

Data Poisoning against Differentially-Private Learners: Attacks and Defenses

Blinded for Review

Abstract

Data poisoning attacks aim to manipulate the model produced by a learning algorithm by adversarially modifying the training set. We consider *differential privacy* as a defensive measure against this type of attack. We show that such learners are resistant to data poisoning attacks when the adversary is only able to poison a small number of items. However, this protection degrades as the adversary poisons more data. To illustrate, we design attack algorithms targeting *objective* and *output perturbation* learners, two standard approaches to differentially-private machine learning. Experiments show that our methods are effective when the attacker is allowed to poison sufficiently many training items.

1 Introduction

As machine learning is increasingly used for consequential decisions in the real world, the security concerns have received more and more scrutiny. Most machine learning systems were originally designed without much thought to security, but researchers have since identified several kinds of attacks under the umbrella of *adversarial machine learning*. The most well-known example is *adversarial examples* [Szegedy *et al.*, 2013], where inputs are crafted to fool classifiers. More subtle methods aim to recover training examples [Fredrikson *et al.*, 2015], or even extract the model itself [Tramèr *et al.*, 2016].

In *data poisoning* attacks [Biggio *et al.*, 2012; Koh *et al.*, 2018; Mei and Zhu, 2015; Alfeld *et al.*, 2016; Li *et al.*, 2016; Xiao *et al.*, 2015; Muñoz-González *et al.*, 2017], the adversary corrupts examples at training time to manipulate the learned model. As is generally the case in adversarial machine learning, the rise of data poisoning attacks has outpaced the development of robust defenses. While attacks are often evaluated against specific target learning procedures, effective defenses should provide protection—ideally guaranteed—against a broad class of attacks. In this paper, we study *differential privacy* [Dwork *et al.*, 2006; Dwork, 2011] as a general defensive technique against data poisoning. While differential privacy was originally designed to formalize privacy—the output should not depend too much on any single individual’s private data—it also provides a

defense against data poisoning. Concretely, we establish quantitative bounds on how much an adversary can change the distribution over learned models by manipulating a fixed number of training items. We are not the first to design defenses to data poisoning [Steinhardt *et al.*, 2017; Raghunathan *et al.*, 2018; Alfeld *et al.*, 2017], but our proposal has several notable strengths compared to previous work. First, our defense provides provable protection against a worst-case adversary. Second, our defense is general. Differentially-private learning procedures are known for a wide variety of tasks, and new algorithms are continually being proposed. These learners are all resilient against data poisoning.

We complement our theoretical bounds with an empirical evaluation of data poisoning attacks on differentially private learners. Concretely, we design an attack based on stochastic gradient descent to search for effective training examples to corrupt against specific learning algorithms. We evaluate attack on two private learners: objective perturbation [Kifer *et al.*, 2012] and output perturbation [Chaudhuri *et al.*, 2011]. Our evaluation confirms the theoretical prediction that private learners are vulnerable to data poisoning attacks when the adversary can poison sufficiently many examples. A gap remains between performance of attack and theoretical limit of data poisoning attacks—it seems like differential privacy provides a stronger defense than predicted by theory. We discuss possible causes and leave further investigation to future work.

2 Preliminaries

Differential Privacy. Let the data space be $\mathcal{Z} = \mathcal{X} \times \mathcal{Y}$, where \mathcal{X} is the feature space and \mathcal{Y} is the label space. We write $\mathcal{D} = \cup_{n=0}^{\infty} \mathcal{Z}^n$ for the space of all training sets, and write $D \in \mathcal{D}$ for a particular training set. A randomized learner $\mathcal{M} : \mathcal{D} \times \mathbb{R}^d \mapsto \Theta$ maps a training set D and noise $b \in \mathbb{R}^d$ drawn from a distribution ν to a model in the model space Θ .

Definition 1. (*Differential Privacy*) \mathcal{M} is (ϵ, δ) -differentially-private if $\forall D, \tilde{D} \in \mathcal{D}$ that differ by one item, and $\forall S \subset \Theta$,

$$\mathbf{P}(\mathcal{M}(D, b) \in S) \leq e^\epsilon \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in S) + \delta, \quad (1)$$

where the probability is taken over $b \sim \nu$. When $\delta = 0$, we say that \mathcal{M} is ϵ -differentially private.

Many standard machine learning tasks can be phrased as optimization problems modeling empirical risk minimization (ERM). Broadly speaking, there are two families of

techniques in the privacy literature for solving these problems. Objective perturbation injects noise into the objective function of a vanilla machine learner to train a randomized model [Chaudhuri *et al.*, 2011; Kifer *et al.*, 2012; Nozari *et al.*, 2016]. In contrast, output perturbation runs the vanilla learner but after training, it randomly perturbs the output model [Chaudhuri *et al.*, 2011]. We will consider data poisoning attacks against both kinds of learners.

Threat Model. We first fix the adversarial attack setting.

Knowledge of the attacker: The attacker has full knowledge of the full training set D and the differentially-private machine learner \mathcal{M} , including the noise distribution ν . However, the attacker does not know the realization of b .

Ability of the attacker: The attacker is able to modify the clean training set D by changing the features or labels, adding additional items, or deleting existing items. Nevertheless, we limit the attacker to modify at most k items. Formally, the poisoned training set \tilde{D} must lie in the ball $\mathcal{B}(D, k) \subset \mathcal{D}$, where the center is the clean data D and the radius k is the maximum number of item changes.

Goal of the attacker: the attacker aims to force the (stochastic) model learned from the poisoned data $\tilde{\theta} = \mathcal{M}(\tilde{D}, b)$ to achieve certain nefarious target. Formally, we define a cost function $C : \Theta \mapsto \mathbb{R}$ that measures how much the poisoned model $\tilde{\theta}$ deviates from the attack target. Then the attack problem can be formulated as minimizing an objective function J :

$$\min_{\tilde{D} \in \mathcal{B}(D, k)} J(\tilde{D}) := \mathbf{E}_b \left[C(\mathcal{M}(\tilde{D}, b)) \right]. \quad (2)$$

This formulation differs from previous works (e.g. [Biggio *et al.*, 2012; Mei and Zhu, 2015; Xiao *et al.*, 2015]) because the differentially-private learner produces a stochastic model, so the objective takes the expected value of C .

Example 1. (Parameter-Targeting Attack) If the attacker wants the output model to be close to a target model θ' , the attacker can define $C(\tilde{\theta}) = \frac{1}{2} \|\tilde{\theta} - \theta'\|^2$, a non-negative function. Minimizing $J(\tilde{D})$ pushes the poisoned model close to θ' in expectation.

Example 2. (Label-Targeting Attack) If the attacker wants small prediction losses on an evaluation set $\{z_i^*\}_{i \in [m]}$, the attacker can define $C(\tilde{\theta}) = \frac{1}{m} \sum_{i=1}^m \ell(\tilde{\theta}, z_i^*)$ where $\ell(\tilde{\theta}, z_i^*)$ is the loss on item $z_i^* = (x_i^*, y_i^*)$. Minimizing $J(\tilde{D})$ pushes the prediction on x_i^* towards the target label y_i^* .

Example 3. (Label-Aversion Attack) If the attacker wants to induce large prediction error on an evaluation set $\{z_i^*\}_{i \in [m]}$, the attacker can define $C(\tilde{\theta}) = -\frac{1}{m} \sum_{i=1}^m \ell(\tilde{\theta}, z_i^*)$, a non-positive cost. Minimizing $J(\tilde{D})$ pushes the prediction on x_i^* away from the true label y_i^* .

Now, we turn to our two main contributions. *i)* We show that differentially-private learners have *some* natural immunity against data poisoning attacks. Specifically, in section 3 we present a lower bound on how much the attacker can reduce $J(\tilde{D})$ under a fixed k (the number of changes). *ii)* When k increases, the attacker's power grows and it becomes possible to attack differentially-private learners. In section 4 we propose a stochastic gradient descent algorithm to solve the attack

optimization problem (2). To our knowledge, ours is the first data poisoning attack targeting differentially-private learners.

