

# Sort Algorithms

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# Contents

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- Basic concepts.
- Quadratic algorithms.
- Logarithmic algorithms.

# Contents

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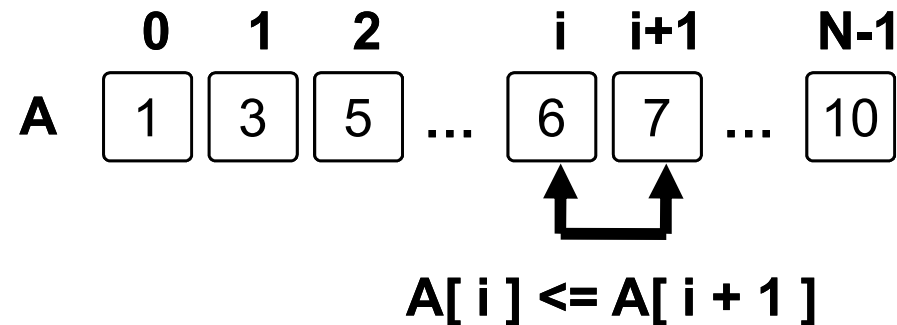
- **Basic concepts.**
- Quadratic algorithms.
- Logarithmic algorithms.

# Basic concepts



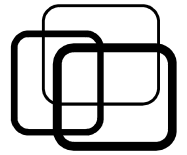
## ■ Array sorting problem:

- Given an array A size N.
- A is sorted in ascending order...
  - ⇔ Adjacent pair  $A_i \leq A_{i+1}$



- Brute force algorithm:  $O(N!)$ .
- Reference: [www.sorting-algorithms.com](http://www.sorting-algorithms.com)

# Basic concepts



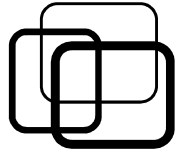
## ■ Algorithm analysis:

Families	Algorithms	Complexity			Space
		Best	Worst	Average	
Quadratic Comparison	Bubble sort	$N$	$N^2$	$N^2$	1
	Selection sort	$N^2$	$N^2$	$N^2$	1
	Insertion sort	$N$	$N^2$	$N^2$	1
Logarithmic Comparison	Merge sort	$N \log N$	$N \log N$	$N \log N$	$N$
	Quick sort	$N \log N$	$N^2$	$N \log N$	$\log N$
	Heap sort	$N \log N$	$N \log N$	$N \log N$	1
Counting	Radix sort	$K N$	$K N$	$K N$	$K + N$

- In-place sort: no extra temporary memory.
- Stable sort: keep relative orders of equal elements.

# Contents

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- Basic concepts.
- **Quadratic algorithms.**
- Logarithmic algorithms.

# Quadratic algorithms



## ■ Bubble sort idea:

### ■ “Bubble” up lighter element.

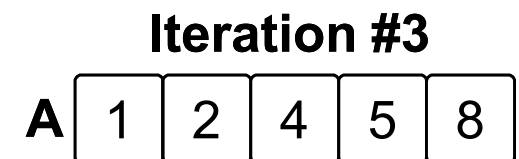
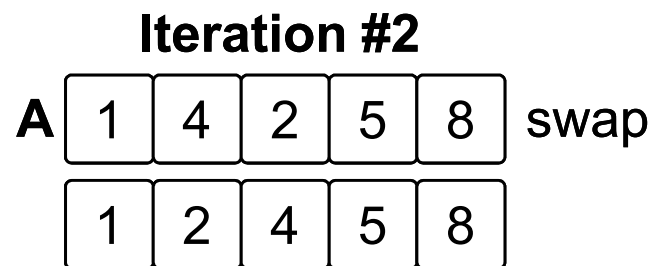
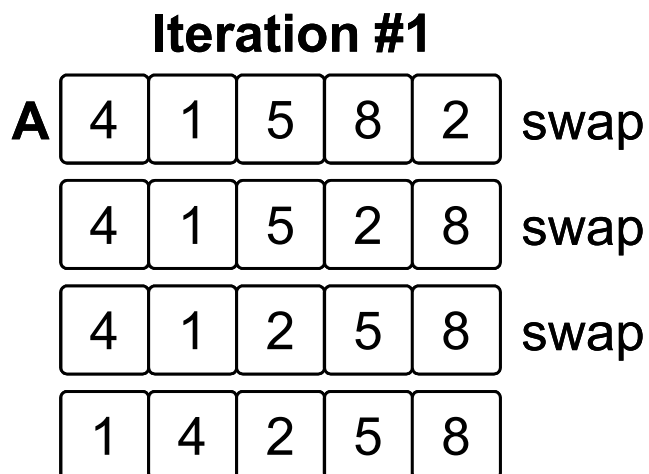
➤  $A[i]$  is lighter  $\Leftrightarrow A[i] < A[i - 1]$ .

