```
1 using System;
 2 using Matrix_0;
 3
 4 namespace ConsoleApp33
 5 {
 6
        internal class Program
 7
            static void Main(string[] args)
 8
 9
10
                // 建構系統矩陣A。
11
                double[,] M0 = \{ \{2, 0\}, \{0, 1\} \};
12
                ReMatrix M = new ReMatrix(M0);
                double[, ] K0 = { {3, -1}, {-1, 1} };
13
14
                ReMatrix K = new ReMatrix(K0);
15
                double[,] C0 = \{ \{0.4, -0.05\}, \{-0.05, 0.2\} \};
16
                ReMatrix C = new ReMatrix(C0);
17
                Console. Write("\n 質量矩陣M:\n{0}", new PR(M));
18
                Console. Write("\n 勁度矩陣K:\n{0}", new PR(K));
                Console. Write("\n 阻尼矩陣C:\n{0}", new PR(C));
19
20
21
                MKCMatrix MKC = new MKCMatrix(M, K, C);
                ReMatrix A = MKC. Matrix;
22
23
                Console. Write("\n 系統矩陣A:\n{0}\n", new PR(A));
24
25
                // 建構系統矩陣B:(使用矩陣運算子,兩者相同)
26
                Iden Id = new Iden(2);
27
                ReMatrix I = Id. GetMatrix;
28
                Zero Ze = new Zero(2);
29
                ReMatrix 0 = Ze. GetMatrix;
30
31
                ReMatrix B = (-1.0 * \sim M * C & -1.0 * \sim M * K) | (I & 0);
32
                Console. Write("\n 系統矩陣B:\n{0}\n", new PR(B));
33
            }
34
        }
35 }
36
   /*輸出結果如下:
37
    質量矩陣M:
38
                            0.00000
           2.00000
39
           0.00000
                            1.00000
40
    勁度矩陣K:
41
           3.00000
                           -1.00000
42
          -1.00000
                            1.00000
```

```
阻尼矩陣C:
43
44
                            -0.05000
            0.40000
          -0.05000
                             0.20000
45
     系統矩陣A:
46
                   0.02500
                              -1.50000
47
     -0.20001
                                           0.50000
                               1.00000
48
      0.05000
                  -0.20000
                                          -1.00000
      1.00000
                   0.00000
                               0.00000
49
                                           0.00000
50
      0.00000
                   1.00000
                               0.00000
                                           0.00000
51
     系統矩陣B:
52
     -0.20000
                              -1.50000
                                           0.50000
                   0.02500
                               1.00000
53
      0.05000
                  -0.20000
                                          -1.00000
      1.00000
                               0.00000
54
                   0.00000
                                           0.00000
                   1.00000
                               0.00000
                                           0.00000
      0.00000
55
56 */
57
```