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# You are using Python

given N*N

from collections import deque

def shortest_clear_path(grid):
    n = len(grid)
    if grid[0][0] == 1 or grid[n-1][n-1] == 1:
        return -1 # No path if starting or ending cell is blocked

    # Directions for 8-connectivity
    directions = [(-1, 0), (1, 0), (0, -1), (0, 1),
                  (-1, -1), (-1, 1), (1, -1), (1, 1)]

    # BFS setup
    queue = deque([(0, 0, 1)]) # (x, y, path_length)
    visited = set((0, 0))

    while queue:
        x, y, length = queue.popleft()

        # If we reach the bottom-right corner
        if x == n - 1 and y == n - 1:
            return length

        for dx, dy in directions:
            nx, ny = x + dx, y + dy

            # Check if the new position is within bounds and not visited
            if 0 <= nx < n and 0 <= ny < n and (nx, ny) not in visited and grid[nx][ny] == 0:
                visited.add((nx, ny))
                queue.append((nx, ny, length + 1))

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return -1 # No path found

# Input reading and processing
n = int(input().strip())
grid = [list(map(int, input().strip().split())) for _ in range(n)]

# Output the result
print(shortest_clear_path(grid))

## rat
def find_paths(maze, N):
    def dfs(x, y, path):
        # If we reach the destination
        if x == N - 1 and y == N - 1:
            paths.append(path)
            return

        # Directions: down, left, right, up
        directions = [(1, 0, 'D'), (0, -1, 'L'), (0, 1, 'R'), (-1, 0, 'U')]

        for dx, dy, direction in directions:
            nx, ny = x + dx, y + dy
            # Check if the new cell is within bounds and not visited
            if 0 <= nx < N and 0 <= ny < N and maze[nx][ny] == 1 and not visited[nx][ny]:
                visited[nx][ny] = True # Mark the cell as visited
                dfs(nx, ny, path + direction) # Recur with the new path
                visited[nx][ny] = False # Backtrack and unmark the cell

# Initial checks for the start and end cells
if maze[0][0] == 0 or maze[N - 1][N - 1] == 0:

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    return ["-1"] # If start or end is blocked

paths = []
visited = [[False] * N for _ in range(N)]
visited[0][0] = True # Mark the starting cell as visited
dfs(0, 0, "") # Start DFS from the top-left corner

if not paths:
    return ["-1"] # If no paths were found

paths.sort() # Sort paths lexicographically
return paths

# Reading input
N = int(input())
maze = [list(map(int, input().split())) for _ in range(N)]

# Finding paths
result = find_paths(maze, N)

# Printing result
print(" ".join(result))

##grid
def findLongestPath(grid, M, N):
    def dfs(x, y, start_char, visited):
        max_length = 0

        # Define possible movements: right, down, left, up
        directions = [(0, 1), (1, 0), (0, -1), (-1, 0)]

        for dx, dy in directions:
            nx, ny = x + dx, y + dy

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        # Check boundaries and if the next node is unvisited and of different type
        if 0 <= nx < M and 0 <= ny < N and (nx, ny) not in visited and grid[nx][ny] != start_char:
            visited.add((nx, ny)) # Mark as visited

            # Recursively explore the next node
            length = dfs(nx, ny, grid[nx][ny], visited) # Change start_char to current char
            max_length = max(max_length, length)

            visited.remove((nx, ny)) # Backtrack

    return max_length + 1 # Include the current node

longest_path = 0
for i in range(M):
    for j in range(N):
        start_char = grid[i][j]
        visited = {(i, j)} # Start with the current node
        # Explore paths from this node
        longest_path = max(longest_path, dfs(i, j, start_char, visited))

return longest_path

# Reading input
M, N = map(int, input().split())
grid = [input().strip() for _ in range(M)]

# Finding the longest path
result = findLongestPath(grid, M, N)

# Printing the result
print(result)

##Shakshi

class TreeNode:

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def __init__(self, value):
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    self.value = value
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    self.left = None
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    self.right = None
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class BinaryTree:
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    def __init__(self):
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        self.root = None
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    def insert_level_order(self, values):
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        if not values:
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            return
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        self.root = TreeNode(values[0])
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        queue = [self.root]
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        index = 1
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        while index < len(values):
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            current = queue.pop(0)
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            if index < len(values):
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                current.left = TreeNode(values[index])
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                queue.append(current.left)
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                index += 1
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            if index < len(values):
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                current.right = TreeNode(values[index])
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                queue.append(current.right)
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                index += 1
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    def post_order_cubed(self):
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        result = []

        self._post_order_cubed_rec(self.root, result)

        return result

def _post_order_cubed_rec(self, node, result):
    if node:
        self._post_order_cubed_rec(node.left, result)
        self._post_order_cubed_rec(node.right, result)
        result.append(node.value ** 3)

def main():
    n = int(input().strip())
    values = list(map(int, input().strip().split()))

    # Construct binary tree
    binary_tree = BinaryTree()
    binary_tree.insert_level_order(values)

    # Get post-order traversal with cubed values
    post_order_result = binary_tree.post_order_cubed()

    # Print the result
    print(" ".join(map(str, post_order_result)))

if __name__ == "__main__":
    main()

##you r

def minimax(scores, depth, is_maximizing):
    # Base case: If we are at the leaf level
    if depth == 0:
        return scores[0]

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# Calculate the number of scores at the current depth
num_scores = 2 ** depth
left_scores = scores[:num_scores // 2]
right_scores = scores[num_scores // 2:num_scores]

if is_maximizing:
    # Maximizing player's turn
    left_value = minimax(left_scores, depth - 1, False)
    right_value = minimax(right_scores, depth - 1, False)
    return max(left_value, right_value)
else:
    # Minimizing player's turn
    left_value = minimax(left_scores, depth - 1, True)
    right_value = minimax(right_scores, depth - 1, True)
    return min(left_value, right_value)

def optimal_value(scores):
    # Calculate the depth based on the number of scores
    n = len(scores)
    depth = n.bit_length() - 1 # log2(n)
    return minimax(scores, depth, True)

if __name__ == "__main__":
    n = int(input())
    scores = list(map(int, input().split()))
    result = optimal_value(scores)
    print(result)

##alex

def minimax_with_alpha_beta(values, depth, is_maximizing, alpha, beta):
    # Base case: if at leaf node, return the value

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if depth == 0:
    return values[0]

num_values = len(values)

# Split values into left and right children
left_values = values[:num_values // 2]
right_values = values[num_values // 2:num_values:]

if is_maximizing:
    max_value = float('-inf')
    for child in [left_values, right_values]:
        value = minimax_with_alpha_beta(child, depth - 1, False, alpha, beta)
        max_value = max(max_value, value)
        alpha = max(alpha, max_value)
        if beta <= alpha:
            break # Beta cut-off
    return max_value
else:
    min_value = float('inf')
    for child in [left_values, right_values]:
        value = minimax_with_alpha_beta(child, depth - 1, True, alpha, beta)
        min_value = min(min_value, value)
        beta = min(beta, min_value)
        if beta <= alpha:
            break # Alpha cut-off
    return min_value

def optimal_supply_allocation(depth, leaf_values):
    # Compute the optimal value using Minimax with Alpha-Beta pruning
    optimal_value = minimax_with_alpha_beta(leaf_values, depth, True, float('-inf'), float('inf'))

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# Add reserve
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value_with_reserve = optimal_value + 10
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return optimal_value, value_with_reserve
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def main():
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    d = int(input())
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    leaf_values = list(map(int, input().split()))
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    optimal_value, value_with_reserve = optimal_supply_allocation(d, leaf_values)
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# Print the output in the required format
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print(f"Optimal value: {optimal_value}\nValue with 10 units reserve: {value_with_reserve}")
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if __name__ == "__main__":
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    main()
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