### ■ A bubble up iteration:

➤ For element  $A[i]$  from last to first.

➤ If  $A[i]$  is lighter  $\Rightarrow$  swap up.

### ■ Do bubble iteration until no swap.



# Quadratic algorithms



## ■ Bubble sort algorithm:

*// Original version.*

```
bubbleSort( array A, size N ) {  
    do {  
        isSwap = bubbleUp( A, N );  
    } loop isSwap  
}
```

■ *// Improved version.*

```
bubbleSort2( array A, size N ) {  
    do {  
        isSwap = bubbleUp( A, N, from last to i );  
        i = i + 1;  
    } loop swapFlag  
}
```

Lightest element  
stable at each iteration



# Quadratic algorithms

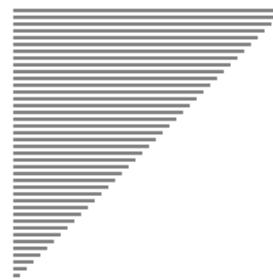


## ■ Bubble sort analysis:

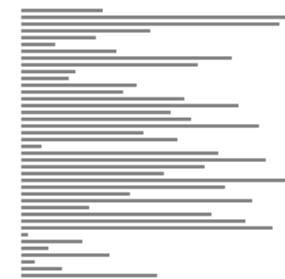
Scenario	When occur?	Complexity
Best-case	Array is already sorted	$O(n)$
Worst-case	Array is in reversed order	$O(n^2)$
Average-case	Array is in random order	$O(n^2)$



Best-case



Worst-case



Average-case

■ A stable and in-place sort algorithm.

➔ Space complexity:  $O(1)$ .

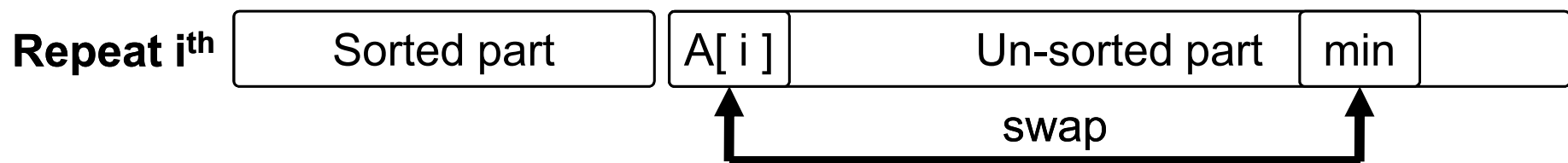
➔ Slow and rarely used!

# Quadratic algorithms



## ■ Selection sort idea:

- Select min element, move to first.
- Repeat with the remaining elements.
- Repeat  $i^{\text{th}}$ :
  - Select min from  $i^{\text{th}}$ .
  - Move min to  $i^{\text{th}}$  place.



# Quadratic algorithms



## ■ Selection sort algorithm:

*// Original version...*

```
selectionSort( array A, size N ) {  
    for i from 0 to N - 1 {  
        minpos = findMin( A, N, from i );  
        swap( A[ i ], A[ minpos ] );  
    }  
}
```

*// Improved version...*

```
selectionSort( array A, size N ) {  
    for i from 0 to N - 2 {  
        minpos = findMin( A, N, from i );  
  
        if ( minpos != i )  
            swap( A[ i ], A[ minpos ] );  
    }  
}
```

# Quadratic algorithms



## ■ Selection sort analysis:

Scenario	When occur?	Complexity
Best-case	Array is already sorted	$O(n^2)$
Worst-case	Array is in reversed order	$O(n^2)$
Average-case	Array is in random order	$O(n^2)$

