```
1 // Ray W. Clough & Joseph Penzien "Dynamics of Structures"
  2 // Page 第202頁至第203頁
  4 using Matrix_0;
  5
  6 // 初始值InitVal(速度, 變位)。
  7 double[,] InitVal = { { 0 }, { 9 }, { 0 }, { 0.5 }, { 0.4 },
              \{0.3\};
  8
  9 // 建構系統矩陣A。
10 double[,] M = \{ \{ 1, 0, 0 \}, \{ 0, 1.5, 0 \}, \{ 0, 0, 2 \} \};
11 double[,] K = \{ \{ 600, -600, 0 \}, \{ -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200 \}, \{ 0, -600, 1800, -1200, -1200 \}, \{ 0, -600, 1800, -1200, -1200 \}, \{ 0, -600, 1800, -1200, -1200, -1200 \}, \{ 0, -600, 1800, -1200, -1200, -1200 \}, \{ 0, -600, 1800, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1200, -1
              -1200, 3000 \} ;
12 ReMatrix C = (new Zero(3)). GetMatrix;
13 MKCMatrix mkc = new MKCMatrix(M, K, C);
14 ReMatrix A = mkc. Matrix;
15
16 // 系統特徵值V和模態(特徵向量)矩陣Q。
17 EIG eig = new EIG(A);
18 CxMatrix D = eig. CxMatrixD;
19 CxMatrix V = eig. CxVector;
20 CxMatrix Q = eig.CxMatrixQ;
21
22 // 系統係數向量d
23 CxHexp Hexp = new CxHexp(D, Q, 0);
24 CxMatrix MatTemp = Hexp. GetCxMatrix;
25 CxMatrix d = MatTemp * InitVal;
26
27 // 列印系統與狀態參數V, Q, d。
28 Console. Write (
                   "\n****{0,5}系{0,5}統{0,5}與{0,5}狀{0,5}態{0,5}參{0,5}數{0,5}
29
                         ****\n", "");
30
31 Console. Write ("\n***{0,5} 系統特徵值V{0,5}***\n{1}\n", "", new PR
              (V));
32 Console. Write("\n***{0,5} 模態矩陣Q{0,5}***\n{1}\n", "", 33 Console. Write("\n***{0,5} 係數向量d{0,5}***\n{1}\n", "",
                                                                                                                                                 new PR(Q);
                                                                                                                                               , new PR(d):
34
35 // 狀態響應。速度,變位,加速度。(t = 40秒)
36 \text{ double step} = 0.5;
37 int iRow = (int)(40 / step + 1);
38 int iCol = M. GetLength(1) + 1;
39 ReMatrix Disp = new ReMatrix(iRow, iCol);
40 ReMatrix Vel = new ReMatrix(iRow, iCol);
41 ReMatrix Acc = new ReMatrix(iRow, iCol);
42 for (int i = 0; i != iRow; i++)
43 {
```

```
44
       double t = step * i:
45
46
       Hexp = new CxHexp(D, Q, t);
47
       MatTemp = Hexp. GetCxMatrix;
48
       CxMatrix yh_Cx = MatTemp * d;
49
       ReMatrix yh_Re = (ReMatrix)yh_Cx;
50
       ReMatrix yhDot Re = A * yh Re;
51
52
       // 加速度Acc。
       Acc. Matrix[i, 0] = t;
53
       Acc. Matrix[i, 1] = yhDot Re. Matrix[0, 0];
54
       Acc. Matrix[i, 2] = yhDot Re. Matrix[1, 0];
55
       Acc. Matrix[i, 3] = yhDot Re. Matrix[2, 0];
56
57
       // 速度Vel。
58
59
       Vel.Matrix[i, 0] = t;
       Vel. Matrix[i, 1] = yh_Re. Matrix[0, 0];
60
       Vel. Matrix[i, 2] = yh Re. Matrix[1, 0];
61
62
       Vel. Matrix[i, 3] = yh_Re. Matrix[2, 0];
63
64
       // 位移Disp。
65
       Disp. Matrix[i, 0] = t;
       Disp. Matrix[i, 1] = yh Re. Matrix[3, 0];
66
       Disp. Matrix[i, 2] = yh_Re. Matrix[4, 0];
67
       Disp. Matrix[i, 3] = yh Re. Matrix[5, 0];
68
69
70 }
71
72 // 列印標題。
73 Console. Write ("\n**** {0, 10} 狀 {0, 5} 態 {0, 5} 響 {0, 5} 應 {0, 10} ****\n",
     "");
74
75 // 列印狀態響應(節點的變位,速度,和加速)。
76 Console. Write ("\n{0,5}***位移反應量***{0,5}\n{0,8} 時間(秒)"+
77
        "{0,8}第0點位移{0,8}第1點位移{0,8}第2點位移\n\n{1}",
       "", new PR(Disp));
78
   Console. Write ("\n{0,5}***速度反應量***{0,5}\n{0,8}時間(秒)"+
79
       "{0,8}第0點速度{0,8}第1點速度{0,8}第2點速度\n\n{1}",
80
       "", new PR(Ve1));
81
   Console. Write ("\n*** {0,5} 加速度反應量 {0,5} *** \n {0,8} 時間 (秒)" +
       "{0,7}第0點加速度{0,7}第1點加速度{0,7}第2點加速度\n\n{1}",
83
84
       "", new PR(Acc));
85
86 // 分別列印時間、節點變位、速度、和加速度等序列。
   Console. Write("\n時間序列:\n{0}\n", new PR4(Disp, 0));
87
88
