

Ant Colony Optimization

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Swarm Intelligence

Short introduction and examples

What is swarm intelligence

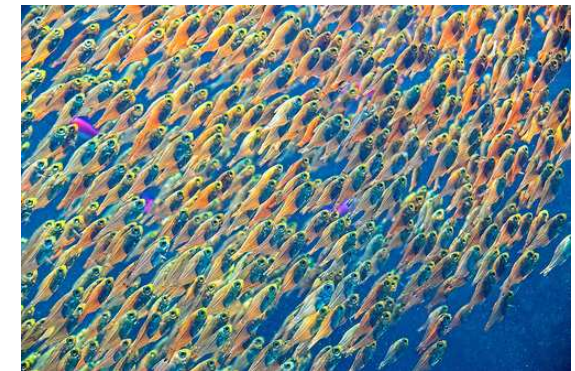
In a nutshell: AI discipline whose goal is designing intelligent multi-agent systems by taking inspiration from the collective behaviour of animal societies such as ant colonies, flocks of birds, or fish schools



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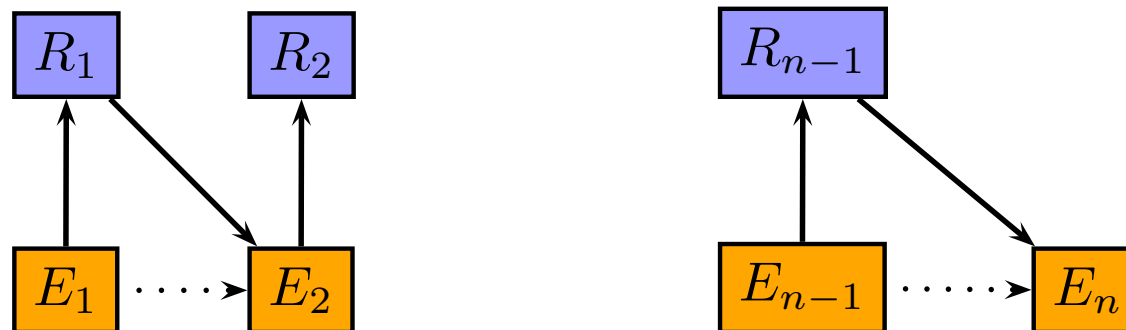


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Swarm intelligence

Properties:

- ▶ Consist of a set of simple entities
- ▶ Distributedness: No global control
- ▶ Self-organization by:
 - ★ **Direct communication:** visual, or chemical contact
 - ★ **Indirect communication:** Stigmergy (Grassé, 1959)



Result: Complex tasks/behaviors can be accomplished/exhibited in cooperation

Swarm intelligence

Examples of social insects:

- ▶ Ants
- ▶ Termites
- ▶ Some wasps and bees



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Ant Colony Optimization

A metaheuristics for optimization

Inspiration of ACO (1)

Communication strategies:

- ▶ **Direct communication:** For example, recruitment
- ▶ Indirect communication: via chemical pheromone trails



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Inspiration of ACO (2)

Communication strategies:

- ▶ Direct communication: For example, recruitment
- ▶ Indirect communication: via chemical pheromone trails

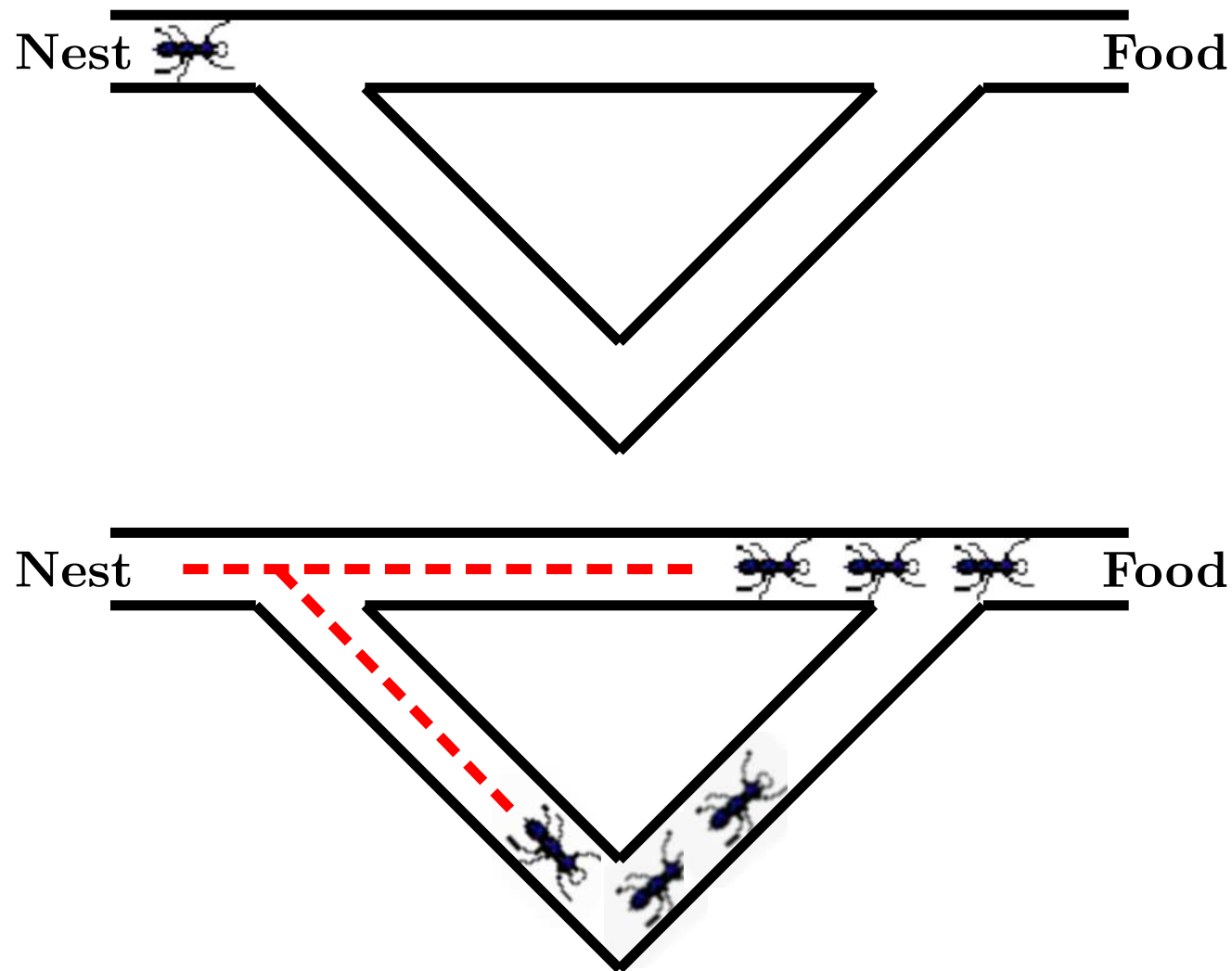
Basic behaviour:



