

# Chapter 4

## The Processor



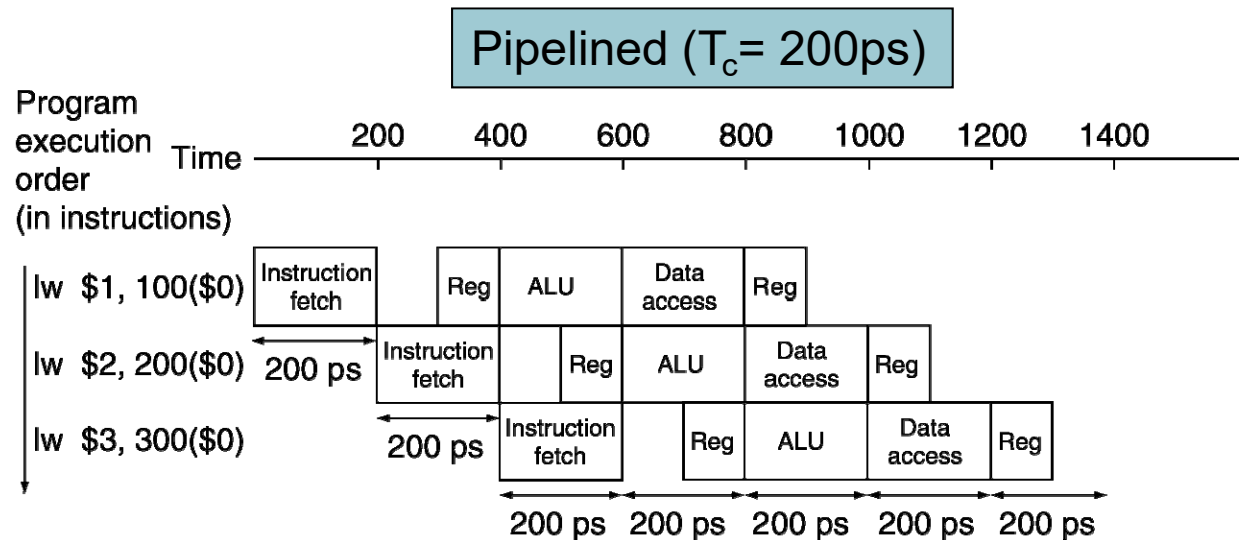
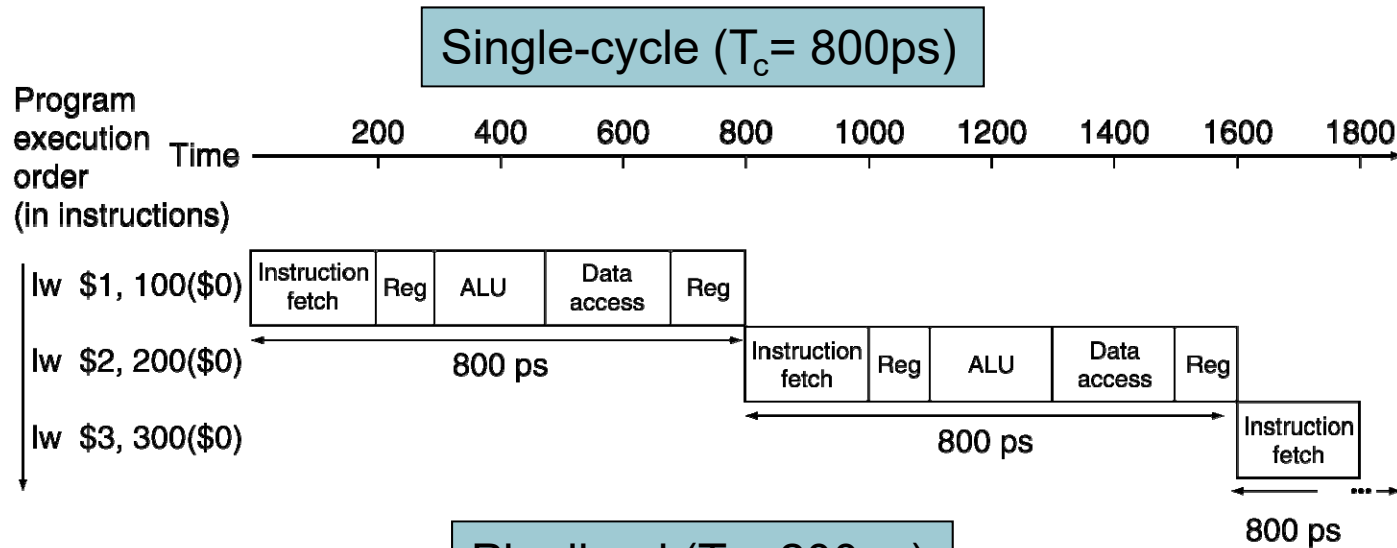
# Pipeline Performance

- Assume time for stages is
  - 100ps for register read or write
  - 200ps for other stages
- Compare pipelined datapath with single-cycle datapath

Instr	Instr fetch	Register read	ALU op	Memory access	Register write	Total time
lw	200ps	100 ps	200ps	200ps	100 ps	800ps
sw	200ps	100 ps	200ps	200ps		700ps
R-format	200ps	100 ps	200ps		100 ps	600ps
beq	200ps	100 ps	200ps			500ps