89 Console. Write ("\n第0點變位序列:\n{0}\n", new PR4(Disp, 1));
```

```
90 Console. Write ("\n第1點變位序列:\n{0}\n", new PR4(Disp, 2));
91 Console. Write ("\n第2點變位序列:\n{0}\n", new PR4(Disp, 3));
 92 Console. Write("\n第0點速度序列:\n{0}\n", new PR4(Vel, 1));
93 Console. Write("\n第1點速度序列:\n{0}\n", new PR4(Vel, 2));
 94 Console. Write ("\n第2點速度序列:\n{0}\n", new PR4(Ve1, 3));
 95 Console. Write("\n第0點加速度序列:\n{0}\n", new PR4(Acc, 1));
 96 Console. Write("\n第1點加速度序列:\n{0}\n", new PR4(Acc, 2));
 97 Console. Write("\n第2點加速度序列:\n{0}\n", new PR4(Acc, 3));
 98
 99 /*輸出結果如下:
100 ****
             系
                    統
                           與
                                  狀
                                         熊
                                                       數
                                                              ****
101
            系統特徵值V
102 ***
                            ***
            0.00000
                              46.09947i
103
                              46.09947i
104
            0.00000
105
            0.00000 +
                              31.04770i
106
            0.00000 -
                              31.04770i
            0.00000 +
                              14. 52167 i
107
108
            0.00000 -
                              14. 52167 i
109
110 ***
            系統特徵向量Q
                              ***
      0.27298 + 0.00000i,
111
                            0.27298 + 0.00000i,
                                                  0.73905 + 0.00000i,
112
      0.73905 + 0.00000i,
                            0.81141 + 0.00000i,
                                                  0.81141 + 0.00000i
113
114
     -0.69390 + 0.00000i
                           -0.69390 + 0.00000i
                                                 -0.44830 + 0.00000i
115
     -0.44830 + 0.00000i,
                            0.52623 + 0.00000i
                                                  0. 52623 + 0. 00000i
116
117
      0.66597 + 0.00000i,
                            0.66597 + 0.00000i
                                                 -0.50180 + 0.00000i
118
     -0.50180 + 0.00000i,
                            0.24492 + 0.00000i
                                                  0. 24492 + 0. 00000i
119
120
      0.00000 - 0.00592i,
                            0.00000 + 0.00592i,
                                                  0.00000 - 0.02380i,
      0.00000 + 0.02380i,
                            0.00000 - 0.05588i,
                                                  0.00000 + 0.05588i
121
122
123
      0.00000 + 0.01505i,
                            0.00000 - 0.01505i,
                                                  0.00000 + 0.01444i
      0.00000 - 0.01444i,
                            0.00000 - 0.03624i,
                                                  0.00000 + 0.03624i
124
125
126
      0.00000 - 0.01445i,
                            0.00000 + 0.01445i,
                                                  0.00000 + 0.01616i,
127
      0.00000 - 0.01616i,
                            0.00000 - 0.01687i
                                                  0.00000 + 0.01687i
128
129 ***
            係數向量d
                          ***
130
           -2.78170 +
                               1.63905i
131
           -2.78170 -
                               1.63905i
132
           -2.23945 -
                               2. 30387i
           -2.23945 +
133
                               2. 30387i
134
            2. 97558
                    +
                               5. 28200i
135
            2.97558
                               5.28200i
136
```

