Introduction to Machine Learning CS/SE 4X03

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Outline

This is a summary of Sections 1-4 from C. F. Higham, D. J. Higham, Deep Learning: An Introduction for Applied Mathematicians

Figures are cropped from this article

Example

- ullet Points in \mathbb{R}^2 classified in two categories A and B
- This is labeled data

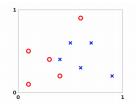
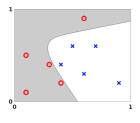


Figure 1: Labeled data points in \mathbb{R}^2 . Circles denote points in category A. Crosses denote points in category B.

 Given a new point, how to use the labeled data to classify this point?
 Possible classification



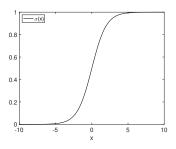
10 points

Activation function

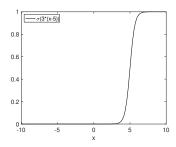
- A neuron fires or is inactive
- Activation can be modeled by the sigmoid function

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

• $\sigma(0)=0.5$, $\sigma(x)\approx 1$ when x large, $\sigma(x)\approx 0$ when x small



- Steepness can be changed by scaling
- Location can be changed by shifting
- Useful property $\sigma'(x) = \sigma(x)(1 \sigma(x))$



A simple network

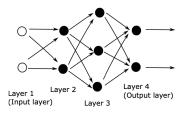


Figure 3: A network with four layers.

- Each neuron
 - o outputs a real number
 - o sends to every neuron in next layer
- Neuron in next layer
 - forms a linear combination of inputs + bias
 - o applies activation function

Consider layers 2 and 3

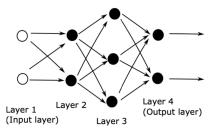
Layer 2: neurons 1 and 2 output real a_1 and a_2 , respectively, and send to neurons 1,2,3 in layer 3 Layer 3:

neuron 1 combines a_1 and a_2 and ads bias b_1 :

$$w_{11}a_1 + w_{12}a_2 + b_1$$

outputs $\sigma (w_{11}a_1 + w_{12}a_2 + b_1)$

- neuron 2 outputs $\sigma (w_{21}a_1 + w_{22}a_2 + b_2)$
- neuron 3 outputs $\sigma (w_{31}a_1 + w_{32}a_2 + b_3)$



Denote

$$W = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \\ w_{31} & w_{32} \end{bmatrix}, \qquad a = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}, \qquad b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$
$$z = Wa + b$$

W is a matrix with weights, b is a bias vector For a vector z, apply σ component wise

$$(\sigma(z))_i = \sigma(z_i)$$

The output of layer 3 is

$$\sigma(z) = \sigma(Wa + b)$$

- Denote the input by x, the W and b at layer i by $W^{[i]}$ and $b^{[i]}$, and the output of layer i by $a^{[i]}$
- Output of layer 2 is

$$a^{[2]} = \sigma \left(W^{[2]} x + b^{[2]} \right) \in \mathbb{R}^2, \qquad W^{[2]} \in \mathbb{R}^{2 \times 2}, \ b^{[2]} \in \mathbb{R}^2$$

• Output of layer 3 is

$$a^{[3]} = \sigma \left(W^{[3]} a^{[2]} + b^{[3]} \right) \in \mathbb{R}^3, \qquad W^{[3]} \in \mathbb{R}^{3 \times 2}, \ b^{[3]} \in \mathbb{R}^3$$

• Output of layer 4 is

$$a^{[4]} = \sigma \left(W^{[4]} a^{[3]} + b^{[4]} \right) \in \mathbb{R}^2, \qquad W^{[4]} \in \mathbb{R}^{2 \times 3}, \ b^{[4]} \in \mathbb{R}^2$$

• Write the above as

$$F(x) = \sigma \left(W^{[4]} \sigma \left(W^{[3]} \sigma \left(W^{[2]} x + b^{[2]} \right) + b^{[3]} \right) + b^{[4]} \right)$$

• Layer *i*:

- $\circ W^{[i]}$ is of size (# outputs) \times (# inputs)
- o $b^{[i]}$ is of size (# outputs)

Number of parameters is 23:

| $layer\ i$ | inputs | outputs | $W^{[i]}$ | $b^{[i]}$ |
|------------|--------|---------|--------------|-----------|
| 2 | 2 | 2 | 2×2 | 2 |
| 3 | 2 | 3 | 3×2 | 3 |
| 4 | 3 | 2 | 2×3 | 2 |
| | | | 16 | 7 |

- F(x) is a function from $\mathbb{R}^2 \to \mathbb{R}^2$ with 23 parameters
- Training is about finding parameters

Training Residual

- Denote the input points by $x^{\{i\}}$
- Let

$$y\left(x^{\{i\}}\right) = \begin{cases} \begin{bmatrix} 1\\0 \end{bmatrix} & \text{if } x^{\{i\}} \in A \\ \begin{bmatrix} 0\\1 \end{bmatrix} & \text{if } x^{\{i\}} \in B \end{cases}$$