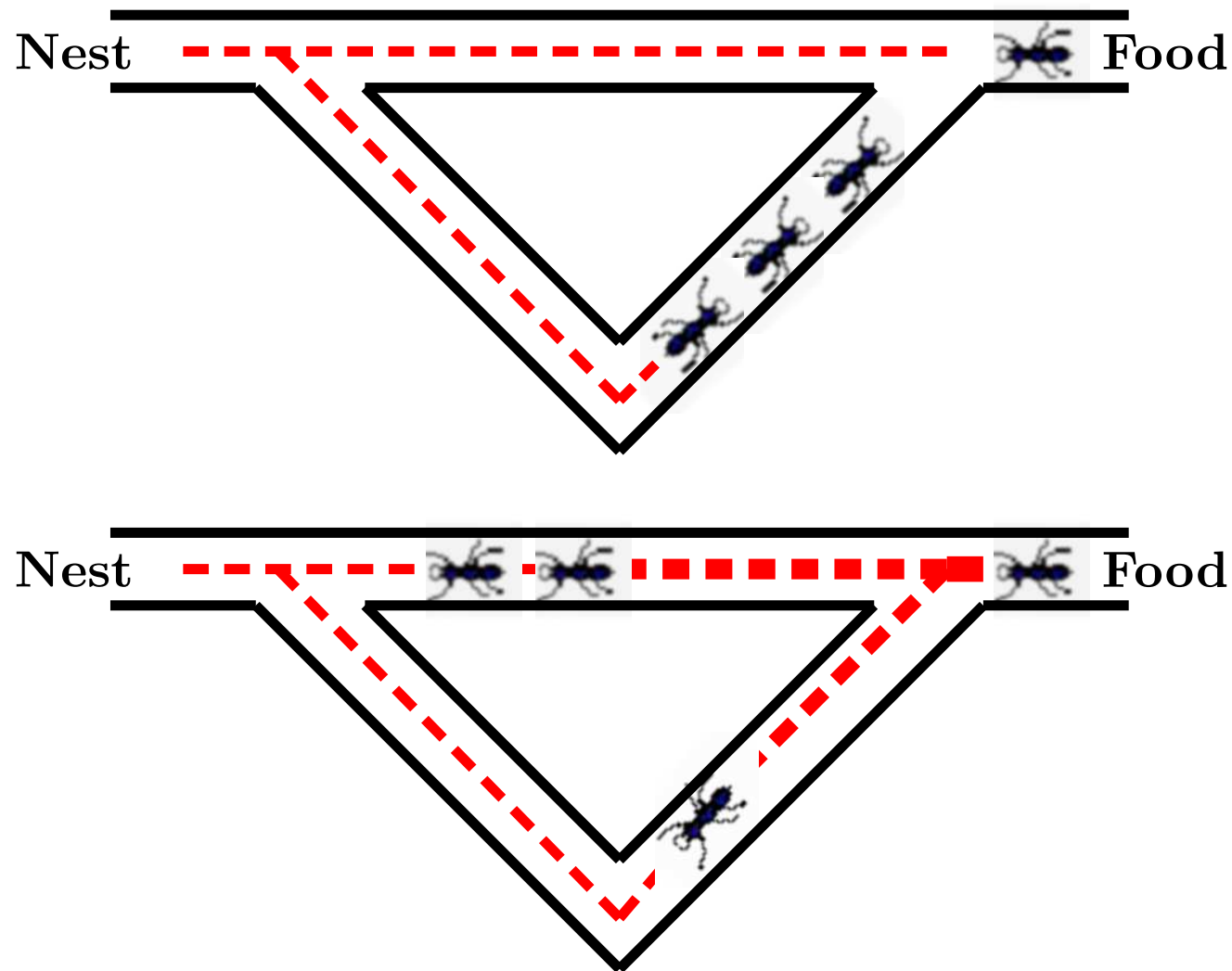
Inspiration of ACO (3)



Inspiration of ACO: double-bridge experiment (1)



Inspiration of ACO: double-bridge experiment (2)

