

SCOTTYRANK.JL: AN IMPLEMENTATION OF PAGERANK & HITS

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1. MATHEMATICAL BACKGROUND

1.1. Definitions. Positive matrices are defined as matrices with positive entries.

Markov matrices are defined as square matrices with nonnegative entries and column sum 1 across all of its columns. Note that for a $n \times n$ matrix M , the latter condition is equivalent to $M^T \vec{1} = \vec{1}$, where $\vec{1} \in \mathbb{R}^n$ has all ones as components.

Positive Markov matrices are defined as, well, positive Markov matrices.

1.2. Facts. (Perron-Frobenius theorem) Let A be a positive square matrix. Let λ_1 be A 's maximum eigenvalue in terms of absolute values. Then λ_1 is positive and has algebraic (and subsequently geometric) multiplicity 1.

Let M be a Markov matrix. Let λ_1 be M 's maximum eigenvalue in terms of absolute values. Then $\lambda_1 = 1$.

Let M' be a positive Markov matrix. Let λ_1 be M' 's maximum eigenvalue in terms of absolute values. Then $\lambda_1 = 1$ and has algebraic (and subsequently geometric) multiplicity 1.

1.3. Usage. Let M be a $n \times n$ Markov matrix. Then M specifies a discrete memoryless transition process between n states, namely the process where

$$(\forall (t, i, j) \in \mathbb{N} \times [n] \times [n]) [\Pr(\text{state } i \text{ at time } t+1 \mid \text{state } j \text{ at time } t) = M_{ij}].$$

Let $\vec{v} \in \mathbb{R}^n$ such that \vec{v} has nonnegative components and $\vec{v}^T \vec{1} = 1$ (a stochastic vector). Then \vec{v} specifies an (initial) discrete probability distribution over the n states, namely the distribution where

$$(\forall i \in [n]) [\Pr(\text{state } i \text{ at time } 0) = \vec{v}_i].$$

Then

$$(\forall (k, i) \in \mathbb{N} \times [n]) [\Pr(\text{state } i \text{ at time } k) = (M^k \vec{v})_i].$$