```
1 // .NET 8. @ C:\2302\Misc 10\App 41
 2 // Dennis G. Zill "Differential Equations with Boundary-Value
 3 // Problems 9th Edition" Page 322 Example 1
 4
 5 using Matrix_0;
 6
 7 // 已知數據(空間維度m=2, 狀態維度r=2)
 8 double[,] M = \{ \{ 1, 0 \}, \{ 0, 1 \} \};
9 double[,] C = { { 0, 0 }, { 0, 0 } };
10 double[,] K = \{ \{ 10, -4 \}, \{ -4, 4 \} \};
11 // t=0時的初始值[y'0|y'1|y0|y1] = [1|-1|0|0]
12 double[,] y0Start = { { 1 }, { -1 }, { 0 }, { 0 } };
13
14 // 建構系統矩陣A
15 SysMatrix2 SysMat = new SysMatrix2(M, C, K);
16 ReMatrix A = SysMat. GetMatrix;
17
18 // 特徵矩陣D與模態矩陣Q。
19 EIG eig = new EIG(A);
20 CxMatrix D = eig. CxMatrixD;
21 CxMatrix V = eig. CxVector;
22 CxMatrix Q = eig.CxMatrixQ;
23
24 // 係數向量d
25 CxHexp Hexp = new CxHexp(D, Q, 0);
26 CxMatrix MatTemp = Hexp. GetCxMatrix;
27 CxMatrix d = "MatTemp * yOStart;
28
29 // 列印系統特徵矩陣、模態矩陣、和係數向量。
30 Console. Write ("\n****{0,6} 系 {0,5} 統 {0,5} 與 {0,5} 狀 {0,5} 態 {0,5} 參 {0,5} ⊋
     數\{0,6\}***\n", "");
31 Console. Write ("\n*** {0,5} 系統特徵值V {0,5} *** \n {1} \n", "", new PR
     (V):
32 Console. Write ("\n***{0,5} 系統特徵矩陣D{0,5}***\n{1}\n", "", new PR マ
     (D);
33 Console. Write ("\n***{0,5} 系統模態矩陣Q{0,5}***\n{1}\n", "", new PR →
     (Q));
34 Console. Write ("\n***{0,5}係數向量d{0,5}***\n{1}\n", "", new PR(d));
36 // 建構Disp、Vel、和Acc三個空的儲存矩陣
37 double step = 0.25;
38 int iRow = (int)(20 / step + 1);
39 int iCol = M.GetLength(1) + 1;
40 ReMatrix Disp = new ReMatrix(iRow, iCol);
41 ReMatrix Vel = new ReMatrix(iRow, iCol);
42 ReMatrix Acc = new ReMatrix(iRow, iCol);
43
```

```
44 // 將計算的結果存入Vel、Disp、和Acc矩陣中
45 for (int i = 0; i != iRow; i++)
46
   {
47
       double t = step * i;
48
       Hexp = new CxHexp(D, Q, t);
49
       MatTemp = Hexp.GetCxMatrix;
       ReMatrix yh Re = (ReMatrix)(MatTemp * d);
50
51
52
       // 速度
       Vel.Matrix[i, 0] = t;
53
       Vel. Matrix[i, 1] = yh Re. Matrix[0, 0];
54
       Vel. Matrix[i, 2] = yh Re. Matrix[1, 0];
55
       // 位移
56
       Disp. Matrix[i, 0] = t;
57
       Disp. Matrix[i, 1] = yh_Re. Matrix[2, 0];
58
59
       Disp. Matrix[i, 2] = yh Re. Matrix[3, 0];
60
       // 加速度
       ReMatrix yhDot_Re = A * yh_Re;
61
62
       Acc. Matrix[i, 0] = t;
       Acc. Matrix[i, 1] = yhDot Re. Matrix[0, 0];
63
64
       Acc. Matrix[i, 2] = yhDot Re. Matrix[1, 0];
65 }
66
67 // 列印節點之狀態響應(變位,速度,和加速),適用於Excel繪圖
68 Console. Write ("\n****{0,6} 空 {0,5} 間 {0,5} 狀 {0,5} 態 {0,5} 響 {0,5} 應 {0,6} マ
     ***\n", "");
69 Console. Write ("\n{0,5}***位移反應量***{0,5}\n{0,8} 時間(秒)"+
70 "{0,8} 第0點位移 {0,8} 第1點位移 \n\n{1}", "", new PR(Disp));
71 Console. Write ("\n{0,5}***速度反應量***{0,5}\n{0,8} 時間(秒)"+
72 "{0,8}第0點速度{0,8}第1點速度\n\n{1}", "", new PR(Ve1));
73 Console. Write ("\n***{0,5}加速度反應量{0,5}***\n{0,8}時間(秒)"+
74 "{0,8}第0點加速度{0,7}第1點加速度\n\n{1}", "", new PR(Acc));
75
76 // 列印時間、變位、速度、和加速度等序列,適用於Matplotlib.pyplot套件→
     繪圖。
77 Console. Write ("\n時間序列:\n{0}\n", new PR4(Disp, 0, "{0,8:F2}"));
78 Console.Write("\n第0點變位序列:\n{0}\n", new PR4(Disp, 1));
79 Console. Write ("\n第1點變位序列:\n{0}\n", new PR4(Disp, 2));
80 Console.Write("\n第0點速度序列:\n{0}\n", new PR4(Vel, 1));
81 Console. Write("\n第1點速度序列:\n{0}\n", new PR4(Ve1, 2));
82 Console. Write("\n第0點加速度序列\n{0}\n", new PR4(Acc, 1));
83 Console.Write("\n第1點加速度序列\n{0}\n", new PR4(Acc, 2));
84 Console. Write (" \ n \ ");
85
86 /* 輸出
87 ****
            系
                   統
                         與
                                狀
                                       態
                                             參
                                                    數
                                                           ***
88
```

```
89
    ***
             系統特徵值V
                              ***
 90
                   3.46410i
        0.00000 +
 91
        0.00000 -
                   3.46410i
 92
        0.00000 +
                   1.41421i
 93
        0.00000 -
                   1. 41421i
 94
             系統特徵矩陣D
 95
    ***
                                ***
 96
     -0.00000 +
                  3.46410i,
                               0.00000 +
                                          0.00000i,
 97
      0.00000 +
                  0.00000i,
                               0.00000 +
                                          0.00000i
 98
 99
      0.00000 +
                  0.00000i,
                              -0.00000 -
                                          3.46410i,
100
      0.00000 +
                  0.00000i,
                               0.00000 +
                                          0.00000i
101
102
      0.00000 +
                  0.00000i.
                               0.00000 +
                                          0.00000i.
103
      0.00000 +
                               0.00000 +
                                          0.00000i
                  1.41421i,
104
105
      0.00000 +
                  0.00000i.
                               0.00000 +
                                          0.00000i.
106
      0.00000 +
                  0.00000i.
                               0.00000 -
                                          1. 41421i
107
             系統模態矩陣Q
                                ***
108
    ***
109
      0.85934 +
                  0.00000i,
                               0.85934 +
                                          0.00000i,
110
      0.36515 +
                  0.00000i,
                               0.36515 +
                                          0.00000i
111
112
     -0.42967 +
                  0.00000i,
                              -0.42967 +
                                          0.00000i,
      0.73030 +
                  0.00000i,
                               0.73030 +
                                          0.00000i
113
114
115
      0.00000 -
                  0.24807i,
                               0.00000 +
                                          0.24807i,
                                          0.25820i
      0.00000 -
                               0.00000 +
116
                  0.25820i,
117
118
      0.00000 +
                  0.12403i,
                               0.00000 -
                                          0.12403i,
119
      0.00000 -
                  0.51640i,
                               0.00000 +
                                          0.51640i
120
             係數向量d
                            ***
121
122
        0.69821 +
                    0.00000i
123
       0.69821 +
                    0.00000i
124
      -0.27386 +
                    0.00000i
125
      -0.27386 +
                    0.00000i
126
127
               空
                      間
                              狀
                                     態
                                                    應
    ****
                                                            ***
128
129
          ***位移反應量***
130
             時間(秒)
                              第0點位移
                                                第1點位移
131
             0.00000
                               0.00000
                                                0.00000
             0.25000
                               0.21492
                                               -0.22987
132
133
             0.50000
                               0.25004
                                               -0.35470
134
             0.75000
                               0.05573
                                               -0.33640
135
             1.00000
                              -0.24948
                                               -0.22449
```