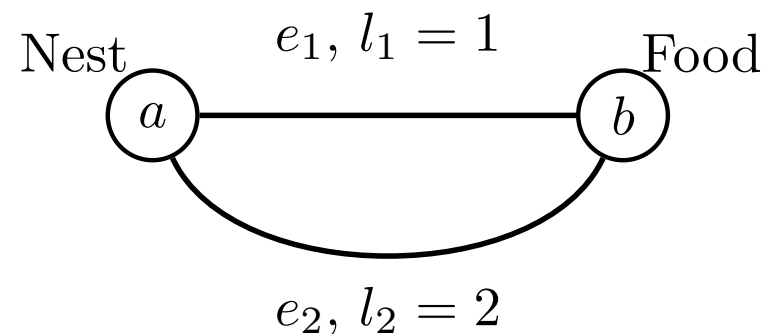


The ant colony optimization metaheuristic

- ▶ Simulation of the foraging behaviour
- ▶ The ACO metaheuristic
- ▶ Example: traveling salesman problem (TSP)
- ▶ A closer look at algorithm components

Simulation of the foraging behaviour (1)

Technical simulation:



1. We introduce artificial pheromone parameters:

\mathcal{T}_1 for e_1 and \mathcal{T}_2 for e_2

2. We initialize the pheromone values:

$$\tau_1 = \tau_2 = c > 0$$

Simulation of the foraging behaviour (2)

Algorithm:

Iterate:

1. Place n_a ants in node a .
2. Each of the n_a ants traverses from a to b either
 - ▶ via e_1 with probability $\mathbf{p}_1 = \frac{\tau_1}{\tau_1 + \tau_2}$,
 - ▶ or via e_2 with probability $\mathbf{p}_2 = 1 - \mathbf{p}_1$.
3. Evaporate the artificial pheromone: $i = 1, 2$

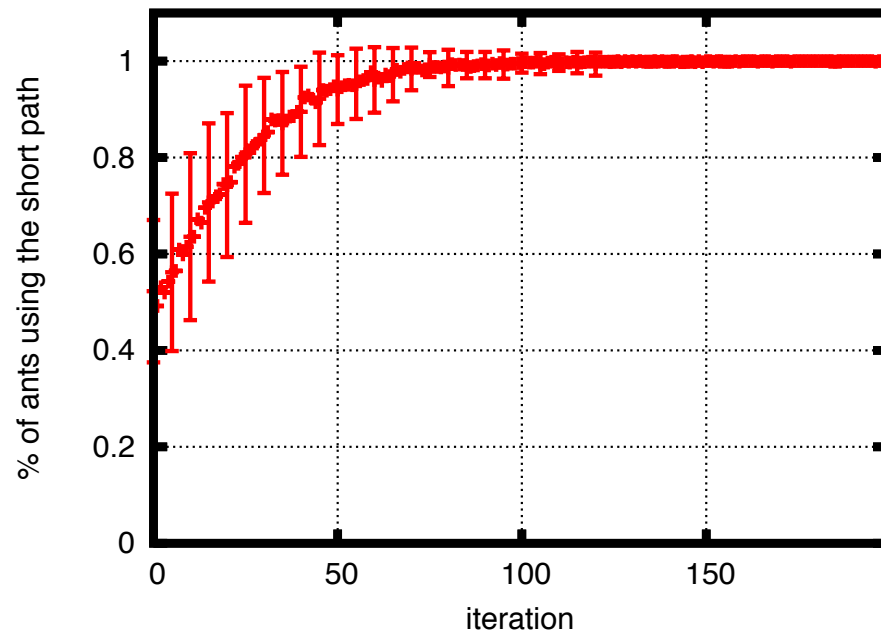
$$\tau_i \leftarrow (1 - \rho)\tau_i, \rho \in (0, 1]$$

4. Each ant leaves pheromone on its traversed edge e_i :

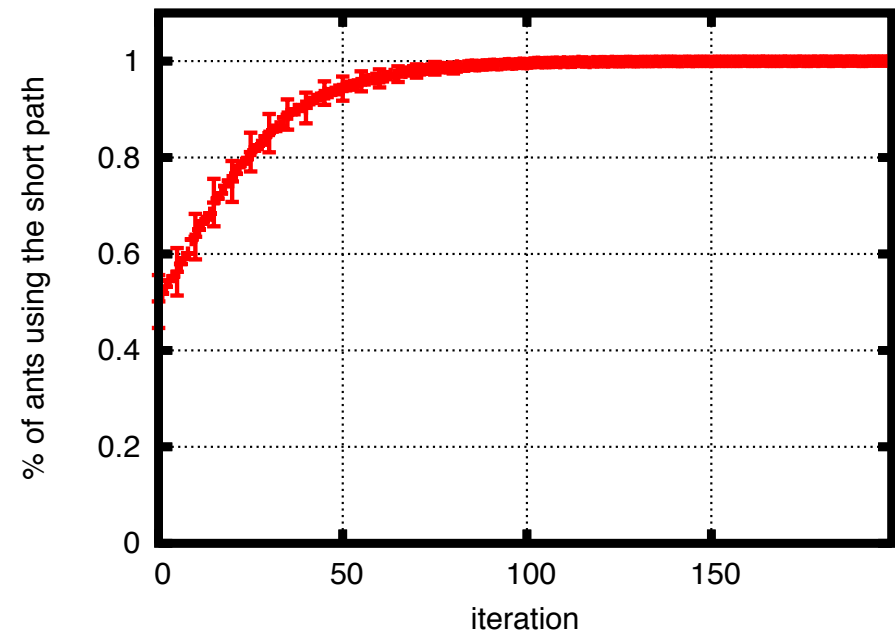
$$\tau_i \leftarrow \tau_i + \frac{1}{l_i}$$

Simulation of the foraging behaviour (3)

Simulation results:



Colony size: 10 ants



Colony size 100 ants

Observation: Optimization capability is due to co-operation

Simulation of the foraging behaviour (4)

Main differences between model and reality:

