### KPI1.

**Summer 2019** 

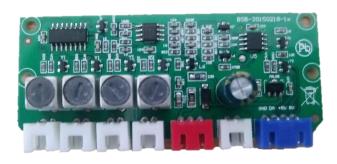
## Sensor Fusion: Ultrasonic Sensor PGA460 and Murata MA58MF14-7N

Presenter: My Uyen Nguyen, MIT

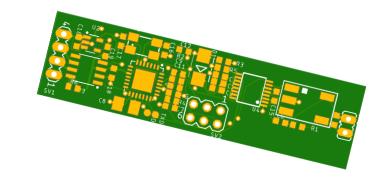
Mentor: Ankur Deo

#### Related Works

#### On Vehicle



## Developed Embedded Platform



# Product specs

- 4 ultrasonic sensors
- Up to 2 meters
- 4 frames per second

- 1 ultrasonic sensor
- Unknown distance range
- Unknown feed rate

#### **Project Objectives**

- Accurate and consistent distance measurement of up to 2 meters
- Feed rate of >= 10 frames per second
- Multiple sensors configuration using 1 microcontroller



Microcontroller



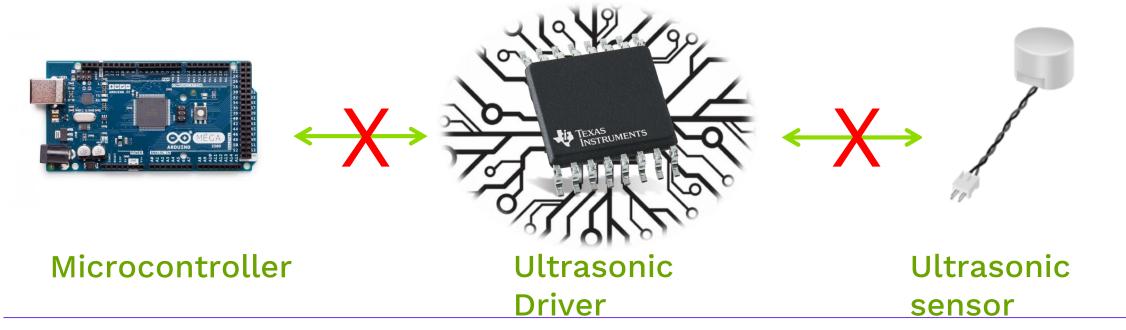
Ultrasonic Driver



Ultrasonic sensor

#### Challenges and Troubleshooting

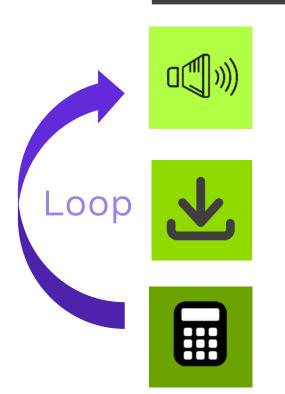
- Unreliable hardware and software
- Failed serial communication and burst+listen
  - → Constant distance measurement regardless of object detection
  - → Invalid data transmission
- Incomplete understanding of ultrasonic driver's method of operation

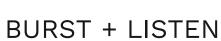


#### **Method of Operation**



INITIALIZATION - EEPROM, Threshold, AFEGAIN + TVG



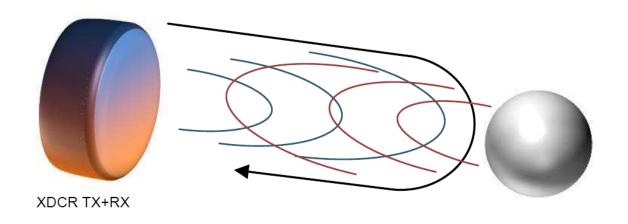




PULL + FILTER DATA



COMPUTE DISTANCE

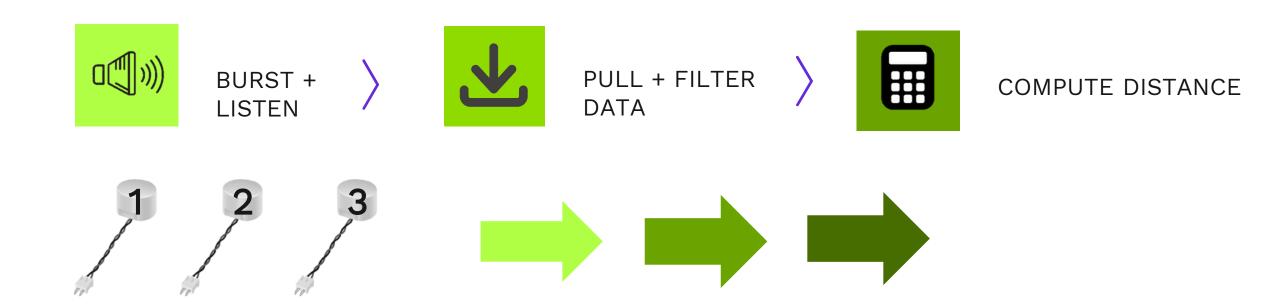


Mono-Static Configuration



#### **Modified Method of Operation**

- Additional Methods of Data Communication
  - USB Communication for PC
  - CAN Bus for ECUs



#### Results

Performance Comparison					
	Third-Party Device	Inherited Device	Developed Embedded System		
Number of sensors	4	1	1	2	3
Min distance (m)	N/A	N/A	0.25	0.25	0.25
Max distance (m)	2.0	N/A	3.5	3.5	3.5
Frames per second	4	N/A	45-50	44	43
Accuracy	N/A	N/A	+/02	+/02	+/02





- Manufacture PCB for multiple-sensors setup (IN PROGRESS)
- Test PCB outside of lab and confirm maximum distance range
- Install sensors onto vehicle for real-time testing
- Increase number of ultrasonic sensors driven by one microcontroller using SoftwareSerial

## KPI1

# Thank you for a wonderful time at KPIT and in India

