Performance Metrics for Parallel Systems and Asymptotic Analysis of Parallel Programs

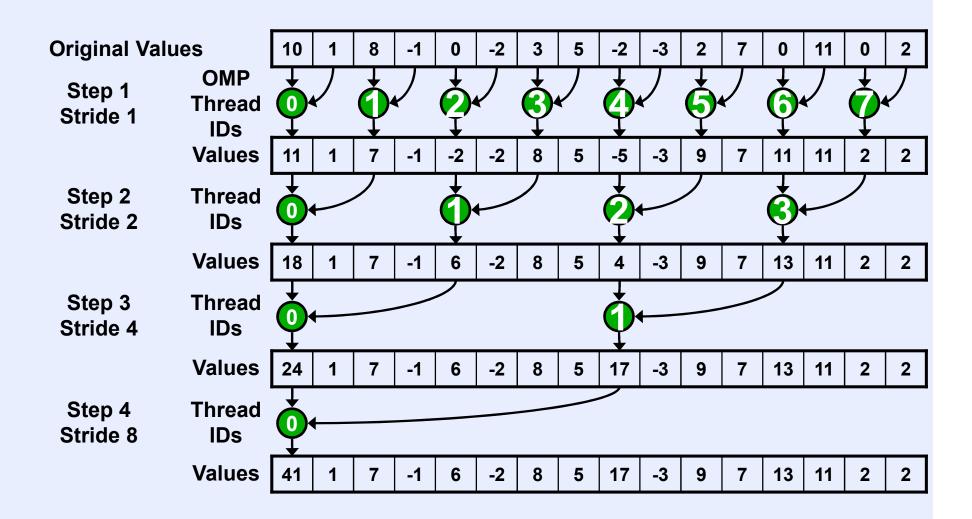
Ref: ``Introduction to Parallel Computing'', Addison Wesley, 2003. A Grama, A Gupta, G Karypis, and V Kumar

Effect of Granularity on Performance

- Often, using fewer processors improves performance of parallel systems.
- Using fewer than the maximum possible number of processing elements to execute a parallel algorithm is called scaling down a parallel system.
- A naive way of scaling down is to think of each processor in the original case as a virtual processor and to assign virtual processors equally to scaled down processors.
- ➢ Since the number of processing elements decreases by a factor of *n* / *p*, the computation at each processing element increases by a factor of *n* / *p*.
- ➤ The communication cost should not increase by this factor since some of the virtual processors assigned to a physical processors might talk to each other. This is the basic reason for the improvement from building granularity.

- \triangleright Consider the problem of adding n numbers on p processing elements such that p < n and both n and p are powers of 2.
- ➤ Use the parallel algorithm for *n* processors, except, in this case, we think of them as virtual processors.
- ➤ Each of the p processors is now assigned n / p virtual processors.
- \triangleright The first $\log p$ of the $\log n$ steps of the original algorithm are simulated in $(n/p)\log p$ steps on p processing elements.
- Subsequent log n log p steps do not require any communication.
- A single processing element is left with n/p numbers taking time O(n/p).

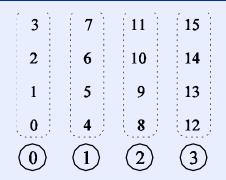
Parallel Reduction SUM

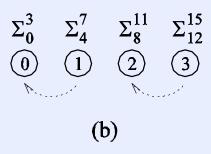


The overall parallel execution time of this parallel system is
 ⊙ ((n / p) log p).

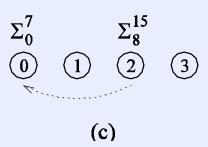
The cost is Θ ($n \log p$), which is asymptotically higher than the Θ (n) cost of adding n numbers sequentially. Therefore, the parallel system is not cost-optimal.

Can we build granularity in the example in a cost-optimal fashion?





Each processing element locally adds its n / p numbers in time
 Θ (n / p).



(a)

$$\Sigma_0^{15}$$
0 1 2 3

A cost-optimal way of computing the sum of 16 numbers using four processing elements.

The p partial sums on p processing elements can be added in time $\Theta(n/p)$.

> The parallel runtime of this algorithm is

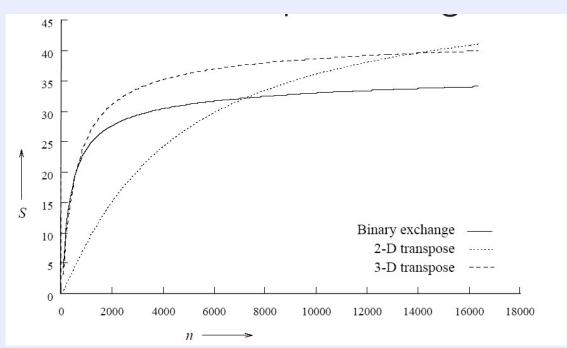
$$T_P = \Theta(n/p + \log p),$$

- ightharpoonup The cost is $\Theta(n+p\log p)$
- \succ This is cost-optimal, so long as $n = \Omega(p \log p)$

Scalability of Parallel Systems

How do we extrapolate performance from small problems and small systems to larger problems on larger configurations?