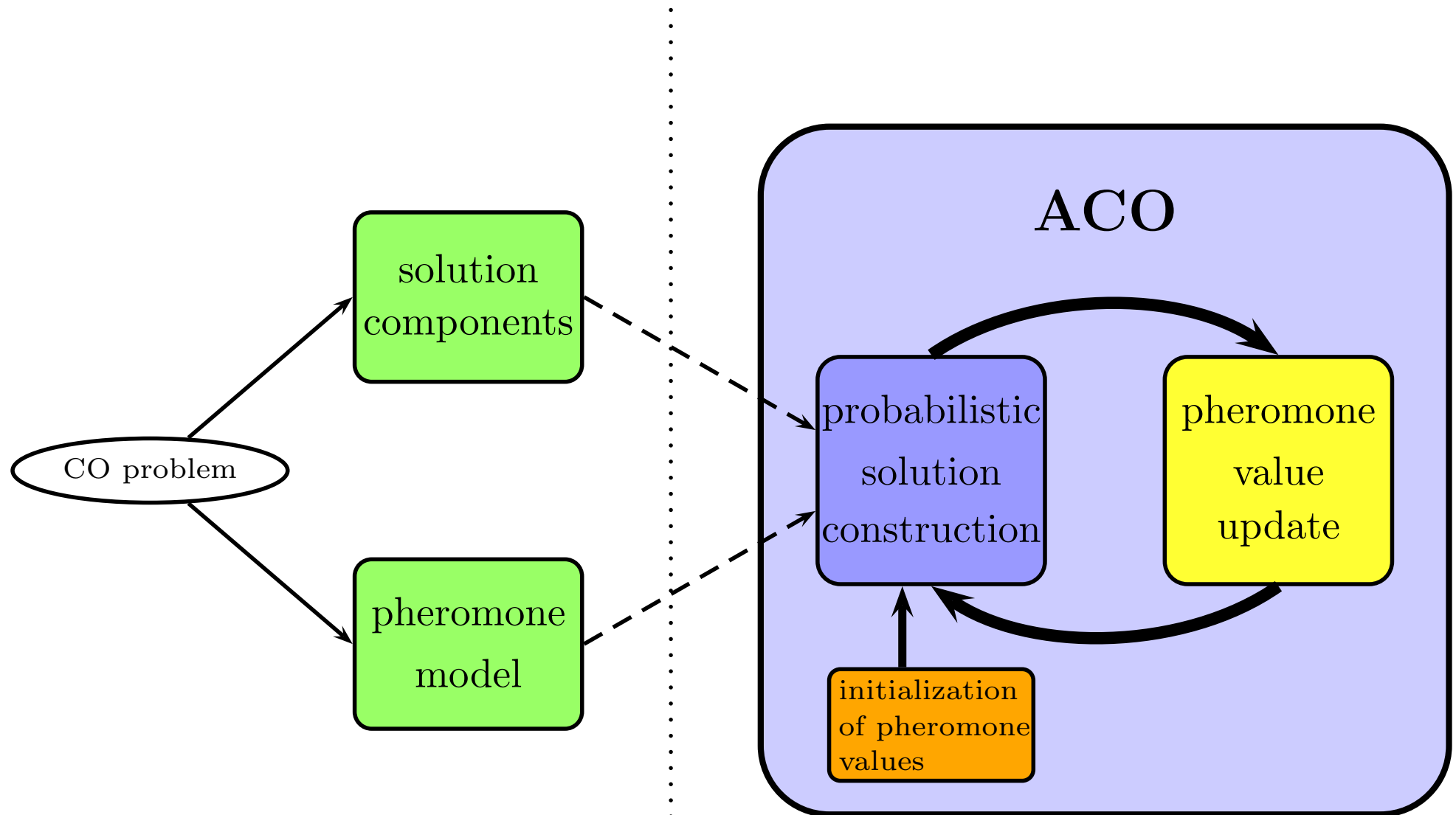
	Real ants	Simulated ants
Ants' movement	asynchronous	synchronized
Pheromone laying	while moving	after the trip
Solution evaluation	implicitly	explicit quality measure

Problem: In combinatorial optimization we want to find good solutions

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The ACO framework



The ACO pseudocode

input: An instance P of a combinatorial problem \mathcal{P} .

InitializePheromoneValues(\mathcal{T})

while termination conditions not met **do**

$S_{iter} \leftarrow \emptyset$

for $j = 1, \dots, n_a$ **do**

$s \leftarrow \text{ConstructSolution}(\mathcal{T})$

$s \leftarrow \text{LocalSearch}(s)$ — optional —

$S_{iter} \leftarrow S_{iter} \cup \{s\}$

end for

 ApplyPheromoneUpdate(\mathcal{T})

end while

output: The best solution found

Metaheuristics: Timeline of their introduction

Metaheuristics:

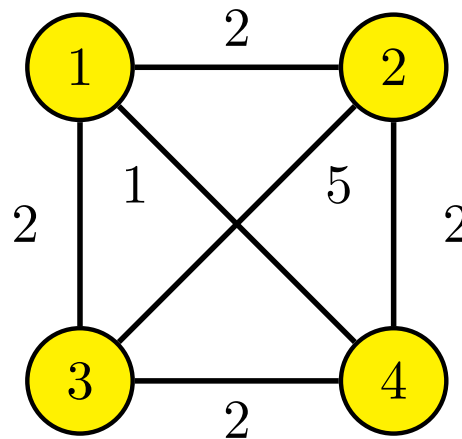
- ▶ Simulated Annealing (SA) [Kirkpatrick, 1983]
- ▶ Tabu Search (TS) [Glover, 1986]
- ▶ Genetic and Evolutionary Computation (EC) [Goldberg, 1989]
- ▶ **Ant Colony Optimization (ACO) [Dorigo, 1992]**
- ▶ Greedy Randomized Adaptive Search Procedure (GRASP) [Resende, 1995]
- ▶ Particle Swarm Optimization (PSO) [Kennedy, 1995]
- ▶ Guided Local Search (GLS) [Voudouris, 1997]
- ▶ Iterated Local Search (ILS) [Stützle, 1999]
- ▶ Variable Neighborhood Search (VNS) [Mladenović, 1999]

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TSP: definition (1)

Example: Traveling salesman problem (TSP). Given a completely connected, undirected graph $G = (V, E)$ with edge-weights.