	1002 (grenub (hpp_oon (hppoo			
137	****	響	應 ***	*
138	***位移反應量***			
139	時間(秒)	第0點位移	第1點位移	第2點位移
140	0.00000	0.50000	0.40000	0. 30000
141	0.50000	0.71318	0. 29042	0. 16971
142	1.00000	-0. 01535	0. 19230	-0.02364
	1. 50000	-0. 45288	-0. 39900	-0. 13435
143				
144	2.00000	-0.64474	-0. 47086	-0. 14171
145	2. 50000	-0. 28078	-0. 03707	-0.14830
146	3.00000	0. 46792	0. 19118	0. 13277
147	3. 50000	0.62626	0.42805	0.30532
148	4. 00000	0.40897	0. 26710	-0.05157
149	4. 50000	-0.38328	-0.15425	0.03183
150	5.00000	-0.51417	-0.57092	-0.23664
151	5. 50000	-0.64593	-0.11707	-0.13498
152	6.00000	0.31567	-0.03181	-0.02128
153	6.50000	0.50226	0.44260	0.35189
154	7. 00000	0.66808	0. 36601	-0.02597
155	7. 50000	-0. 13772	0. 04499	0. 12603
156	8. 00000	-0. 41434	-0. 50809	-0. 19846
157	8. 50000	-0. 77276	-0. 24203	-0. 20482
158	9. 00000	-0. 02862	-0.17046	-0.07039
159	9. 50000	0. 43813	0. 28498	0. 25114
160	10.00000	0.66708	0. 50256	0.08316
161	10. 50000	0. 26517	0. 15105	0. 11488
162	11.00000	-0.35858	-0. 29612	-0.03524
163	11. 50000	-0.67015	-0.37204	-0 . 32482
164	12. 00000	-0. 44939	-0. 23447	-0.04575
165	12. 50000	0.36402	0.03065	0.07631
166	13.00000	0.50896	0. 59078	0. 18753
167	13. 50000	0.63502	0. 22004	0.08130
168	14.00000	-0 . 22135	-0.05398	0. 13428
169	14.50000	-0.49983	-0.39754	-0 . 37623
170	15.00000	-0.72605	-0.30203	-0.05364
171	15. 50000	0. 14465	-0. 18758	-0.04114
172	16.00000	0.36380	0. 52861	0.17253
173	16. 50000	0.77542	0. 32159	0. 12000
174	17. 00000	0.09183	0. 10459	0. 20183
175	17. 50000	-0. 38986	-0. 25446	-0. 28274
	18. 00000			-0. 14590
176		-0. 73472	-0.40708	
177	18. 50000	-0. 23415	-0.30140	-0.04495
178	19. 00000	0. 28227	0. 31084	0. 02365
179	19. 50000	0.66356	0. 43831	0. 22214
180	20.00000	0. 49849	0. 16925	0. 17619
181	20. 50000	-0.30366	-0.00127	-0.09758
182	21.00000	-0.55408	-0. 48213	-0 . 25362
183	21. 50000	-0.60562	-0.35351	-0.00270

