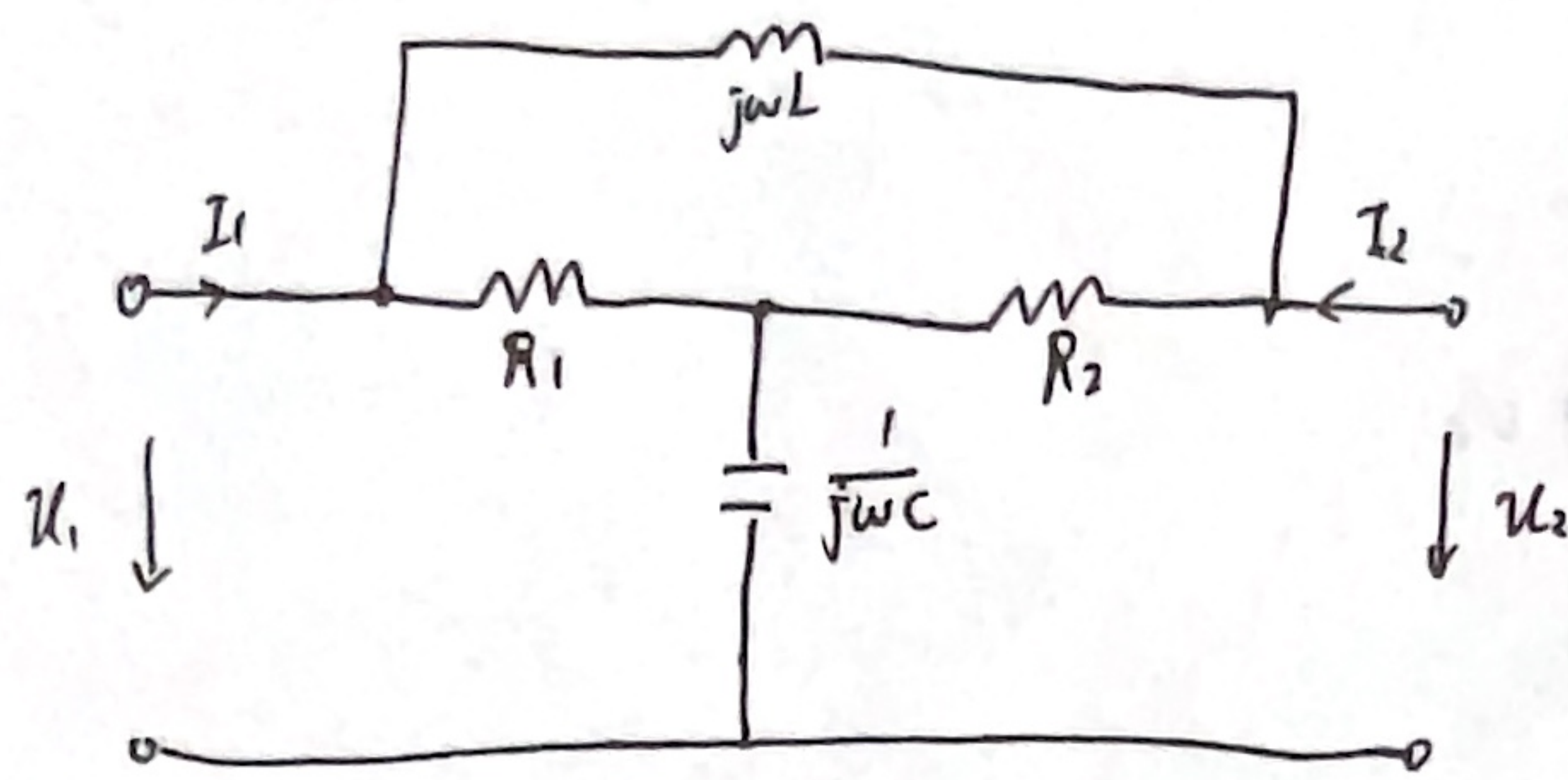