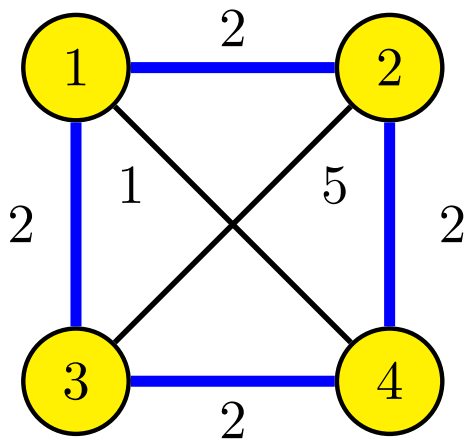
Goal:

Find a tour (a Hamiltonian cycle) in G with minimal sum of edge weights.

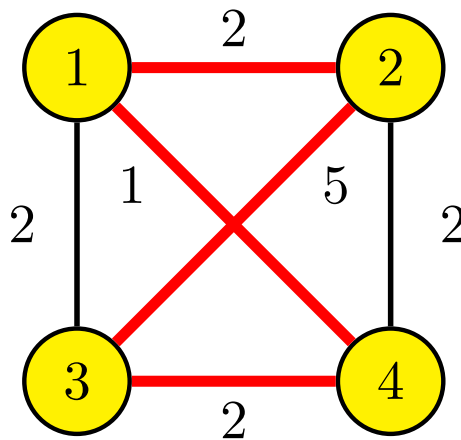
TSP definition (2)

TSP in terms of a combinatorial optimization problem $\mathcal{P} = (\mathcal{S}, f)$:

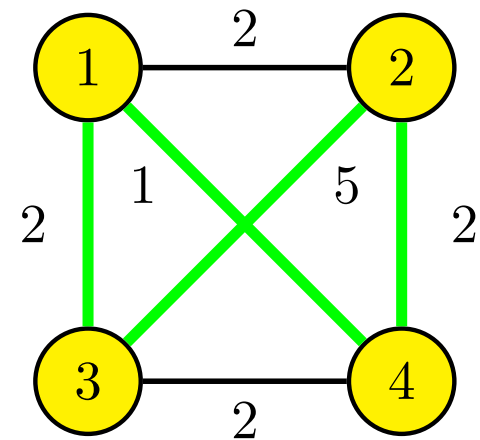
- ▶ \mathcal{S} consists of all possible Hamiltonian cycles in G .
- ▶ Objective function $f : \mathcal{S} \mapsto \mathbb{R}^+$: $s \in \mathcal{S}$ is defined as the sum of the edge-weights of the edges that are in s .



