## Chapter 8: Index Structures

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## Outline<sup>1</sup>

- Mash-based Index Structures
  - Extensible Hash Tables
  - Linear Hash Tables
- Tree-based Index Structures
  - B+ Trees

<sup>1</sup>Updated on April 2, 2020

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#### Hash-based Index Structures

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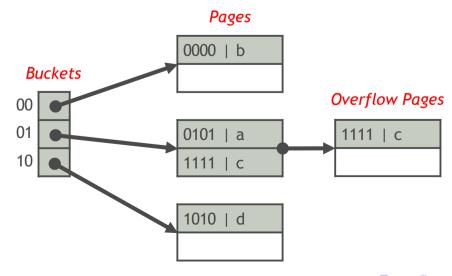
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# Secondary-Storage Hash Tables (外存哈希表)

- A secondary-storage hash table consists of a number of buckets
- An index entry with key K is put in the bucket numbered hash(K), where hash is a hash function
- Each bucket stores a pointer to a linked list of pages holding the index entries in the bucket



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## Categories of Secondary-Storage Hash Tables

#### Static Hash Tables (静态哈希表)

• The number of buckets does not change

#### Dynamic Hash Tables (动态哈希表)

- The number of buckets is allowed to vary so that there is about one block per bucket
- Extensible hash tables (可扩展哈希表)
- Linear hash tables (线性哈希表)

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Hash-based Index Structures Extensible Hash Tables

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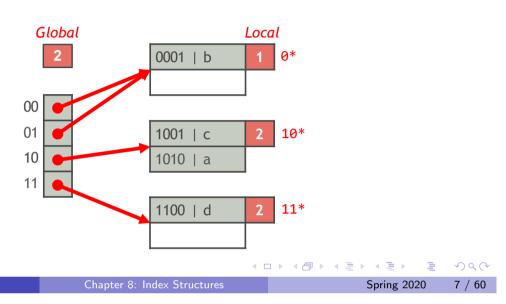
## Extensible Hash Tables (可扩展哈希表)

An extensible hash table is comprised of  $2^i$  buckets

- *i* is called the global depth
- An index entry with key K belongs to the bucket numbered by the first i bits of hash(K)

#### Example:

$$hash(a) = 1010, hash(b) = 0001, hash(c) = 1001, hash(d) = 1100$$

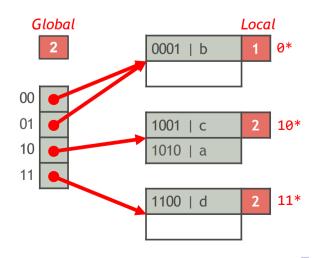


## Extensible Hash Tables (Cont'd)

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Every bucket keeps a pointer to a page where the index entries in the bucket are stored

- Several buckets can share a page if all the index entires in those buckets can fit in the page
- Every page records # bits of hash(K) (local depth) used to determine the membership of index entires in this page

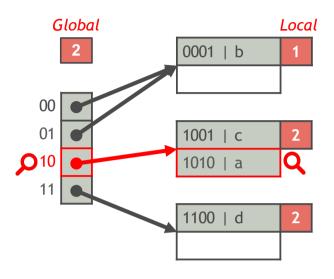


## Extensible Hash Table Lookup

#### Find the index entry with key K

- 1 Determine the bucket where the entry belongs to
- Find the entry in the page that the bucket points to

Example: K = a, hash(a) = 1010



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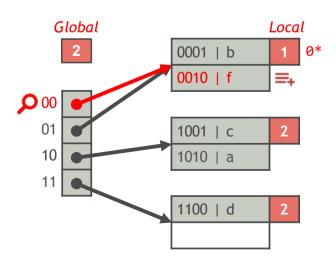
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## Extensible Hash Table Insert

#### Insert an index entry with key K

- Find the page P where the entry is to be inserted
- If P has enough space, done!
  Otherwise, split P into P and a new page P'

Example: K = f, hash(f) = 0010



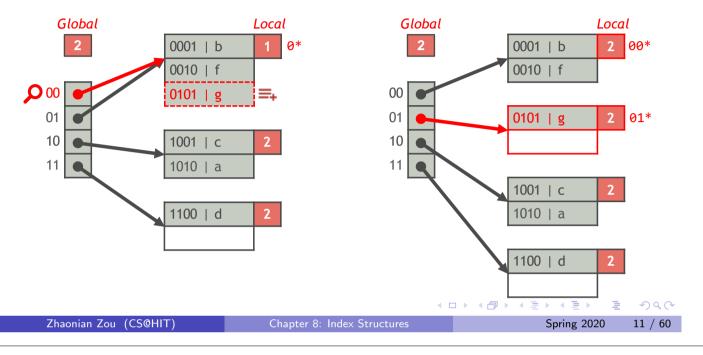
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## Extensible Hash Table Insert (Cont'd)

If P overflows and the local depth of P is less than the global depth,

- 1 Increase P's local depth by 1
- 2 Re-assign some index entries in P to a new bucket page P' (P and P' have the same local depth)