14.08332

1.78250

2.94614

11.87037

-0.19173

1.61119

229

230

2.50000

3.00000

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231	3.50000	5. 18683	-6. 55677	0.57594
232	4.00000	-11.97648	-3 . 56951	0.33584
233	4.50000	-7.42981	-3 . 60689	-8.71605
234	5.00000	-2.55209	-3. 19460	4.62928
235	5.50000	8.97992	3. 15400	1.57246
236	6.00000	7. 20647	10.81837	-0.55501
237	6.50000	4.83712	-1.15846	4. 53819
238	7.00000	-4. 37584	-4.90792	-1.71387
239	7.50000	-13. 29732	-1.09006	-5. 76174
240	8.00000	-1.44402	-8.49277	-0.08125
241	8.50000	0.87613	3.63960	4. 16419
242	9.00000	11.82981	8. 17069	-3. 76891
243	9.50000	3. 99124	3. 78712	8. 21829
244	10.00000	3. 11170	-4. 96532	-2.74508
245	10. 50000	-15.47425	1. 29217	-3. 63336
246	11.00000	-2. 26484	-11. 44975	-2 . 59615
247	11. 50000	-4. 28417	1. 51922	4. 10922
248	12. 00000	10. 56982	6. 99733	-4 . 58883
249	12. 50000	6. 66775	5. 10658	8. 31448
250	13. 00000	5. 86182	-1.74449	-0. 25186
251	13. 50000	-10. 87514	1. 49846	-4. 55765
252	14. 00000	-6. 87280	-10. 31943	-1. 16832
253	14. 50000	-4 . 40982	-3. 61251	0.65962
254	15. 00000	3. 29085	7. 72438	-2. 65327
255	15. 50000	11. 88790	2. 91551	5. 11949
256	16. 00000	4. 76194	3. 33953	4. 47562
257	16. 50000	-2 . 42353	0. 79801	-6. 94293
258	17. 00000	-11.64520	-6. 98571	1. 98944
259	17. 50000	-2. 92726	-8. 82065	-3. 19132
260	18. 00000	-4. 79129	7. 82960	-1.00160
261	18. 50000	14. 40031	0. 26079	2. 09249
262	19. 00000	4. 58335	6. 59754	7. 57409
263	19. 50000	3. 79427	2. 13052	-7. 24410
264	20.00000	-11. 23429	-4.73813	3. 21249
265	20. 50000	-4. 37452	-10.64943	-3.81547
266	21.00000	-8. 37729	4. 92784	-2. 58342
267	21. 50000	10. 36199	-0. 30185	2. 02033
268	22.00000	8. 13716	5. 74779	6. 68191
269	22. 50000	4. 67438	6. 50756	-4. 03420
270	23. 00000	-4. 48876	-4. 67228	1. 41083
271	23. 50000	-8.88479	-8. 58901	-0. 78948
272	24. 00000	-7. 30524	-0. 20438	-6. 82484
273	24. 50000	1. 73755	0. 58493	4. 00030
274	25. 00000	12. 75050	2. 15261	3. 40915
275	25. 50000	2. 86816	11. 48012	0. 22972
276	26. 00000	3. 98552	-4. 67492	-0.81799
277	26. 50000	-11. 72331	-5. 42986	2. 73335
	_ = = = = = = = = = = = = = = = = = = =	111111111111111111111111111111111111111		

323

7.50000

109.62647

-8.25181

-162.05566

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324	8.00000	-56. 24746	285. 19775	-7. 15825			
325	8.50000	318. 43992	-182.52617	162.01390			
326	9.00000	-85 . 10239	136. 79493	3.30209			
327	9.50000	-91.89025	34. 18751	-205.72180			
328	10.00000	-98.71229	-269.71310	176. 79921			
329	10.50000	-68. 47478	16.71956	-81.69619			
330	11.00000	37. 47981	183.71560	-124.81005			
331	11.50000	178.86692	-81.46940	264.00674			
332	12.00000	128. 95448	65.00480	-72.05710			
333	12. 50000	-200.02294	169.87403	-96.06918			
334	13.00000	49.08788	-355 . 32260	73. 17046			
335	13.50000	-248. 98601	55.00270	10.06751			
336	14.00000	100. 42107	83.66610	-233.81590			
337	14.50000	61. 37613	-23.86646	325. 81623			
338	15.00000	254. 41000	29. 10716	-100.75919			
339	15. 50000	-199.34095	250. 04824	-50.83884			
340	16.00000	98. 88729	−350 . 79511	58. 38004			
341	16. 50000	-272.29994	20. 26789	12. 94556			
342	17.00000	7.65692	72.69373	-240.00014			
343	17.50000	81. 24360	-76.79000	271. 43661			
344	18.00000	196. 58236	77. 88756	-25 . 39264			
345	18.50000	-40 . 35313	232. 06420	-113. 41902			
346	19.00000	17. 13673	-241. 17438	151. 02933			
347	19. 50000	−135 . 15219	-82. 83803	−70 . 21759			
348	20.00000	-197.54394	137. 25163	-162.73926			
349	20. 50000	181. 43296	-198.00283	145. 60555			
350	21.00000	43. 16998	154. 02475	91. 15648			
351	21. 50000	151. 26532	179. 80380	-208. 05766			
352	22. 00000	-67. 02081	-114. 41938	255. 96049			
353	22. 50000	10. 62764	-160. 57835	-135. 17300			
354	23. 00000	-341. 92282	183. 58765	-110. 73412			
355	23. 50000	201. 08198	-278. 81583	66. 27627			
356	24. 00000	-35. 43744	155. 27789	133. 95116			
357	24. 50000	203. 95440	187. 36944	-225. 98940			
358	25. 00000	-11.05820	-69. 18616	266. 92086			
359	25. 50000	26. 45271	-132. 51217	-90. 77657			
360	26. 00000	-304. 57551	146. 40216	-159. 72804			
361	26. 50000	60. 89364	-258. 45619	97. 24833			
362	27. 00000	26. 97604	47. 65532	62. 73767			
363	27. 50000	81. 84166	270. 64791	-147. 38660			
364	28. 00000	174. 98420	-112 . 07178	180. 87322			
365	28. 50000	-63. 16467	-21. 76644	39. 75532			
366	29. 00000	-144. 09767	64. 58988	-267. 26021			
367	29. 50000	-140. 12942	-184. 92503	180. 78449			
368	30. 00000	124. 04544	-94. 14112	-42. 42856			
369	30. 50000	-80. 07282	346. 97099	-64. 46491			
370	31.00000	330. 19124	-156. 46794	98. 54444			