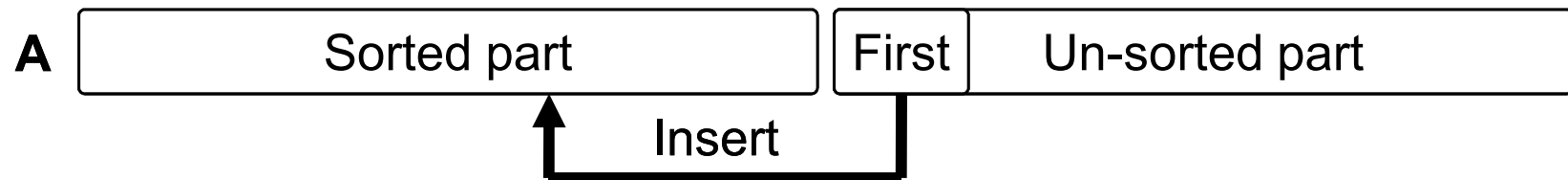
- A stable and in-place sort algorithm.
  - ➔ Space complexity:  $O(1)$ .
- Faster than bubble sort on average-case.
- Simple way to sort **small** array.

# Quadratic algorithms

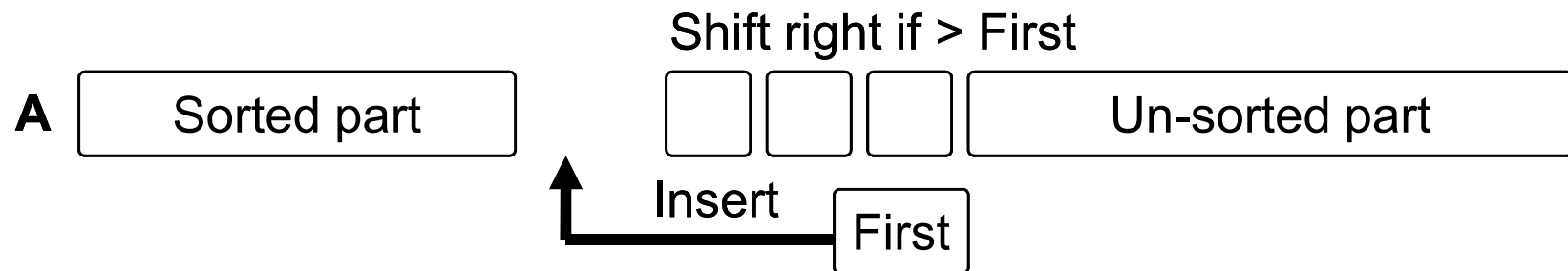


## ■ Insertion sort idea:

- Split array into sorted part & un-sorted part.
  - At beginning, sorted part is the first element.
- Get first element of un-sorted part
  - ➔ Insert backward into sorted part (keep order).



## ■ How to insert into sorted part (keep order)?



# Quadratic algorithms



## ■ Insertion sort algorithm:

```
insertBackward( array A, size N, index i ) {  
    temp = A[ i ];  
    for each A[ j ] befor A[ i ]  
        if ( A[ j ] > temp )  
            Shift A[ j ] forward;  
        else {  
            Insert temp after A[ j ];  
            Stop;  
        }  
}
```

```
insertionSort( array A, size N ) {  
    for each A[ i ] in un-sorted part {  
        insertBackward( A, N, i );  
    }  
}
```

*// begin from 2<sup>nd</sup> element.*

# Quadratic algorithms



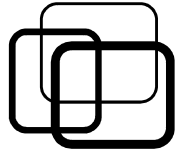
## ■ Insertion sort analysis:

Scenario	When occur?	Complexity
Best-case	Array is nearly sorted	$O(n)$
Worst-case	Array is in reversed order	$O(n^2)$
Average-case	Array is in random order	$O(n^2)$

- A stable and in-place sort algorithm.
  - ➔ Space complexity:  $O(1)$ .
- Faster than bubble & selection sort on average-case.
- Efficient way to sort:
  - **Small** array ( $< 100$  elements).
  - **Nearly sorted** array.