Example: K = g, hash(g) = 0101



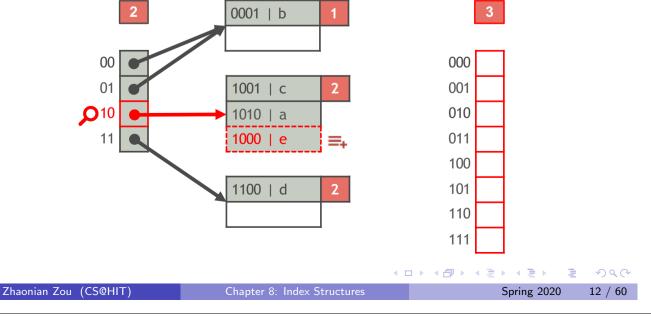
## Extensible Hash Table Insert (Cont'd)

If P overflows and the local depth of P is equal to the global depth,

- Increase the global depth by 1 (double # buckets)
- 2 Re-organize the buckets; if a page overflows, split it

Example: K = e, hash(e) = 1000

Global

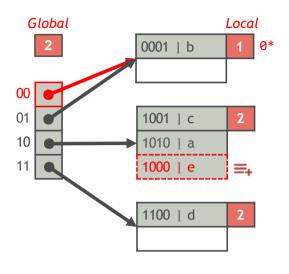


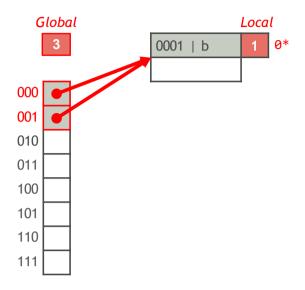
Local

Global

## Extensible Hash Table Insert: Example

Example: K = e, hash(e) = 1000





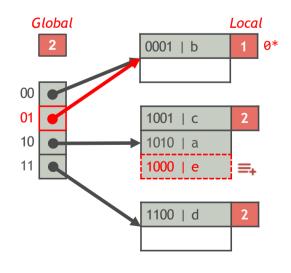
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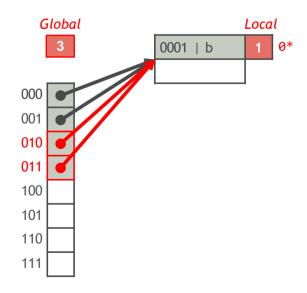
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## Extensible Hash Table Insert: Example

Example: K = e, hash(e) = 1000

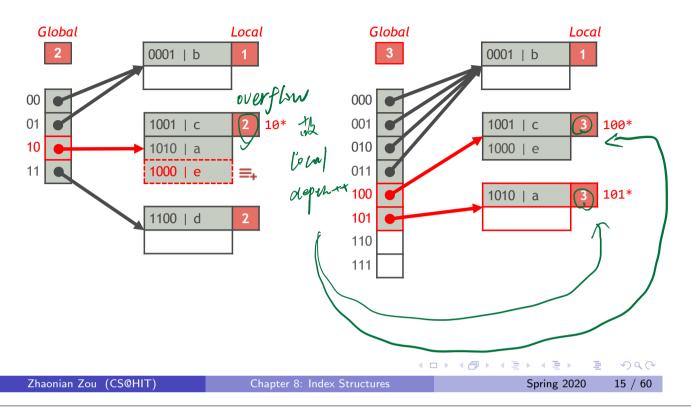




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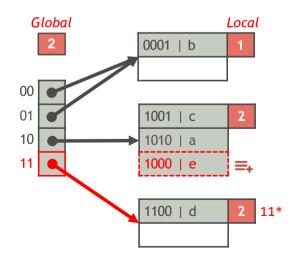
## Extensible Hash Table Insert: Example

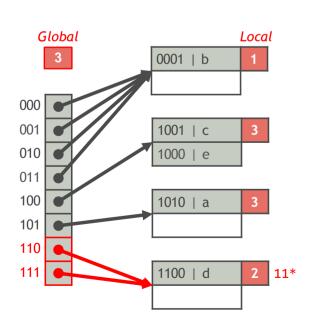
Example: K = e, hash(e) = 1000



## Extensible Hash Table Insert: Example

Example: K = e, hash(e) = 1000



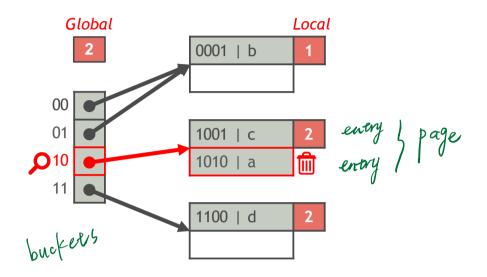


## Extensible Hash Table Delete

#### Delete the index entry with key K

- Find the page where the entry belongs to
- 2 Delete the entry from the page

Example: K = a, hash(a) = 1010



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Hash-based Index Structures Linear Hash Tables

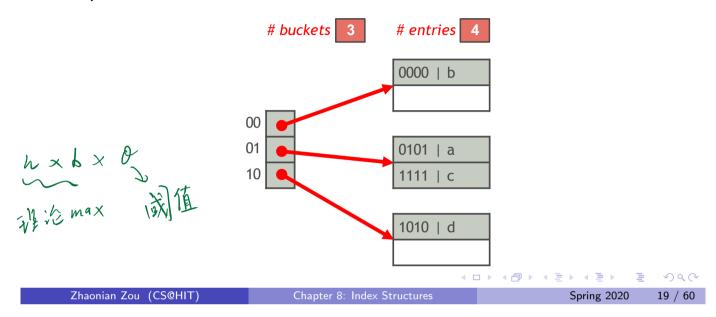
# Linear Hash Tables (线性哈希表)

