

Distributional Treatment Effect with Latent Rank Invariance

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Distributional treatment effect

Potential outcome setup: with $D \in \{0, 1\}$,

$$Y = D \cdot Y(1) + (1 - D) \cdot Y(0).$$

We do not observe $Y(1)$ and $Y(0)$ simultaneously; focus on ATE, LATE, etc.

Some questions can only be answered with **distribution** of treatment effect $Y(1) - Y(0)$.

“How many people are better off under the treatment?”

“How heterogeneous is the treatment effect at the individual level?”

Various distributional treatment effect (DTE) parameters can be defined:

$\text{Var}(Y(1) - Y(0))$, $\Pr\{Y(1) - Y(0) \geq 0\}$, etc.

Distributional treatment effect

Existing approaches

- Partial identification: put a bound on $\Pr \{Y(1) - Y(0) \leq y\}$

Heckman et al. (1997); Fan and Park (2010); Fan et al. (2014); Firpo and Ridder (2019)
Frandsen and Lefgren (2021); Kaji and Cao (2023) and more

- Independence: assume $Y(1) \perp\!\!\!\perp Y(0)$ or $Y(0) \perp\!\!\!\perp (Y(1) - Y(0))$

Heckman et al. (1997); Noh (2023)

In this paper, I follow the latter, assuming a latent variable U such that

$$Y(1) \perp\!\!\!\perp Y(0) \mid U$$

and two proxy variables X and Z to identify the cond. dist. of $Y(d)$ given U .

Distributional treatment effect: setup

An econometrician observes $\{Y_i, D_i, X_i, Z_i\}_{i=1}^n$:

$$Y_i = D_i \cdot Y_i(1) + (1 - D_i) \cdot Y_i(0).$$

$Y_i, X_i, Z_i \in \mathbb{R}$, $D_i \in \{0, 1\}$ and $(Y_i(1), Y_i(0), D_i, X_i, Z_i, U_i) \sim iid$.

X_i and Z_i are proxy variables for U_i . $U_i \in \mathbb{R}$.

Assumption 1. $(Y_i(1), Y_i(0), X_i) \perp\!\!\!\perp (D_i, Z_i) \mid U_i$.

- One of the proxy Z_i and the latent variable U_i are confounders.
- In proximal inference terminology,

X_i is outcome-aligned proxy and Z_i is treatment-aligned proxy.

Hu and Schennach (2008); Miao et al. (2018); Deaner (2023); Nagasawa (2022) and more

Assumption 2. $Y_i(1), Y_i(0), X_i$ are mutually independent given U_i .

Distributional treatment effect: example 1 (*rank invariance*)

Assume **rank invariance** between $Y_i(1)$ and $Y_i(0)$:

$$\Pr \{ F_{Y(1)}(Y_i(1)) = F_{Y(0)}(Y_i(0)) \} = 1.$$

When D_i is random, Assumptions 1-2 trivially hold with

$$U_i = X_i = Z_i = F_{Y(1)}(Y_i(1)) = F_{Y(0)}(Y_i(0)).$$

Rank invariance is a commonly used assumption in quantile treatment effect/IV literature:

Chernozhukov and Hansen (2005, 2006); Athey and Imbens (2006); Callaway and Li (2019) and more.

In this paper,

1. U_i is latent and not a deterministic function of $Y_i(1)$ or $Y_i(0)$;
2. *conditional expectation of $Y_i(d)$ given U_i* have the same rank.

Hence '*latent* rank invariance.'

Distributional treatment effect: example 2 (*hidden Markov model*)

Consider a panel where $T = 3$ and $D_i = 1$ means being treated for $t = 2, 3$.

$$Y_{it}(d) = g_d(U_{it}, \varepsilon_{it}(d)).$$

There are a common shock U_{it} and treatment-status-specific shocks $(\varepsilon_{it}(0), \varepsilon_{it}(1))$.

Assumption 2 holds when 1) $\{U_{it}\}_{t=1}^3$ is first-order Markov given D_i and
2) $(\{U_{it}\}_{t=1}^3, D_i), \varepsilon_{i1}(0), \varepsilon_{i2}(1), \varepsilon_{i2}(0), \varepsilon_{i3}(1), \varepsilon_{i3}(0) \sim \text{ind.}$

Hidden Markov model: Kasahara and Shimotsu (2009); Hu and Shum (2012) and more.

Panel data model with proxy: Deaner (2023)

In this paper,

1. treatment-status-specific shocks are introduced and assumed to be $\varepsilon_{it}(1) \perp\!\!\!\perp \varepsilon_{it}(0)$.

Identification

Assumption 3/4. full rank/completeness of $f_{X|Z}$ when U_i is discrete/continuous: A3 A4

“Both of the proxy variables are informative for the latent variable U_i .”

Assumption 5. $\mathbf{E}[Y_i(1)|U_i = u]$ and $\mathbf{E}[Y_i(0)|U_i = u]$ are strictly increasing in u .

“Conditional expectation of $Y_i(1)$ given U_i and that of $Y_i(0)$ given U_i have the same rank.”

U_i can be thought of as a ‘latent’ or ‘interim’ rank.