# Contents

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- Basic concepts.
- Quadratic algorithms.
- **Logarithmic algorithms.**

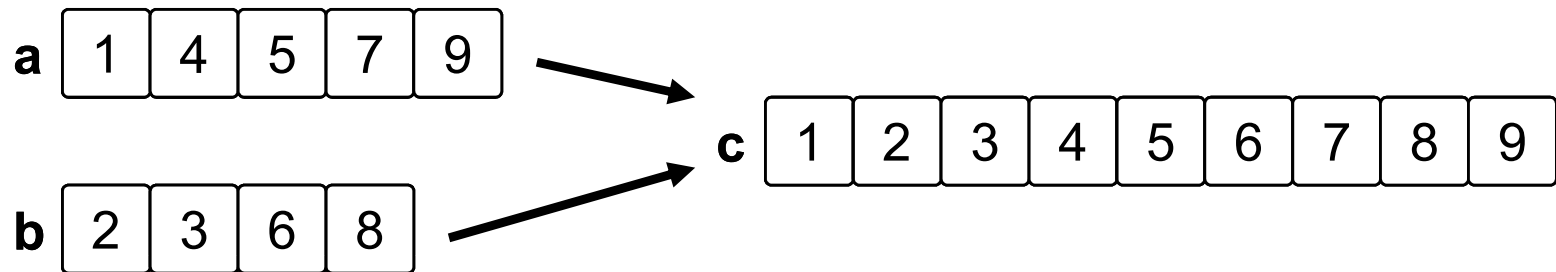


# Logarithmic algorithms



## ■ Merge array problem:

- Merge two sorted arrays into sorted one?



- For each position in **c**, copy element from **a** or **b**?

*// i, ia, ib current positions of c, a, b.*

if (  $a[ia] < b[ib]$  )

$c[i++] = a[ia++]$ ;

else

$c[i++] = b[ib++]$ ;

➔  $c[i++] = ( a[ia] < b[ib] ) ? a[ia++] : b[ib++]$ ;

# Logarithmic algorithms



## ■ Merge array problem:

```
mergeArray( array A, size NA, array B, size NB, array C )  
{  
    set up i, ia, ib start positions of A, B, C.  
  
    loop if A, B are still not end  
        C[ i++ ] = ( A[ ia ] < B[ ib ] ) ? A[ ia++ ] : B[ ib++ ];  
  
    loop if A is still not end  
        Copy element from A to C.  
  
    loop if B is still not end  
        Copy element from B to C.  
}
```

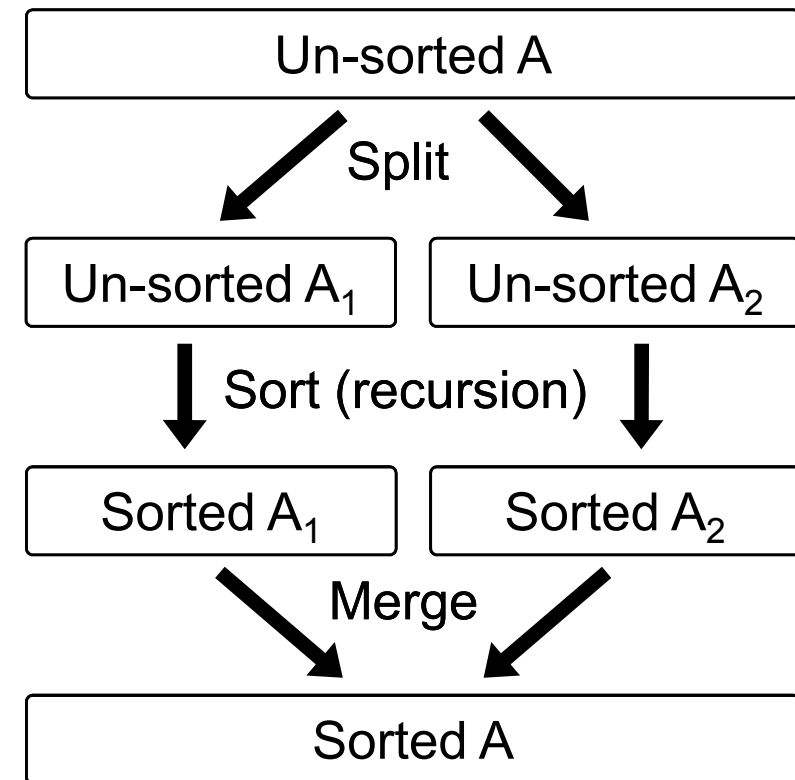
# Logarithmic algorithms



## ■ Merge sort idea:

*// Divide-and-conquer technique.*

```
mergeSort( array A, size N )  
{  
    if ( A has one element )  
        Stop;  
    else  
    {  
        Split A into A1 (size N1) and A2 (size N2);  
        mergeSort( A1, N1 );  
        mergeSort( A2, N2 );  
  
        mergeArray( A1, N1, A2, N2, A );  
    }  
}
```