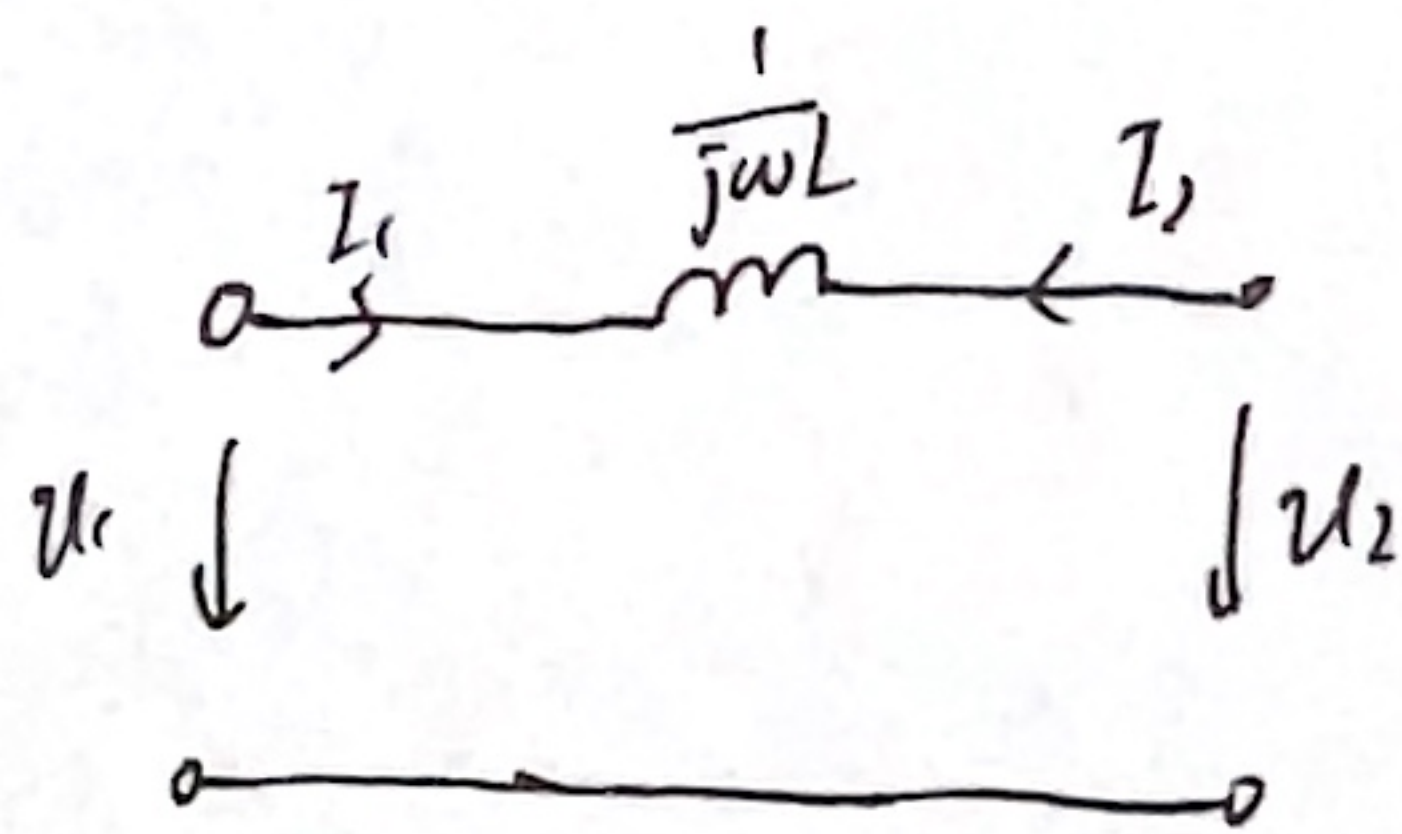