I apply Hu and Schennach (2008) to treated subpopulation and to untreated subpopulation. more

Theorem 1.

Assumptions 1-3 or Assumptions 1-2, 4-5 hold. Then, the distribution of $(Y_i(1), Y_i(0), D_i, X_i, Z_i)$ is identified.

Identification

From Theorem 1, the following two distributional treatment effect (DTE) parameters are identified:

$$F_{Y(0), Y(1)}(y, y') = \int_{\mathbb{R}} F_{Y(0), Y(1)|U}(y, y'|u) f_U(u) du = \int_{\mathbb{R}} \textcolor{red}{F}_{Y(0)|U}(y|u) \cdot \textcolor{blue}{F}_{Y(1)|U}(y'|u) f_U(u) du,$$
$$F_{Y(1)-Y(0)}(\delta) = \int_{\mathbb{R}} F_{Y(1)-Y(0)|U}(\delta|u) f_U(u) du = \int_{\mathbb{R}} \int_{\mathbb{R}} \textcolor{blue}{F}_{Y(1)|U}(y + \delta|u) \cdot \textcolor{red}{f}_{Y(0)|U}(y|u) f_U(u) dy du.$$

Other distributional parameters $\text{Var}(Y_i(1) - Y_i(0))$ are identified and can be estimated as well.

To estimate DTEs, estimate $\{\textcolor{blue}{F}_{Y(1)|U}(\cdot|u)\}_u$, $\{\textcolor{red}{F}_{Y(0)|U}(\cdot|u)\}_u$ and $f_U(\cdot)$.

Implementation: finite support assumption

To let U_i be continuous and apply the standard semiparametric estimation theory, Shen (1997); Chen and Shen (1998); Ai and Chen (2003) and more
Need strong assumptions such as bounded support of Y_i and X_i .

Why? DTE parameters are inner products of densities. sieve

Instead, I assume $U_i \in \{u^1, \dots, u^K\}$ with $K < \infty$. choice of K

Reasoning behind the finite support assumption:

1. Finite mixture: Henry et al. (2014) and more.
Discretization as approximation: Bonhomme et al. (2022) and more.
2. DTE parameters are identified with quadratic moments;
a limiting distribution is derived from U stat. theory and Neyman orthogonality.
3. Identification is not tied to the finite support;
alternative asymptotic theory could be developed as well.

Implementation: premise

From Assumptions 1-2 and $U_i \in \{u^1, \dots, u^K\}$, we have a finite mixture representation:

$$\begin{aligned} & \left(F_{Y|D=d,Z}(y|\mathcal{Z}^1) \quad \cdots \quad F_{Y|D=d,Z}(y|\mathcal{Z}^K) \right) \\ &= \left(F_{Y(d)|U}(y|u^1) \quad \cdots \quad F_{Y(d)|U}(y|u^K) \right) \\ & \quad \cdot \underbrace{\begin{pmatrix} \Pr\{U_i = u^1|D_i = d, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr\{U_i = u^1|D_i = d, Z_i \in \mathcal{Z}^K\} \\ \vdots & \ddots & \vdots \\ \Pr\{U_i = u^K|D_i = d, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr\{U_i = u^K|D_i = d, Z_i \in \mathcal{Z}^K\} \end{pmatrix}}_{=\Lambda_d}. \end{aligned}$$

With Λ_d^{-1} , the distribution of $Y_i(d)$ given U_i are linear in observed distributions.

Implementation: nonnegative matrix factorization

Fix K . Given some partitions $\{\mathcal{Y}^m\}_m, \{\mathcal{X}^{m'}\}_{m'}, \{\mathcal{Z}^l\}_l$, let

$$\mathbf{H}_d = \begin{pmatrix} \Pr\{Y_i \in \mathcal{Y}^1, X_i \in \mathcal{X}^1 | D_i = d, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr\{Y_i \in \mathcal{Y}^1, X_i \in \mathcal{X}^1 | D_i = d, Z_i \in \mathcal{Z}^{M_Z}\} \\ \vdots & \ddots & \vdots \\ \Pr\{Y_i \in \mathcal{Y}^{M_Y}, X_i \in \mathcal{X}^{M_X} | D_i = d, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr\{Y_i \in \mathcal{Y}^{M_Y}, X_i \in \mathcal{X}^{M_X} | D_i = d, Z_i \in \mathcal{Z}^{M_Z}\} \end{pmatrix}$$

$$= \Gamma_d \cdot \Lambda_d$$

where $\Gamma_d = \left(\Pr\{Y_i(d) \in \mathcal{Y}^m, X_i \in \mathcal{X}^{m'} | U_i = u^k\} \right)_{(m,m'),k}$

$$\Lambda_d = \left(\Pr\{U_i = u^k | D_i = d, Z_i \in \mathcal{Z}^l\} \right)_{k,l}.$$

\mathbf{H}_d is a discretization of $f_{Y,X|D=d,Z}$.

The full rank condition implies $|\text{supp}_Z| \geq K$; if $|\text{supp}_Z| > K$, use partition $\{\mathcal{Z}^l\}_{l=1}^K$.