3 Differential Privacy Resists Data Poisoning

Fixing the number of poisoned items k and a differentially private learner, can a powerful attacker achieve arbitrarily low attack cost $J(\tilde{D})$? We show that the answer is no: differential privacy implies a lower bound on how far $J(\tilde{D})$ can be reduced, so private learners are inherently resistant to data poisoning attacks. Previous work [Lecuyer *et al.*, 2018] proposed defenses based on differential privacy, but for test-time attacks. While effective, these defenses require the classifier to make randomized predictions. In contrast, our defense against data poisoning only requires the *learning algorithm*, not the classification process, to be randomized.

Our first result is for ϵ -differentially private learners: if an attacker can manipulate at most k items in the clean data, then the attack cost is lower bounded. All proofs are given in the anonymized full paper at <https://anonymous.4open.science/repository/5ec6ab48-2ce8-433c-8fce-6d086517d7ca/>.

Theorem 1. Let \mathcal{M} be an ϵ -differentially-private learner. Let $J(\tilde{D})$ be the attack cost, where $\tilde{D} \in \mathcal{B}(D, k)$, then

$$\begin{aligned} J(\tilde{D}) &\geq e^{-k\epsilon} J(D) \quad (C \geq 0), \\ J(\tilde{D}) &\geq e^{k\epsilon} J(D) \quad (C \leq 0). \end{aligned} \quad (3)$$

Note that for $C \geq 0$, Theorem 1 shows that no attacker can achieve the trivial lower bound $J(\tilde{D}) = 0$. For $C \leq 0$, although $J(\tilde{D})$ could be unbounded from below, Theorem 1 shows that no attacker can reduce $J(\tilde{D})$ arbitrarily. These results crucially rely on the differential privacy property of \mathcal{M} . Corollary 2 re-states the theorem in terms of the minimum number of items an attacker has to modify to sufficiently reduce the attack cost $J(\tilde{D})$.

Corollary 2. Let \mathcal{M} be an ϵ -differentially-private learner. Assume $J(D) \neq 0$. Let $\tau \geq 1$. Then the attacker has to modify at least $k \geq \lceil \frac{1}{\epsilon} \log \tau \rceil$ items in D in order to achieve

$$\begin{aligned} i). \quad J(\tilde{D}) &\leq \frac{1}{\tau} J(D) \quad (C \geq 0). \\ ii). \quad J(\tilde{D}) &\leq \tau J(D) \quad (C \leq 0). \end{aligned}$$

To generalize Theorem 1 to (ϵ, δ) -private learners, we need an additional assumption that C is bounded.

Theorem 3. Let \mathcal{M} be (ϵ, δ) -differentially-private and $J(\tilde{D})$ be the attack cost, where $|C| \leq \bar{C}$ and $\tilde{D} \in \mathcal{B}(D, k)$. Then,

$$\begin{aligned} J(\tilde{D}) &\geq \max \left\{ e^{-k\epsilon} \left(J(D) + \frac{\bar{C}\delta}{e^\epsilon - 1} \right) - \frac{\bar{C}\delta}{e^\epsilon - 1}, 0 \right\} \quad (C \geq 0), \\ J(\tilde{D}) &\geq \max \left\{ e^{k\epsilon} \left(J(D) - \frac{\bar{C}\delta}{e^\epsilon - 1} \right) + \frac{\bar{C}\delta}{e^\epsilon - 1}, -\bar{C} \right\} \quad (C \leq 0). \end{aligned} \quad (4)$$

As a corollary, we can lower-bound the minimum number of modifications needed to sufficiently reduce attack cost.

Corollary 4. Let \mathcal{M} be an (ϵ, δ) -differentially-private learner. Assume $J(D) \neq 0$. Then

- i). ($C \geq 0$): in order to achieve $J(\tilde{D}) \leq \frac{1}{\tau} J(D)$ for $\tau \geq 1$, the attacker has to modify at least the following number of items in D .

$$k \geq \left\lceil \frac{1}{\epsilon} \log \frac{(e^\epsilon - 1)J(D)\tau + \bar{C}\delta\tau}{(e^\epsilon - 1)J(D) + \bar{C}\delta\tau} \right\rceil. \quad (5)$$

- ii). ($C \leq 0$): in order to achieve $J(\tilde{D}) \leq \tau J(D)$ for $\tau \in [1, -\frac{\bar{C}}{J(D)}]$, the attacker has to modify at least the following number of items in D .

$$k \geq \left\lceil \frac{1}{\epsilon} \log \frac{(e^\epsilon - 1)J(D)\tau - \bar{C}\delta}{(e^\epsilon - 1)J(D) - \bar{C}\delta} \right\rceil. \quad (6)$$

Note that in (5), the lower bound on k is always finite even if $\tau = \infty$, which means an attacker might be able to reduce the attack cost $J(\tilde{D})$ to 0. This is in contrast to ϵ -differentially-private learner, where $J(\tilde{D}) = 0$ can never be achieved. The weaker (ϵ, δ) -differential privacy guarantee gives weaker protection against attacks.

4 Data Poisoning Attacks on Private Learners

The results in the previous section provide a theoretical bound on how effective a data poisoning attack can be against a private learner. To evaluate how strong the protection is in practice, we propose a range of attacks targeting general differentially-private learners. Our adversary will *modify* (not add or delete) any continuous features (for classification or regression) and the continuous labels (for regression) on at most k items in the training set. Restating the attack problem (2):

$$\min_{\tilde{D} \subset \mathcal{B}(D, k)} J(\tilde{D}) = \mathbf{E}_b \left[C(\mathcal{M}(\tilde{D}, b)) \right] \quad (7)$$

This is a combinatorial problem—the attacker must pick k items to modify. We propose a two-step attack procedure.

step I) use heuristic methods to select k items to poison.

step II) apply stochastic gradient descent to reduce $J(\tilde{D})$.

Step II) could lead to poisoned items taking arbitrary features or labels. However, differentially-private learners typically assume training examples are bounded. To avoid trivially-detectable poisoned examples, we project poisoned features and labels back to a bounded space after each iteration of SGD. We now detail step II), assuming that the attacker has fixed k items to poison. We'll return to step I) later.

4.1 SGD on Differentially-Private Victims (DPV)

Our attacker uses stochastic gradient descent to minimize the cost $J(\tilde{D})$. We first show how to compute a stochastic gradient with respect to a training item.

Proposition 5. Assume $\mathcal{M}(\tilde{D}, b)$ is a differentiable function of \tilde{D} , then a stochastic gradient of $J(\tilde{D})$ w.r.t. a particular item \tilde{z}_i is $\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i}$, where $b \sim \nu(b)$.

The concrete form of the stochastic gradient depends on the target private learner \mathcal{M} . In the following, we derive the stochastic gradient for objective perturbation and output perturbation in the context of parameter-targeting attack with cost $C(\tilde{\theta}) = \frac{1}{2} \|\tilde{\theta} - \theta'\|^2$.

4.1.1 Instantiating Attack on Objective Perturbation

We first consider objective-perturbed private learners:

$$\mathcal{M}(\tilde{D}, b) = \operatorname{argmin}_{\theta \in \Theta} \sum_{i=1}^n \ell(\theta, \tilde{z}_i) + \lambda \Omega(\theta) + b^\top \theta, \quad (8)$$

where ℓ is some convex learning loss, Ω is a regularization, and Θ is the model space. Note that the noise b enters the objective via linear product with the model θ . By Proposition 5, the stochastic gradient is $\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i} = \frac{\partial C(\tilde{\theta})}{\partial \tilde{z}_i}$, where $\tilde{\theta} = \mathcal{M}(\tilde{D}, b)$ is the poisoned model. By the chain rule, we have

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{z}_i} = \left(\frac{\partial \tilde{\theta}}{\partial \tilde{z}_i} \right)^\top \frac{dC(\tilde{\theta})}{d\tilde{\theta}}. \quad (9)$$

Note that $\frac{dC(\tilde{\theta})}{d\tilde{\theta}} = \tilde{\theta} - \theta'$. Next we focus on deriving $\frac{\partial \tilde{\theta}}{\partial \tilde{z}_i}$. Since (8) is convex, the learned model $\tilde{\theta}$ must satisfy the following Karush-Kuhn-Tucker (KKT) condition:

$$f(\tilde{\theta}, \tilde{z}_i) := \sum_{j=1}^n \frac{\partial \ell(\tilde{\theta}, \tilde{z}_j)}{\partial \tilde{\theta}} + \lambda \frac{d\Omega(\tilde{\theta})}{d\tilde{\theta}} + b = 0. \quad (10)$$

By using the derivative of implicit function, we have $\frac{\partial \tilde{\theta}}{\partial \tilde{z}_i} = -\left(\frac{\partial f}{\partial \tilde{\theta}}\right)^{-1} \frac{\partial f}{\partial \tilde{z}_i}$. We now give two examples where the base learner is logistic regression and ridge regression, respectively.