obj. function value: 8



obj. function value: 10



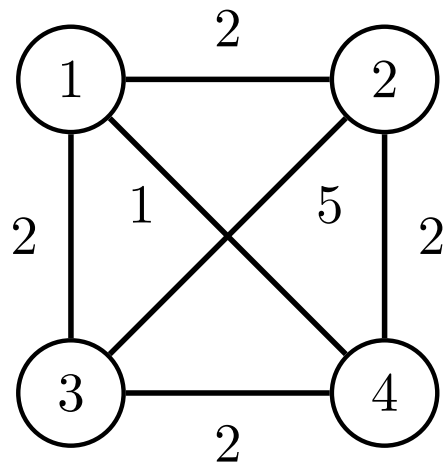
obj. function value: 10

Applying ACO to the TSP

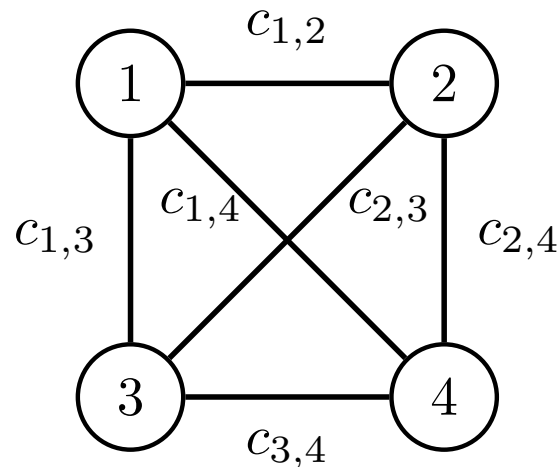
Preliminary step: Definition of the

- ▶ solution components
- ▶ pheromone model

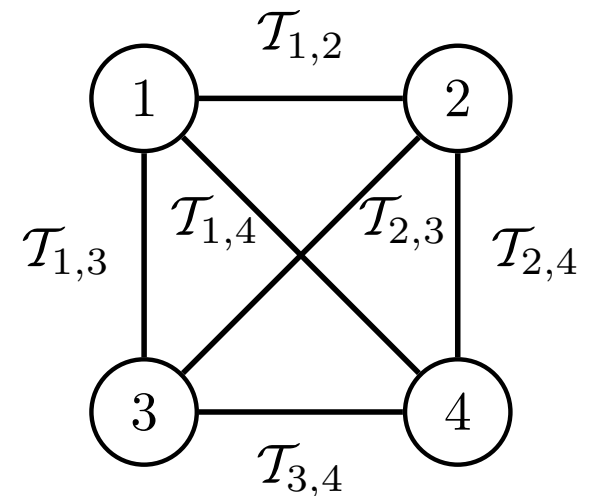
example instance



solution components



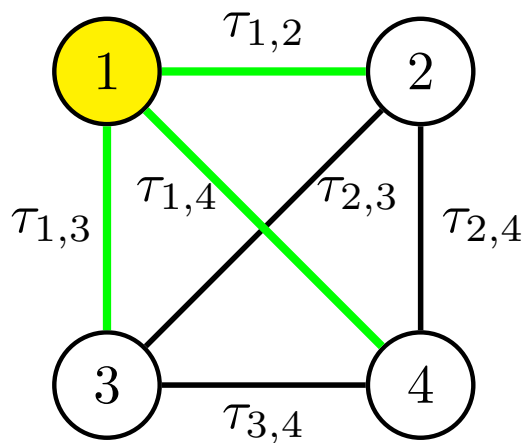
pheromone model



TSP: solution construction

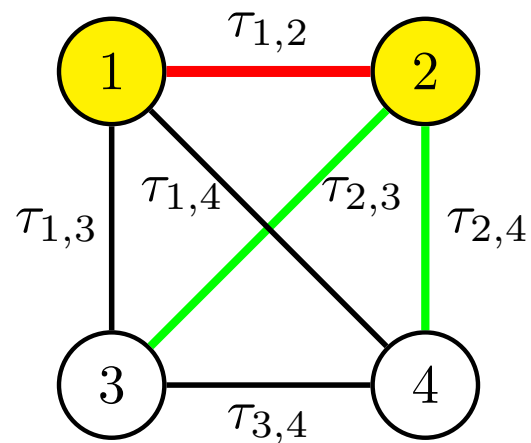
Tour construction:

Step 1



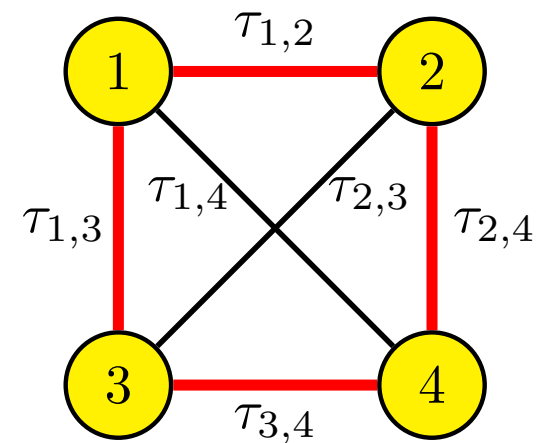
$$p(c_{i,j}) = \frac{\tau_{i,j}}{\tau_{1,2} + \tau_{1,3} + \tau_{1,4}}$$

Step 2



$$p(c_{i,j}) = \frac{\tau_{i,j}}{\tau_{2,3} + \tau_{2,4}}$$

Finished



TSP: pheromone update (1)

Pheromone update: For example with the Ant System (AS) update rule

Pheromone evaporation

$$\tau_{i,j} \leftarrow (1 - \rho) \cdot \tau_{i,j}$$

Reinforcement

$$\tau_{i,j} \leftarrow \tau_{i,j} + \rho \cdot \sum_{\{s \in S_{iter} \mid c_{i,j} \in s\}} F(s)$$

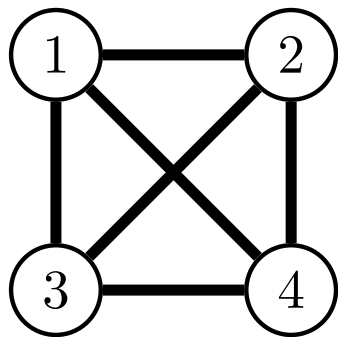
where

- ▶ evaporation rate $\rho \in (0, 1]$
- ▶ S_{iter} is the set of solutions generated in the current iteration
- ▶ quality function $F : S \mapsto \mathbb{R}^+$. We use $F(\cdot) = \frac{1}{f(\cdot)}$

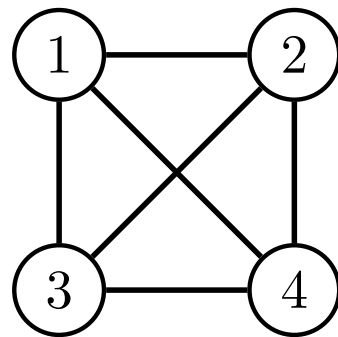
TSP: pheromone update (2)

Pheromone update: For example with the Ant System (AS) update rule

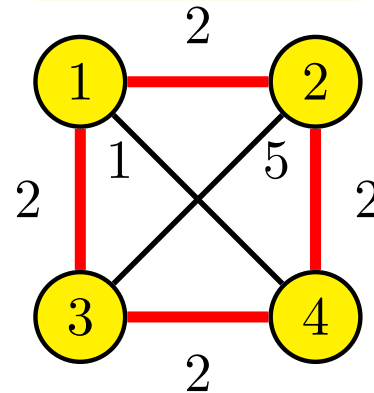
start



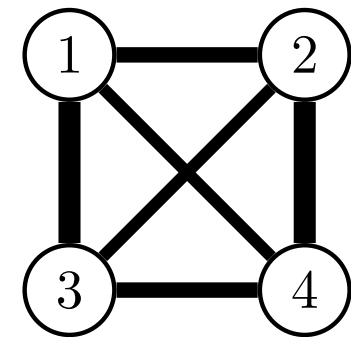
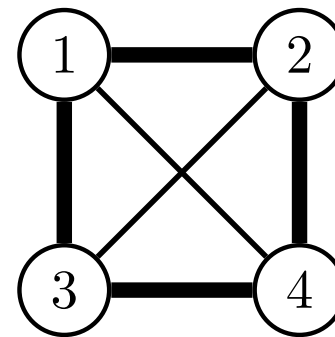
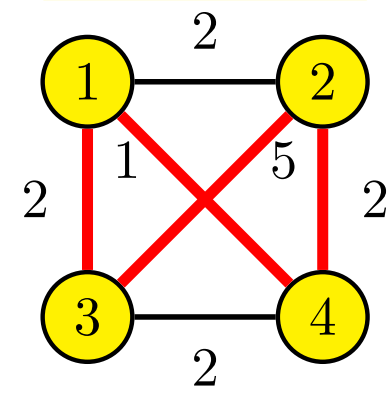
evaporation



