Mochammad Dzahwan Fadhloly 24060121140168 Informatika B

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1. Dik = A (2,5)
      radius = 13
  Dit: Pembuatan lingkaran dengan algoritma bressenham mid point algorithm!
  Jawab:
  \rightarrow (x = x.x_z, y = y.y_z)
       x_0, y_0 = (0, 13) (x_2, y_2) = (2.5) initial point
      Po = 1-1
         = 1-13 = -12
      PK < 0 = plot (xk+1, yk)
              LD Pk+1 = Pk + 2(xk+1)+1
     Pk > 0 = plot (xu.+1, yk -1)
              Lo Pu+1 = Pk + 2 (xk+1)+1 -2(yk-1)
  ·> Menenthkan Pixel
     K=0 , Po = -12 , (1,13)
     k=1 , P, = Po + 2(x+1)+1
              = -12 + 2 (0+1) +1
              = -9, (2, 13)
     k=2, Pz = -9 +2(1+1)+1
              = -4, (3,13)
     4=3, P3 = -4 +2(2+1)+1 -D P2 + 2(xz+1)+1
             = 3, (4,12)
    k=4, P4 = 3 + 2(3+1)+1-2(13-1) - P3+2(x3+1)+1-2(y3-1)
              = 3 + 8 + 1 - 24
              = -12', (5,12)
   k=5, P5 = -12 + 2 (4+1)+1 -0 Py + 2(xy+1) +1
              =-1, (6,12)
   k=6, P6 =-1 + 2(5+1)+1 -D P5 + 2(x5+1)+1
              = -1 + 12 +1
              = 12 , (7,11)
   k=7, P7 = 12 + 2(6+1)+1-2(12-1) -D P6+2(x6+1)+1-2(46-1)
             = 12 + 14 + 1 - 22
             = 5, (8,10)
   k=8, P8=5+2(7+1)+1-2(11-1) - P7+2(x7+1)+1-2(47-1)
            = 5 + 16 +1 - 20
            = 2 , (9,9)
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	k	PK	(x4+1, 44+1)	2 x 15+1	24x+1	(b,a)	12 1 1 1 1 1 1
	0	-17	(1,13)	. 2	26	(3,18)	rpitel
	1.	<u>-g</u>	(2,13)	4	26	(.4,18)	doest - w
	2	-4	(3,13)	6	26	(5,18)	12 00 00 5
	3	3	(4,12)	8	24	(6,17)	8 F 8 F 2
	4	-12	(5,12)	10	24	(7,17)	P 8
	5	-1	(6,12)	[12	24	(8,17)	
	6	12	(7,11)	14	22	(9,16)	· ·
	7	5	(8,10)	16	20	(10,15)	
1000	8	2	(9,9)	18	18	(11,14)	5 5 J 7-

2. a.) Marriks transformasi

								Na A Personal Property lies and the last lies an
Matriks translasi		1	0	tx	7 Matriles rotasi:	(cos 30°	-8/n30°	07
		0	1	ty		sin 30°	co\$30°	O
The second secon		0	0	1	(ata) so	10	0	1
C 17 /0 11	1	_				1 \ 0	_	

$$\left(\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{3}/2 & -\frac{1}{2} & 0 \\ \frac{1}{2} & \sqrt{3}/2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$= \left(\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{3}/2 & -\frac{1}{2} & 2\sqrt{3}/2 \\ \frac{1}{2} & \sqrt{3}/2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ y \end{bmatrix} \begin{bmatrix} Perhitungan : \\ P' = Tx R \times T \times P \\ \vdots Tx(R \times T) \times P \end{bmatrix} \right)$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \sqrt{3}/2 & -\frac{1}{2} & \sqrt{3}+2 \\ \frac{1}{2} & \sqrt{3}/2 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} (T \times (R \times T)) \times P \\ y \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \sqrt{3}/2 & -1/2 & \sqrt{3}+2 \\ 1/2 & \sqrt{3}/2 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \\ 1 \end{bmatrix}$$

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$$\begin{pmatrix} x' \\ y' \\ l \end{pmatrix} = \begin{pmatrix} 3\sqrt{3} + \frac{1}{2} \\ 3\sqrt{3}/2 \\ l \end{pmatrix}$$

3.) Dile : Balok P

 $\{(0,0,1),(3,0,1),(3,2,1),(0,2,1),(0,0,0),(3,0,0),(3,2,0),(0,2,0)\}$

Jawab:

$$\mathsf{mobj} = \begin{bmatrix} 0 & 3 & 3 & 0 & 0 & 3 & 0 \\ 0 & 0 & 2 & 2 & 0 & 2 & 2 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

m Rx = Rotasi sebagai & dimana & adalah sudut antara 2-axis dengan B' yang diproyeksikan ke 2y-plane