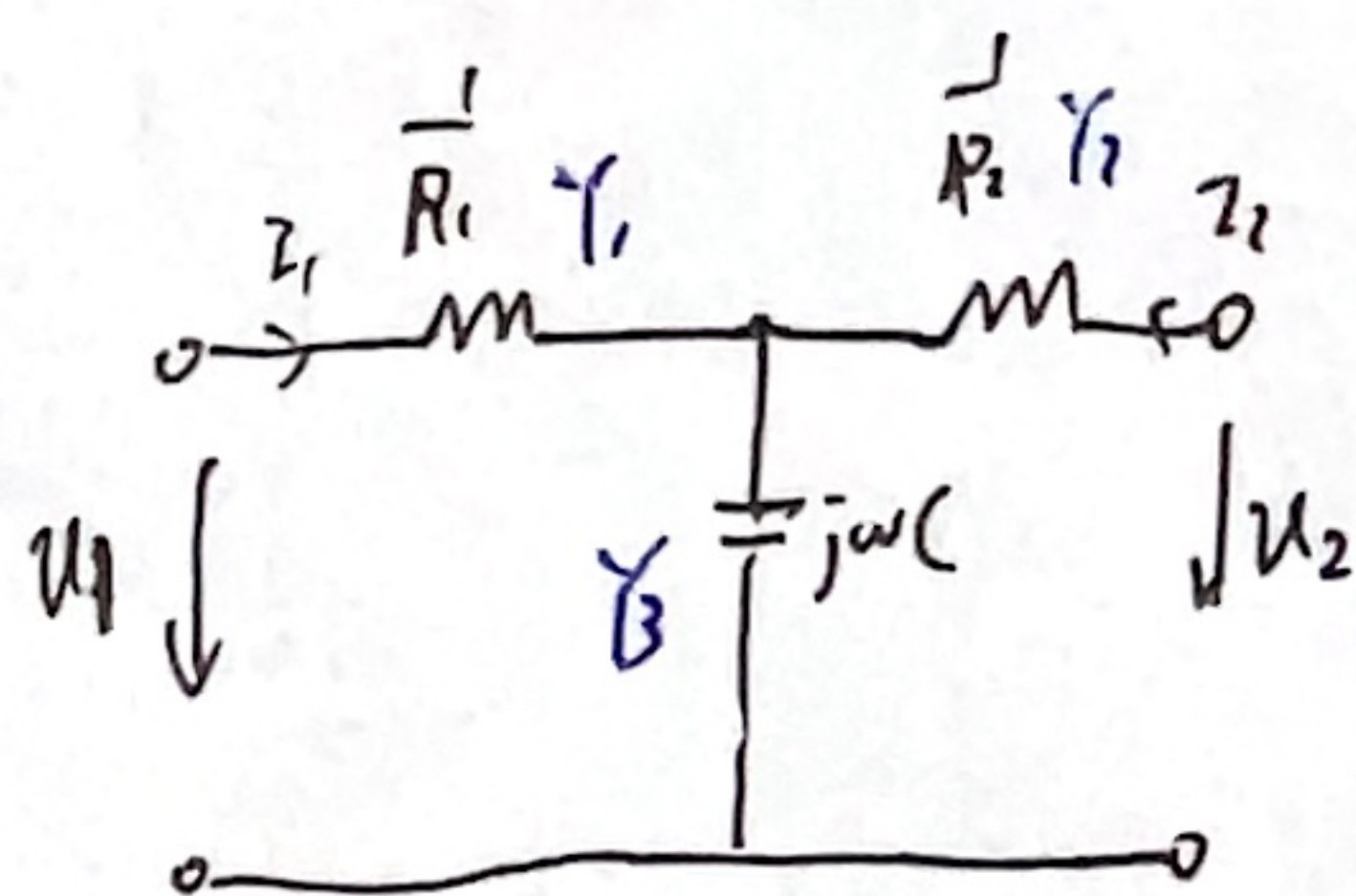
Zweiter



mit \underline{Y} Matrix



$$\underline{Y} = \begin{pmatrix} Y & -Y \\ -Y & Y \end{pmatrix} \Rightarrow \underline{Y}_1 = \begin{pmatrix} j\omega L & -\frac{1}{j\omega L} \\ -\frac{1}{j\omega L} & j\omega L \end{pmatrix}$$



$$\underline{Y} = \frac{1}{N} \begin{pmatrix} Y_1(Y_2 + Y_3) & -Y_1 Y_2 \\ -Y_1 Y_2 & Y_2(Y_1 + Y_3) \end{pmatrix}$$

