

MUHAMMAD ZEESHAN KARAMAT

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EDUCATION

Bachelor of Electrical Engineering

Sept. 2017 – June 2021

School of Electrical Engineering and Computer Science (SEECs)

CGPA 3.56/4.00

National University of Sciences & Technology (NUST), Islamabad, Pakistan

- Final year Thesis: "Whole Slide Image Scanner with Deep Learning Applications"

TECHNICAL SKILLS

Languages: C/C++, Python, Qml, SQL, MATLAB, JavaScript, HTML/CSS

Frameworks/Platform: ROS, PyTorch, Keras, fast.ai, CUDA, DeepStream, GStreamer, OpenCV, Qt

Development Tools: Linux, Git, CMake, Amazon Web Services, Jupyter Notebook, Anaconda, Google Colab, Qt Creator

EXPERIENCE

Software Engineer II, *vResolv LLC*

Aug. 2023 – Present

- Leading an AI project focused on detection, training and optimization of **Yolov7** model for improved inference.
- Integrated Deepstream **NvDCF** for real-time object tracking and deployed the model on Jetson Orin.
- Set up docker and integrated **Nvidia Hardware accelerated Gstreamer** pipeline with opencv for **H.264** encoding.
- Developed Qt-based **Linux** application plugins, and integrated a user-friendly graphical interface with live camera output.

Software Engineer, *Conntac GmbH — Remote*

Jan. 2023 – Aug. 2023

- Development of Self Service Android and IOS app using Qt in Qml and C++
- Collaborated with the design team to transform designs into interactive UI using the **Model-View-Controller** pattern
- Developed the router login feature using camera scan with the **Google ML API**, enhancing user authentication convenience.

Development Engineer, *Sedenius Engineering GmbH*

Aug. 2021 – Dec. 2022

- Research and Development of Autonomous Vehicle project "ABSOLUT"
- Development of **Sensor Fusion** algorithm for LIDAR, RADAR, and Vision data based on **Kalman Filter**.
- Development of ROS node for Object Detection, and Tracking and deployed on **NVIDIA DRIVE AGX**.
- Development of modules and user interfaces for **Sensor-Data-Visualization** and simulation software

Research Intern, *University of Western Australia* [[Presentation](#)] [[Paper](#)]

July 2021 – Aug. 2021

- Worked on the Classification of synthesized galaxy images from computer simulations using deep learning.
- Addressed class imbalance in a large dataset for classification, and analyzed the physical properties based on the results.
- Arranged and conducted talks of speakers and led a team of interns in different cross-cultural activities.

Research Assistant, *SIGMA Lab in collaboration with TUKU Lab*

July 2019 – Jan. 2021

- Researched about GANs for data augmentation for unbalanced classes in medical imaging.
- Worked with QuPath to extract image tiles from Whole slide images for AI-based computer-aided detection.
- Implemented SOTA Deep learning models in **PyTorch** on NVIDIA's Jetson Nano 4GB and 2GB kit, and compared metrics.

PROJECTS

Whole Slide Image (WSI) Scanner with Deep Learning Applications [[Demo](#)] [[Results](#)] [[Thesis](#)] [[Paper](#)]

- * Developed end-to-end automated robotic machine to digitize pathological slides for AI-based analysis.
- * Developed an automated scanning system using actuators, incorporating autofocus algorithm based on edge detection.
- * Developed Image stitching algorithm in Python based on **Cross-correlation** and **Laplacian blending**.
- * Trained a **YOLOv4** object detection model to detect Mitotic cells and acquired **92.29% mAP**.

Agricultural Robot for Precision Spraying

- * Developed autonomous robot for precision spraying using computer vision based on **ROS**.
- * Trained a classifier to calculate the density of plants based on the area covered by leaves.
- * Fed the density value to the controller which controls the amount of spray based on an algorithm.

Vision Based Smart Security System [[Demo](#)]

- * Designed an intrusion detection system using the knowledge of embedded systems and Computer Vision.
- * Trained a model for intrusion detection and optimized inference using **TensorRT SDK** for Nvidia Jetson Nano
- * Designed **REST API** to communicate with the company app.

Image Segmentation for Epithelium Classification in Oral Squamous Cell Carcinoma

- * Implemented a **U-NET** based epithelium segmentation utilizing masks extracted from annotated WSI and phone images.
- * Evaluated performance on both smartphone-acquired and WSI-scanned images; identified a minor performance degradation in smartphone-based segmentation (**F1 score = 0.7631**) compared to WSI (**F1 score = 0.7846**).

Classification of B-Acute Lymphoblastic Leukemia

- * Trained deep learning model in **Keras** for classification of benign and malignant B-ALL cells.
- * Utilized **GANs** to create synthetic cell images, significantly augmenting the dataset and improving model performance.

Emergency Response UAV for Swift Rescue Operations

- * Developed a **YOLOv3** equipped UAV system for real-time detection of individuals in hazardous environments.
- * Implemented a **REST API** for communication between the UAV and ground control, enhancing response efficiency.

AI/Neural Network Deployment on STM32 Microcontroller (TinyML)

- * Deployed a cat and dog classifier on an STM32 microcontroller using the **CMSIS-NN** library, and tested in real time.

HONOURS AND AWARDS

- Rector Gold Medal** Award among the batch of 200 students
- Distinction** at International level during **SDURI** program conducted by University of Western Australia
- Certification from Nvidia for **Jetson AI Specialist**
- Full Merit Scholarship** at Pakturk International College