C. \Z30Z\{	31 tilub (App_41 (F1	ogram. cs		
136	1.25000	-0.46009	-0.11667	
137	1.50000	-0.42719	-0.08772	
138	1.75000	-0.16339	-0.13694	
139	2.00000	0. 16470	-0.19127	
140	2.25000	0.35150	-0.16148	
141	2.50000	0. 29406	-0.01133	
142	2.75000	0.06104	0. 20983	
143	3. 00000	-0. 15916	0. 39484	
144	3. 25000	-0. 19405	0. 44820	
145	3. 50000	-0.01072	0. 34900	
146	3. 75000	0. 25996	0. 16362	
147	4. 00000	0. 41574	-0. 00063	
148	4. 25000	0. 32686	-0. 06818	
149	4. 50000	0. 02989	-0. 04347	
150	4. 75000	-0. 29475	-0.00140	
150	5. 00000	-0. 44636	-0. 02744	
151	5. 25000	-0.34180	-0. 15056	
		-0. 07117	-0. 31695	
153	5. 50000 5. 75000			
154	5. 75000	0. 16771	-0. 42386	
155	6.00000	0. 20952	-0.39017	
156	6. 25000	0. 03749	-0. 21425	
157	6. 50000	-0. 20635	0. 02175	
158	6. 75000	-0. 32377	0. 20462	
159	7. 00000	-0. 20324	0. 26322	
160	7. 25000	0.09796	0. 21151	
161	7. 50000	0. 39066	0. 13182	
162	7. 75000	0. 48419	0. 11123	
163	8. 00000	0. 31878	0. 17642	
164	8. 25000	0.00684	0. 27333	
165	8. 50000	-0. 24565	0. 30628	
166	8. 75000	-0. 28252	0. 20873	
167	9. 00000	-0. 10476	-0.00449	
168	9. 25000	0. 13358	-0. 24096	
169	9. 50000	0. 23739	-0 . 38862	
170	9.75000	0. 11133	-0 . 38795	
171	10.00000	-0. 17031	-0. 26839	
172	10. 25000	-0.41411	-0 . 12402	
173	10.50000	-0. 44314	-0.04607	
174	10.75000	-0.22224	-0.05999	
175	11.00000	0. 11545	-0.11112	
176	11.25000	0.35943	-0.10880	
177	11.50000	0.36673	0.00308	
178	11.75000	0.15905	0. 19940	
179	12.00000	-0.09587	0.38483	
180	12. 25000	-0.20504	0.45571	
181	12.50000	-0.08778	0.36968	
182	12.75000	0.16696	0.17462	