Attacking Objective-Perturbed Logistic Regression. In the case $\ell(\theta, \tilde{z}) = \log(1 + \exp(-\tilde{y}\theta^\top \tilde{x}))$ and $\Omega(\theta) = \frac{1}{2} \|\theta\|^2$, learner (8) is objective-perturbed logistic regression:

$$\mathcal{M}(\tilde{D}, b) = \operatorname{argmin}_{\theta \in \Theta} \sum_{i=1}^n \log(1 + \exp(-\tilde{y}_i \theta^\top \tilde{x}_i)) + \frac{\lambda}{2} \|\theta\|^2 + b^\top \theta, \quad (11)$$

where $\Theta = \mathbb{R}^d$. Our attacker will only modify the features, thus $\tilde{y}_i = y_i$. We now derive stochastic gradient for \tilde{x}_i . Define $s_j = \exp(y_j \tilde{\theta}^\top \tilde{x}_j)$. By (9), one can verify that $\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} =$

$$\left(\frac{y_i}{1 + s_i} I - \frac{s_i \tilde{\theta} \tilde{x}_i^\top}{(1 + s_i)^2} \right) \left(\lambda I + \sum_{j=1}^n \frac{s_j \tilde{x}_j \tilde{x}_j^\top}{(1 + s_j)^2} \right)^{-1} (\tilde{\theta} - \theta').$$

The detailed derivation is in Appendix F. Note that the noise b enters into stochastic gradient through $\tilde{\theta} = \mathcal{M}(\tilde{D}, b)$.

Attacking Objective-Perturbed Ridge Regression. In the case $\ell(\theta, \tilde{z}) = \frac{1}{2} (\tilde{y} - \tilde{x}^\top \theta)^2$ and $\Omega(\theta) = \frac{1}{2} \|\theta\|^2$, learner (8) is the objective-perturbed ridge regression:

$$\mathcal{M}(\tilde{D}, b) = \operatorname{argmin}_{\theta \in \Theta} \frac{1}{2} \|\tilde{X}\theta - \tilde{y}\|^2 + \frac{\lambda}{2} \|\theta\|^2 + b^\top \theta, \quad (12)$$

where $\Theta = \{\theta \in \mathbb{R}^d : \|\theta\|_2 \leq \rho\}$, $\tilde{X} \in \mathbb{R}^{n \times d}$ is the feature matrix, and $\tilde{y} \in \mathbb{R}^n$ is the label vector. Unlike logistic regression, the objective-perturbed ridge regression requires the model space to be bounded (see e.g. [Kifer *et al.*, 2012]). The attacker can modify both the features and the labels. By (9), the stochastic gradient of \tilde{x}_i is $\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} =$

$$\left(\tilde{\theta} \tilde{x}_i^\top + (\tilde{x}_i^\top \tilde{\theta} - \tilde{y}_i) I \right) \left(\tilde{X}^\top \tilde{X} + (\lambda + \mu) I \right)^{-1} (\theta' - \tilde{\theta}),$$

where μ is the dual variable of constraint $\frac{1}{2}\|\theta\|^2 \leq \frac{\rho^2}{2}$ when solving (12). The stochastic gradient of \tilde{y}_i is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{y}_i} = \tilde{x}_i^\top \left(\tilde{X}^\top \tilde{X} + (\lambda + \mu)I \right)^{-1} (\tilde{\theta} - \theta').$$

The detailed derivation is in Appendix G. Note that the noise b enters into the stochastic gradient through $\tilde{\theta} = \mathcal{M}(\tilde{D}, b)$.

4.1.2 Instantiating Attack on Output Perturbation

We now consider the output perturbation mechanism:

$$\mathcal{M}(\tilde{D}, b) = b + \operatorname{argmin}_{\theta \in \Theta} \left\{ \sum_{i=1}^n \ell(\theta, \tilde{z}_i) + \lambda \Omega(\theta) \right\}. \quad (13)$$

We present the derivations of stochastic gradient in Appendix H as they are similar to objective perturbation. Again, we instantiate on two examples where the base learner is logistic regression and ridge regression, respectively.

Attacking Output-Perturbed Logistic Regression. The output-perturbed logistic regression takes the following form:

$$\mathcal{M}(\tilde{D}, b) = b + \operatorname{argmin}_{\theta \in \mathbb{R}^d} \sum_{i=1}^n \log(1 + \exp(-\tilde{y}_i \theta^\top \tilde{x}_i)) + \frac{\lambda}{2} \|\theta\|^2, \quad (14)$$

Let $s_j = \exp(y_j(\tilde{\theta} - b)^\top \tilde{x}_j)$, then we have $\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} =$

$$\left(\frac{y_i}{1 + s_i} I - \frac{s_i(\tilde{\theta} - b)\tilde{x}_i^\top}{(1 + s_i)^2} \right) \left(\lambda I + \sum_{j=1}^n \frac{s_j \tilde{x}_j \tilde{x}_j^\top}{(1 + s_j)^2} \right)^{-1} (\tilde{\theta} - \theta').$$

Attacking Output-Perturbed Ridge Regression. The output-perturbed ridge regression takes the following form

$$\mathcal{M}(\tilde{D}, b) = b + \operatorname{argmin}_{\theta \in \Theta} \frac{1}{2} \|\tilde{X}\theta - \tilde{y}\|^2 + \frac{\lambda}{2} \|\theta\|^2, \quad (15)$$

where $\Theta = \{\theta : \|\theta\|_2 \leq \rho\}$. Let μ be the dual variable for the constraint $\frac{1}{2}\|\theta\|^2 \leq \frac{\rho^2}{2}$ when solving (15). Then the stochastic gradients of \tilde{x}_i and \tilde{y}_i are

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left((\tilde{\theta} - b)\tilde{x}_i^\top + \tilde{x}_i^\top (\tilde{\theta} - b)I - \tilde{y}_i I \right) \cdot \left(\tilde{X}^\top \tilde{X} + (\lambda + \mu)I \right)^{-1} (\theta' - \tilde{\theta}).$$

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{y}_i} = \tilde{x}_i^\top \left(\tilde{X}^\top \tilde{X} + (\lambda + \mu)I \right)^{-1} (\tilde{\theta} - \theta').$$

4.2 SGD on Surrogate Victims (SV)

We also consider an alternative, simpler way to perform step II). When $b = \mathbf{0}$, the differentially-private learning algorithms revert to the base learner which returns a deterministic model $\mathcal{M}(\tilde{D}, \mathbf{0})$. The adversary can simply attack the base learner (without b) as a surrogate for the differentially-private learner \mathcal{M} (with b) by solving the following problem:

$$\min_{\tilde{D}} C(\mathcal{M}(\tilde{D}, \mathbf{0})). \quad (16)$$

Since the objective is deterministic, we can work with its gradient rather than its stochastic gradient, plugging in $b = \mathbf{0}$ into all derivations in section 4.1. Note that the attack found by (16) will still be evaluated w.r.t. differentially-private learners in our experiments.

4.3 Selecting Items to Poison

Now, we return to step I) of our attack: how can we select the k items for poisoning? We give two heuristic methods: shallow and deep selection.