B'Projected = (0,3,4)

=D B" (B'yang diproyeusikan he xz-plane) adalah (0,0,5)

Lo B" sudah ada di Z-axis, tidak perlu mencari mRy, alias mfy adalah

matriles identifias

	cos go	sin go ·	0	0	1	10	1	0	0	7
mRz =	-sin go°	cos 90°	0	0		-1	0	0	O	
	0	0	1	0		0	0	1	0	
	0	0	0	1		0	0	0	Ι,	

MTrans = mTr. mRx.mRz.mRx-1. mTr-1

THE RESIDENCE OF THE PARTY.		-		-										-		-	-	-	-			
	$\int I$	0	0	0	7	Γ1	0	0	G	7	0	1	0	0	751	0	0 (5	7	١	0 0	6]
=	0	(0	0		٥	4/5	-3/5	0		-1	0	0	0	0	4/5	3/5	0	$\ $	0	10	0
	0	O	1	0		0	3/5	4/5	Ó		0	٥	1	0	0	-3/5	4/5	Ь		0	01	0
	L-4	1	1	1	J	. 0	0	٥	1		0	٥	1	0,	Lo	O	0	1 .		.4	-1-1	1

$$= \begin{bmatrix} 0 & 4/s & -3/s & 0 \\ -4/s & 9/2s & 1^{2}/2s & 0 \\ \hline & & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & & \\ & & & \\ & & \\ & & & \\ & & \\ &$$

mobj' = mTrans. mobj

$$= \begin{bmatrix} -\frac{3}{5} & -\frac{3}{5} & 1 & 1 & 0 & 0 & \frac{8}{5} & \frac{8}{5} \\ \frac{1^{2}}{125} & -\frac{48}{125} & -\frac{6}{5} & \frac{6}{5} & 0 & -\frac{17}{5} & -\frac{42}{125} \\ \frac{16}{125} & \frac{6}{125} & \frac{17}{5} & \frac{8}{5} & 0 & \frac{9}{5} & \frac{69}{25} & \frac{24}{25} \\ -\frac{30}{125} & -\frac{323}{125} & \frac{73}{5} & \frac{26}{5} & 1 & -\frac{52}{5} & -\frac{92}{125} \end{bmatrix}$$



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4.) Clipping algoritma Cohen-Sutherland
   1) Kategori 1 (visible) = GH
      G : 0000
      H = 0000 AND
           0000 - Accept
  2) Kategori 2(not visible) = kL, AB
      k = 0101
                            A = 1000
      L = 1001 AND
                         B=1010 AND
         0001 - Reject 1000 - DReject
  3) kategori 3 (leandidat clipping) = EF, CD, IJ
      E = 0000
                                       I = 1001
                        C = 1000
     F = 0100 AND
                        D = 0010 AND J = 0100 AND
         0000
                                          0000
                           0000
```

Garis yang tidak di clip	- is - of the last the in it
· Garis 17 - 7 (-3,5)] (0,2)	4-3 7-43 - M
$m = \frac{2-5}{0+3} = -3 = -1$	8 2 8 9
0+3 3	'aimt agu pta sinit w
I' (-3,-2)	min (it - mink) disk is a
6 y = -3 + 1 (-z + 3)	(35 +1 1 (1 ± ± 7) + 0 ±
= -3 +1	(%(%*)-=
(a) T = -2	(4/2-) "(" nint not pro some some
J' (-2,2)	
Lo x = x, + (ymin-4,)/m	
= 0 + (0-2)/1	
= -2	
· Garis FF - D F (1,2) F(2,-1)	
M = -1 - 2 = -3 = -3	
E'(5/3,0)	
$L_{D} \times = \times_{l} + (y_{min} - y_{l}) / m$	
= 1 + (0-2) /-3	
= 1 + -2/-3	
= 5/3	
· Garis (D -D C(-1,5) D(5,2)	
m = 2-5 = -3 = -1	
5+1 6 2	
C'(-1,4)	
Lo x = x, + (ymax -4,) /m	
= -1 + (4-5) / 1-1/z) = -1 + 2 = -1	
D' (3,9/2)	
0 (21.112)	
LD y = Y, + m (xmax - y,)	
= 5 + (-1/2) (3-2)	
= 5 - 1/z	
= 9/2	the same and