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A linear hash table is comprised of *n* buckets

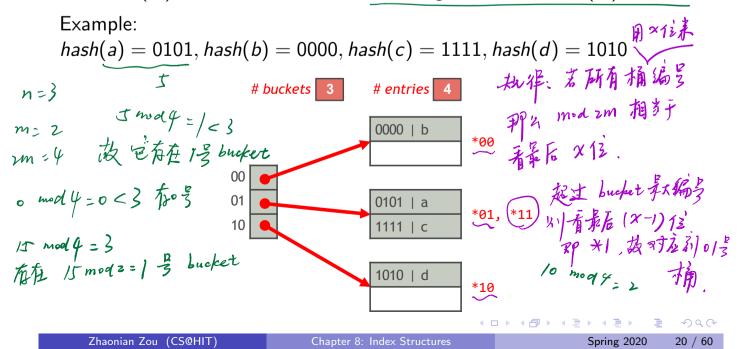
- Every bucket keeps a pointer to a linked list of pages holding the index entries in the bucket
- Suppose each page can hold at most b index entries. The linear hash table stores at most  $\theta bn$  entries, where  $0 < \theta < 1$  is a threshold

Example: b = 2,  $\theta = 0.85$ 



# Hashing Scheme Scheme Log $m = \lfloor \log_2 n \rfloor \leq \log_2 n$ • The buckets are numbered from 0 to n-1• Lot $m = 2^{\lfloor \log_2 n \rfloor}$

- Let  $m = 2^{\lfloor \log_2 n \rfloor}$ , so m < n < 2m
- If  $hash(K) \mod 2m < n$ , index entry with key K belongs to bucket  $hash(K) \mod 2m$ ; Otherwise, it belongs to bucket  $hash(K) \mod m$



#### Linear Hash Table Insert

Insert an index entry with key K

- Insert the entry into the bucket B where it belongs to
- 2 Increase # entries by 1
- 3 If # entries  $\le \theta bn$ , done! Otherwise, increase # buckets by 1 and redistribute the entries in B

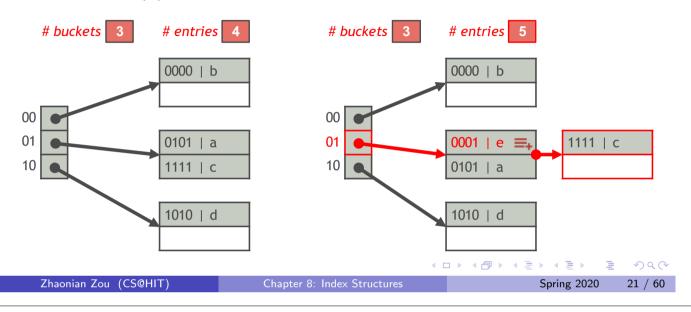
Example: hash(e) = 0001,  $\theta = 0.85$ 

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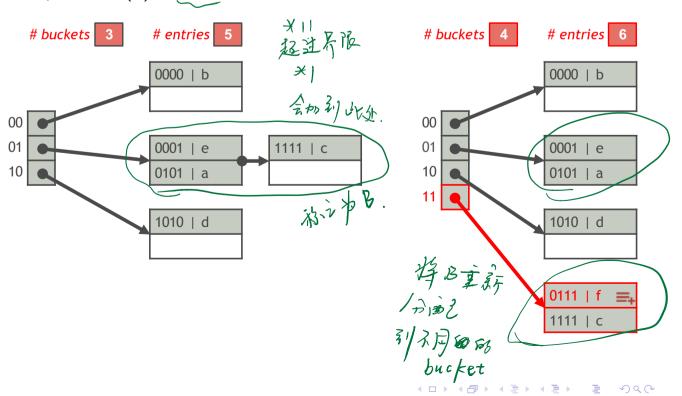
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## Linear Hash Table Insert (Cont'd)

Example: hash(f) = 0111,  $\theta = 0.85$ 

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Tree-based Index Structures

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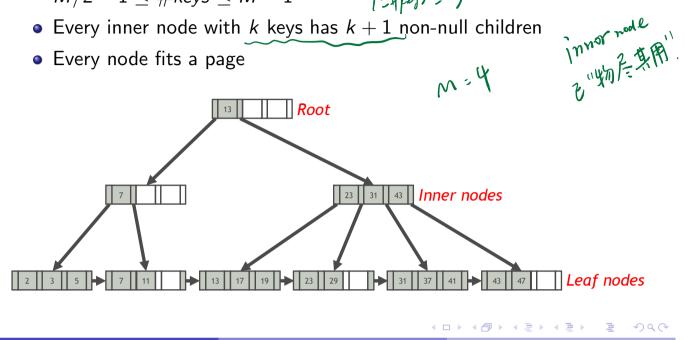
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#### B+ Trees