Shallow selection selects top- k items with the largest initial gradient norm $\|\frac{\partial J(\tilde{D})}{\partial \tilde{z}_i} \big|_{\tilde{D}=\tilde{D}}\|$. Intuitively, modifying these items will reduce the attack cost the most, at least initially. The precise gradients to use during selection depend on the attack in step II). When targeting differentially-private learners directly, computing the gradient of $J(\tilde{D})$ is difficult. We use Monte-Carlo sampling to approximate the gradient g_i of item z_i : $g_i \approx \frac{1}{m} \sum_{s=1}^m \frac{\partial}{\partial \tilde{z}_i} C(\mathcal{M}(\tilde{D}, b_s)) \big|_{\tilde{D}=\tilde{D}}$, where b_s are random samples of privacy parameters. Then, the attacker picks the k items with the largest $\|g_i\|$ to poison. When targeting surrogate victim, the objective is $C(\mathcal{M}(\tilde{D}, \mathbf{0}))$, thus the attacker computes the gradient of $C(\mathcal{M}(\tilde{D}, \mathbf{0}))$ of each clean item z_i : $g_i = \frac{d}{d\tilde{z}_i} C(\mathcal{M}(\tilde{D}, \mathbf{0})) \big|_{\tilde{D}=\tilde{D}}$, and then picks those k items with the largest $\|g_i\|$.

Deep selection selects items by estimating the influence of an item on the final attack cost. When targeting a differentially-private victim directly, the attacker first solves the following **relaxed attack** problem: $\min_{\tilde{D}} J(\tilde{D}) + \alpha R(\tilde{D})$. Importantly, here \tilde{D} allows changes to all training items, not just k of them. $R(\tilde{D})$ is a regularizer penalizing data modification with weight $\alpha > 0$. We take $R(\tilde{D}) = \sum_{i=1}^n r(\tilde{z}_i)$, where $r(\tilde{z}_i)$ is the distance between the poisoned item \tilde{z}_i and the clean item z_i . We define $r(\tilde{z}_i) = \frac{1}{2} \|\tilde{x}_i - x_i\|^2$ for logistic regression and $r(\tilde{z}_i) = \frac{1}{2} \|\tilde{x}_i - x_i\|^2 + \frac{1}{2} (\tilde{y}_i - y_i)^2$ for ridge regression. After solving the relaxed attack problem with SGD, the attacker evaluates the amount of change $r(\tilde{z}_i)$ for all training items and pick the top k to poison. When targeting a surrogate victim, the attacker can instead solve the following relaxed attack first: $\min_{\tilde{D}} C(\mathcal{M}(\tilde{D}, \mathbf{0})) + \alpha R(\tilde{D})$, and then select k top items.

In summary, we have four attack algorithms based on combinations of methods used in step I) and step II): shallow-SV, shallow-DPV, deep-SV and deep-DPV. In the following, we evaluate the performance of these four algorithms.

5 Experiments

We now evaluate our attack with experiments, taking objective-perturbed learners [Kifer *et al.*, 2012] and output-perturbed learners [Chaudhuri *et al.*, 2011] as our victims. Through the experiment, we use $\alpha = 10^{-4}$ for deep selection, and fix a constant step size $\eta = 1$ for (stochastic) gradient descent. After each iteration of SGD, we project poisoned items to ensure the feature norm is at most 1, and the label is in $[-1, 1]$.

5.1 Attacks Intelligently Modify Data

As a first example, we use label-aversion attack to illustrate that our attack leads to desired data modification. The victim is an objective-perturbed learner for ϵ -differentially private logistic regression, with $\epsilon = 0.1$ and regularizer $\lambda = 10$. The training set contains $n = 21$ items uniformly sampled in the interval $[-1, 1]$ with labels $y_i = \mathbb{1}[x_i \geq 0]$, see Figure 1(a). To generate the evaluation set, we construct $m = 21$ evenly-spaced items in the interval $[-1, 1]$, i.e., $x_i^* = 0.1i, -10 \leq$

$i \leq 10$ and labeled as $y_i^* = \mathbb{1}[x_i^* \geq 0]$. The cost function is defined as $C(\theta) = -\frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i^* x_i^{*\top} \theta))$. To achieve small attack cost J , a negative model $\theta < 0$ is desired.¹ We run deep-DPV with $k = n$ (attacker can modify all items) for $T = 300$ iterations. In Figure 1(a), we show the position of the poisoned items on the vertical axis as the SGD iteration, t , grows. As expected, the attacker flips the positions of positive (blue) items and negative (red) items. As a result, our attack causes the learner to find a model with $\tilde{\theta} < 0$.

5.2 Attacks Can Achieve Different Goals

We now study a 2D example to show that our attack is effective for different attack goals. The victim is the same as in section 5.1. The clean training set in Figure 1(b) contains $n = 317$ items uniformly sampled in a unit sphere with labels $y_i = \mathbb{1}[x_i^\top \theta^* \geq 0]$ where $\theta^* = (1, 1)$. We now describe the attack settings for different attack goals.

Label-aversion attack. We generate an evaluation set containing $m = 317$ grid points (x_i^*, y_i^*) lying in a unit sphere and labeled by a vertical decision boundary, see Figure 1(c). The cost function is $C(\theta) = -\frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i^* x_i^{*\top} \theta))$.

Label-targeting attack. The evaluation set remains the same as in the label-aversion attack. The cost function is $C(\theta) = \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i^* x_i^{*\top} \theta))$.

Parameter-targeting attack. We first train vanilla logistic regression on the evaluation set to obtain the target model $\theta' = (2.6, 0)$, then define cost function as $C(\theta) = \frac{1}{2} \|\theta - \theta'\|^2$.

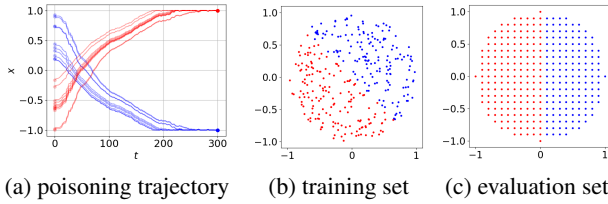


Figure 1: (a) 1D example (b, c) 2D example

We run deep-DPV with $k = n$ for $T = 5 \times 10^3$ iterations. In Figure 2(a)-(c), we show the poisoning trajectories for the three attack goals respectively. Each translucent point is an original training point, and the connected solid point is its final position after attack. The curve connecting them shows the trajectory as the attack algorithm gradually poisons the data.

In label-aversion attack the attacker aims to maximize the logistic loss on the evaluation set. It ends up moving positive (negative) items to the left (right), so that the poisoned data deviates from the evaluation set.

In contrast, the label-targeting attack tries to minimize the logistic loss, thus items are moved to produce a poisoned data aligned with the evaluation set. However, the attack does not produce exactly the evaluation set. To understand that, we compute the model learnt by vanilla logistic regression on the evaluation set and the poisoned data, which are $(2.60, 0)$

¹Differentially-private machine learning typically considers homogeneous learners, thus the 1D model is just a scalar.

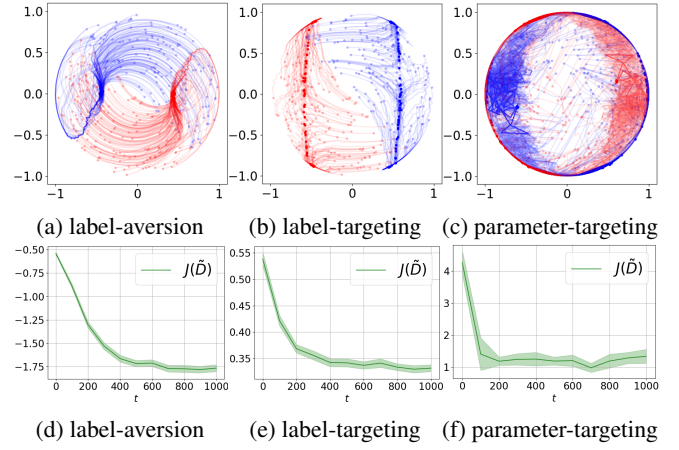


Figure 2: poisoning trajectories in 2D.

and $(2.94, 0.01)$. Note that both models are aligned with the evaluation set, but the latter has larger norm, which leads to smaller attack cost, thus our result is a better attack.

