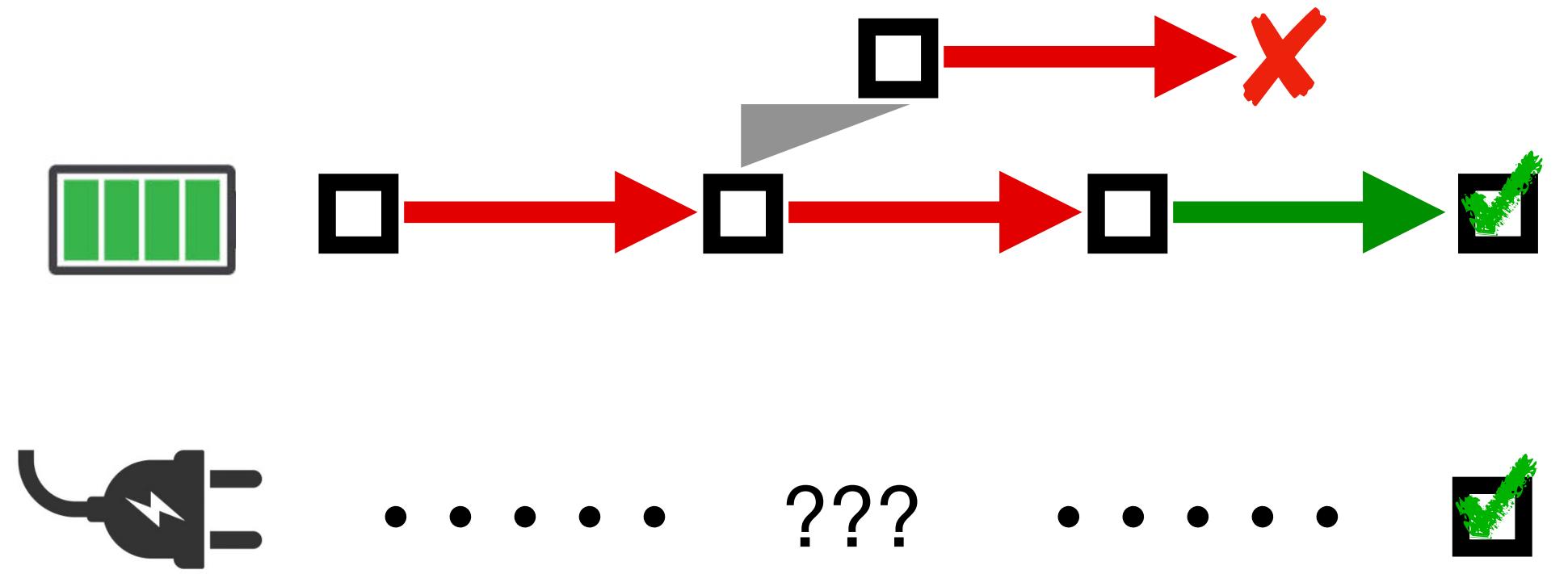
# Future work

- Repeated I/O bugs



# Future work

- Repeated I/O bugs
- Shared memory concurrency



# Future work

- Repeated I/O bugs
- Shared memory concurrency
- Other systems crash too!

$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\square \rightarrow \uparrow C)$$

Commit

PwOff

Restore

# Modal Crash Types for Intermittent Computing

**Myra Dotzel**  
**PhD student, CSD, CMU**

**Joint work with Farzaneh Derakhshan,  
Milijana Surbatovich, and Limin Jia**