A B+ tree is an M-way search tree with the following properties:

- It is perfectly balanced (i.e., every leaf node is at the same depth)
- Every node other than the root is at least half-full  $M/2 - 1 \le \# keys \le M - 1$ 15# ceys 5 3
- Every inner node with k keys has k+1\_non-null children
- Every node fits a page



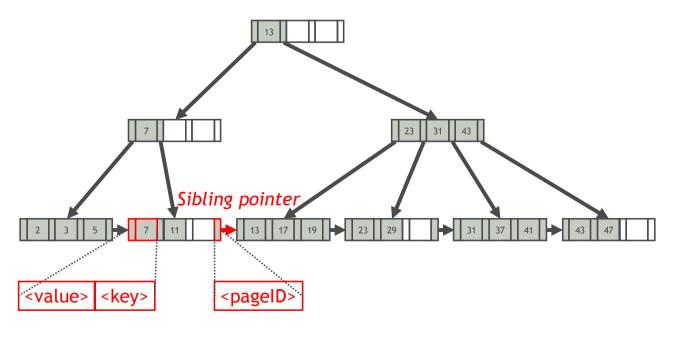
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#### B+ Tree Leaf Nodes

Every leaf node is comprised of an array of index entries (key/value pairs) and a pointer to its right sibling 克美加娃

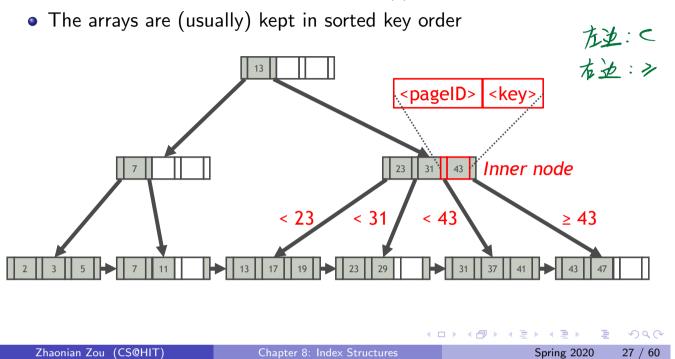
• The index entry array is (usually) kept in sorted key order



#### B+ Tree Inner Nodes

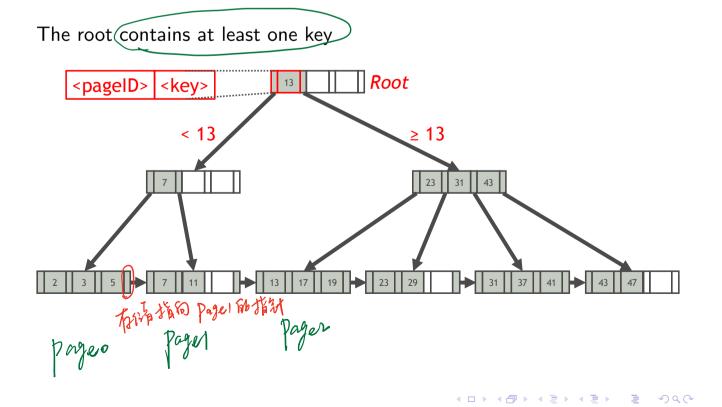
Every inner node is comprised of an array of keys and an array of pointers to its children

• The keys are derived from the attribute(s) that the index is based on



B+ Tree Root Node

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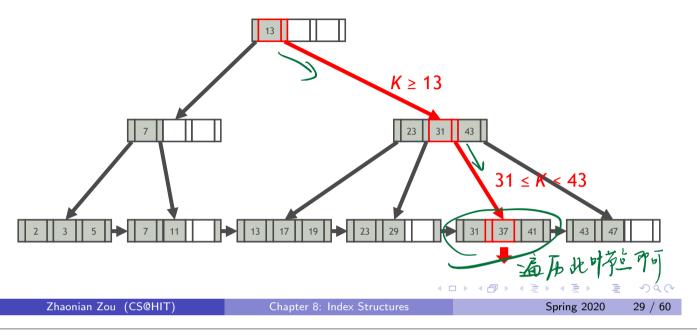
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## B+ Tree Lookup

#### Find the index entry with key K

- Find the leaf node where K belongs to by following the direction of the keys in the inner nodes

Example: K = 37

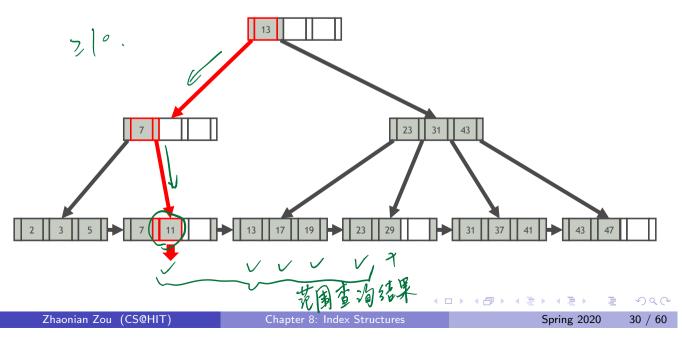


# B+ Tree Range Query

Find the index entries with keys  $K \in [L, U]$ 

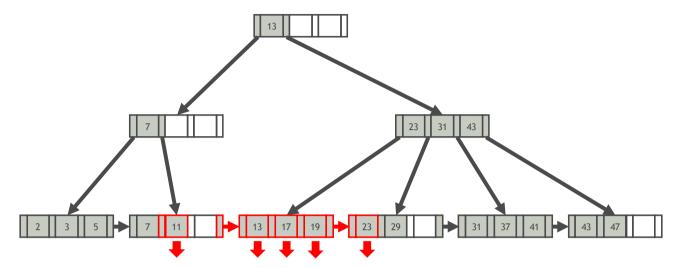
- Find the first index entry E with the smallest key  $\geq L$
- ② Scan the contiguous index entries with keys  $\leq U$  to the right of E