In parameter-targeting attack, we compute the model learnt by vanilla logistic regression on the clean data and poisoned data, which are $(1.86, 1.85)$ and $(2.21, 0.04)$. Note that the attack pushes the model closer to the target model $(2.6, 0)$.

To quantify the attack performance, we evaluate the attack cost $J(\tilde{D})$ via Monte-Carlo sampling. We run private learners $T_e = 10^3$ times, each time with a random b_s to produce a cost $C_s = C(\mathcal{M}(\tilde{D}, b_s))$. Then we average to obtain an estimate of the cost $J(\tilde{D}) \approx \frac{1}{T_e} \sum_{s=1}^{T_e} C_s$. In Figure 2(d)-(f), we show the attack cost $J(\tilde{D})$ and its 95% confidence interval (green, $\pm 2 \cdot \text{stderr}$) up to $t = 10^3$ iterations. $J(\tilde{D})$ decreases in all plots, showing that our attack is effective for all attack goals.

5.3 Attacks Become More Effective as k Increases

The theoretical protection provided by differential privacy weakens as the adversary is allowed to poison more training items. In this section, we show that our attacks indeed become more effective as the number of poisoned items k increases. The data set is the same as in section 5.2. We consider k from 20 to 100 in steps of 20. For each k , we run our four attack algorithms for $T = 5 \times 10^3$ iterations and estimate the attack cost $J(\tilde{D})$ on $T_e = 2 \times 10^3$ samples. Figure 3(a)-(c) show that the attack cost $J(\tilde{D})$ decreases as k grows, indicating better attack performance. We also show the poisoning trajectory produced by deep-DPV with $k = 10$ in Figure 3(d)-(f). The corresponding attack costs $J(\tilde{D})$ are $-0.60, 0.49$ and 3.43 respectively. Compared to that of $k = n$, $-1.79, 0.32$ and 1.20 , we see that poisoning only 10 items is not enough to reduce the attack cost $J(\tilde{D})$ significantly, although the attacker is making effective modification.

5.4 Attacks Effective on Both Privacy Mechanisms

We now show experiments on real data to illustrate that our attacks are effective on both objective and output perturbation mechanisms. We focus on label-targeting attack.

The first real data set is vertebral column from the UCI Machine Learning Repository [Dua and Karra Taniskidou, 2017].

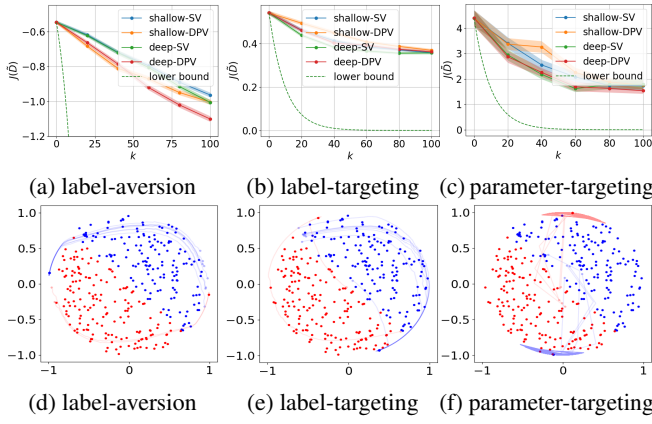


Figure 3: (a-c) The attack cost $J(\tilde{D})$ decreases as k grows. (d-f) The sparse attack trajectories for $k = 10$

This data set contains 6 features of 310 orthopaedic patients, and the task is to predict if the vertebra of any patient is abnormal (positive class) or not (negative class). We normalize the features so that the norm of any item is at most 1. Since this is a classification task, we use logistic regression as the victim. To generate the evaluation set $\{(x_i^*, y_i^*)\}$, we randomly pick one positive item and find its 10 nearest neighbours within the positive class, and set $y_i^* = -1$ for all 10. Intuitively, this attack targets a small cluster of abnormal patients and the goal is to mislead the learner to classify these patients as normal. The other experimental parameters remain the same as in section 5.2. Note that in order to push the prediction on x_i^* toward y_i^* , the attacker requires $y_i^* x_i^{*\top} \tilde{\theta} > 0$, which indicates $C(\tilde{\theta}) = \log(1 + \exp(-y_i^* x_i^{*\top} \tilde{\theta})) < \log 2 \approx 0.69$, so should $J(\tilde{D})$. As shown in Figure 4, the attacker indeed reduces the attack cost $J(\tilde{D})$ below 0.69 for both privacy mechanisms, thus our attack is successful.

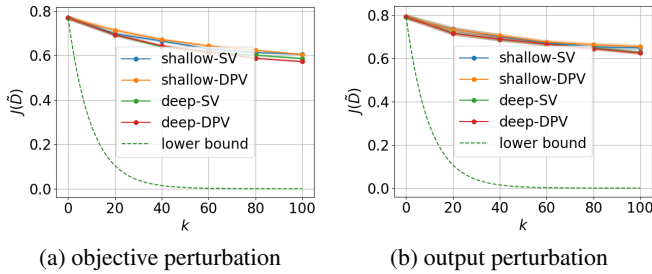


Figure 4: attack on objective and output-perturbed logistic regression.

The second data set is red wine quality from UCI. The data set contains 11 features of 1598 wine samples, and the task is predict the wine quality, a number between 0 and 10. We normalize the features so that the norm of any item is at most 1. Labels are also normalized to ensure the value is in $[-1, 1]$. The victim is private ridge regression with $\epsilon = 0.1$, regularizer $\lambda = 20$, and bound on model space $\rho = 1$. To generate the evaluation set, we pick one item x_i^* with the smallest quality value, and then set the target label to be $y_i^* = 1$. The cost function is defined as $C(\tilde{\theta}) = \frac{1}{2}(x_i^{*\top} \tilde{\theta} - y_i^*)^2$. The other parameters of attack remain the same as in section 5.2. This

attack aims to force the learner to predict a low-quality wine as having a high quality. Figure 5 shows the results on objective perturbation and output perturbation respectively. Note that the attack cost can be effectively reduced even if the attacker only poisons $100/1598 \approx 6.3\%$ of the whole data set.

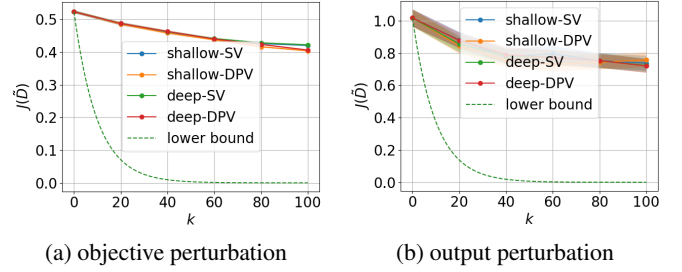


Figure 5: attack on objective and output-perturbed ridge regression.

Given experimental results in all previous sections, we make another two observations here. First, deep-DPV is in general the most effective attack among all four attack methods. Second, while being effective, there remains a gap between the performance of deep-DPV and the theoretical lower bound, leaving space to design more effective attacks or to tighten the lower bound.

5.5 Attack Is Easier with Weaker Privacy

Finally, we show that the attack is more effective as the privacy guarantee becomes weaker, i.e., as we increase ϵ . To illustrate, we run experiments on the data set in section 5.2, where we fix $k = 100$ and vary ϵ from 0.1 to 0.5. In Figure 6, we show the attack cost $J(\tilde{D})$ against ϵ . Note that the attack cost $J(\tilde{D})$ approaches the lower bound as ϵ grows. This means weaker privacy guarantee (smaller ϵ) leads to easier attacks.

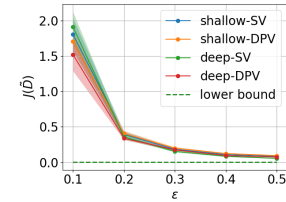


Figure 6: Attacker can reduce cost $J(\tilde{D})$ more as ϵ grows.

