Whitaker and Hamill 2002 In practice, we don't perturb observations for each member In the update step of serial EnKF:

for 
$$k = 1, 2, ..., N$$
  

$$X_{(j+1),k} = X_{(j),k} + K_{j}(y_{j,k}^{\circ} - y_{(j),k}) \qquad (1)$$

X and x' are updated separately instead:

$$\overline{X_{(j+1)}} = \overline{X_{(j)}} + K_j(y_j^* - \overline{y_{(j)}})$$
 (2)

for k=1,2,...,N $\chi'_{(j+1),k} = \chi'_{(j),k} + K_j (0-y'_{(j),k})$  (3)

$$= (I - K_j h_j) \times y_{j,k}$$

Missing observation perturbations will cause PG+1) to be erroneous.

The correct P(j+1) = (I-Kjhj)P(j) according to Kalman filter.

The actual P(5+1) according to (3) is

$$P^{(j+1)} = \frac{1}{N-1} \sum_{k=1}^{N} x'_{j+1}, k x'_{j+1}, k$$

$$= \left( I - K_{j}h_{j} \right) \frac{1}{N-1} \sum_{k=1}^{N} x'_{j+1}, k x'_{j+1}, k \left( I - K_{j}h_{j} \right)^{T}$$

$$= \left( I - K_{j}h_{j} \right) p^{(j)} \left( I - K_{j}h_{j} \right)^{T}$$

-> on extra (I-Kjhj) factor cause P(3+1) to be too small.

(56)

Note: the correct 
$$P^{(j+1)} = (I - K_j h_j) P^{(j)}$$

$$= (I - K_j h_j) P^{(j)} (I - K_j h_j)^T + K_j R_{jj} K_j^T$$

To reconcile, add a "square root modification" factor of for the Kj in update egns for x'

(3) becomes for 
$$k=1,2,...,N$$

$$X'_{(j+1),k} = (I - \phi K_j h_j) X'_{(j),k}$$
 (4)

So that 
$$p^{(j+1)} = (I - \phi K_j h_j) p^{(j)} (I - \phi K_j h_j)^T = (I - K_j h_j) p^{(j)}$$
(5)

Solve for 
$$\phi$$
:

(5) =  $p^{(5)} - \phi K_j h_j p^{(j)} - \phi p^{(j)} h_j^T K_j^T + \phi^2 K_j h_j p^{(j)} h_j^T K_j^T$ 

can show that 
$$P^{(j)}h_{j}^{T}K_{j}^{T} = K_{j}h_{j}P^{(j)}$$

$$K_{j}(h_{j}P^{(j)}h_{j}^{T} + R_{jj})K_{j}^{T} = P^{(j)}h_{j}^{T}K_{j}^{T}$$

$$= K_{j}h_{j}P^{(j)}$$

$$= K_{j}h_{j}P^{(j)}$$

$$= K_{j}(h_{j}P^{(j)}h_{j}^{T} + R_{jj}) = P^{(j)}h_{j}^{T}$$
(7)

symmetric matrices

$$(5) = \rho^{(j)} - 2\phi K_{j}h_{j} p^{(j)} + \phi^{2}K_{j} h_{j} p^{(j)}h_{j}^{T} K_{j}^{T}$$

$$(6) = p^{(j)} - K_{j}h_{j} p^{(j)}$$

$$\phi^{2}K_{j} h_{j} p^{(j)}h_{j}^{T} K_{j}^{T} - (2\phi - 1) K_{j}h_{j} p^{(j)} = 0$$

use (7): 
$$K_{j}\left(\phi^{2}h_{j}P^{(j)}h_{j}^{T}\right)K_{j}^{T}-(2\phi-1)\underbrace{K_{j}\left(h_{j}P^{(j)}h_{j}^{T}+K_{jj}\right)K_{j}^{T}}_{Scalar}=0$$

$$\phi^{2}h_{j}P^{(j)}h_{j}^{T}-(2\phi-1)\underbrace{\left(h_{j}P^{(j)}h_{j}^{T}+K_{jj}\right)}_{Scalar}=0$$

$$h_{j}P^{(j)}h_{j}^{T}+K_{jj}$$

$$\phi^{2}-2\phi+1=0$$

$$\phi^{2}-\frac{1}{a}\phi+\frac{1}{a^{2}}-\frac{1}{a^{2}}+\frac{1}{a}\phi=0$$

$$\left(\phi-\frac{1}{a}\right)^{2}=\frac{1}{a^{2}}-\frac{1}{a}=\frac{1-a}{a^{2}}$$

$$\phi=\frac{1}{a}\pm\frac{\sqrt{1-a}}{a}$$

$$choose solution within  $(0,1): \phi=\frac{1-\sqrt{1-a}}{a}=\frac{1}{1+\sqrt{1-a}}$$$

$$\phi = \left(1 + \sqrt{\frac{R_{jj}}{h_{j}\rho^{gj}h_{j}^{T} + R_{jj}}}\right)^{-1}$$

Note: 
$$R_{jj} = var(y_j^e)$$
  
 $h_j P^{(j)} h_j^T = var(y_{(j)})$   
 $\phi$  is calculated for each observation  $(j)$ .