# ALJABAR LINIER

DR. RETNO KUSUMANINGRUM, S.SI., M.KOM.

## Sistem Persamaan Linear

### LINEAR EQUATION

■ A **linear equation** in the variables  $X_1, \ldots, X_n$  is an equation that can be written in the form

$$a_1 x_1 + a_2 x_2 + \dots + a_n x_n = b$$
,

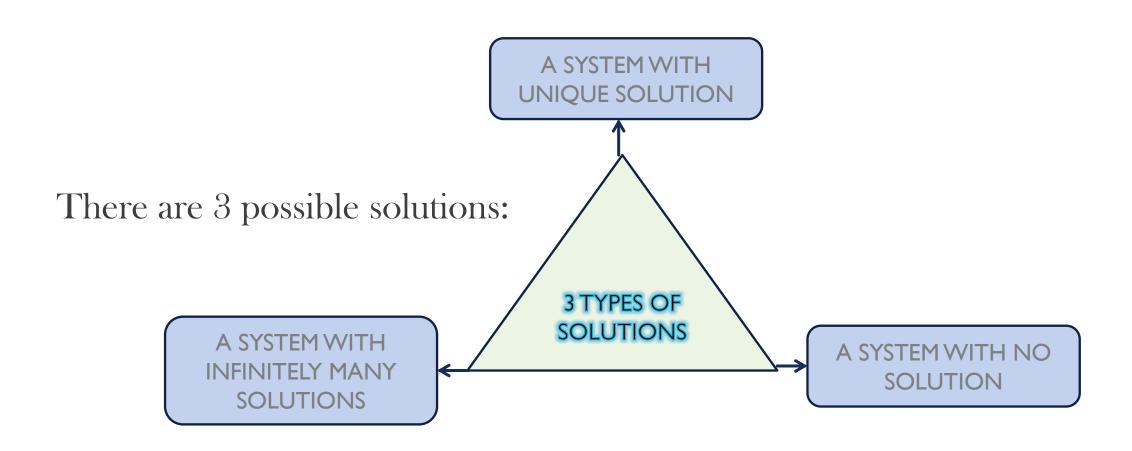
where b and the coefficients  $a_1, \ldots, a_n$  are real or complex numbers that are usually known in advance.

• A system of linear equations (or a linear system) is a collection of one or more linear equations involving the same variables — say,  $x_1, ..., x_n$ .

### LINEAR EQUATION

- A **solution** of the system is a list  $(s_1, s_2, ..., s_n)$  of numbers that makes each equation a true statement when the values  $s_1, ..., s_n$  are substituted for  $x_1, ..., x_n$ , respectively.
- The set of all possible solutions is called the solution set of the linear system.
- Two linear systems are called equivalent if they have the same solution set.

### TYPES OF SOLUTIONS TO SYSTEMS OF LINEAR EQUATIONS



### A SYSTEMS WITH UNIQUE SOLUTION

$$x_1 + 2x_2 = 3$$

$$x_1 + 2x_2 = 3$$
$$0x_1 + x_2 = 2$$

Augmented matrix: 
$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{bmatrix}$$

The system has unique solution:

$$x_2 = 2, \quad x_1 = -1$$

#### A SYSTEMS WITH INFINITELY MANY SOLUTION

Consider the system: 
$$x_1 + 2x_2 = 3$$

$$x_1 + 2x_2 = 3$$
$$0x_1 + 0x_2 = 0$$

Augmented matrix: 
$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

The system has many solutions: let  $x_2 = s$ , where s is called a free variable. Then,  $x_1 = 3 - 2s$ ,

#### A SYSTEMS WITH NO SOLUTION

Consider the system:  $x_1 + 2x_2 = 3$ 

$$0x_1 + 0x_2 = 2$$

Augmented matrix:  $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 2 \end{bmatrix}$ 

■ The system has no solution, since coefficient of  $x_2$  is '0'.

$$(0x_2 \neq 2)$$

### SOLVING SYSTEMS OF EQUATIONS

### Systems of linear equations:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

#### SOLVING SYSTEMS OF EQUATIONS

## 4 methods used to solve systems of equations.

- 1) The Inverse of the Coefficient Matrix
- 2) Gauss Elimination
- 3) Gauss-Jordan Elimination
- 4) Cramer's Rule

#### SOLVING SYSTEMS OF EQUATIONS

Matrix Form: AX = B

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

To find  $X: X = A^{-1}B$ 

Method :  $X = A^{-1}B$ 

### Example:

Solve the system by using  $A^{-1}$ , the inverse of the coefficient matrix:

$$x + y + z = 0$$
$$2x - y + z = -1$$
$$-x + 3y - z = -8$$

Solution:
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ -1 & 3 & -1 \end{bmatrix} \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

$$AX = B$$
:

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ -1 & 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

Find 
$$A^{-1}$$
: 
$$A^{-1} = \frac{1}{|A|} adj [A]$$

Cofactor of 
$$A$$
:
$$\begin{bmatrix}
-2 & 1 & 5 \\
4 & 0 & -4 \\
2 & 1 & -3
\end{bmatrix}$$

Therefore: 
$$adj[A] = \begin{bmatrix} -2 & 4 & 2 \\ 1 & 0 & 1 \\ 5 & -4 & -3 \end{bmatrix}, \quad |A| = 4$$

Find 
$$X$$
:  $X = A^{-1}B$ 

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -2 & 4 & 2 \\ 1 & 0 & 1 \\ 5 & -4 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

$$= \begin{bmatrix} -5 \\ -2 \\ 7 \end{bmatrix} \qquad \therefore x = -5, y = -2, z = 7$$