6 Conclusion and Future Work

We showed that differentially private learners are provably resistant to data poisoning attacks, with the protection degrading exponentially as the attacker poisons more items. Then, we proposed attacks that can effectively poison private learners, and demonstrated the attack performance on a variety of privacy mechanisms and learners with both synthetic and real data. While the attacks are effective, there remains a gap between the theoretical lower bound and the empirical performance of our attacks. This could be because the lower bound is loose, or our attack is not effective enough; closing the gap remains future work. Taken together, our study is a first step towards understanding the strengths and weaknesses of differential privacy as a defensive measure against data poisoning.

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Appendices

A Proof of Theorem 1

Theorem 1. Let \mathcal{M} be an ϵ -differentially-private learner. Let $J(\tilde{D})$ be the attack cost, where $\tilde{D} \in \mathcal{B}(D, k)$, then

$$\begin{aligned} J(\tilde{D}) &\geq e^{-k\epsilon} J(D) \quad (C \geq 0), \\ J(\tilde{D}) &\geq e^{k\epsilon} J(D) \quad (C \leq 0). \end{aligned} \quad (3)$$

Proof. For any poisoned data $\tilde{D} \in \mathcal{B}(D, k)$, one can view it as being produced by manipulating the clean data D k times, where each time one item is changed. Thus one can apply Lemma 6 k times to obtain (3). \square

Lemma 6. Let \mathcal{M} be an ϵ -differentially-private learner. Let $J(\tilde{D})$ be the attack cost, where $\tilde{D} \in \mathcal{B}(D, 1)$, then

$$\begin{aligned} J(\tilde{D}) &\geq e^{-\epsilon} J(D), \quad (C \geq 0), \\ J(\tilde{D}) &\geq e^{\epsilon} J(D), \quad (C \leq 0). \end{aligned} \quad (17)$$

Proof. We first consider $C \geq 0$. Define $\Theta(a) = \{\theta : C(\theta) > a\}$, $\forall a \geq 0$. Since $\tilde{D} \in \mathcal{B}(D, 1)$, \tilde{D} and D differ by at most one item, thus differential privacy guarantees that $\forall a \geq 0$,

$$\mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) \leq e^{\epsilon} \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)). \quad (18)$$

Since $J(D)$ is non-negative, by the integral identity, we have

$$\begin{aligned} J(D) &= \mathbf{E}_b [C(\mathcal{M}(D, b))] = \int_0^\infty \mathbf{P}(C(\mathcal{M}(D, b)) > a) da \\ L &= \int_0^\infty \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) da \\ &\leq \int_0^\infty e^{\epsilon} \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) da \\ &= e^{\epsilon} \int_0^\infty \mathbf{P}(C(\mathcal{M}(\tilde{D}, b)) > a) da \\ &= e^{\epsilon} J(\tilde{D}). \end{aligned} \quad (19)$$

Thus $J(\tilde{D}) \geq e^{-\epsilon} J(D)$. Next we consider $C \leq 0$. Define $\Theta(a) = \{\theta : C(\theta) < a\}$, $\forall a \leq 0$. Again due to \mathcal{M} being differentially private,

$$\mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) \leq e^{\epsilon} \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)). \quad (20)$$

Since $J(\tilde{D})$ is non-positive, by the integral identity, we have

$$\begin{aligned} J(\tilde{D}) &= \mathbf{E}_b [C(\mathcal{M}(\tilde{D}, b))] \\ &= - \int_{-\infty}^0 \mathbf{P}(C(\mathcal{M}(\tilde{D}, b)) < a) da \\ &= - \int_{-\infty}^0 \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) da \\ &\geq - \int_{-\infty}^0 e^{\epsilon} \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) da \\ &= - \int_{-\infty}^0 e^{\epsilon} \mathbf{P}(C(\mathcal{M}(D, b)) < a) da \\ &= e^{\epsilon} J(D). \end{aligned} \quad (21)$$

\square

B Proof for Corollary 2

Corollary 2. Let \mathcal{M} be an ϵ -differentially-private learner. Assume $J(D) \neq 0$. Let $\tau \geq 1$. Then the attacker has to modify at least $k \geq \lceil \frac{1}{\epsilon} \log \tau \rceil$ items in D in order to achieve

$$\begin{aligned} i). \quad J(\tilde{D}) &\leq \frac{1}{\tau} J(D) \quad (C \geq 0). \\ ii). \quad J(\tilde{D}) &\leq \tau J(D) \quad (C \leq 0). \end{aligned}$$

Proof. For $C \geq 0$, by Theorem 1, if $\tilde{D} \in \mathcal{B}(D, k)$ then $J(\tilde{D}) \geq e^{-k\epsilon} J(D)$. Since we require $J(\tilde{D}) \leq \frac{1}{\tau} J(D)$, we have $e^{-k\epsilon} J(D) \leq \frac{1}{\tau} J(D)$, thus $k \geq \lceil \frac{1}{\epsilon} \log \tau \rceil$. Similarly, one can prove the case for $C \leq 0$. \square

C Proof for Theorem 3

Theorem 3. Let \mathcal{M} be (ϵ, δ) -differentially-private and $J(\tilde{D})$ be the attack cost, where $|\tilde{C}| \leq \bar{C}$ and $\tilde{D} \in \mathcal{B}(D, k)$. Then,

$$\begin{aligned} J(\tilde{D}) &\geq \max\{e^{-k\epsilon}(J(D) + \frac{\bar{C}\delta}{e^{\epsilon}-1}) - \frac{\bar{C}\delta}{e^{\epsilon}-1}, 0\} \quad (C \geq 0), \\ J(\tilde{D}) &\geq \max\{e^{k\epsilon}(J(D) - \frac{\bar{C}\delta}{e^{\epsilon}-1}) + \frac{\bar{C}\delta}{e^{\epsilon}-1}, -\bar{C}\} \quad (C \leq 0). \end{aligned} \quad (4)$$

Proof. We first consider $0 \leq C \leq \bar{C}$. For any poisoned data $\tilde{D} \in \mathcal{B}(D, k)$, one can view it as being produced by manipulating the clean data D k times, where each time one item is changed. Thus we have a sequence of intermediate \tilde{D}_i , $0 \leq i \leq k$, which is the data set where i items are modified. We define $\tilde{D}_0 = D$ and $\tilde{D}_k = \tilde{D}$. Let $J_i = J(\tilde{D}_i)$, then by Lemma 7

$$J_i \geq e^{-\epsilon}(J_{i-1} - \bar{C}\delta), \forall 1 \leq i \leq k. \quad (22)$$

Adding $\frac{\bar{C}\delta}{e^{\epsilon}-1}$ to both sides, we have

$$J_i + \frac{\bar{C}\delta}{e^{\epsilon}-1} \geq e^{-\epsilon}(J_{i-1} - \bar{C}\delta) + \frac{\bar{C}\delta}{e^{\epsilon}-1} = e^{-\epsilon}(J_{i-1} + \frac{\bar{C}\delta}{e^{\epsilon}-1}). \quad (23)$$

We then recursively apply (23) k times to obtain

$$J_k + \frac{\bar{C}\delta}{e^{\epsilon}-1} \geq e^{-k\epsilon}(J_0 + \frac{\bar{C}\delta}{e^{\epsilon}-1}) = e^{-k\epsilon}(J(D) + \frac{\bar{C}\delta}{e^{\epsilon}-1}). \quad (24)$$

Note $J_k = J(\tilde{D}_k) = J(\tilde{D})$, thus we have

$$J(\tilde{D}) \geq e^{-k\epsilon}(J(D) + \frac{\bar{C}\delta}{e^{\epsilon}-1}) - \frac{\bar{C}\delta}{e^{\epsilon}-1}. \quad (25)$$

Meanwhile $J(\tilde{D}) \geq 0$ automatically holds due to $C \geq 0$, thus our result holds.