Example:  $K \in [10, 25]$ 



## B+ Tree Range Query (Cont'd)

Example:  $K \in [10, 25]$ 



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#### Insert an index entry with key K

- Find the correct leaf node L where the entry is to be inserted
- 2 Put the entry into *L* in sorted key order
- If L has enough space, done! Otherwise, split the keys in L into L and a new node  $L_2$  the entries evenly, copy up the middle key 3 If L has enough space, done!

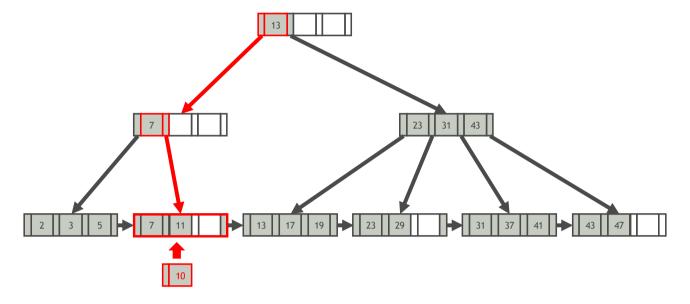
  - 2 Insert an index entry pointing to  $L_2$  into the parent of L

To split an inner node,

- Redistribute the entries evenly
- 2 Push up the middle key



Example: K = 10



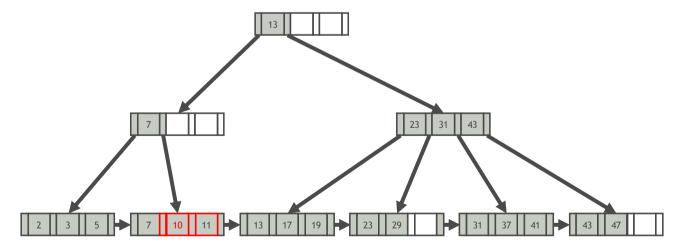
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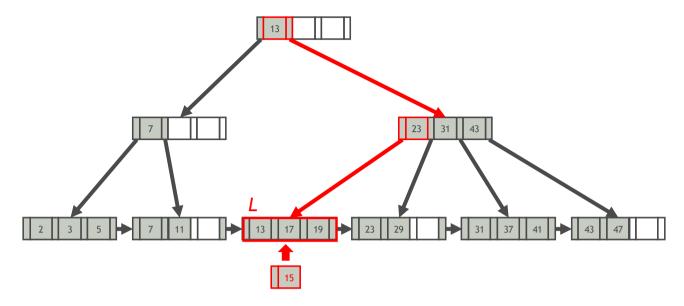
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## B+ Tree Insert: Example 1 (w/o Node Split)

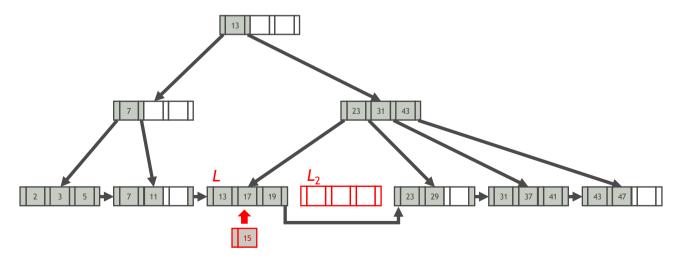


Example: K = 15

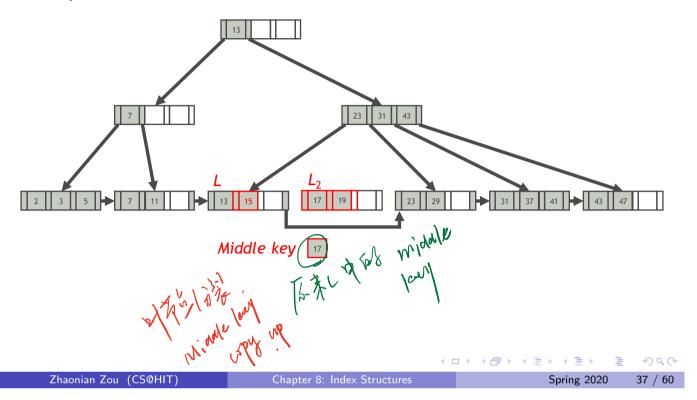


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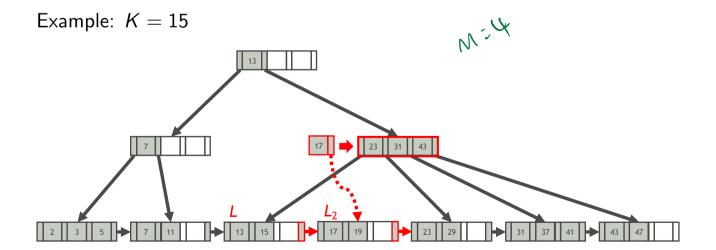
# B+ Tree Insert: Example 2 (w/ Node Split)