C:\230	C:\2302\github\App_41\Program.cs							
183	13.00000	0.36405	-0.02355					
184	13. 25000	0.34155	-0. 13153					
185	13.50000	0.08761	-0.12865					
186	13.75000	-0.24773	-0.07456					
187	14.00000	-0.45468	-0.06013					
188	14. 25000	-0.40817	-0. 13687					
189	14. 50000	-0. 15337	-0.27557					
190	14.75000	0. 12764	-0.38380					
191	15.00000	0. 24444	-0.37035					
192	15. 25000	0. 13147	-0. 21132					
193	15. 50000	-0.10790	0.02893					
194	15.75000	-0.27710	0. 23718					
195	16.00000	-0.22823	0.32420					
196	16. 25000	0.03016	0. 28046					
197	16. 50000	0.33595	0. 17648					
198	16.75000	0. 48512	0. 10818					
199	17.00000	0.37409	0. 12661					
200	17. 25000	0.07243	0. 20154					
201	17.50000	-0.22502	0. 24496					
202	17.75000	-0.33324	0. 17738					
203	18.00000	-0. 20426	-0.01013					
204	18. 25000	0.04250	-0. 24264					
205	18.50000	0. 20792	-0.40710					
206	18.75000	0. 15650	-0.42564					
207	19.00000	-0.08581	-0.30576					
208	19. 25000	-0.34866	-0.13248					
209	19.50000	-0.43720	-0.00840					
210	19.75000	-0.27055	0.01617					
211	20.00000	0.05899	-0.02598					
212								
213	***速度反應量**	* *						
214	時間(秒)	第0點速度	第1點速度					
215	0.00000	1.00000	-1.00000					
216	0.25000	0.58980	-0.76397					
217	0.50000	-0 . 34472	-0.20776					
218	0.75000	-1.12473	0.31822					
219	1.00000	-1.16932	0.50669					
220	1.25000	-0.40848	0.30209					
221	1.50000	0.66276	-0.06981					
222	1.75000	1.32798	-0.27106					
223	2.00000	1. 14918	-0.09891					
224	2.25000	0.27150	0.36384					
225	2.50000	-0.68137	0.80239					
226	2.75000	-1.04714	0.89027					
227	3.00000	-0.59027	0. 52147					
228	3. 25000	0.33488	-0.10947					
229	3.50000	1.03764	-0.63639					