Consider three parallel algorithms for computing an *n*-point Fast Fourier Transform (FFT) on 64 processing elements.



A comparison of the speedups obtained by the binary-exchange, 2-D transpose and 3-D transpose algorithms on 64 processing elements. Clearly, it is difficult to infer scaling characteristics from observations on small datasets on small machines.

Scaling Characteristics

The efficiency of a parallel program can be written as:

$$E = \frac{S}{p} = \frac{T_S}{pT_P}$$

$$E = \frac{1}{1 + \frac{T_o}{T_S}}.$$

or

 \succ The total overhead function T_o is an increasing function of p .

Scaling Characteristics

- For a given problem size (i.e., the value of T_s remains constant), as we increase the number of processing elements, T_o increases.
- ➤ The overall efficiency of the parallel program goes down. This is the case for all parallel programs.

Scaling Characteristics

- Consider the problem of adding n numbers on p processing elements.
- We have seen that:

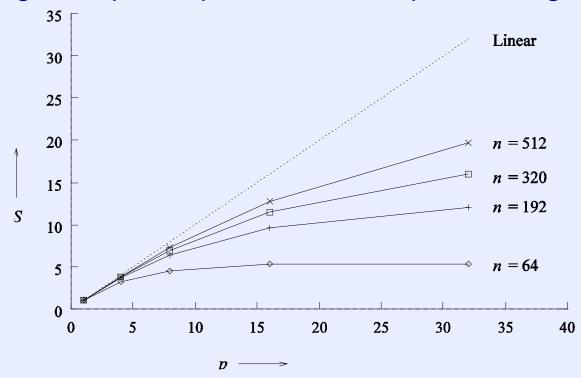
$$T_P = \frac{n}{p} + 2\log p$$

$$S = \frac{n}{\frac{n}{p} + 2\log p}$$

$$E = \frac{1}{1 + \frac{2p \log p}{n}}$$

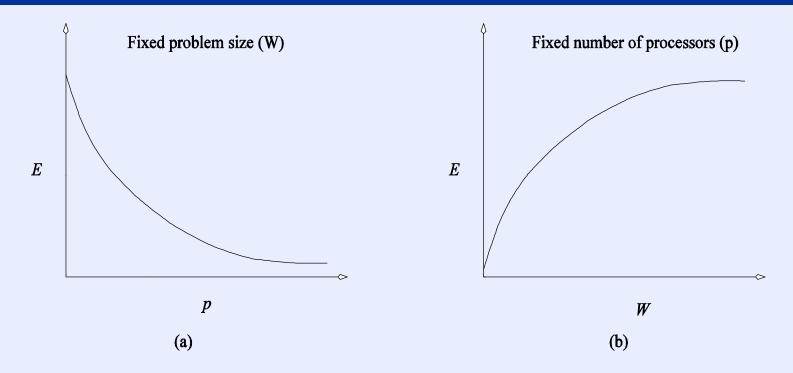
Scaling Characteristics of Parallel Programs

Plotting the speedup for various input sizes gives us:



Speedup versus the number of processing elements for adding a list of numbers.

Speedup tends to saturate and efficiency drops as a consequence of Amdahl's law.



Variation of efficiency: (a) as the number of processing elements is increased for a given problem size; and (b) as the problem size is increased for a given number of processing elements. The phenomenon illustrated in graph (b) is not common to all parallel systems.

- ➤ What is the rate at which the problem size must increase with respect to the number of processing elements to keep the efficiency fixed?
- ➤ This rate determines the scalability of the system. The slower this rate, the better.
- Before we formalize this rate, we define the problem size
 W as the asymptotic number of operations associated with the best serial algorithm to solve the problem.

We can write parallel runtime as:

$$T_P \,=\, rac{W + T_o(W,p)}{p}$$

The resulting expression for speedup is

$$S = rac{W}{T_P} \ - rac{Wp}{W + T_o(W,p)}.$$

Finally, we write the expression for efficiency as

$$E = \frac{S}{p}$$

$$= \frac{W}{W + T_o(W, p)}$$

$$= \frac{1}{1 + T_o(W, p)/W}$$

- For scalable parallel systems, efficiency can be maintained at a fixed value (between 0 and 1) if the ratio T_o / W is maintained at a constant value.
- For a desired value E of efficiency,

$$E=rac{1}{1+T_o(W,p)/W}, \ rac{T_o(W,p)}{W}=rac{1-E}{E}, \ W=rac{E}{1-E}T_o(W,p).$$

➤ If K = E / (1 - E) is a constant depending on the efficiency to be maintained, since T_o is a function of W and p, we have

$$W = KT_o(W, p)$$
.

- ➤ The problem size W can usually be obtained as a function of p by algebraic manipulations to keep efficiency constant.
- This function is called the isoefficiency function.
- ➤ This function determines the ease with which a parallel system can maintain a constant efficiency and hence achieve speedups increasing in proportion to the number of processing elements