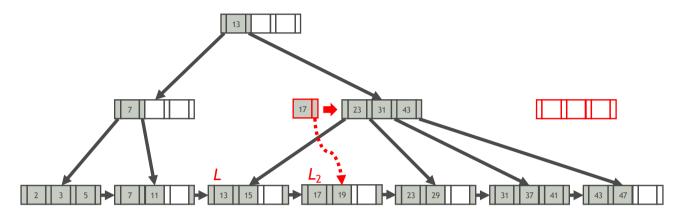
Example: K = 15



## B+ Tree Insert: Example 2 (w/ Node Split)



Example: K = 15

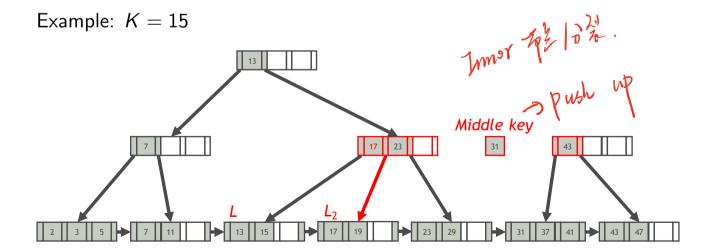


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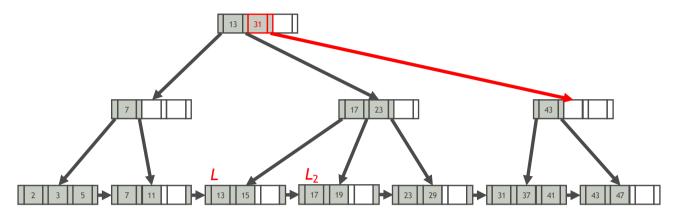
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## B+ Tree Insert: Example 2 (w/ Node Split)



Example: K = 15



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#### B+ Tree Delete

#### Delete an index entry with key K

- Find the leaf node L where the entry belongs to
- 2 Remove the entry from *L*
- 3 If L is at least half-full, done! Otherwise,

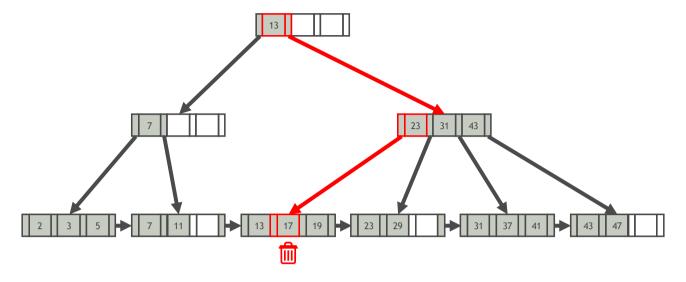


- 1 Try to redistribute, borrowing from sibling
- ② If redistribution fails, merge L and its sibling

If merge occurred, must delete entry pointing to  $\boldsymbol{L}$  or the sibling from the parent of  $\boldsymbol{L}$ 

## B+ Tree Delete: Example 1 (w/o Node Underflow)

Example: K = 17



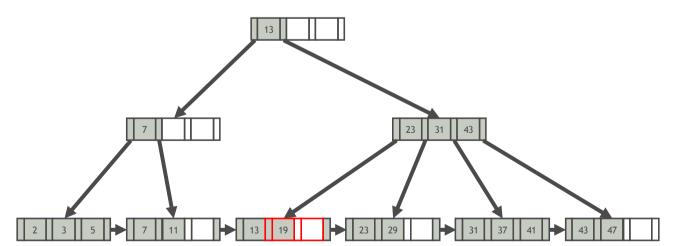
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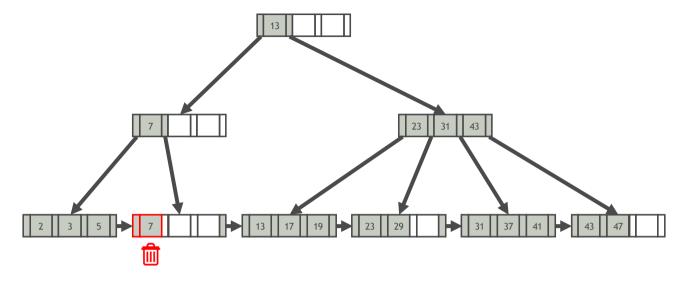
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## B+ Tree Delete: Example 1 (w/o Node Underflow)