- \bullet Suppose we have computed $W^{[2]},W^{[3]},W^{[4]},b^{[2]},b^{[3]},b^{[4]}$ and evaluate $F\left(x^{\{i\}}\right)$
- Residual

$$\left\| y\left(x^{\{i\}}\right) - F\left(x^{\{i\}}\right) \right\|_{2}$$

Training Cost function

Cost function

$$\begin{split} \mathsf{Cost}\left(W^{[2]}, W^{[3]}, W^{[4]}, b^{[2]}, b^{[3]}, b^{[4]}\right) \\ &= \frac{1}{10} \sum_{i=1}^{10} \frac{1}{2} \left\| y\left(x^{\{i\}}\right) - F\left(x^{\{i\}}\right) \right\|_2^2 \end{split}$$

- Training: find the parameters that minimize the cost function
- Nonlinear least squares problem

Classifying

- Suppose we have computed values for the parameters
- Given $x \in \mathbb{R}^2$, compute y = F(x)
- If $y_1 > y_2$ classify x as A, y closer to $[1,0]^T$
- If $y_1 < y_2$ classify x as B, y closer to $[0,1]^T$
- Tie breaking when =

Steepest descent

- Consider the parameters in a vector $p \in \mathbb{R}^s$. Here s=23
- Cost function is Cost(p)
- ullet Find Δp such that

$$\mathsf{Cost}(p + \Delta p) < \mathsf{Cost}(p)$$

• For small Δp ,

$$\begin{aligned} \mathsf{Cost}(p + \Delta p) &\approx \mathsf{Cost}(p) + \sum_{r=1}^{s} \frac{\partial \mathsf{Cost}(p)}{\partial p_r} \Delta p_r \\ &= \mathsf{Cost}(p) + \nabla \mathsf{Cost}(p)^T \Delta p \\ \nabla \mathsf{Cost}(p) &= \left[\frac{\partial \mathsf{Cost}(p)}{\partial p_1}, \frac{\partial \mathsf{Cost}(p)}{\partial p_2}, \cdots, \frac{\partial \mathsf{Cost}(p)}{\partial p_s} \right]^T \end{aligned}$$

Example

• To illustrate the above, suppose

$$\mathsf{Cost}(p) = p_1^2 + p_2^2 + 2p_1 + 3$$

• Gradient is

$$\nabla \mathsf{Cost}(p) = [2p_1 + 2, 2p_2]^T$$

$$\begin{aligned} \mathsf{Cost}(p + \Delta p) &\approx \mathsf{Cost}(p) + \nabla \mathsf{Cost}(p)^T \Delta p \\ &= \mathsf{Cost}(p) + (2p_1 + 2)\Delta p_1 + 2p_2 \Delta p_2 \end{aligned}$$

Steepest descent cont

- $\mathsf{Cost}(p) \ge 0$
- From

$$Cost(p + \Delta p) \approx Cost(p) + \nabla Cost(p)^T \Delta p$$

we want to make $\nabla \mathsf{Cost}(p)^T \Delta p$ as negative as possible

- Given $\nabla \mathsf{Cost}(p)$ how to choose Δp ?
- For $u, v \in \mathbb{R}^s$,

$$u^T v = \|u\| \cdot \|v\| \cos \theta$$

is most negative when v = -u

• Chose Δp in the direction of $-\nabla \mathrm{Cost}(p)$ That is move along the direction of steepest descent

$$\Delta p = p_{\mathsf{new}} - p = -\eta \nabla \mathsf{Cost}(p)$$
$$p_{\mathsf{new}} = p - \eta \nabla \mathsf{Cost}(p)$$

 η is learning rate

Steepest descent:

chose initial p repeat

$$p \leftarrow p - \eta \nabla \mathsf{Cost}(p)$$

until stopping criterion is met or $\max \#$ of iterations is reached

 \bullet In general N input points

$$\begin{split} \mathsf{Cost}(p) &= \frac{1}{N} \sum_{i=1}^{N} \underbrace{\frac{1}{2} \left\| y\left(x^{\{i\}}\right) - F\left(x^{\{i\}}\right) \right\|_{2}^{2}}_{C_{i}(p)} \\ &= \frac{1}{N} \sum_{i=1}^{N} C_{i}(p) \\ \nabla \mathsf{Cost}(p) &= \frac{1}{N} \sum_{i=1}^{N} \nabla C_{i}(p) \end{split}$$

- \bullet N can be large
- Number of parameters can be very large
- Evaluating $\nabla \mathsf{Cost}(p)$ can be very expensive

Stochastic gradient descent

- \bullet Idea: replace $\frac{1}{N} \sum_{i=1}^N \nabla C_i(p)$ by random $\nabla C_i(p)$
- Iterate until a stopping criterion is met or max # of iterations is reached:
 - \circ pick a random integer i from $\{1, 2, \dots, N\}$
 - $\circ p \leftarrow p \eta \nabla C_i(p)$