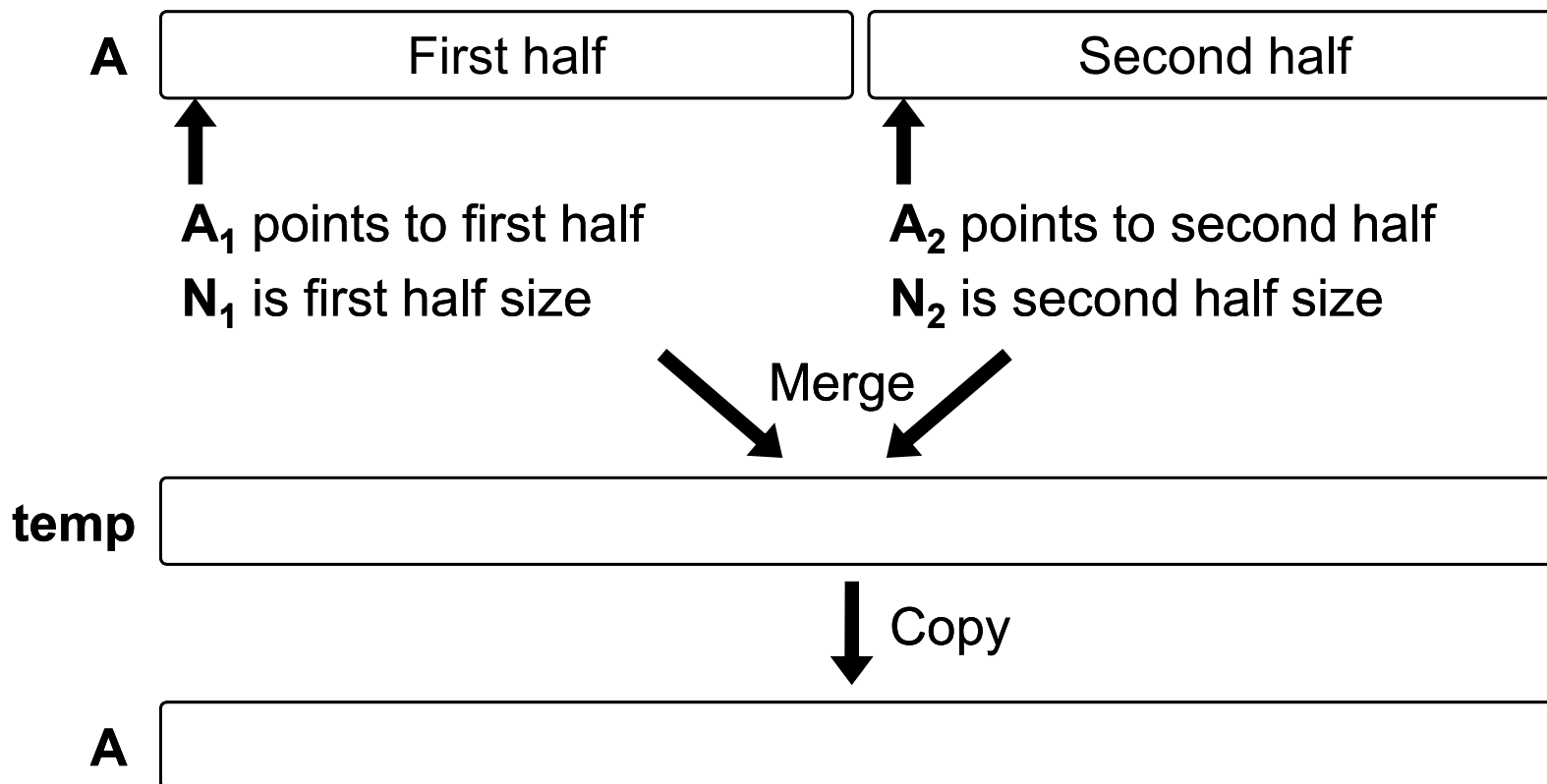


# Logarithmic algorithms



## ■ Merge sort improvement:

### ■ Splitting in same array:



# Logarithmic algorithms



## ■ Merge sort improvement:

- Cut off splitting & use insertion sort.

```
mergeSort2( array A, size N )
```

```
{
```

```
  if ( N small enough )
```

```
    insertionSort( A, N );
```

```
  else
```

```
  {
```

```
    Split A into A1 (size N1) and A2 (size N2);
```

```
    mergeSort2( A1, N1 );
```

```
    mergeSort2( A2, N2 );
```

```
    mergeArray( A1, N1, A2, N2, temp );
```

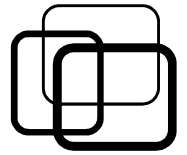
```
    copyArray( temp, A );
```

```
  }
```

```
}
```

insertion sort is efficient  
for small array!!

# Logarithmic algorithms



## ■ Merge sort analysis:

Scenario	When occur?	Complexity