# Pipeline Performance

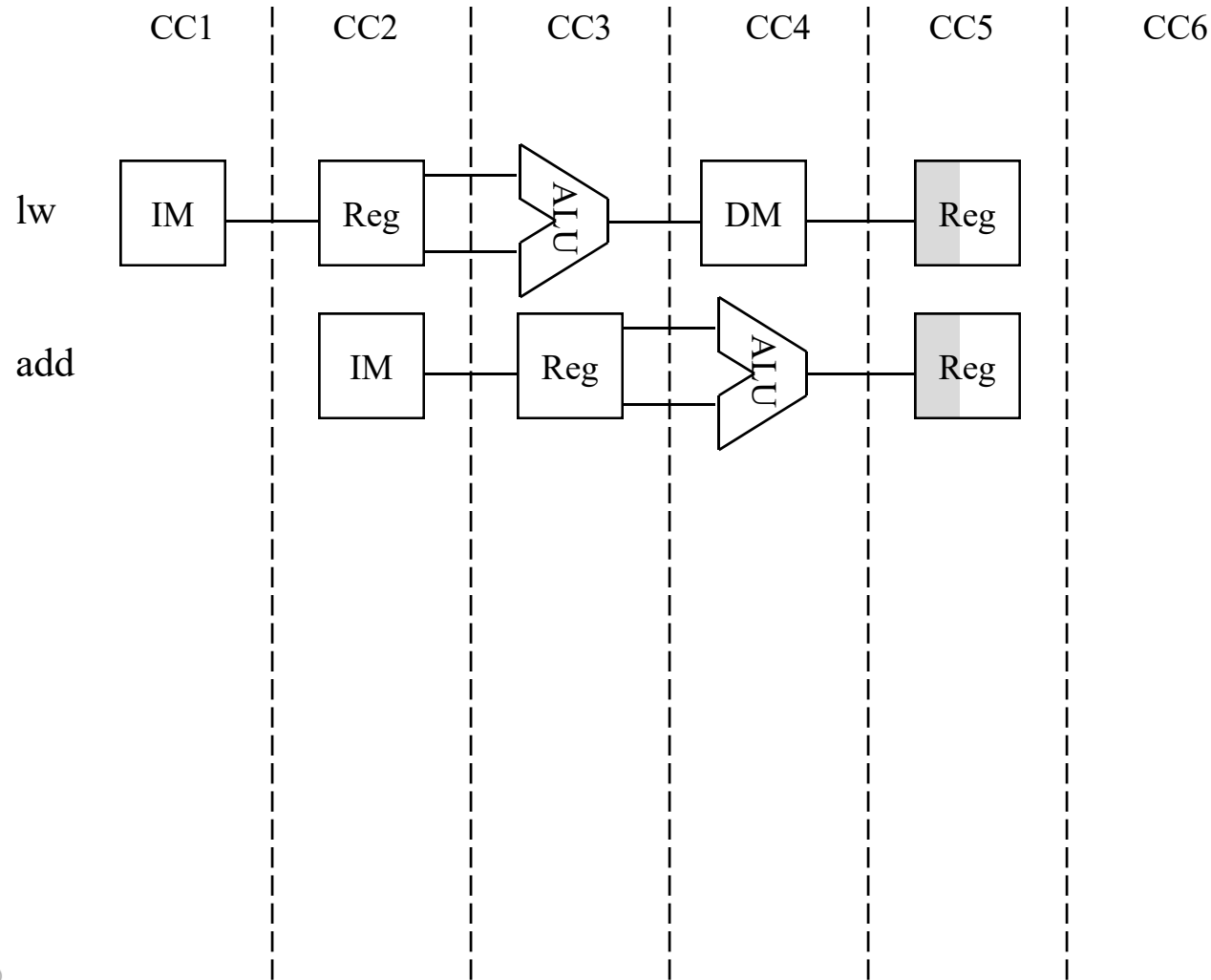


# Pipeline Speedup

- If all stages are balanced
  - i.e., all take the same time
  - Time between instructions<sub>pipelined</sub>  
= 
$$\frac{\text{Time between instructions}_{\text{nonpipelined}}}{\text{Number of stages}}$$
- If not balanced, speedup is less
- Speedup due to increased throughput
  - Latency (time for each instruction) does not decrease



# Mixed Instructions in the Pipeline



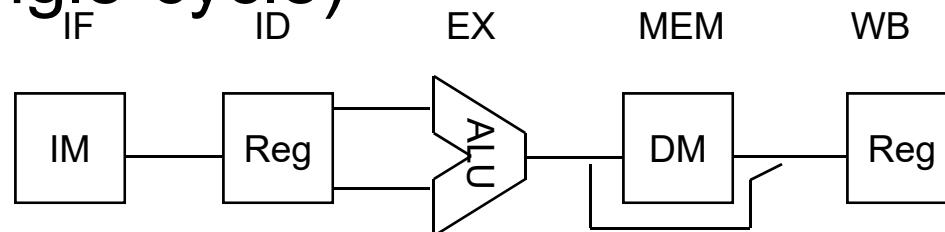
# Pipelining and ISA Design

- MIPS ISA designed for pipelining
  - All instructions are 32-bits
    - Easier to fetch and decode in one cycle
    - c.f. x86: 1- to 17-byte instructions
  - Few and regular instruction formats
    - Can decode and read registers in one step
  - Load/store addressing
    - Can calculate address in 3<sup>rd</sup> stage, access memory in 4<sup>th</sup> stage
  - Alignment of memory operands
    - Memory access takes only one cycle



# Pipeline Principles

- All instructions that share a pipeline must have the same stages in the same order.
  - therefore, add does nothing during Mem stage
  - sw does nothing during WB stage
- All intermediate values must be latched each cycle.
- There is no functional block reuse
  - example: we need 2 adders and ALU (like in single-cycle)



# Pipeline registers

- Need registers between stages
  - To hold information produced in previous cycle