Implementation: nonnegative matrix factorization

Solve the following nonnegative matrix factorization problem:

$$\left(\hat{\Gamma}_0, \hat{\Gamma}_1, \hat{\Lambda}_0, \hat{\Lambda}_1\right) = \arg \min \left\|\mathbb{H}_0 - \Gamma_0 \cdot \Lambda_0\right\|_F + \left\|\mathbb{H}_1 - \Gamma_1 \cdot \Lambda_1\right\|_F \quad (1)$$

subject to 1) $\Gamma_0, \Gamma_1, \Lambda_0, \Lambda_1$ are nonnegative.

Also, their columnwise sums are one. \dots (*linear constraints*)

2) Γ_0 and Γ_1 satisfy $Y_i(d) \perp\!\!\!\perp X_i \mid U_i \dots$ (*quadratic constraints*)

3) Γ_0 and Γ_1 imply the same marginal distribution of $X_i \dots$ (*linear constraints*)

The objective becomes quadratic once we fix (Γ_0, Γ_1) or (Λ_0, Λ_1) .

The quadratic constraint becomes linear once we fix Γ_X or $(\Gamma_{Y0}, \Gamma_{Y1})$.

(1) is solved iteratively. algorithm

Implementation: nonnegative matrix factorization

Theorem 2. Assumptions 1-3 hold. Up to some permutation on $\{u^1, \dots, u^K\}$,

$$\left\| \hat{\Lambda}_0 - \Lambda_0 \right\|_F = O_p \left(\frac{1}{\sqrt{n}} \right) \quad \text{and} \quad \left\| \hat{\Lambda}_1 - \Lambda_1 \right\|_F = O_p \left(\frac{1}{\sqrt{n}} \right)$$

as $n \rightarrow \infty$.

The convergence rate is $n^{-\frac{1}{2}}$.

A direct corollary is that $(\hat{\Lambda}_d)^{-1}$ is consistent for $(\Lambda_d)^{-1}$ at the same rate.

Implementation: plug-in GMM

Then, quadratic moments identify DTE:

$$F_{Y(1),Y(0)}(y, y') = \sum_{k,l,m=1}^K w_{klm} \cdot \mathbf{E}[\mathbf{1}\{Y_i \leq y, D_i = 1, Z_i \in \mathcal{Z}^m, Y_j \leq y', D_j = 0, Z_j \in \mathcal{Z}^l\}]$$

$$F_{Y(1)-Y(0)}(\delta) = \sum_{k,l,m=1}^K w_{klm} \cdot \mathbf{E}[\mathbf{1}\{Y_i \leq Y_j + \delta, D_i = 1, Z_i \in \mathcal{Z}^m, D_j = 0, Z_j \in \mathcal{Z}^l\}]$$

for all $(y, y') \in \mathbb{R}^2$ and $\delta \in \mathbb{R}$, with $(Y_i, D_i, Z_i) \perp\!\!\!\perp (Y_j, D_j, Z_j)$ and

- $w_{klm} = \frac{p_U(k) \tilde{\lambda}_{lk,0} \tilde{\lambda}_{mk,1}}{p_{D,Z}(0,l) p_{D,Z}(1,m)}.$
- $\tilde{\lambda}_{lk,d}$ is l -th row k -th column component of $(\Lambda_d)^{-1} \quad \forall d = 0, 1.$
- $p_U(k) := \Pr\{U_i = u^k\} \quad \forall k = 1, \dots, K.$
- $p_{D,Z}(d, l) := \Pr\{D_i = d, Z \in \mathcal{Z}^l\} \quad \forall d = 0, 1 \text{ and } l = 1, \dots, K.$

Implementation: plug-in GMM

The DTE estimators are plug-in GMM estimator from (orthogonalized) moment: Lemma 1.

$$\begin{aligned}\widehat{F}_{Y(1)-Y(0)}(\delta) = & \sum_{k,l,m=1}^K \widehat{w}_{klm} \cdot \frac{1}{n(n-1)} \sum_{i=1}^n \sum_{j \neq i} \mathbf{1}\{\textcolor{blue}{Y}_i \leq \textcolor{red}{Y}_j + \delta, \textcolor{blue}{D}_i = 1, Z_i \in \mathcal{Z}^m, \textcolor{red}{D}_j = 0, Z_j \in \mathcal{Z}^l\} \\ & + \text{orthogonalization term}\end{aligned}$$

$$\text{where } \widehat{w}_{klm} = \frac{\widehat{p}_U(k) \widehat{\lambda}_{lk,0} \widehat{\lambda}_{mk,1}}{\widehat{p}_{D,Z}(0,l) \widehat{p}_{D,Z}(1,m)}.$$

Theorem 3. Assumptions 1-3 hold. Then, as $n \rightarrow \infty$,

$$\begin{aligned}\sqrt{n} \left(\widehat{F}_{Y(1),Y(0)}(y, y') - F_{Y(1),Y(0)}(y, y') \right) & \xrightarrow{d} \mathcal{N}(0, \sigma(y, y')^2) \\ \sqrt{n} \left(\widehat{F}_{Y(1)-Y(0)}(\delta) - F_{Y(1)-Y(0)}(\delta) \right) & \xrightarrow{d} \mathcal{N}(0, \sigma(\delta)^2).\end{aligned}$$

Empirical Illustration

I revisit Jones et al. (2019), which studies the effect of workplace wellness program. The program *eligibility* was randomly assigned to employees at UIUC; *intent-to-treat*. Using the University-provided health insurance data, Jones et al. (2019) estimates its effect on medical spending.