## B+ Tree Delete: Example 2 (Key Redistribution)

Example: K = 7



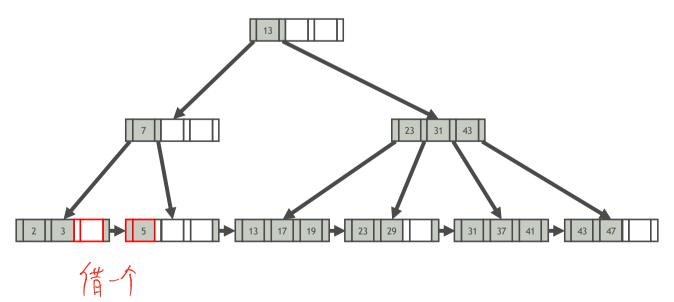
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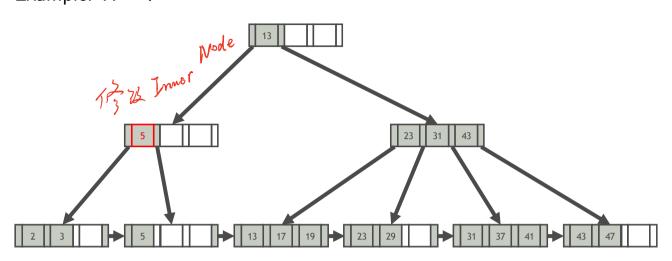
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## B+ Tree Delete: Example 2 (Key Redistribution)



# B+ Tree Delete: Example 2 (Key Redistribution)

Example: K = 7



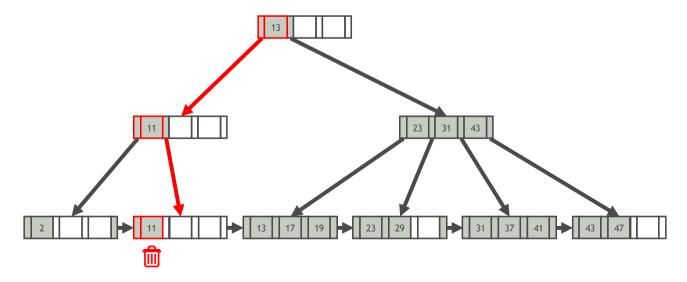
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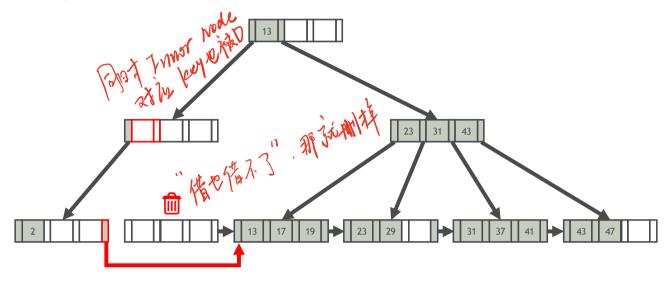
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# B+ Tree Delete: Example 3 (w/ Node Merge)



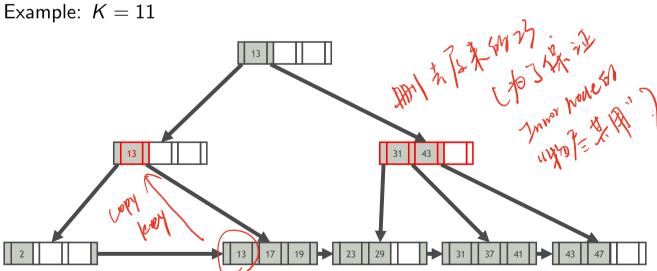
## B+ Tree Delete: Example 3 (w/ Node Merge)

Example: K = 11

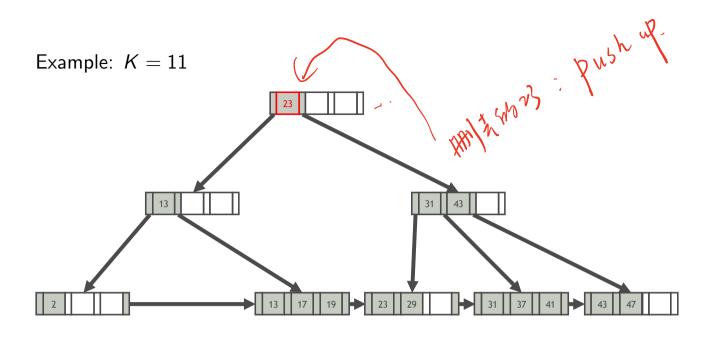


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## B+ Tree Delete: Example 3 (w/ Node Merge)



## B+ Tree Delete: Example 3 (w/ Node Merge)



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## **Key Compression**

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- The number of disk I/Os to retrieve a data entry in a B+ tree = the height of the tree  $\approx \log_{fan\_out}(\# \text{ of data entries})$
- The fan-out (扇出) of the tree is the number of index entries fit on a page, which is determined by the size of index entries
- The size of an index entry depends primarily on the size of the search key value
- Search key values are very long  $\Longrightarrow$  the fan-out is low  $\Longrightarrow$  the tree is high  $\Longrightarrow$  the query time is long

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## Prefix Compression (前缀压缩)



- Sorted keys in the same leaf node are likely to have the same prefix
- Instead of storing the entire key each time, extract common prefix and store only unique suffix for each key