Next, we consider $-\bar{C} \leq C \leq 0$. Define J_i as before, then by Lemma 7

$$J_i \geq e^{\epsilon} J_{i-1} - \bar{C}\delta. \quad (26)$$

Subtracting both sides by $\frac{\bar{C}\delta}{e^{\epsilon}-1}$ we have

$$J_i - \frac{\bar{C}\delta}{e^{\epsilon}-1} \geq e^{\epsilon}(J_{i-1} - \frac{\bar{C}\delta}{e^{\epsilon}-1}), \forall 1 \leq i \leq k. \quad (27)$$

Thus we have

$$J(\tilde{D}) - \frac{\bar{C}\delta}{e^{\epsilon}-1} \geq e^{-k\epsilon}(J(D) - \frac{\bar{C}\delta}{e^{\epsilon}-1}). \quad (28)$$

Combined with the natural lower bound $-\bar{C}$, we have

$$J(\tilde{D}) \geq \max\{e^{-k\epsilon}(J(D) - \frac{\bar{C}\delta}{e^\epsilon - 1}) + \frac{\bar{C}\delta}{e^\epsilon - 1}, -\bar{C}\}. \quad (29)$$

□

Lemma 7. Let \mathcal{M} be an (ϵ, δ) -differentially-private learner. Let $J(\tilde{D})$ be the attack cost, where $|C| \leq \bar{C}$ and $\tilde{D} \in \mathcal{B}(D, 1)$, then

$$\begin{aligned} J(\tilde{D}) &\geq e^{-\epsilon}(J(D) - \bar{C}\delta), \quad (C \geq 0), \\ J(\tilde{D}) &\geq e^\epsilon J(D) - \bar{C}\delta, \quad (C \leq 0). \end{aligned} \quad (30)$$

Proof. We first consider $0 \leq C \leq \bar{C}$. Define $\Theta(a) = \{\theta : C(\theta) > a\}$, $\forall a \geq 0$. Since $\tilde{D} \in \mathcal{B}(D, 1)$, \tilde{D} and D differ by at most one item, thus the differential privacy guarantees that $\forall a \geq 0$,

$$\mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) \leq e^\epsilon \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) + \delta. \quad (31)$$

Note that $J(D)$ is non-negative, thus by the integral identity, we have

$$\begin{aligned} J(D) &= \mathbf{E}_b[C(\mathcal{M}(D, b))] \\ &= \int_0^{\bar{C}} \mathbf{P}(C(\mathcal{M}(D, b)) > a) da \\ &= \int_0^{\bar{C}} \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) da \\ &\leq \int_0^{\bar{C}} [e^\epsilon \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) + \delta] da \\ &= e^\epsilon \int_0^{\bar{C}} \mathbf{P}(C(\mathcal{M}(\tilde{D}, b)) > a) da + \bar{C}\delta \\ &= e^\epsilon J(\tilde{D}) + \bar{C}\delta. \end{aligned} \quad (32)$$

Rearranging we have $J(\tilde{D}) \geq e^{-\epsilon}(J(D) - \bar{C}\delta)$.

Next we consider $-\bar{C} \leq C \leq 0$. Define $\Theta(a) = \{\theta : C(\theta) < a\}$, $\forall a \leq 0$. Again, due to \mathcal{M} being private, we have

$$\mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) \leq e^\epsilon \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) + \delta. \quad (33)$$

Since $J(\tilde{D})$ is non-positive, by the integral identity, we have

$$\begin{aligned} J(\tilde{D}) &= \mathbf{E}_b[C(\mathcal{M}(\tilde{D}, b))] \\ &= - \int_{-\bar{C}}^0 \mathbf{P}(C(\mathcal{M}(\tilde{D}, b)) < a) da \\ &= - \int_{-\bar{C}}^0 \mathbf{P}(\mathcal{M}(\tilde{D}, b) \in \Theta(a)) da \\ &\geq - \int_{-\bar{C}}^0 [e^\epsilon \mathbf{P}(\mathcal{M}(D, b) \in \Theta(a)) + \delta] da \\ &= - \int_{-\bar{C}}^0 e^\epsilon \mathbf{P}(C(\mathcal{M}(D, b)) < a) da - \bar{C}\delta \\ &= e^\epsilon J(D) - \bar{C}\delta, \end{aligned} \quad (34)$$

concluding the proof. □

D Proof for Corollary 4

Corollary 4. Let \mathcal{M} be an (ϵ, δ) -differentially-private learner. Assume $J(D) \neq 0$. Then

- i). ($C \geq 0$): in order to achieve $J(\tilde{D}) \leq \frac{1}{\tau} J(D)$ for $\tau \geq 1$, the attacker has to modify at least the following number of items in D .

$$k \geq \lceil \frac{1}{\epsilon} \log \frac{(e^\epsilon - 1)J(D)\tau + \bar{C}\delta\tau}{(e^\epsilon - 1)J(D) + \bar{C}\delta\tau} \rceil. \quad (5)$$

- ii). ($C \leq 0$): in order to achieve $J(\tilde{D}) \leq \tau J(D)$ for $\tau \in [1, -\frac{\bar{C}}{J(D)}]$, the attacker has to modify at least the following number of items in D .

$$k \geq \lceil \frac{1}{\epsilon} \log \frac{(e^\epsilon - 1)J(D)\tau - \bar{C}\delta}{(e^\epsilon - 1)J(D) - \bar{C}\delta} \rceil. \quad (6)$$

Proof. For $0 \leq C \leq \bar{C}$, by Theorem 1, if $\tilde{D} \in \mathcal{B}(D, k)$, then $J(\tilde{D}) \geq \max\{e^{-k\epsilon}(J(D) + \frac{\bar{C}\delta}{e^\epsilon - 1}) - \frac{\bar{C}\delta}{e^\epsilon - 1}, 0\}$. Since we require $J(\tilde{D}) \leq \frac{1}{\tau} J(D)$, we have $e^{-k\epsilon}(J(D) + \frac{\bar{C}\delta}{e^\epsilon - 1}) - \frac{\bar{C}\delta}{e^\epsilon - 1} \leq \frac{1}{\tau} J(D)$. Rearranging gives the result. The proof for $-\bar{C} \leq C \leq 0$ is similar. □

E Proof for Proposition 5

Proposition 5. Assume $\mathcal{M}(\tilde{D}, b)$ is a differentiable function of \tilde{D} , then a stochastic gradient of $J(\tilde{D})$ w.r.t. a particular item \tilde{z}_i is $\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i}$, where $b \sim \nu(b)$.

Proof. Note that

$$\mathbf{E}_b \left[\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i} \right] = \int \frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i} \nu(b) db. \quad (35)$$

Under certain conditions, one can exchange the order of integration and differentiation, and we have

$$\mathbf{E}_b \left[\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i} \right] = \frac{d \int C(\mathcal{M}(\tilde{D}, b)) \nu(b) db}{d \tilde{z}_i} = \frac{dJ(\tilde{D})}{d \tilde{z}_i}. \quad (36)$$

Thus $\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{z}_i}$ is a stochastic gradient. □

F Stochastic Gradient Descent for Objective-Perturbed Logistic Regression

We compute the stochastic gradient for objective-perturbed logistic regression, where $C(\theta) = \frac{1}{2} \|\tilde{\theta} - \theta'\|^2$. The stochastic gradient is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left(\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i} \right)^\top \frac{dC(\tilde{\theta})}{d\tilde{\theta}}. \quad (37)$$

Note that $\frac{dC(\tilde{\theta})}{d\tilde{\theta}} = \tilde{\theta} - \theta'$, thus we focus on computing $\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i}$, which can be derived from the KKT condition of (11):

$$\lambda \tilde{\theta} - \sum_{j=1}^n \frac{y_j \tilde{x}_j}{1 + \exp(y_j \tilde{\theta}^\top \tilde{x}_j)} + b = 0. \quad (38)$$

Let $f(\tilde{\theta}, \tilde{x}_i) = \lambda \tilde{\theta} - \sum_{j=1}^n \frac{y_j \tilde{x}_j}{1 + \exp(y_j \tilde{\theta}^\top \tilde{x}_j)} + b$ and define $s_j = \exp(y_j \tilde{\theta}^\top \tilde{x}_j)$, then one can verify that

$$\frac{\partial f}{\partial \tilde{\theta}} = \lambda I + \sum_{j=1}^n \frac{s_j}{(1 + s_j)^2} \tilde{x}_j \tilde{x}_j^\top. \quad (39)$$

and

$$\frac{\partial f}{\partial \tilde{x}_i} = \frac{s_i}{(1 + s_i)^2} \tilde{x}_i \tilde{\theta}^\top - \frac{y_i}{1 + s_i} I. \quad (40)$$