### Example 2:

Solve the system by using  $A^{-1}$ , the inverse of the coefficient matrix:

$$x-3y+z=1$$

$$2x-y+2z=2$$

$$x+2y-3z=-1$$

Answer: 
$$x = \frac{1}{2}, y = 0, z = \frac{1}{2}$$

Consider the systems of linear eq:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

Write in augmented form:  $[A \mid B]$ 

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_n \end{bmatrix}$$

Using ERO, such that A may be reduce in REF/Upper Triangular

### Example:

Solve the system by using Gauss Elimination method:

$$x + y + z = 0$$
$$2x - y + z = -1$$
$$-x + 3y - z = -8$$

### Solution:

Write in augmented form:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & -1 & 1 & -1 \\ -1 & 3 & -1 & -8 \end{bmatrix}$$

Reduce to REF: (Diagonal = 1)

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & -1 & 1 & -1 \\ -1 & 3 & -1 & -8 \end{bmatrix} H_{21(-2)} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 4 & 0 & -8 \end{bmatrix} H_{32(\frac{4}{3})} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 0 & -\frac{4}{3} & -\frac{28}{3} \end{bmatrix} H_{2(-\frac{1}{3})} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & \frac{1}{7} \end{bmatrix}$$

## GAUSS JORDAN ELIMINATION

### GAUSS JORDAN ELIMINATION

Written in augmented form :  $[A \mid B]$ 

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_n \end{bmatrix}$$

Using ERO, such that A may be reduce in RREF/IDENTITY
 (DIAGONAL = 1, OTHER ENTRIES = 0)

Reduce to RREF: (Diagonal = 1, Other entries = 0)

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & -1 & 1 & -1 \\ -1 & 3 & -1 & -8 \end{bmatrix} H_{21(-2)} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 4 & 0 & -8 \end{bmatrix} H_{32(\frac{4}{3})} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 0 & -\frac{4}{3} & -\frac{28}{3} \end{bmatrix} H_{2(-\frac{1}{3})} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & \frac{1}{7} \end{bmatrix}$$

#### Example 2:

Solve the system by Gauss elimination.

$$x-3y+z=1$$

$$2x-y+2z=2$$

$$x+2y-3z=-1$$

Answer: 
$$x = \frac{1}{2}, y = 0, z = \frac{1}{2}$$

### GAUSS JORDAN ELIMINATION

#### Example 4:

Solve the system by Gauss Jordan elimination.

$$x + y + z = 4$$

$$x - y - z = 0$$

$$x - y + z = 0$$

$$x = 2$$
,  $y = 2$ ,  $z = 0$ 

Answer:

## **CRAMMER RULES**

#### Theorem 5

#### Cramer's Rule for 3x3 system

Given the system:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_1 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_2 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

with:

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \neq 0$$

If: 
$$D_{x_1} = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix} \quad D_{x_2} = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix} \quad D_{x_3} = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Then: 
$$x = \frac{D_{x_1}}{D} \quad y = \frac{D_{x_2}}{D} \quad z = \frac{D_{x_3}}{D}$$

$$D_{x_1} = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix} \quad D_{x_2} = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix} \quad D_{x_3} = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Step to solve *n* linear inhomogeneous equations in *n* variables proceed as follows:

- i. Compute |D|, the determinant of the coefficient matrix, and, if  $|D| \neq 0$ , proceed to the next step.
- ii. Compute the modified coefficient determinants  $|D_i|$ , i = 1, 2, ..., n where  $D_i$  is derived from D by replacing the i-th column of D by the inhomogeneous vector B;
- iii. The solutions  $x_1, x_2, ..., x_n$  are given by  $x_i = \frac{|D_i|}{|D|}$  for i = 1, 2, ..., n.
- iv. If |D| = 0 the Cramer's rule cannot be applied. In such a case, either a unique solution to the system does not exist or there is no solution.

#### Example 5:

Solve the system by using the Cramer's Rule.

$$x + y + z = 4$$

$$x - y - z = 0$$

$$x - y + z = 0$$

#### **Solution**

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 1 & -1 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

#### Determinant of A:

$$|A| = D = 1$$
 $\begin{vmatrix} -1 & -1 \\ -1 & 1 \end{vmatrix} - \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix} + \begin{vmatrix} 1 & -1 \\ 1 & -1 \end{vmatrix} = -4$ 

$$D_{x} = \begin{vmatrix} 4 & 1 & 1 \\ 0 & -1 & -1 \\ 0 & -1 & 1 \end{vmatrix} = 4 \begin{vmatrix} -1 & -1 \\ -1 & 1 \end{vmatrix} = -8 \quad \Rightarrow \quad x = \frac{-8}{-4} = 2$$

$$D_{y} = \begin{vmatrix} 1 & 4 & 1 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{vmatrix} = -4 \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix} = -8 \quad \Rightarrow \quad y = \frac{-8}{-4} = 2$$

$$D_{x} = \begin{vmatrix} 1 & 1 & 4 \\ 1 & -1 & 0 \\ 1 & -1 & 0 \end{vmatrix} = 4 \begin{vmatrix} 1 & -1 \\ 1 & -1 \end{vmatrix} = 0 \quad \Rightarrow \quad z = \frac{0}{-4} = 0$$

#### Example 6:

Solve the system by using Cramer's Rule. x+2y=z-1 x=4+y-z x+y-3z=-2

Answer:

$$x = 2$$
,  $y = -1$ ,  $z = 1$