solution s_1



solution s_2

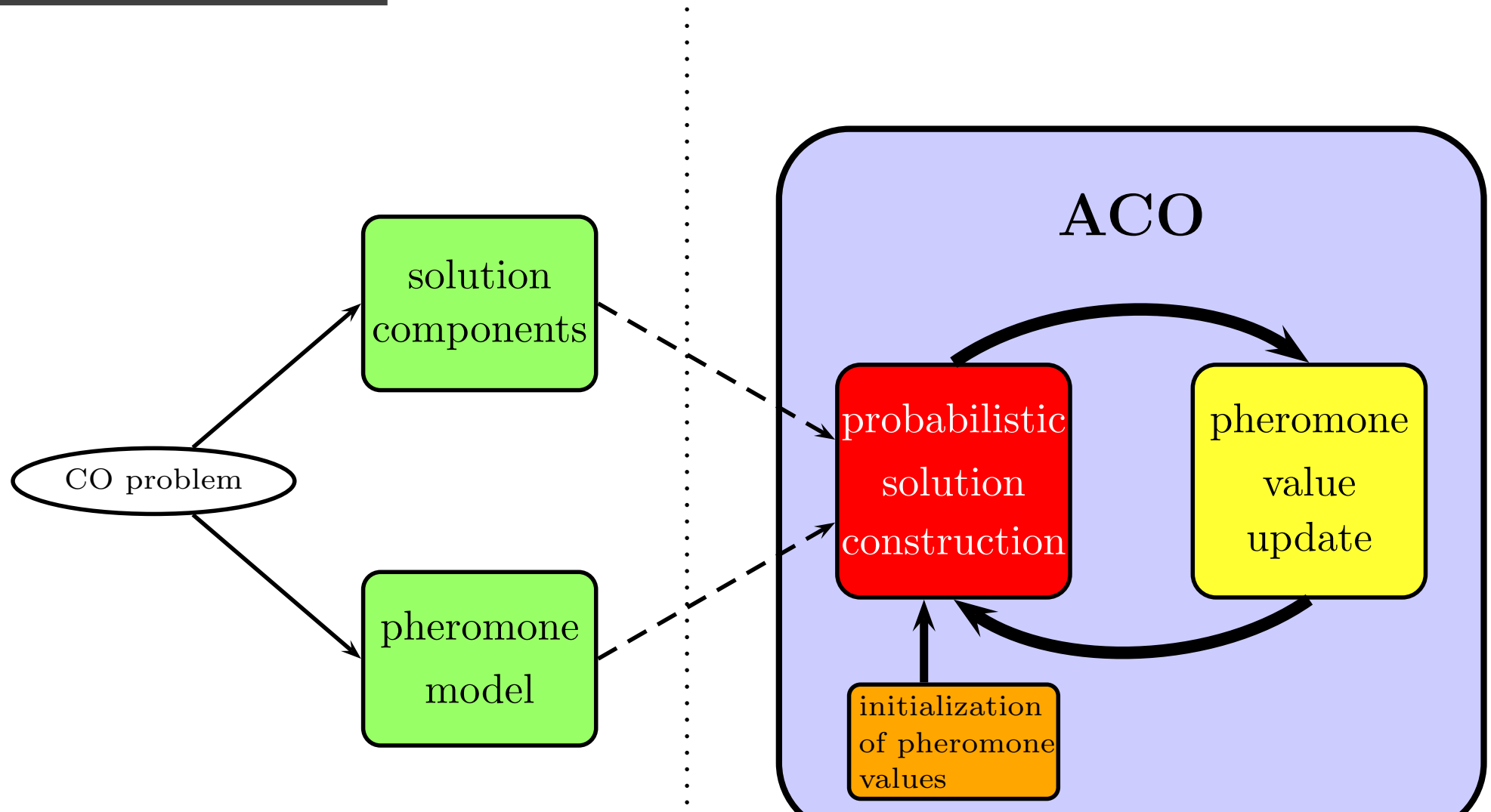


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Solution construction (1)

Solution construction: A closer look



Solution construction (2)

A general constructive heuristic:

- ▶ $s^p = \langle \rangle$
- ▶ Determine $N(s^p)$
- ▶ **while** $N(s^p) \neq \emptyset$
 - ★ $c \leftarrow \text{ChooseFrom}(N(s^p))$
 - ★ $s^p \leftarrow$ extend s^p by adding solution component c
 - ★ Determine $N(s^p)$
- ▶ **end while**

Problem: How to implement function $\text{ChooseFrom}(N(s^p))$?