301	39. 30000		0. 90000	90.00211	290. 955C
388	40.00000	O	1. 35128	21. 26411	249. 5987
389					
390	時間序列:				
391	0.0000,	0.5000,	1.0000,	1.5000,	2.0000,
392	2.5000,	3.0000,	3.5000,	4.0000,	4.5000,
393	5.0000,	5.5000,	6.0000,	6.5000,	7.0000,
394	7.5000,	8.0000,	8.5000,	9.0000,	9.5000,
395	10.0000,	10.5000,	11.0000,	11.5000,	12.0000,
396	12.5000,	13.0000,	13.5000,	14.0000,	14.5000,
397	15.0000,	15.5000,	16.0000,	16.5000,	17.0000,
398	17.5000,	18.0000,	18.5000,	19.0000,	19.5000,
399	20.0000,	20.5000,	21.0000,	21.5000,	22.0000,
400	22.5000,	23.0000,	23.5000,	24.0000,	24.5000,
401	25.0000,	25.5000,	26.0000,	26.5000,	27.0000,
402	27.5000,	28.0000,	28.5000,	29.0000,	29.5000,
403	30.0000,	30.5000,	31.0000,	31.5000,	32.0000,
404	32.5000,	33.0000,	33.5000,	34.0000,	34.5000,
405	35.0000,	35. 5000,	36.0000,	36.5000,	37.0000,
406	37.5000,	38.0000,	38.5000,	39.0000,	39.5000,
407	40.0000,				
408					
409	第0點變位序列	:			
410	0.5000,	0.7132,	-0.0153,	-0.4529,	-0.6447,
411	-0.2808,	0.4679,	0.6263,	0.4090,	-0.3833,
412	-0.5142,	-0.6459,	0.3157,	0.5023,	0.6681,
413	-0.1377,	-0.4143,	-0.7728,	-0.0286,	0.4381,
414	0.6671,	0. 2652,	-0.3586,	-0.6702,	-0.4494,
415	0.3640,	0.5090,	0.6350,	-0.2214,	-0.4998,
416	-0.7260,	0.1447,	0.3638,	0.7754,	0.0918,
417	-0.3899,	-0.7347,	-0.2341,	0. 2823,	0.6636,