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230	3.75000	0. 98231	-0. 76972
231	4.00000	0. 17047	-0. 49033
232	4. 25000	-0.85551	-0.05376
233	4. 50000	-1.39079	0. 19702
234	4. 75000	-1.06230	0. 07757
235	5.00000		-0.30718
236	5. 25000		-0.63940
237	5. 50000		-0. 61797
238	5. 75000		-0. 17891
239	6. 00000	-0. 30947	0. 44983
240	6. 25000	-0. 96446	0. 89883
241	6. 50000	-0. 84346	0. 90829
242	6. 75000	-0. 01543	0. 50405
243	7. 00000		-0. 02466
244	7. 25000		-0. 32944
245	7. 50000		-0. 24519
	7. 75000	-0. 16423	0. 09982
246	8. 00000		
247		-1.07829	0. 38275
248	8. 25000	-1. 26926	0. 32347
249	8. 50000		-0. 10814
250	8. 75000		-0.66211
251	9.00000		-0. 97773
252	9. 25000		-0. 83397
253	9. 50000		-0. 30495
254	9. 75000	-0. 91927	0. 28885
255	10.00000	-1. 19483	0. 59990
256	10. 25000	-0. 62831	0. 48960
257	10. 50000	0. 42146	0. 11597
258	10. 75000		-0. 18759
259	11.00000		-0. 15581
260	11. 25000	0. 54914	0. 21527
261	11. 50000	-0. 47486	0. 66225
262	11.75000	-1.06577	0.84014
263	12.00000	-0. 83473	0. 56903
264	12. 25000	0.01942	-0. 03238
265	12. 50000	0.85463	-0.62152
266	12. 75000	1.04284	-0.86314
267	13.00000	0. 41724	-0.65558
268	13. 25000	-0.60601	-0. 19390
269	13. 50000	-1. 31786	0. 17354
270	13. 75000	-1. 21428	0. 19331
271	14.00000	-0.35161	-0. 11527
272	14. 25000	0.69109	-0. 47786
273	14.50000	1.21635	-0. 56536
274	14.75000	0.89490	-0. 23480
275	15.00000	-0.00743	0.35989
276	15. 25000	-0.82181	0.86655

$C: \setminus 2$	C:\2302\github\App_41\Program.cs								
277		15. 50000	-0.95159	0. 97454					
278		15.75000	-0.29536	0.62783					
279		16.00000	0.68039	0.06196					
280		16. 25000	1.27035	-0.36076					
281		16. 50000	1.02935	-0. 40194					
282		16.75000	0.08958	-0. 10769					
283		17.00000	-0.92789	0. 23319					
284		17.25000	-1.34545	0.30267					
285		17.50000	-0.90137	-0.01290					
286		17.75000	0.06986	-0.53470					
287		18.00000	0.87584	-0.91205					
288		18. 25000	0. 95487	-0.86727					
289		18.50000	0.27087	-0.39275					
290		18.75000	-0.66365	0.23885					
291		19.00000	-1.15237	0.65906					
292		19. 25000	-0.81025	0.65360					
293		19. 50000	0. 16022	0. 30322					
294		19. 75000	1. 10687	-0.08266					
295		20. 00000	1. 38330	-0. 19167					
296									
297	***	加速度反應量	***						
298		時間(秒)	第0點加速度	第1點加速度					
299		0.00000	-0.00001	0.00000					
300		0.25000	-3.06865	1.77915					
301		0.50000	-3.91924	2.41899					
302		0.75000	-1.90291	1.56854					
303		1.00000	1.59692	-0.10000					
304		1.25000	4. 13427	-1.37370					
305		1.50000	3.92096	-1.35785					
306		1.75000	1.08615	-0.10580					
307		2.00000	-2.41207	1.42387					
308		2. 25000	<i>−</i> 4. 16093	2.05191					
309		2.50000	-2.98595	1. 22157					
310		2.75000	0. 22894	-0.59516					
311		3.00000	3. 17096	-2 . 21599					
312		3.25000	3.73331	-2 . 56899					
313		3.50000	1.50325	-1.43891					
314		3.75000	-1.94513	0.38535					
315		4.00000	-4.15996	1.66549					
316		4. 25000	-3 . 54126	1. 58013					
317		4.50000	-0.47276	0. 29344					
318		4.75000	2.94195	-1.17342					
319		5.00000	4. 35380	-1.67566					
320		5. 25000	2.81575	-0.76496					
321		5.50000	-0.55606	0.98310					
322		5.75000	-3. 37252	2. 36626					
323		6.00000	-3.65585	2. 39875					