$$N = Y_1 + Y_2 + Y_3$$

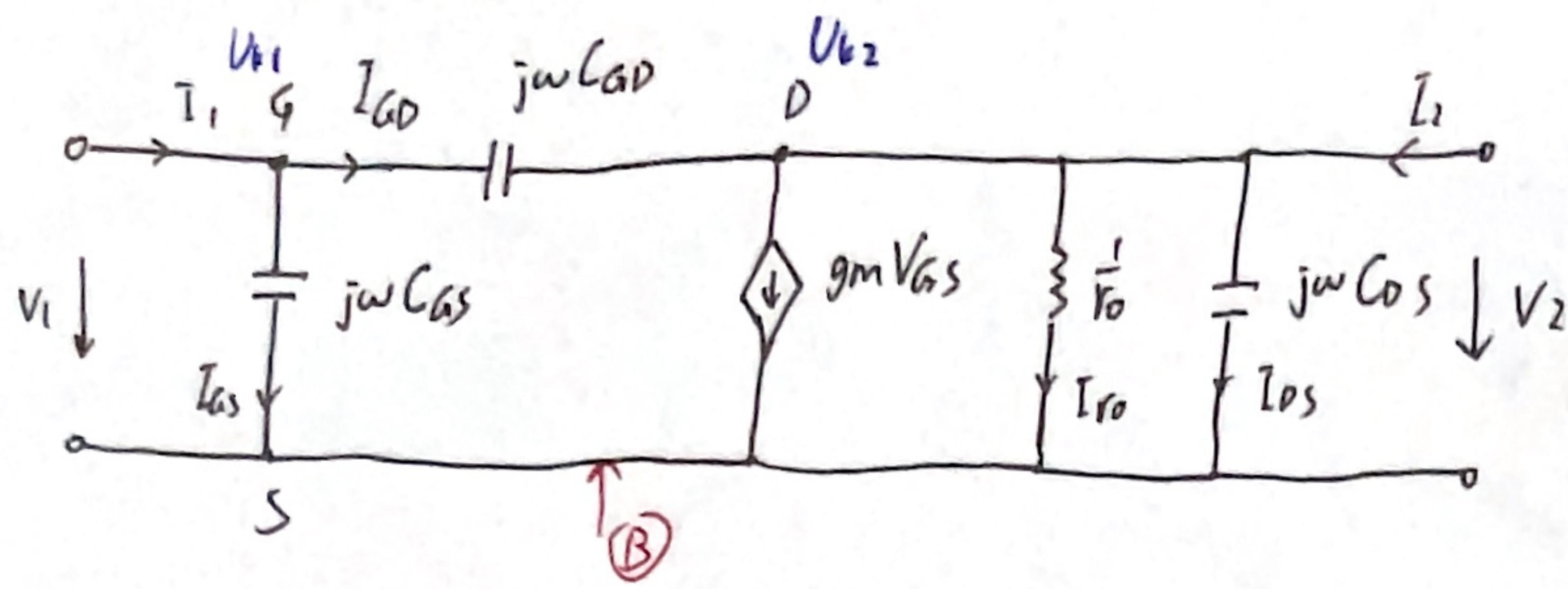
$$N = \frac{1}{R_1} + \frac{1}{R_2} + j\omega C$$

$$Y_{11} = \frac{1}{R_1} \left(\frac{1}{R_2} + j\omega C \right), \quad Y_{12} = Y_{21} = -\frac{1}{R_1 R_2}, \quad Y_{22} = \frac{1}{R_2} \left(\frac{1}{R_1} + j\omega C \right)$$

$$\underline{Y}_2 = \begin{pmatrix} \frac{1}{R_1} \left(\frac{1}{R_2} + j\omega C \right) & -\frac{1}{R_1 R_2} \\ -\frac{1}{R_1 R_2} & \frac{1}{R_2} \left(\frac{1}{R_1} + j\omega C \right) \end{pmatrix} \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + j\omega C}$$