Microsoft Microwave Microphone ↓ Prefix compression

Prefix: Micro phone soft wave

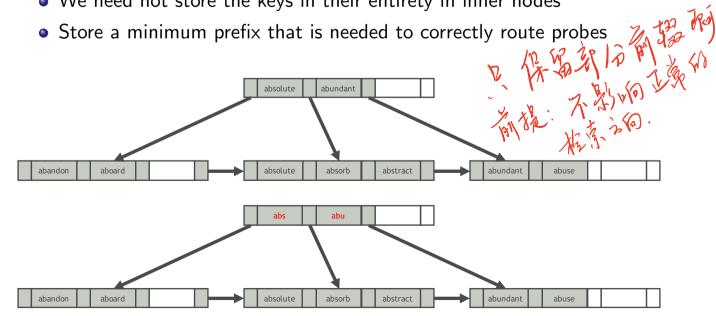
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## Suffix Truncation (后缀截断)

- The keys in the inner nodes are only used to direct traffic
- We need not store the keys in their entirety in inner nodes



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## Bulk Loading (批量加载)

Creating a B+ tree on an existing set of index entries

Top-Down Approach

- Insert the index entries one at a time
- Expensive, because each entry requires to start from the root and go down to the appropriate leaf node

#### Bottom-Up Approach 1

- (Sort) the index entries according to the search key
- Allocate an empty inner node as the root and insert a pointer to the first page of sorted entries into it
- On Entries for the leaf pages are always inserted into the right-most inner node just above the leaf level. When that page fills up, it is split

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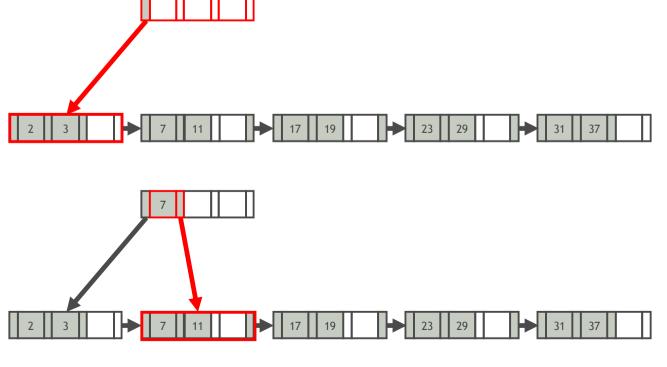
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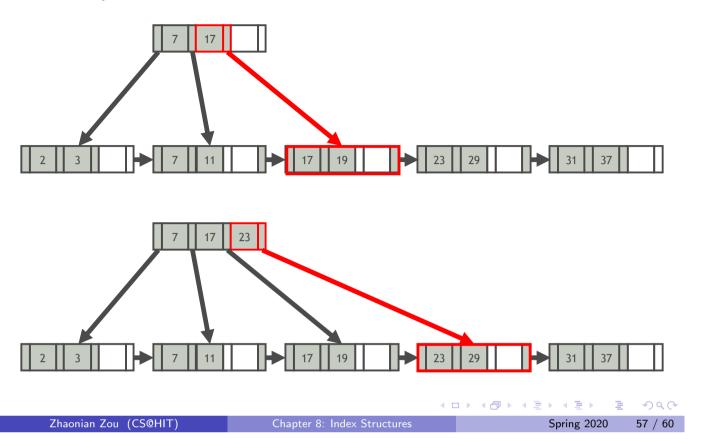
## Bulk Loading: Example

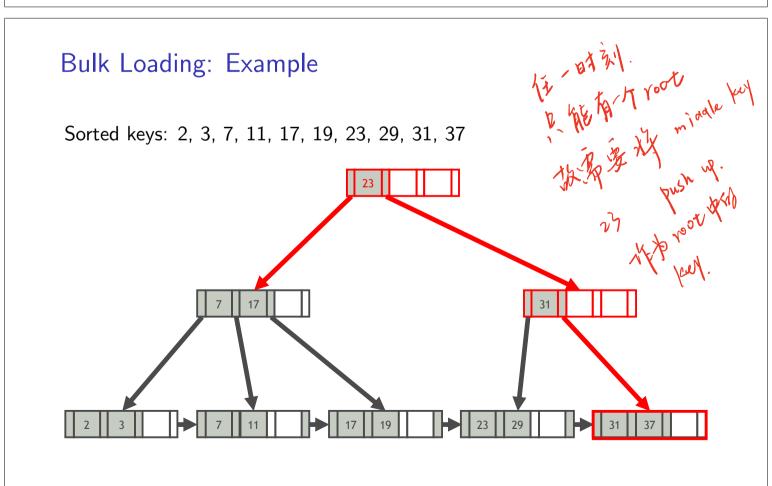
Sorted keys: 2, 3, 7, 11, 17, 19, 23, 29, 31, 37



#### Bulk Loading: Example

Sorted keys: 2, 3, 7, 11, 17, 19, 23, 29, 31, 37





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## Summary

- Mash-based Index Structures
  - Extensible Hash Tables
  - Linear Hash Tables
- Tree-based Index Structures
  - B+ Trees

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Q&A

当B+树进行删除操作时,若一个节点不足半满,是优先向左兄弟借,还是优先向右兄弟借呢?

答: 都可以,取决于B+树的具体实现方法。

