

# Bayesian Approach

(13)

Probability function of event  $A$  in sample space  $S$ :

Kolmogorov's Axioms:  $P(A) \geq 0 \forall A$ ,  $P(S) = 1$ ,

$P(\cup A_i) = \sum P(A_i)$  if  $A_i$  are disjoint  
(mutually exclusive)

Joint probability: discrete example for events  $A$  and  $B$

	$A$	not $A$
$B$	55	5
not $B$	10	30

total 100 observations made.

Outcome logged in a contingency table.

$$P(A) = \frac{55+10}{100} = 0.65 \quad P(!A) = 0.35$$

$$P(B) = 0.6 \quad P(!B) = 0.4$$

Conditional probability:

$$P(A|B) = \frac{55}{55+5} = 0.917$$

probability of  $A$  given  
that event  $B$  occurs.

$$P(A \cap B) = \frac{55}{100} \quad \text{probability that both } A, B \text{ occurs.}$$

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{0.55}{0.6} = 0.917$$

Bayes' Theorem:

$$P(A \cap B) = P(A|B) P(B) = P(B|A) P(A).$$

$$\therefore P(B|A) = \frac{P(A|B) P(B)}{P(A)}$$

If  $A$  and  $B$  are not independent, i.e. they are correlated.  
Given information from observing event  $B$ , one can infer  
about event  $A$ .

Note: two events A and B are statistically independent if  $p(A \cap B) = p(A) p(B)$

$$\rightarrow p(A|B) = p(A) \quad \text{and} \quad p(B|A) = p(B)$$

Example:  $A = \text{drug test positive}$   
 $B = \text{athlete used drug}$

prior knowledge: estimate 60% of athletes do drugs.  
 $p(B) = 0.6$

Drug test result bring extra information:

$$p(A|B) = 0.917 \quad 91.7\% \text{ test positive for actual drug users}$$

$$p(A|\neg B) = 0.25 \quad 25\% \text{ False alarm rate}$$

Since A and B are correlated (not independent) a "positive drug test" increases the probability of "athlete used drug"

$$p(B|A) = \frac{p(A|B)}{p(A)} p(B) = \frac{0.917}{0.65} 0.6 = 0.846$$

posterior      "evidence"      prior  
                         or "support"  
                         for B given A

Note:  $p(A|B)$  is also the likelihood function  $L(B|A)$

$$p(A) = p(A|B)p(B) + p(A|\neg B)p(\neg B) \quad \text{is a normalizing term.}$$

Conclusion: the athlete is found guilty more easily given his positive drug test result.

Multivariate, Continuous case:

probability density function (pdf) of a Gaussian random variable  $X \sim N(x^b, B)$

$$p(x) = \frac{1}{\sqrt{(2\pi)^n |B|}} \exp\left(-\frac{1}{2}(x^b - x)^T B^{-1}(x^b - x)\right)$$

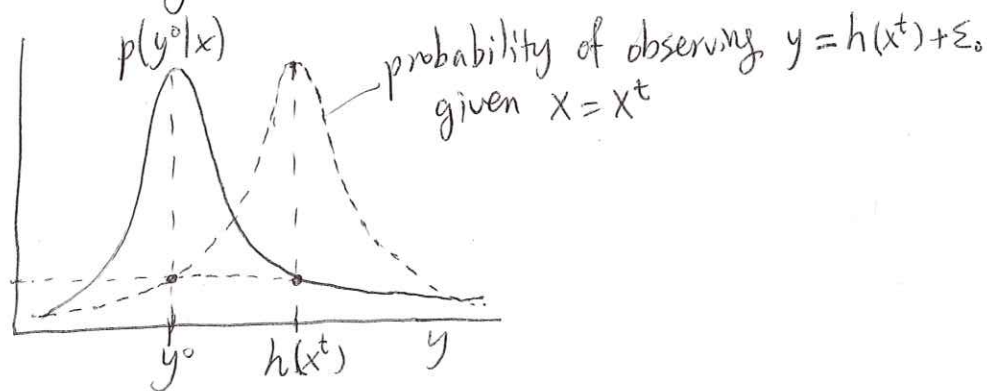
$p(x)$  is the probability of  $x = x^t$ , prior distribution

$x^b$  is prior mean (first moment)

$B$  is prior error covariance (second moment)

Note:  $n$ -th moment =  $\int (x - x^b)^n p(x) dx$ , for  $n > 1$

$p(y^o|x)$  is the probability of observing a value  $y^o$  given that  $x = x^t$ . It is also the likelihood function of  $x = x^t$  given that  $y^o$  is observed.  $L(x|y^o)$



$$p(y^o|x) = \frac{1}{\sqrt{(2\pi)^p |R|}} \exp\left(-\frac{1}{2}(y^o - h(x))^T R^{-1}(y^o - h(x))\right)$$

"observation likelihood"

According to Bayes' Theorem, posterior distribution

$$p(x|y^0) = \frac{p(y^0|x) p(x)}{\int p(y^0|x) p(x) dx} = p(y^0) \text{ is a normalizing factor.}$$

multiplication of two Gaussian pdf  $\rightarrow$  a Gaussian pdf

$p(x|y^0) = N(x^a, A)$  can show that:

$$x^a = x^b + W(y^0 - h(x^b))$$

$$A = (I - WH)B$$

$$W = BH^T(HBH^T + R)^{-1}$$

Proof in one-variable case:

$$-2 \ln(p(x|x^0)) = -2 \ln(p(x^0|x) p(x)) + C_1$$

$$\frac{(x - x^a)^2}{\sigma_a^2} = \frac{(x - x^b)^2}{\sigma_b^2} + \frac{(x^0 - x)^2}{\sigma_0^2} + C_1$$

$$= \frac{x^2 - 2xx^b + x^{b2}}{\sigma_b^2} + \frac{x^2 - 2xx^0 + x^{02}}{\sigma_0^2} + C_1$$

$$= \left( \frac{1}{\sigma_b^2} + \frac{1}{\sigma_0^2} \right) x^2 - 2x \left( \frac{x^b}{\sigma_b^2} + \frac{x^0}{\sigma_0^2} \right) + C_2$$

complete  
the square

$$= \left( \frac{1}{\sigma_b^2} + \frac{1}{\sigma_0^2} \right) \left( x^2 - 2x \frac{\frac{x^b}{\sigma_b^2} + \frac{x^0}{\sigma_0^2}}{\frac{1}{\sigma_b^2} + \frac{1}{\sigma_0^2}} + x^{a2} \right) + C_3$$

$$= \frac{1}{\sigma_a^2} = x^a = \frac{x^b \sigma_0^2 + x^0 \sigma_b^2}{\sigma_b^2 + \sigma_0^2}$$