Best-case	Array is already sorted	$O(n \log(n))$
Worst-case	Array is in reversed order	$O(n \log(n))$
Average-case	Array is in random order	$O(n \log(n))$

N	Insertion sort swap	Merge sort swap
10	~ 100	~ 40
1,000	~ 1,000,000	~ 10,000
100,000	~ 10,000,000,000	~ 1,700,000

■ Not an in-place sort algorithm.

➔ Need a temporary array.

➔ Good for sorting **LARGE** array with **ENOUGH MEMORY**.

# Logarithmic algorithms



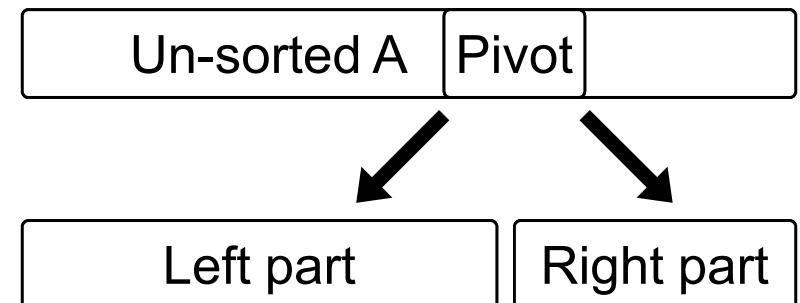
## ■ Quicksort overview:

- Developed by Tony Hoare, 1961.
- An  $O(n \log n)$  sort algorithm.
- Three times faster than Merge sort.
- Standard sort algorithm for libraries.

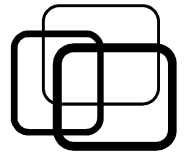


## ■ Quicksort idea:

- Partitioning array:
  - Given a pivot.
  - Left part  $\leq$  pivot.
  - Right part  $\geq$  pivot.