The variables in the dataset are:

Y_i = monthly medical spending over August 2016-July 2017

$D_i = \mathbf{1}\{\textit{eligible for the wellness program starting in September 2016}\}$

X_i = monthly medical spending over July 2015-July 2016

Z_i = monthly medical spending over August 2017-January 2019

“Underlying health status U_i depends on past health status, but not on medical spendings.”

Empirical Illustration: setup

The eigenvalue ratio estimator and the Kleibergen-Paap rank test suggest $K = 3$. choice of K

I use $K = 5$ and used 5-fold partitions for Y_i , X_i and Z_i :

e.g. $F_Y^{-1}(0)$, $F_Y^{-1}(1/5)$, \dots , $F_Y^{-1}(1)$ and so on.

As a falsification test, I test the null hypothesis $f_{X|D=1,U}(\cdot|u) = f_{X|D=0,U}(\cdot|u)$ for all u :
with $W_n = \left(\hat{f}_{X|D=1,U}(\mathcal{X}^m|u) - \hat{f}_{X|D=0,U}(\mathcal{X}^m|u) \right)_{m,u} \in \mathbb{R}^{25}$,

$$nW_n^\top Avar(W)^{-1}W_n = 16.435$$

The p -value is 0.689.

Empirical Illustration: joint distribution of potential outcomes

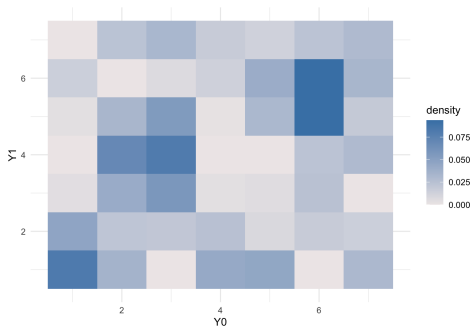


Figure 1: Joint density of $(Y(1), Y(0))$.

y -axis is $Y(1)$ and x -axis $Y(0)$; each cell corresponds to $F_X^{-1}(0), F_X^{-1}(1/7), \dots, F_X^{-1}(1)$.
No noticeable treatment effect; in Jones et al. (2019), p -values for ATE are 0.86-0.94.

Empirical Illustration: treatment effect distribution

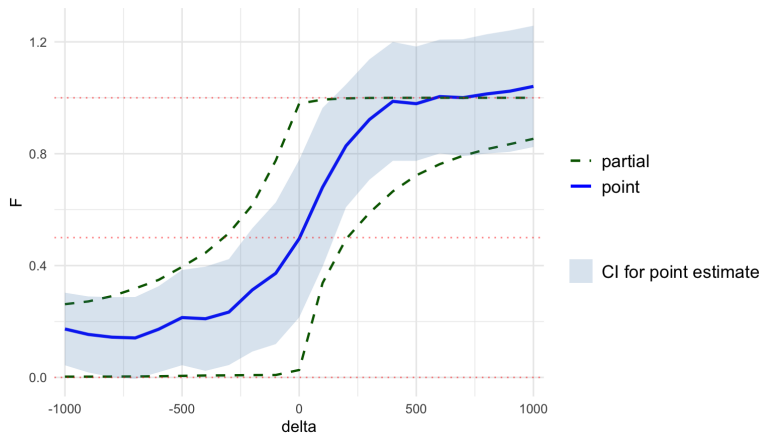


Figure 2: Marginal density of $Y(1) - Y(0)$.

Information gain from partial identification (Fan and Park, 2010).

Summary

- Assume a latent variable U such that

$$Y_i(1) \perp\!\!\!\perp Y_i(0) \mid U_i.$$

This assumption could be thought of as a ‘latent rank invariance’ condition when $\mathbf{E}[Y_i(d)|U_i = u]$ is monotone increasing in u .

- Use two proxy variables X_i and Z_i to identify the distribution of $Y_i(d)|U_i$.
- Nonnegative matrix factorization estimates distribution of U_i given (D_i, Z_i) .
- An asymptotic distribution is derived for the plug-in GMM estimator.

Identification à la Hu and Schennach (2008)

An essential building block in the identification argument: $f_{Y,X|D,Z}$.

Fix y and d and discretize X_i and Z_i :

$$\mathbf{H} = \left(f_{Y=y, X|D=d, Z}(x|z) \right)_{x,z} = \left(f_{X|U}(x|u) \right)_{x,u} \cdot \text{diag} \left(f_{Y|U}(y|u) \right)_u \cdot \left(f_{U|D=d, Z}(u|z) \right)_{u,z}.$$

H is a $|\text{supp}_X| \times |\text{supp}_Z|$ matrix whose rows correspond to X_i and columns to Z_i .

Likewise, define $\mathbf{H}_X = \left(f_{X|D=d, Z}(x|z) \right)_{x,z}$.