$C: \2302 \github \App_38A \App38. cs$						
418	0.4985,	-0.3037,	-0.5541,	-0.6056,	0.1588,	
419	0.4523,	0.7853,	-0.1072,	-0.3640,	-0.7624,	
420	-0.1187,	0.2961,	0.8031,	0. 2443,	-0.2514,	
421	-0.6502,	-0.5022,	0. 1942,	0.6027,	0.6126,	
422	-0. 1358,	-0.4066,	-0. 7924,	0.0202,	0.3671,	
423	0. 7859,	0. 1064,	-0. 2074,	-0.8196,	-0. 2978,	
424	0. 2167,	0. 6795,	0.4622,	-0. 0884,	-0.6042,	
425	-0.6537,	0. 1008,	0. 4109,	0. 7524,	0.0626,	
426	-0. 3258,	0. 1000,	0. 4105,	0.1024,	0.0020,	
427	0. 0200,					
428	第1點變位序列					
429	9.4000,	0. 2904,	0.1923,	-0.3990,	-0.4709,	
430	-0. 0371,	0. 1912,	0. 4280,	0. 2671,	-0. 1542,	
431	-0.5709,	-0.1171,	-0.0318,	0. 4426,	0.3660,	
432	0.0450,	-0.5081,	-0. 2420,	-0. 1705,	0. 2850,	
433	0. 5026,	0. 1510,	-0. 2961,	-0.3720,	-0. 2345,	
434	0.0306,	0.5908,	0. 2200,	-0.0540,	-0. 3975,	
435	-0. 3020,	-0. 1876,	0. 5286,	0. 3216,	0. 1046,	
436	-0.2545,	-0.4071,	-0.3014,	0.3108,	0. 4383,	
437	0. 1692,	-0.0013,	-0.4821,	-0.3535,	0.0471,	
438	0.4700,	0.2155,	0. 2279,	-0.4231,	-0.4225,	
439	-0.1371,	0.3402,	0. 2955,	0.3458,	-0.2065,	
440	-0.5138,	-0.2105,	0.0889,	0.3625,	0.3790,	
441	0.0710,	-0.5400,	-0.2421,	-0.1527,	0.3145,	
442	0.4113,	0.2755,	-0.4159,	-0.2998,	-0.2806,	
443	0.1109,	0.4701,	0.3554,	-0.1620,	-0.3589,	
444	-0.3032,	-0.1670,	0.4845,	0.3695,	0.0975,	
445	-0.3235,					
446						
447	第2點變位序列	:				
448	0.3000,	0.1697,	-0.0236,	-0.1344,	-0.1417,	
449	-0.1483,	0.1328,		-0.0516,	0.0318,	
450	-0. 2366,	-0.1350,	-0.0213,	0.3519,	-0.0260,	
451	0. 1260,	-0.1985,	-0. 2048,	-0.0704,	0.2511,	
452	0.0832,	0.1149,	-0.0352,	-0.3248,		
453	•	0. 1875,				
454	*	-0.0411,	•		·	
455	-0. 2827,		-0.0449,	0.0236,		
456	0. 1762,			•	*	
457	0. 2781,	0. 1600,	0.0470,	-0. 2585,	-0.0183,	
458		0. 1966,			·	
459	-0. 1072,			0. 3232,		
460	0. 0567,	-0. 1730 ,				
461	0.0286,			-0. 1940 ,		
462	0. 0280,		-0. 1130, 0. 1328,	-0. 1940, 0. 0642,		
462						
	-0. 1589, -0. 2058	0.0221,	0. 1000,	0.0728,	0. 4000,	
464	-0. 2958,					