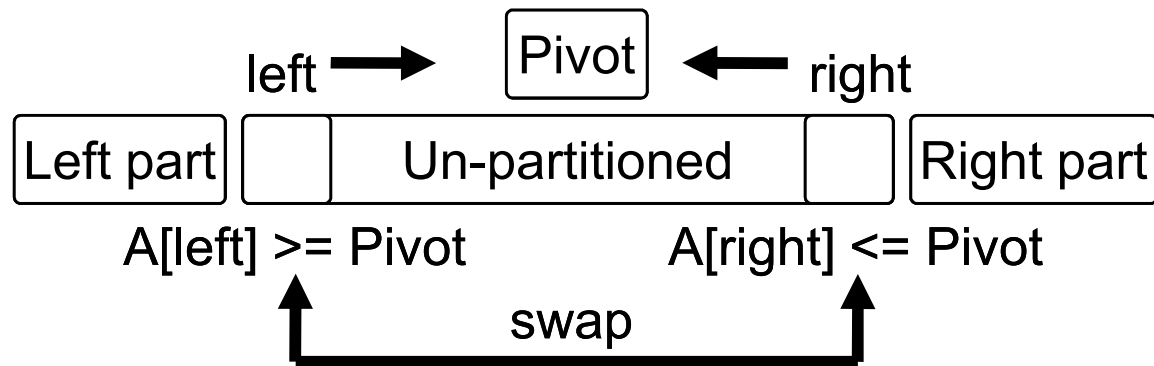
# Logarithmic algorithms



## ■ Partitioning array:

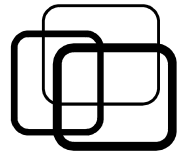
**partitionArray**( array **A**, from **l**, to **r**, pivot **P** ): partition position **K**

```
{  
  loop ( l < r )  
  {  
    l = find from left, first element  $\geq$  P  
    r = find from right, first element  $\leq$  P  
  
    if ( l < r ) {  
      swap( A[ l ], A[ r ] );  
      l++;  
      r--;  
    }  
  }  
  K = r;  
}
```





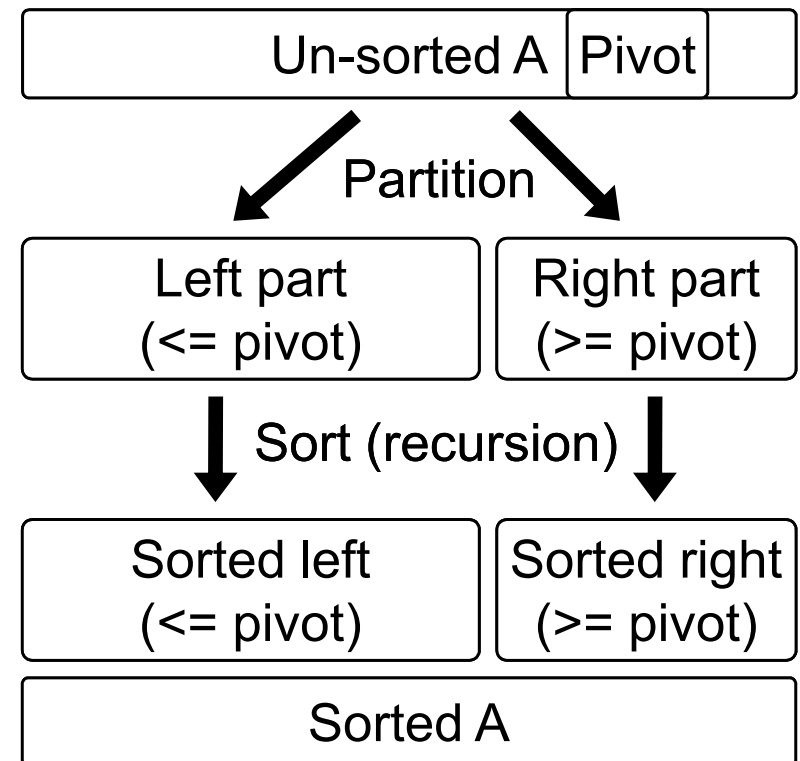
# Logarithmic algorithms



## ■ Quicksort algorithm:

*// Divide-and-conquer technique.*

```
quickSort( array A, from l, to r )  
{  
    if ( sorting range is one )  
        return;  
    else  
    {  
        pivot = select pivot from A;  
        pos = partitionArray( A, l, r, pivot );  
        quickSort( A, l, pos );  
        quickSort( A, pos + 1, r );  
    }  
}
```



# Logarithmic algorithms



## ■ Quicksort improvement:

### ■ Stop prematurely & use insertion sort:

*// A is JUST NEARLY SORTED.*

```
qSort( array A, from l, to r )
{
    if ( range is small )
        stop algorithm;
    else
    {
        pivot = select pivot from A;
        pos = partitionArray( A, l, r, pivot );
        qSort( A, l, pos );
        qSort( A, pos + 1, r );
    }
}
```

Stop  
prematurely!!

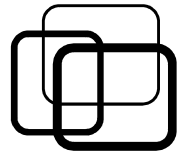
*// Cover function.*

```
quickSort3( array A, size N )
{
    qSort( A, 0, N - 1 );

    // A is nearly sorted.
    // Perform insertion sort.
    insertionSort( A, N );
}
```

Insertion sort is  
very efficient for  
nearly sorted array!!