Under Assumptions 1-2 and **full rank/completeness** of \mathbf{H}_X , A3 A4

$$\mathbf{H} \cdot (\mathbf{H}_X)^{-1} = \left(f_{X|U}(x|u) \right)_{x,u} \cdot \text{diag} \left(\{ f_{Y(d)=y|U}(u) \}_u \right) \cdot \left(\left(f_{X|U}(x|u) \right)_{x,u} \right)^{-1}$$

Spectral decomposition identifies $f_{X|U}$.

Spectral Theorem of Hu and Schennach (2008)

Several deviations from Hu and Schennach (2008):

1. Two decomposition results; treated population and untreated population.

Need to connect $\{f_{Y(1)|U}(\cdot|u)\}_u$ to $\{f_{Y(0)|U}(\cdot|u)\}_u$.

2. Mapping from $\{f_{X|U}(\cdot|u)\}_u$ to u to have distribution of U_i .

1. is easily solved.

Firstly, split the sample into two subsamples $\{i : D_i = 1\}$ and $\{i : D_i = 0\}$ and we get $\{f_{Y(1)|U}(\cdot|u), f_{X=1|U}(\cdot|u)\}_u$ and $\{f_{Y(0)|U}(\cdot|u), f_{X=0|U}(\cdot|u)\}_u$.

Under Assumption 1, $f_{X|D=1,U}(\cdot|u)$ and $f_{X|D=0,U}(\cdot|u)$ should be the same.

Spectral Theorem of Hu and Schennach (2008)

A linear operator $L_{Y=y, X|D=d, X}$ maps a density of Z_i to a density of $(Y_i(d) = y, X_i)$:

$$(L_{Y=y, X|D=d, Z} g)(x) = \int_{\mathbb{R}} f_{Y(d), X|D, Z}(y, x|d, z) g(z) dz.$$

From the decomposition based on Assumption 2, we get

$$L_{Y=y, X|D=d, Z} = L_{X|U} \cdot \Delta_{Y=y|U} \cdot L_{U|D=d, Z}$$

with similarly defined operators $L_{X|U}$, $L_{U|D=d, Z}$ and a diagonal operator $\Delta_{Y=y|U}$. Thus,

$$\begin{aligned} L_{Y=y, X|D=d, Z} (L_{X|D=d, Z})^{-1} &= L_{X|U} \cdot \Delta_{Y=y|U} \cdot L_{U|D=d, Z} \cdot (L_{X|U} \cdot L_{U|D=d, Z})^{-1} \\ &= \underbrace{L_{X|U} \cdot \Delta_{Y=y|U}}_{\text{spectral decomposition}} \cdot (L_{X|U})^{-1}. \end{aligned}$$

Assumption 3

Assumption 3.

- a. (*finitely discrete* U_i) $U_i \in \{u^1, \dots, u^K\}$.
- b. (*full rank*) $\left(f_{U|D=1,Z}(u|z)\right)_{u,z}$, $\left(f_{U|D=0,Z}(u|z)\right)_{u,z}$ and $\left(f_{X|U}(x|u)\right)_{x,z}$ have rank K .
- c. (*no repeated eigenvalue*) For any $k \neq k'$, there exist some $d \in \{0, 1\}$ and y such that

$$f_{Y(d)|U}(y|u^k) \neq f_{Y(d)|U}(y|u^{k'}).$$

"The latent heterogeneity U_i can be *at most* as rich/flexible as the proxy variables." [back](#)

Assumption 4

Assumption 4.

- a. (*continuous* U_i) $U_i \in [0, 1]$.
- b. (*bounded density*) All marginal and conditional densities of $(Y_i(1), Y_i(0), X_i, Z_i, U_i)$ are bounded.
- c. (*completeness*) Let $f_{X|Z,d}$ denote the conditional density of X_i given $(D_i = d, Z_i)$.

$$\int_{\mathbb{R}} |g(x)| dx \quad \text{and} \quad \int_{\mathbb{R}} g(x) f_{X|Z,d}(x|z) dx = 0 \quad \forall d, z$$

implies $g(x) = 0$. Assume similarly for $f_{X|U}$.

- d. (*no repeated eigenvalue*) $\forall u \neq u'$, there exists $d \in \{0, 1\}$ such that

$$\Pr \{ f_{Y(d)|U}(Y_i(d)|u) \neq f_{Y(d)|U}(Y_i(d)|u') | D_i = d \} > 0.$$

Identification: implicit restriction

A crucial step in the identification argument is that there exists some w such that

$$\mathbf{E}[Y_i(1)|Y_i(0) = y] = \int_{\mathbb{R}} \frac{w(y, z)}{f_{Y(0)}(y)} \cdot \mathbf{E}[Y_i|D_i = 1, Z_i = z]dz,$$
$$\mathbf{E}[Y_i(1)Y_i(0)] = \int_{\mathbb{R}} \int_{\mathbb{R}} w(y, z) \cdot y \mathbf{E}[Y_i|D_i = 1, Z_i = z]dydz.$$

$\mathbf{E}[Y_i|D_i = 1, Z_i]$ replaces $Y_i(1)$ and $w(y, z)$ replaces the joint density of $(Y_i(1), Y_i(0))$.

“Proxy variable Z_i creates sufficient variation in the distribution of $Y_i(1)$.”