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465	*** - mt > t 1				
466	第0點速度序列				
467	0.0000,	0.9936,	-14.0466,	-3. 4434,	-0.7554,
468	14. 0833,	1. 7825,	5. 1868,	-11.9765,	-7.4298,
469	-2.5521,	8.9799,	7. 2065,	4.8371,	-4. 3758,
470	-13.2973,	-1.4440,	0.8761,	11.8298,	3.9912,
471	3. 1117,	-15.4743,	-2.2648,	-4. 2842,	10.5698,
472	6.6677,	5.8618,	-10.8751,	-6.8728,	-4. 4098,
473	3. 2909,	11.8879,	4.7619,	-2.4235,	-11.6452,
474	-2. 9273,	-4. 7913,	14. 4003,	4. 5833,	3. 7943,
475	-11. 2343,	-4. 3745,	-8. 3773,	10. 3620,	8. 1372,
476	4. 6744,	-4. 4888,	-8.8848,	-7. 3052,	1. 7376,
477	12. 7505,	2. 8682,	3. 9855,	-11. 7233,	-6. 0810,
478	-5. 4563,	13. 0167,	3. 2401,	8. 3944,	-8. 4419 ,
479	-8. 3463,	-7. 1980 ,	6. 8240,	7. 0180,	7. 5092,
480	0. 0146,	-12. 4737,	-5. 2397,	-1. 9887,	10. 1619,
481	5. 3775,	7. 9085,	-13. 2076,	-4. 5686,	-7. 3301,
	7. 7951,	•	10. 4310,	-7. 5691,	
482	*	6. 3180,	10. 4510,	7. 5091,	-7.4502,
483	-6. 9278,				
484	数1图 比束 庄 壹 利				
485	第1點速度序列		0.7700	2 0705	0 0040
486	9.0000,	-9. 0859 ,	-3. 7733,	-3. 0725,	0.6948,
487	2. 9461,	11. 8704,	-6. 5568 ,	-3. 5695,	-3. 6069 ,
488	-3. 1946,	3. 1540,	10. 8184,	-1. 1585,	-4. 9079,
489	-1.0901,	-8. 4928,	3. 6396,	8. 1707,	3. 7871,
490	-4. 9653,	1. 2922,	-11. 4498,	1. 5192,	6. 9973,
491	5. 1066,	-1.7445,	1.4985,	-10. 3194,	-3. 6125,
492	7. 7244,	2. 9155,	3. 3395,	0.7980,	-6.9857,
493	-8.8207,	7.8296,	0.2608,	6. 5975,	2. 1305,
494	-4. 7381,	-10.6494,	4. 9278,	-0.3019,	5. 7478,
495	6. 5076,	-4. 6723,	-8.5890,	-0.2044,	0.5849,
496	2. 1526,	11.4801,	-4.6749,	-5.4299,	-4.0638,
497	0.0506,	-0.8052,	13.4315,	-2.0789,	-4. 1499,
498	-3.9085,	-3.4689,	-1.3970,	11.2401,	2.9920,
499	-4. 7686,	-0.5208,	-8.0895,	-1.2360,	7. 3335,
500	7.3407,	-4.6096,	2.7523,	-10.1600,	-3.1561,
501	5.0045,	7.8604,	-1.6330,	3.6086,	-7.9831,
502	-7.6774,				
503					
504	第2點速度序列	:			
505	0.0000,	-0. 2446 ,	0.0438,	-8.8658,	7.6128,
506	-0. 1917,	1.6112,	0. 5759,	0. 3358,	-8. 7160,
507	4. 6293,	1. 5725,	-0. 5550,	4. 5382,	-1.7139,
508	-5. 7617,	-0. 0813,	4. 1642,	-3. 7689,	8. 2183,
509	-2. 7451,	-3. 6334,	-2. 5961,	4. 1092,	-4. 5888,
510	8. 3145,	-0. 2519,	-4. 5576,	-1. 1683,	0. 6596,
510	-2. 6533,	5. 1195,	4. 4756,	-6. 9429,	1. 9894,
911	۷. 0000,	J. 119J,	4.4100,	0. 3443,	1. 3034,