$$\Rightarrow \underline{Y} = \underline{Y}_1 + \underline{Y}_2 = \begin{pmatrix} j\omega L + \frac{\frac{1}{R_1} \left(\frac{1}{R_2} + j\omega C \right)}{\frac{1}{R_1} + \frac{1}{R_2} + j\omega C} & -\frac{1}{j\omega L} - \frac{\frac{1}{R_1 R_2}}{\frac{1}{R_1} + \frac{1}{R_2} + j\omega C} \\ -\frac{1}{j\omega L} - \frac{\frac{1}{R_1 R_2}}{\frac{1}{R_1} + \frac{1}{R_2} + j\omega C} & j\omega L + \frac{\frac{1}{R_2} \left(\frac{1}{R_1} + j\omega C \right)}{\frac{1}{R_1} + \frac{1}{R_2} + j\omega C} \end{pmatrix}$$

mit gesteuert



节点电压法, 含受控源

① 对 G, D 列 KCL

$$\begin{cases} I_1 = I_{GD} + I_{GS} \\ I_{GD} = gmV_{GS} + I_{ro} + I_{DS} - I_2 \end{cases} \Leftrightarrow \begin{cases} I_1 = I_{GD} + I_{GS} \\ I_2 = gmV_{GS} + I_{ro} + I_{DS} - I_{GD} \end{cases}$$

② 找到 KCL 中的 V_{GS} 关系

$$\begin{cases} V_{GS} = V_1 \\ I_{GS} = jwC_{GS} \cdot V_{GS} = jwC_{GS} \cdot V_1 \\ I_{GD} = jwC_{GD} \cdot V_{GD} = jwC_{GD} (V_1 - V_2) \end{cases}$$

③ $YV=I$ ---

Knotenpotentialverfahren. 节点电压法

$$\begin{aligned} Y_{11} &= jwC_{GS} + jwC_{GD} \\ Y_{22} &= jwC_{GD} + \frac{1}{r_0} + jwC_{DS} \\ Y_{12} &= jwC_{GD} = Y_{21} \end{aligned} \quad \begin{cases} \text{positiv} \\ \text{negativ} \end{cases}$$

$$I_1 = I_1$$

$$I_2 = I_2 - gmV_{GS}$$

流入正
流出负

$$\begin{pmatrix} jwC_{GS} + jwC_{GD} & -jwC_{GD} \\ -jwC_{GD} & jwC_{GD} + \frac{1}{r_0} + jwC_{DS} \end{pmatrix} \begin{pmatrix} V_{k1} \\ V_{k2} \end{pmatrix} = \begin{pmatrix} I_1 \\ I_2 - gmV_{GS} \end{pmatrix}$$

$$\begin{cases} V_{k1} = V_{GS} = V_1 \\ V_{k2} = V_{DS} = V_2 \\ V_{GS} = V_1 \end{cases}$$

$$\Rightarrow \begin{pmatrix} jwC_{GS} + jwC_{GD} & -jwC_{GD} \\ gm - jwC_{GD} & jwC_{GD} + \frac{1}{r_0} + jwC_{DS} \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$$

$$\Rightarrow V_1 = \frac{\begin{vmatrix} I_2 & -jwC_{GD} \\ I_1 & jwC_{GD} + \frac{1}{r_0} + jwC_{DS} \end{vmatrix}}{\det Y}, \quad V_2 = \frac{\begin{vmatrix} jwC_{GS} + jwC_{GD} & I_1 \\ gm - jwC_{GD} & I_2 \end{vmatrix}}{\det Y}$$

$$Z_{11} = \frac{V_1}{I_1} \Big|_{I_2=0} = \frac{\begin{vmatrix} I_1 & -jwC_{GD} \\ 0 & jwC_{GD} + \frac{1}{r_0} + jwC_{DS} \end{vmatrix}}{I_1 \det Y}$$

$$Z_{12} = \frac{V_1}{I_2} \Big|_{I_1=0} = Z_{21}$$

$$Z_{22} = \frac{V_2}{I_2} \Big|_{I_1=0} = \frac{\begin{vmatrix} jwC_{GS} + jwC_{GD} & 0 \\ gm - jwC_{GD} & I_2 \end{vmatrix}}{I_2 \det Y}$$