The implicit restriction is that

“conditional distribution of $Y_i(1)$ given $Y_i(0)$ is a linear combination of $\{F_{Y|D=1, Z}(\cdot|z)\}_z$.”

Identification: falsification test

The conditional independence of $Y_i(1)$ and $Y_i(0)$ is fundamentally untestable.

Instead, we can test the null

$$f_{X|D=1,U}(\cdot|u) = f_{X|D=0,U}(\cdot|u) \quad \forall u.$$

with

$$\min_{g \text{ monotone}} \mathbf{E} \left[\int_{\mathbb{R}} (f_{X|D=1,U}(x|g(U_i)) - f_{X|D=0,U}(x|U_i))^2 du \middle| D_i = 0 \right] = 0.$$

“Can we construct a latent variable U_i that satisfies 1) conditional independence $X_i \perp\!\!\!\perp Y_i \mid U_i$ and 2) random treatment $X_i \perp\!\!\!\perp D_i \mid U_i$?”

In the short panel context,

- cannot test the conditional independence *across treatment regime*.
- can somewhat test the *intertemporal* conditional independence, given random treatment.

Nonnegative matrix factorization

The objective function in (1) is quadratic with linear constraints, once we fix two out of the three matrices $\Gamma_X, \Gamma_Y, \Lambda$.

Thus, find the (local) minima by iterating among three objects:

1. Given $(\Gamma_0^{(s)}, \Gamma_1^{(s)})$, update (Λ_0, Λ_1) .
2. Given $(\Lambda_0^{(s+1)}, \Lambda_1^{(s+1)}, \Gamma_{Y0}^{(s)}, \Gamma_{Y1}^{(s)})$, update Γ_X .
3. Given $(\Lambda_0^{(s+1)}, \Lambda_1^{(s+1)}, \Gamma_X^{(s+1)})$, update $(\Gamma_{Y0}, \Gamma_{Y1})$.
4. Iterate **1-3** until convergence.

In practice, use many initial values to find the global minimum.

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Sieve MLE

To allow for a continuous U_i , we can directly construct a likelihood using sieves:

$$f_{Y,X|D=d,Z,n}(y,x|z;\theta) = \int_{\mathbb{R}} f_{Y(d)|U,n}(y|u;\theta) \cdot f_{X|U,n}(x|u;\theta) \cdot f_{U|D=d,Z,n}(u|z;\theta) du.$$

The latent rank interpretation is simple to impose with Bernstein polynomials:
a Bernstein polynomial of degree m is

$$g_m(u) = \sum_{k=0}^m \theta_k u^k (1-u)^{m-k}.$$

Then, monotonicity of $\int_0^1 u g_m(u) du$ is a set of linear constraints on $\{\theta_k\}_{k=0}^m$.

Theorem 4. Let Assumptions 1-2,4-6 hold. Then,

$$\left\| \hat{f}_{Y(1),Y(0)} - f_{Y(1),Y(0)} \right\|_{\infty} \xrightarrow{p} 0$$

as $n \rightarrow \infty$ and for any $(y, y') \in \mathbb{R}^2$ and $\delta \in \mathbb{R}$,

$$\begin{aligned} \sqrt{n} \left(\hat{f}_{Y(1),Y(0)}(y, y') - f_{Y(1),Y(0)}(y, y') \right) &\xrightarrow{d} \mathcal{N}(0, \sigma(y, y')^2) \\ \sqrt{n} \left(\widehat{\Pr \{Y_i(1) - Y_i(0) \leq \delta\}} - \Pr \{Y_i(1) - Y_i(0) \leq \delta\} \right) &\xrightarrow{d} \mathcal{N}(0, \sigma(\delta)^2) \end{aligned}$$

as $n \rightarrow \infty$.

Assumption 6 I

Assumption 6

- a. Functions in $\{\Theta_n\}_{n=1}^{\infty} \cup \Theta$ is uniformly bounded. Θ is convex.
- b. $f_{Y(1)|U}, f_{Y(0)|U}, f_{X|U}, f_{U|D=1,Z}, f_{U|D=0,Z}$ are in the interior of $\Lambda_c^{\gamma_1}([0, 1]^2)$ with $\gamma_1 > 1$. Also, for any $\theta \in \Theta_n$ for some n ,

$$f_{Y(1)|U,n}(\cdot; \theta), f_{Y(0)|U,n}(\cdot; \theta), f_{X|U,n}(\cdot; \theta), f_{U|D=1,Z,n}(\cdot; \theta), f_{U|D=0,Z,n}(\cdot; \theta) \in \Lambda_c^{\gamma_1}([0, 1]^2)$$

and $\log f_{Y,X|D,Z}(\cdot; \theta) \in \Lambda_c^{\gamma}([0, 1]^4)$ with $\gamma > 2$.

