

LAB 3: DUE 28 OCTOBER 2015

This Lab is an adaptation of the Assignment 6 for Fredo Durand's Computational Photography course at MIT. You can find a longer description of his assignment in [FredoDurand.pdf](#), which might help you. Note that his notation changes the coordinate system to y, x, w instead of x, y, w . You are free to use his notation if you want, just be consistent!

You don't need to use all the data sets. Do at least, one with 2 images.

Task 1: Apply Homography (20 pts)

Write a function to apply a homography to an image into another. You will iterate over the output image, and take `image2` when possible, and `image1` when the coordinates are outside `image2`.

Test your function on the provided `green.png` and `poster.png` images using the homography: $H = \begin{bmatrix} 0.8025 & 0.0116 & -78.2148 \\ -0.0058 & 0.8346 & -141.3292 \\ -0.0006 & -0.0002 & 1 \end{bmatrix}$

Remember you are using homogeneous coordinates.



image 1

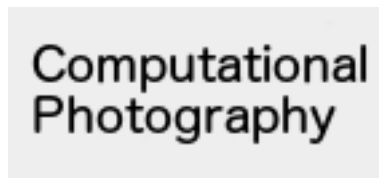


image2

Task 2: Bilinear Interpolation (20)

When sampling, the coordinates will be "between pixels". Use bilinear interpolation to get a better image. https://en.wikipedia.org/wiki/Bilinear_interpolation. Compare with nearest neighbour sampling.

Task 3: Compute Homography from Points (40 pts)

Taking points correspondences from two images, compute the homography. You can do this with 4 points, fixing $i = 0$. (See Lecture notes), and it's worth trying to do so, but the assignment is to use the Least Squares method, using more points and computing the solution with SVD. You have extra notes and the [FredoDurand.pdf](#) documents to help you. Check [tomographies.pdf](#) and [FredoDurand.pdf](#) for more information.

Test your solution with with the previous example:

```
pointListPoster=[array([0, 0, 1]), array([w, 0, 1]), array([w, h, 1]), array([0, h, 1])]
```

```
pointListTrain=[array([95, 170, 1]), array([238,171, 1]), array([235, 233, 1]), array([94, 239, 1])]
```



Try as well with pano/stata-1.png

```
im1=imread('pano/stata-1.png')
```

```
im2=imread('pano/stata-2.png')
```

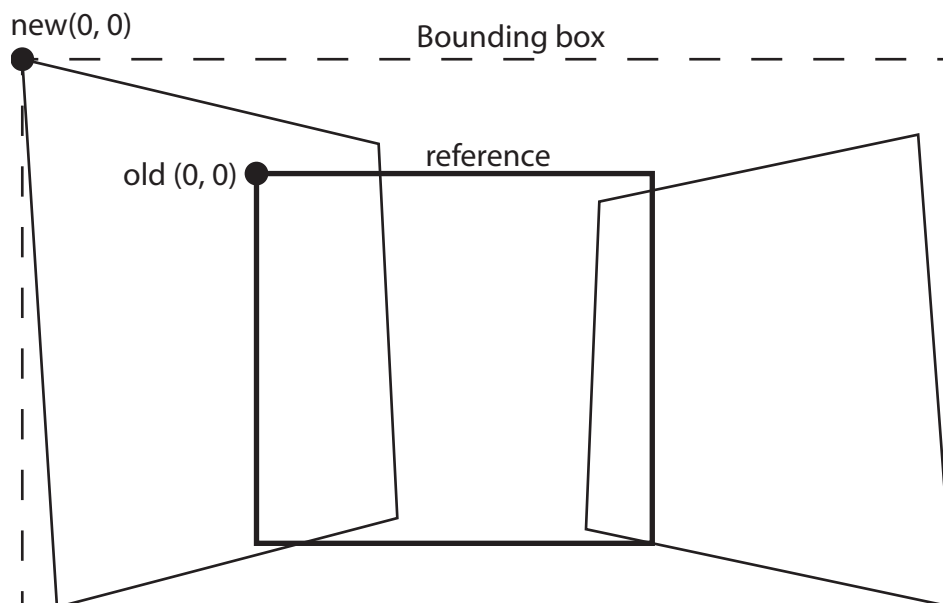
```
pointList1=[array([218, 209, 1]), array([300,425, 1]), array([337, 209, 1]), array([336, 396, 1])]
```

```
pointList2=[array([4, 232, 1]), array([62, 465, 1]), array([125, 247, 1]), array([102, 433, 1])]
```

To ease finding the correspondence, you can use the simple UI in [Pano-UI/click.html](#) . You can change the image in the code. **You have to click in the same order in both images.** **Coordinates X and Y are changed!!**

Task 4: Bounding Box (20)

In the previous examples, you used the boundaries of the first image. For panorama stitching, we want to create a bigger image, as shown in the lecture examples. For this, we



need to estimate the size of the output. You will need to compute the inverse of your Homography, and compute the coordinates for the corners. Then use an offset to translate between “outside of the image” coordinates and the new bigger image coordinates.

Deliverables

Code and images for T1,T2,and T3. You will demo it for marking during the next lab. README file.

- How long did the assignment take?
- Issues and descriptions of your partial solution (for partial credit)
- Any extras?
- Collaboration acknowledgment.
- What was most unclear/difficult?
- What was most exciting?