# Logarithmic algorithms



## ■ Quicksort analysis:

Scenario	When occur?	Complexity
Best-case	Array is already sorted	$O( n \cdot \log(n) )$
Worst-case	Array is in reversed order	$O( n^2 )$
Average-case	Array is in random order	$O( n \cdot \log(n) )$

- An in-place sort algorithm but use recursion.
  - ➔ Space complexity:  $O( \log N )$ .
- Not a stable sort.
- Average-case is closer to best-case than worst-case.
  - ➔ Faster than most of  $O( N \log N )$  algorithms.
  - ➔ Standard sort algorithm for libraries.

# Summary



## ■ Bubble sort:

- Average-case complexity:  $O(n^2)$ .
- Storage space: in-place.

## ■ Selection sort:

- Average-case complexity:  $O(n^2)$ .
- Storage space: in-place.
- Stable sort algorithm.

## ■ Insertion sort:

- Average-case complexity:  $O(n^2)$ .
- Storage space: in-place.
- Efficient for small or nearly sorted array.



# Summary



## ■ Merge sort:

- Average-case complexity:  $O(n \log n)$ .
- Storage space: need temporary array.
- With enough memory, good for large array.

## ■ Merge sort improvement:

- Splitting in same array: use pointers.
- Cut off & use selection sort.
- Stop prematurely & use insertion sort.



# Summary



## ■ Quicksort:

- Average-case complexity:  $O(n \log n)$ .
- Worst-case complexity (rarely):  $O(n^2)$ .
- Storage space: in-place.
- Fast and commonly used in libraries.

## ■ Quicksort improvement:

- Stop prematurely & use insertion sort.





## ■ Practice 5.1:

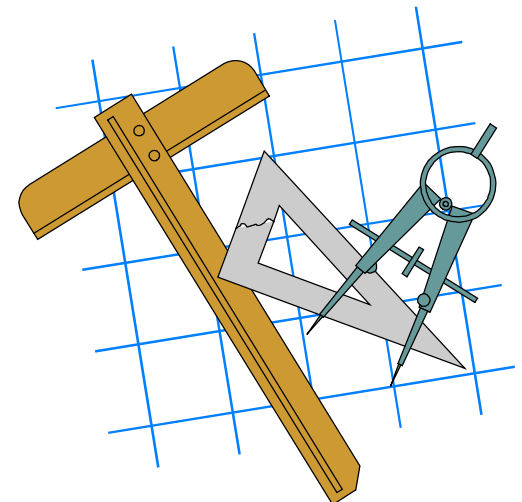
Practice sort algorithms in this slides on the following arrays:

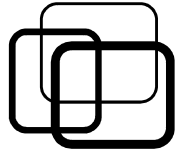
a)  $A = \{ 8 \ 7 \ 2 \ 3 \ 1 \ 4 \ 6 \ 5 \}$ .

b)  $A = \{ 3 \ 5 \ 1 \ 2 \ 8 \ 7 \ 4 \ 6 \}$ .

c)  $A = \{ 8 \ 7 \ 6 \ 5 \ 4 \ 3 \ 2 \ 1 \}$ .

d)  $A = \{ 1 \ 2 \ 3 \ 4 \ 5 \ 6 \ 7 \ 8 \}$ .

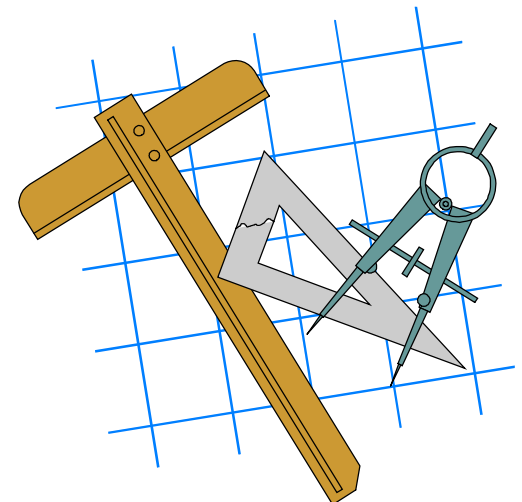




## ■ Practice 5.2:

Construct class **Array** (of integer) and provide it with the following sort methods:

- Bubble sort.
- Selection sort.
- Insertion sort.
- Merge sort.
- Quick sort.







## ■ Practice 5.3:

- a) Implement **Insertion sort** on **Singly Linked List**.
- b) Implement **Merge sort** on **Singly Linked List**.