- c. $\mathbf{E} \left[(\log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i))^2 \right] < \infty$. There exists measurable functions h_1, h_2 such that

$$\begin{aligned} & h_1(y, d, x, z) \\ & \leq \frac{1}{f_{Y,X|D,Z}(y, x|d, z; \theta)} \left(\int_0^1 \frac{f_{Y(d)|U}(y|u; \theta) f_{X|U}(x|u; \theta) f_{U|D=d,Z}(u|z; \theta)}{f_{Y(d)|U}(y|u; \theta) + f_{X|U}(x|u; \theta) + f_{U|D=d,Z}(u|z; \theta)} du \right) \\ & \leq h_2(y, d, x, z) \end{aligned}$$

Assumption 6 II

for all $\theta \in \Theta$ and $\mathbf{E} [(h_1(Y_i, D_i, X_i, Z_i,)) ^2] , \mathbf{E} [(h_2(Y_i, D_i, X_i, Z_i))^2] < \infty$. Also, There exist a measurable function h_3 such that

$$\begin{aligned} & \frac{1}{2f_{Y,X|D,Z}(y, x|d, z; \theta)^2} \left(\int_0^1 \frac{f_{Y(d)|U}(y|u; \theta) f_{X|U}(x|u; \theta) f_{U|D=d,Z}(u|z; \theta)}{f_{Y(d)|U}(y|u; \theta) + f_{X|U}(x|u; \theta) + f_{U|D=d,Z}(u|z; \theta)} du \right)^2 \\ & + \frac{1}{f_{Y,X|D,Z}(y, x|d, z; \theta)} \int_0^1 (f_{Y(d)|U}(y|u; \theta) + f_{X|U}(x|u; \theta) + f_{U|D=d,Z}(u|z; \theta)) du \\ & \leq h_3(y, d, x, z) \end{aligned}$$

for all $\theta \in \Theta$ and $\mathbf{E} [(h_3(Y_i, D_i, X_i, Z_i,)) ^2] < \infty$.

d. $\|\Pi_n \theta^0 - \theta^0\|_\infty = o(n^{-\frac{1}{4}})$ as $n \rightarrow \infty$ where

$$\Pi_n \theta^0 = \arg \max_{\theta \in \Theta_n} \mathbf{E} [\log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta)]$$

Also, $p_n \rightarrow \infty, \frac{p_n \log n}{\sqrt{n}} \rightarrow 0$ as $n \rightarrow \infty$.

Assumption 6 III

e. With some $c_1, c_2 > 0$,

$$c_1 \mathbf{E} \left[\log \frac{f_{Y,X|D,Z}(Y_i, X_i | D_i, Z_i; \theta^0)}{f_{Y,X|D,Z}(Y_i, X_i | D_i, Z_i; \theta)} \right] \leq \|\theta - \theta^0\|^2 \leq c_2 \mathbf{E} \left[\log \frac{f_{Y,X|D,Z}(Y_i, X_i | D_i, Z_i; \theta^0)}{f_{Y,X|D,Z}(Y_i, X_i | D_i, Z_i; \theta)} \right]$$

holds for any $\theta \in \Theta_n$ such that $\|\theta - \theta^0\|_\infty = o(1)$.

f. Let p_1 be the degree of a tensor product Bernstein polynomial used in approximating $f_{Y(1)|U}$ to Θ_n and similarly define p_0, p_X, p_{1Z} and p_{0Z} ; for example, $p_1 = (p^y + 1) \cdot (p^u + 1)$. With some abuse of notation, let $\{\theta_{j,1}\}_{j=1}^{p_1}$ denote the basis functions used in approximating $f_{Y(1)|U}$ and similarly define $\{p_{j,0}\}_{j=1}^{p_0}, \dots, \{p_{j,0Z}\}_{j=1}^{p_{0Z}}$.

Assumption 6 IV

Let

$$\frac{d}{d\theta_1} \log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta^0) [\{\theta_{j,1}\}_{j=1}^{p_1}] = \begin{pmatrix} \frac{d}{d\theta_1} \log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta^0) [\theta_{1,1}] \\ \vdots \\ \frac{d}{d\theta_1} \log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta^0) [\theta_{p_1,1}] \end{pmatrix}$$
$$W_n(Y_i, D_i, X_i, Z_i) = \begin{pmatrix} \frac{d}{d\theta_1} \log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta^0) [\{\theta_{j,1}\}_{j=1}^{p_1}] \\ \vdots \\ \frac{d}{d\theta_{0Z}} \log f_{Y,X|D,Z}(Y_i, X_i|D_i, Z_i; \theta^0) [\{\theta_{j,0Z}\}_{j=1}^{p_{0Z}}] \end{pmatrix}$$

and

$$\Omega_n = \mathbf{E} [W_n(Y_i, D_i, X_i, Z_i) (W_n(Y_i, D_i, X_i, Z_i))^{\mathsf{T}}].$$

Then, the smallest eigenvalue of Ω_n is bounded away from zero uniformly across n .