Thus by (9), the stochastic gradient of \tilde{x}_i is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left[\frac{y_i}{1 + s_i} I - \frac{s_i \tilde{\theta} \tilde{x}_i^\top}{(1 + s_i)^2} \right] \left[\lambda I + \sum_{j=1}^n \frac{s_j \tilde{x}_j \tilde{x}_j^\top}{(1 + s_j)^2} \right]^{-1} (\tilde{\theta} - \theta'). \quad (41)$$

G Stochastic Gradient Descent for Objective-Perturbed Ridge Regression

We compute the stochastic gradient for objective-perturbed ridge regression, where $C(\tilde{\theta}) = \frac{1}{2} \|\tilde{\theta} - \theta'\|^2$. We first compute stochastic gradient for \tilde{x}_i , which is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left(\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i} \right)^\top \frac{dC(\tilde{\theta})}{d\tilde{\theta}}. \quad (42)$$

Note that $\frac{dC(\tilde{\theta})}{d\tilde{\theta}} = \tilde{\theta} - \theta'$, thus it remains to compute $\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i}$, for which we rely on the KKT condition of (12) which is

$$\begin{cases} (\tilde{X}^\top \tilde{X} + \lambda I) \tilde{\theta} - \tilde{X}^\top \tilde{y} + b + \mu \tilde{\theta} = 0 \\ \tilde{\theta}^\top \tilde{\theta} \leq \rho^2 \\ \mu \geq 0 \\ \mu(\tilde{\theta}^\top \tilde{\theta} - \rho^2) = 0, \end{cases} \quad (43)$$

where μ is the Lagrange dual variable for constraint $\frac{1}{2} \|\tilde{\theta}\|^2 \leq \frac{\rho^2}{2}$. Let $f(\tilde{\theta}, \tilde{x}_i, \mu) = (\tilde{X}^\top \tilde{X} + \lambda I) \tilde{\theta} - \tilde{X}^\top \tilde{y} + b + \mu \tilde{\theta}$. One can rewrite $f(\tilde{\theta}, \tilde{x}_i, \mu)$ as

$$\begin{aligned} f(\tilde{\theta}, \tilde{x}_i, \mu) &= (\tilde{x}_i \tilde{x}_i^\top + \sum_{j \neq i} \tilde{x}_j \tilde{x}_j^\top + \lambda I) \tilde{\theta} \\ &\quad - \tilde{x}_i \tilde{y}_i - \sum_{j \neq i} \tilde{x}_j \tilde{y}_j + b + \mu \tilde{\theta}. \end{aligned} \quad (44)$$

Then one can verify that

$$\frac{\partial f}{\partial \tilde{x}_i} = \tilde{x}_i \tilde{\theta}^\top + (\tilde{x}_i^\top \tilde{\theta} - \tilde{y}_i) I. \quad (45)$$

and

$$\frac{\partial f}{\partial \tilde{\theta}} = \tilde{X}^\top \tilde{X} + (\lambda + \mu) I. \quad (46)$$

Thus by (9), the stochastic gradient of \tilde{x}_i is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = [\tilde{\theta} \tilde{x}_i^\top + (\tilde{x}_i^\top \tilde{\theta} - \tilde{y}_i) I] [\tilde{X}^\top \tilde{X} + (\lambda + \mu) I]^{-1} (\theta' - \tilde{\theta}). \quad (47)$$

Next we derive the stochastic gradient of \tilde{y}_i . Now view f as a function of $\tilde{\theta}$, \tilde{y}_i and μ . One can verify that

$$\frac{\partial f}{\partial \tilde{y}_i} = -\tilde{x}_i. \quad (48)$$

and

$$\frac{\partial f}{\partial \tilde{\theta}} = \tilde{X}^\top \tilde{X} + (\lambda + \mu) I. \quad (49)$$

Thus the stochastic gradient of \tilde{y}_i is

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{y}_i} = \tilde{x}_i^\top (\tilde{X}^\top \tilde{X} + \lambda I + \mu I)^{-1} (\tilde{\theta} - \theta'). \quad (50)$$

H Attack Output Perturbation

We explain how to compute the stochastic gradient for output-perturbed private learners. We first give a general form of stochastic gradient and then specialize to logistic regression and ridge regression respectively. We focus on deriving the stochastic gradient of \tilde{x}_i . The stochastic gradient of \tilde{y}_i can be derived in a similar way. By proposition 5, we have that the stochastic gradient of \tilde{x}_i is

$$\frac{\partial C(\mathcal{M}(\tilde{D}, b))}{\partial \tilde{x}_i} = \frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left(\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i} \right)^\top \frac{dC(\tilde{\theta})}{d\tilde{\theta}} \quad (51)$$

where $\tilde{\theta}$ is the poisoned model. Note that by (13), $\tilde{\theta} - b$ must satisfy the Karush-Kuhn-Tucker (KKT) condition of the base learner, thus we have

$$\sum_{i=1}^n \frac{\partial \ell}{\partial \tilde{\theta}} (\tilde{\theta} - b, \tilde{z}_i) + \lambda \frac{d\Omega}{d\tilde{\theta}} (\tilde{\theta} - b) = 0 \quad (52)$$

Let $f(\tilde{\theta}, \tilde{x}_i) = \sum_{i=1}^n \frac{\partial \ell}{\partial \tilde{\theta}} (\tilde{\theta} - b, \tilde{z}_i) + \lambda \frac{d\Omega}{d\tilde{\theta}} (\tilde{\theta} - b)$. Then by using the derivative of implicit function, we have

$$\frac{\partial \tilde{\theta}}{\partial \tilde{x}_i} = - \left(\frac{\partial f}{\partial \tilde{\theta}} \right)^{-1} \frac{\partial g}{\partial \tilde{x}_i}. \quad (53)$$

Next we instantiate for both output-perturbed logistic regression and ridge regression. First, we consider logistic regression. One can verify that

$$f(\tilde{\theta}, \tilde{x}_i) = \lambda(\tilde{\theta} - b) - \sum_{j=1}^n \frac{y_j \tilde{x}_j}{1 + \exp(y_j (\tilde{\theta} - b)^\top \tilde{x}_j)} + b. \quad (54)$$

Define $s_j = \exp(y_j (\tilde{\theta} - b)^\top \tilde{x}_j)$, then we have

$$\frac{\partial f}{\partial \tilde{\theta}} = \lambda I + \sum_{j=1}^n \frac{s_j}{(1 + s_j)^2} \tilde{x}_j \tilde{x}_j^\top. \quad (55)$$

and

$$\frac{\partial f}{\partial \tilde{x}_i} = \frac{s_i}{(1 + s_i)^2} \tilde{x}_i (\tilde{\theta} - b)^\top - \frac{y_i}{1 + s_i} I. \quad (56)$$

Thus by (9) we have

$$\frac{\partial C(\tilde{\theta})}{\partial \tilde{x}_i} = \left[\frac{y_i}{1 + s_i} I - \frac{s_i (\tilde{\theta} - b) \tilde{x}_i^\top}{(1 + s_i)^2} \right] \left[\lambda I + \sum_{j=1}^n \frac{s_j \tilde{x}_j \tilde{x}_j^\top}{(1 + s_j)^2} \right]^{-1} (\tilde{\theta} - \theta'). \quad (57)$$

For output-perturbed ridge regression, one can verify that

$$f(\tilde{\theta}, \tilde{x}_i, \mu) = (\tilde{X}^\top \tilde{X} + \lambda I) (\tilde{\theta} - b) - \tilde{X}^\top \tilde{y} + b + \mu (\tilde{\theta} - b). \quad (58)$$

Then one can follow the same strategy as for output-perturbed logistic regression to derive the stochastic gradient of \tilde{x}_i and \tilde{y}_i respectively.