C:\2302\github\App_41\Program.cs						
324	6. 25000	-1.23187	1.00696			
325	6.50000	2. 15049	-0. 91239			
326	6.75000	4.05613	-2.11353			
327	7.00000	3. 08526	-1.86584			
328	7.25000	-0. 13356	-0. 45420			
329	7.50000	-3.37930	1.03536			
330	7. 75000	-4.39701	1. 49184			
331	8.00000	-2. 48209	0. 56943			
332	8. 25000	1. 02494	-1.06597			
333	8. 50000	3. 68159	-2. 20770			
334	8. 75000	3. 66015	-1. 96501			
335	9. 00000	1. 02961	-0. 40107			
336	9. 25000	-2. 29966	1. 49816			
337	9. 50000	-3. 92842	2. 50406			
338	9. 75000	-2. 66510	1. 99713			
339	10. 00000	0. 62954	0. 39233			
340	10. 25000	3. 64501	-1. 16036			
341	10. 50000	4. 24715	-1. 58829			
342	10. 75000	1. 98240	-0. 64900			
343	11. 00000	-1. 59904	0. 90631			
344	11. 25000	-4. 02951	1. 87293			
345	11. 50000	-3. 65500	1. 45460			
346	11. 75000	-0. 79295	-0. 16137			
347	12. 00000	2. 49801	-1. 92279			
348	12. 25000	3. 87320	-2. 64298			
349	12. 50000	2. 35652	-1. 82985			
350	12. 75000	-0. 97113	-0. 03063			
351	13. 00000	-3. 73471	1. 55041			
352	13. 25000	-3. 94160	1. 89232			
353	13. 50000	-1. 39072	0. 86505			
	13. 75000	2. 17902	-0. 69265			
354		4. 30628	-1. 57820			
355	14. 00000 14. 25000	3. 53423	-1. 08522			
356	14. 50000					
357		0. 43145	0. 48878			
358	14. 75000	-2. 81159	2. 04576			
359	15. 00000	-3. 92586	2. 45919			
360	15. 25000	-2. 15997	1. 37115			
361	15. 50000	1. 19476	-0. 54733			
362	15. 75000	3. 71966	-2. 05709			
363	16. 00000	3. 57907	-2. 20970			
364	16. 25000	0. 82022	-1. 00121			
365	16. 50000	-2. 65356	0. 63787			
366	16. 75000	-4. 41847	1. 50775			
367	17. 00000	-3. 23445	0. 98993			
368	17. 25000	0. 08186	-0. 51644			
369	17. 50000	3. 23009	-1. 87995			
370	17. 75000	4. 04190	-2. 04248			

9

401 402 位移序列:

16.25,

17. 50,

18.75,

20.00,

16.50,

17. 75,

19.00,

403 404 第 0 點

397

398

399

400

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18.00,

19.25,

17.00,

18. 25,

19.50,

17.25,

18.50,

19.75,

C:\2302\github\App_41\Program.cs							
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422	第 1 點						
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424	-0.1167,	-0.0877,		-0. 1913,			
425		0.2098,					
426	0. 1636,			-0.0435,			
427	-0.0274,			-0.4239,	-0.3902,		
428	-0.2143,	0.0217,	0.2046,	0.2632,	0. 2115,		
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431	-0.2684,	-0.1240,		-0.0600,			
432	-0.1088,	0.0031,	0.1994,	0.3848,	0.4557,		
433	0.3697,	0.1746,	-0.0236,	-0.1315,	-0.1286,		
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436	0.2805,	0.1765,	0.1082,	0.1266,	0.2015,		
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445	-0.4085,	0.6628,	1.3280,	1. 1492,	0. 2715,		
446	-0.6814,	-1.0471,	-0.5903,	0.3349,	1.0376,		
447	0. 9823,	0. 1705,	-0.8555,	-1.3908,	-1.0623,		
448	-0.0910,	0.8625,					
449	-0.9645,	-0.8435,	-0.0154,	0.9387,	1.3350,		
450		-0. 1642,			-0.6386,		
451	0.3426,		0.7977,				
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460	1. 3833,						
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         -0.6938,
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516	2. 3286,	0.8798,	-0.8647,	-1.7152,	-1.1469,
517	0.3399,				
518	*/				