$C:\2302\github\App_38A\App38.cs$						
512	-3. 1913,	-1.0016,	2.0925,	7. 5741,	-7.2441,	
513	3. 2125,	-3.8155,	-2.5834,	2.0203,	6.6819,	
514	-4.0342,	1.4108,	-0.7895,	-6.8248,	4.0003,	
515	3.4091,	0.2297,	-0.8180,	2.7333,	-10.0648,	
516	4. 5583,	1.5051,	1.7244,	-0.1999,	3.5121,	
517	-9.4141,	1.6503,	2.7514,	-0.6786,	3. 4224,	
518	1.7230,	-5.8183,	-2.8899,	5.0984,	-4. 2544,	
519	6.7237,	0.6315,	-2.9704,	-5. 1846,	5.0813,	
520	-5. 4312,	6.3934,	2.8153,	-3.2804,	<i>−</i> 3. 4405,	
521	1.8262,					
522						
523	第0點加速度周	亨列 :				
524	-60.0000,	-253.6570,	124. 5878,	32.3306,	104. 3288,	
525	146. 2270,	-166.0423,	-118.9288,	-85. 1256,	137.4176,	
526	-34.0456,	317. 3125,	-208.4901,	-35.7968,	-181. 2405,	
527	109.6265,	-56. 2475,	318. 4399,	-85. 1024,	-91.8903,	
528	-98.7123,	-68. 4748,	37. 4798,	178.8669,	128.9545,	
529	-200.0229,	49.0879,	-248.9860,	100.4211,	61.3761,	
530	254. 4100,	-199. 3410,	98.8873,	-272.2999,	7.6569,	
531	81. 2436,	196. 5824,	-40.3531,	17. 1367,	-135. 1522,	
532	-197. 5439,	181. 4330,	43. 1700,	151. 2653,	-67.0208,	
533	10.6276,	-341.9228,	201. 0820,	-35. 4374,	203. 9544,	
534	-11.0582,	26. 4527,	-304. 5755,	60. 8936,	26. 9760,	
535	81. 8417,	174. 9842,	-63. 1647,	-144. 0977,	-140. 1294,	
536	124. 0454,	-80.0728,	330. 1912,	-103. 7864,	-31. 5486,	
537	-224. 7414,	101. 4248,	-125. 1201,	311.8553,	10. 3339,	
538	-63. 4803,	-125. 6572,	-64.0987,	-44. 1611,	147. 1557,	
539	210. 3398,	-160.6763,	44. 1455,	-229. 7858,	20.9681,	
540	1. 3513,	,	ŕ	ŕ	ŕ	
541						
542	第1點加速度周	亨列 :				
543			-255.8109,	190. 1648,	193.7673,	
544			-18.8962,			
545			147. 4130,			
546	-8. 2518,			136. 7949,		
547			183. 7156,			
548	· · · · · · · · · · · · · · · · · · ·	-355 . 3226 ,		83.6661,		
549	29. 1072,			20. 2679,		
550	-76. 7900,	77. 8876,	232.0642,		-82. 8380,	
551	137. 2516,			179. 8038,		
552			-278. 8158,			
553	-69. 1862,		146. 4022,			
554	270. 6479,		-21. 7664,			
555	-94. 1411 ,	· ·		66. 5125,		
556	-156. 3763,			-123. 2426,		
557	*	-208. 5643,		210. 3549,		
558	-24. 8222,	258. 9031,		-84. 1350 ,		
	,	,	,	,	,	

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559
        21.2641,
560
     第2點加速度序列:
561
562
      -210.0000,
                      -80.3115,
                                     150.8430,
                                                    -37.8736,
                                                                   -69.9506,
       200.2004,
                      -84.4403,
                                                                  -140.2892,
563
                                    -201.1531,
                                                    237.6190,
564
        12.4053,
                      132. 2312,
                                      12.8407,
                                                   -262.2777,
                                                                   258. 5694,
565
      -162.0557,
                       -7.1583,
                                     162.0139,
                                                      3.3021,
                                                                  -205.7218,
       176.7992,
                      -81.6962,
                                    -124.8101,
                                                    264.0067,
                                                                   -72.0571,
566
       -96.0692,
                                                                   325.8162,
567
                       73. 1705,
                                      10.0675,
                                                   -233.8159,
      -100.7592,
                      -50.8388,
                                      58.3800,
                                                     12.9456,
                                                                  -240.0001,
568
       271.4366,
                      -25.3926,
                                    -113.4190,
                                                    151.0293,
                                                                   -70.2176,
569
570
      -162.7393,
                      145. 6055,
                                      91. 1565,
                                                   -208.0577,
                                                                   255.9605,
571
      -135.1730,
                     -110.7341,
                                      66.2763,
                                                    133.9512,
                                                                  -225.9894,
                      -90.7766,
572
       266. 9209,
                                    -159.7280,
                                                     97. 2483,
                                                                    62.7377,
573
      -147.3866,
                      180.8732,
                                      39. 7553,
                                                   -267.2602,
                                                                   180. 7845,
       -42.4286,
                      -64.4649,
                                      98. 5444,
                                                    142.4843,
                                                                  -318.6346,
574
575
       203.9264,
                      -67.1417,
                                     -80.0764,
                                                    111.0940,
                                                                   135. 5720,
      -253.6145,
                      125.0208,
                                                   -193.4267,
                                                                   198. 1201,
576
                                      14.0774,
                     -134.2588,
577
        56.4800,
                                      20.7699,
                                                    112.4594,
                                                                  -298.9330,
       249.5988,
578
579
580
      */
581
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