# Search Algorithms (cont)

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### Contents

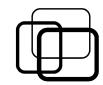


- Hash function.
- Hash table.
- Collision handling.

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- Hash function.
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- Collision handling.



#### Basic concepts:



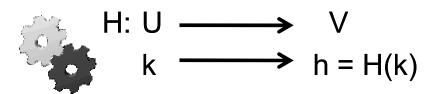
#### Student identity:

- Name?
- Age?
- Hair color?
- Hobbies?



Number identity IS SIMPLER!!

- A hash function is...
  - > A mapping function.
  - > Convert key to integer.





#### Characteristics:

#### ■ The key:

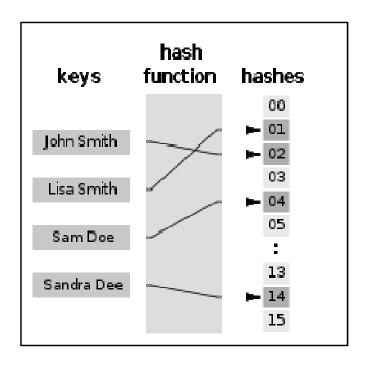
- > Variable length.
- > Big or complex value.
- > Big number, string, object.

#### ■ The hash:

- > Fixed length.
- > 32-bit, 64-bit, 128-bit integer.
- > Key space BIGGER hash space.

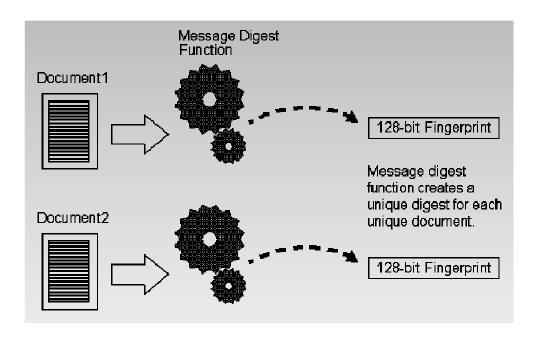
#### ■ The function:

- Key mapped to unique hash (perfectly).
- Fast to compute: H(k) ~ O(1).
- > Hard to invert:  $H^{-1}(k) \sim O(\text{key space})$ .





- Hash function applications:
  - Hash table indexing (see below).
  - Checksum.
  - Cryptograph.





- Hash function examples:
  - Big integer?
  - String?
  - Object?

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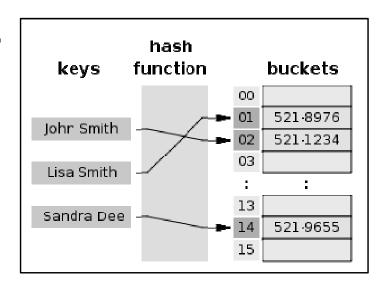


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#### Hash table idea:

- An O(1) search data structure.
- How to achieve O(1) search?
  - Given array A.
  - > Given hash function H.
  - > Given element k.
  - > h = H( k ) is the hash.
  - > k is stored at h in A.
  - → Element is stored at its hash.





#### ADT Hash table:

■ Values: array of elements.

```
class HashTable {
    vector<int *> m_elements;
};
```

#### Operations:

- Initialize: create empty table.
- > Contains: check if a key exists.
- > Find: look for a key.
- Add: insert a key.
- > Remove: delete a key.



### Hash table implementation:

Find: look for a key.
FindKey( array A, key k) {
Get hash h = H(k).
if A[h] is empty → return not found.
else → return found.

■ Add: insert a key.

```
AddKey( array A, key k) {
Get hash h = H(k).
if A[h] is empty → Store k at h.
else → Resolve collision.
}
```



### Complexity analysis:

Operations	Average	Worst
Search	O(1)	O( n )
Add	O(1)	O( n )
Remove	O( 1 )	O( n )

- Additional space: 4\*n bytes.
- Efficient way to store un-ordered, intensively searched array.

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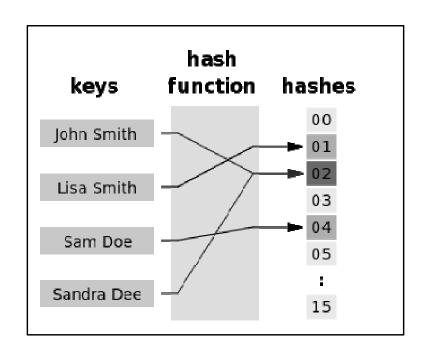


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### Collision problem:

- Key space BIGGER hash space.
  - → Two keys have same hash.
- Definition:
  - > Given hash function H.
  - > If two keys  $k1 \neq k2$ .
  - > But H(k1) = H(k2).





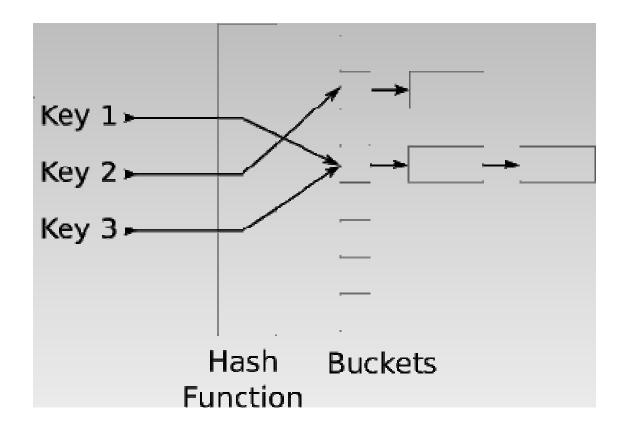
#### ■ Collision resolutions:

- Chaining.
- Open addressing:
  - > Linear probing.
  - > Quadratic probing.
  - > Double hashing.



#### Collision resolutions:

- Chaining:
  - > Collided keys are linked by singly linked list.

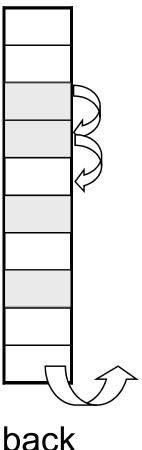




#### Collision resolutions:

- Open addressing Linear probing:
  - > Collided keys are added next to each other.
  - > Probing function:

$$P(k, i) = (H(k) + i) \mod N.$$





#### ■ Collision resolutions:

- Open addressing Quadratic probing:
  - > Collided keys are added in quadratic increment.
  - Probing function:

$$P(k, i) = (H(k) + i^2) \mod N.$$



#### Collision resolutions:

- Open addressing Double hashing:
  - > Collided keys are added by second hash function.
  - > Probing function:

$$P(k, i) = (H(k) + i * H_2(k)) \mod N.$$

> Second hash function:

$$H_2(k) = R + (k \mod R)$$

R is prime number.

# Summary



#### Hash function:

Mapping function converting key to integer.

#### Hash table:

Array storing element at its hash.

### Collision handling:

■ Chaining: link collides by singly linked list.

#### Open addressing:

> Linear probing: stores collides in sequence.

> Quadratic probing: stores collides in quadratic increme

Double hashing: stores collides by second hash.

### Practice



#### ■ Practice 4.1:

Implement ADT **HashTable** (of integer) with values and operations. Try using different collision resolutions:

- Chaining.
- Linear probing.
- Double hashing.