Choice of K

Under Assumption 3, the rank of the following $M_X \times 2M_Z$ matrix is K :

$$\mathbf{H}_X = \begin{pmatrix} \Pr \{X_i \in \mathcal{X}^1 | D_i = 0, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr \{X_i \in \mathcal{X}^1 | D_i = 1, Z_i \in \mathcal{Z}^{M_Z}\} \\ \vdots & \ddots & \vdots \\ \Pr \{X_i \in \mathcal{X}^{M_X} | D_i = 0, Z_i \in \mathcal{Z}^1\} & \cdots & \Pr \{X_i \in \mathcal{X}^{M_X} | D_i = 1, Z_i \in \mathcal{Z}^{M_Z}\} \end{pmatrix}$$

We can apply the Kleibergen-Paap rank test or the eigenvalue ratio test. [back](#)

Kleibergen and Paap (2006); Ahn and Horenstein (2013)

Simulation

Monte Carlo simulations with a simple DGP with $K = 3$ and $Y_i, X_i, Z_i \in \{1, 2, 3\}$.
Nonnegative matrix factorization is applied to two 9×3 matrices.

Informativeness of the two proxy variables:

$$\Gamma_X = \left(\Pr\{X_i = x | U_i = u^k\} \right)_{x,k} = \begin{pmatrix} 0.800 & 0.100 & 0.067 \\ 0.133 & 0.800 & 0.133 \\ 0.067 & 0.100 & 0.800 \end{pmatrix}$$
$$\Lambda = \left(\Pr\{U_i = u^k | Z_i = z\} \right)_{z,k} = \begin{pmatrix} 0.840 & 0.091 & 0.040 \\ 0.077 & 0.772 & 0.055 \\ 0.083 & 0.137 & 0.905 \end{pmatrix}.$$

Their smallest singular values are 0.665 and 0.701.

Simulation

As we shift Λ , estimation worsens:

δ	$\hat{F}_{Y(1)-Y(0)}$					
	$\sigma_{\min}(\Lambda) = 0.701$		$\sigma_{\min}(\Lambda) = 0.501$		$\sigma_{\min}(\Lambda) = 0.310$	
	bias	rMSE	bias	rMSE	bias	rMSE
-2	0.000	0.006	0.001	0.010	0.001	0.025
-1	-0.000	0.017	0.000	0.025	-0.002	0.052
0	-0.007	0.028	-0.012	0.040	-0.014	0.076
1	-0.009	0.025	-0.014	0.040	-0.015	0.084

Table 1: Bias and rMSE of DTE estimator, $B = 200$.

First step NMF worsens as Z_i gets less informative.

Simulation

	$\widehat{F}_{Y(1)-Y(0)}$		
	$\sigma_{\min}(\Lambda) = 0.701$	$\sigma_{\min}(\Lambda) = 0.501$	$\sigma_{\min}(\Lambda) = 0.310$
$\Pr \{F_{Y(1)-Y(0)}(-2) \in \widehat{CI}\}$	0.968	0.970	0.990
$\Pr \{F_{Y(1)-Y(0)}(-1) \in \widehat{CI}\}$	0.978	0.960	0.970
$\Pr \{F_{Y(1)-Y(0)}(0) \in \widehat{CI}\}$	0.960	0.975	0.990
$\Pr \{F_{Y(1)-Y(0)}(1) \in \widehat{CI}\}$	0.970	0.970	0.980
$\Pr \{\text{reject } F_{X D=1,U} = F_{X D=0,U}\}$	0.070	0.063	0.049

Table 2: Coverage of CI and type I error of falsification test, $B = 200$.

Choice of K

In the empirical application, both rank test and eigenvalue ratio estimator suggest $K = 3$.

K	1	2	3	4	5	6	7	8
eigenvalue ratio	3.505	3.991	4.029	2.721	1.653	1.863	1.418	3.309
growth ratio	0.964	1.135	1.472	1.353	0.893	0.956	0.580	1.035

Table 3: Eigenvalue ratios and growth ratios

K	1	2	3	4	5	6
test statistic	884.82	116.23	35.75	20.08	13.80	7.94
p -value	0.000	0.001	0.984	0.998	0.995	0.992

Table 4: Kleibergen-Paap rank test statistics for $H_0 : \text{rank} = K$ and their p -values

Additional moments

The quadratic moment is

$$\begin{aligned} & \sum_{l=1}^K \frac{\tilde{\lambda}_{lk,d}}{p_{D,Z}(d,l)} \cdot \mathbf{E} \left[\frac{1}{2} \mathbf{1}\{Y_i \in \mathcal{Y}, D_i = d, X_i \in \mathcal{X}, Z_i \in \mathcal{Z}^l\} \right] \\ & + \sum_{m=1}^K \frac{\tilde{\lambda}_{mk,d}}{p_{D,Z}(d,m)} \cdot \mathbf{E} \left[\frac{1}{2} \mathbf{1}\{Y_j \in \mathcal{Y}, D_j = d, X_j \in \mathcal{X}, Z_j \in \mathcal{Z}^m\} \right] \\ & - \sum_{l=1}^K \sum_{m=1}^K \frac{\tilde{\lambda}_{lk,d} \tilde{\lambda}_{mk,d}}{p_{D,Z}(d,l) \cdot p_{D,Z}(d,m)} \mathbf{E} [\mathbf{1}\{Y_i \in \mathcal{Y}, D_i = d, Z_i \in \mathcal{Z}^l, X_j \in \mathcal{X}, D_j = d, Z_j \in \mathcal{Z}^m\}] = 0 \end{aligned}$$

with $(Y_i, D_i, Z_i) \perp\!\!\!\perp (Y_j, D_j, Z_j)$. [back](#)

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