Solution construction (3)

Possibilities for implementing ChooseFrom($N(s^p)$):

- ▶ Greedy algorithms:

$$c^* = \operatorname{argmax}_{c_{i,j} \in N(s^p)} \eta(c_{i,j}) \ ,$$

where $\eta : C \mapsto \mathbb{R}^+$ is a Greedy function

Examples for Greedy functions:

- ▶ TSP: Inverse distance between nodes (i.e., cities)
- ▶ SALB: t_i/C

Solution construction (4)

Possibilities for implementing $\text{ChooseFrom}(N(s^p))$:

- ▶ Ant colony optimization:

$$\mathbf{p}(c_{i,j} \mid s^p) = \frac{[\tau_{i,j}]^\alpha \cdot [\eta(c_{i,j})]^\beta}{\sum_{c_{k,l} \in N(s^p)} [\tau_{k,l}]^\alpha \cdot [\eta(c_{k,l})]^\beta}, \quad \forall c_{i,j} \in N(s^p),$$

where α and β are positive values

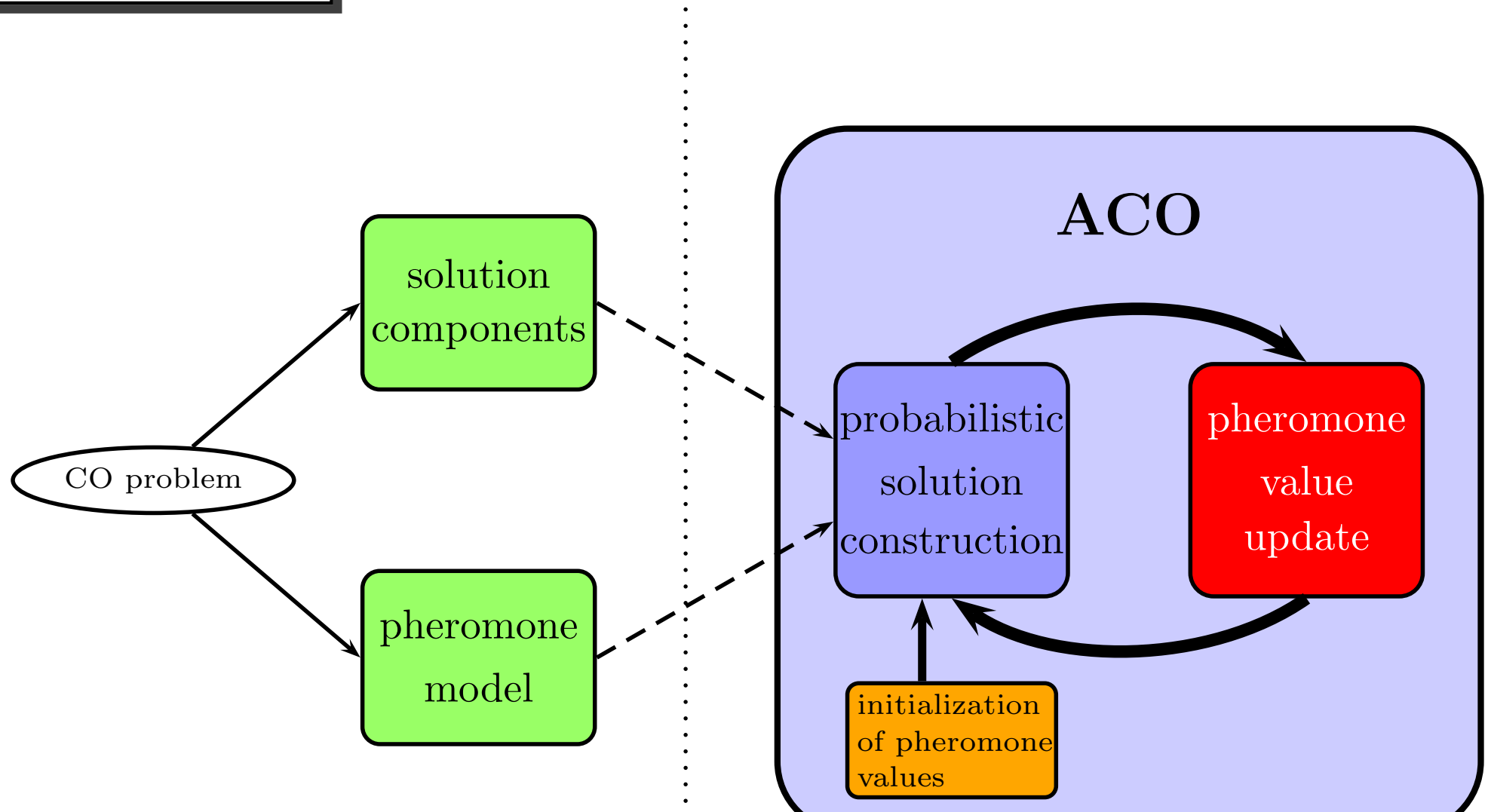
Note: α and β balance between pheromone information and Greedy function

Observations:

- ▶ ACO can be applied if a constructive heuristic exists!
- ▶ ACO can be seen as an iterative, adaptive Greedy algorithm

Pheromone update (1)

Pheromone update: A closer look



Pheromone update (2)

A general update rule:

$$\tau_{i,j} \leftarrow (1 - \rho) \cdot \tau_{i,j} + \rho \cdot \sum_{\{s \in S_{upd} \mid c_{i,j} \in s\}} w_s \cdot F(s) ,$$

where

- ▶ evaporation rate $\rho \in (0, 1]$
- ▶ S_{upd} is the set of solutions used for the update
- ▶ quality function $F : S \mapsto \mathbb{R}^+$. We use $F(\cdot) = \frac{1}{f(\cdot)}$
- ▶ w_s is the weight of solution s

Question: Which solutions should be used for updating?

Pheromone update (3)

ACO update variants:

AS-update	$S_{upd} \leftarrow S_{iter}$ <u>weights:</u> $w_s = 1 \ \forall s \in S_{upd}$
elitist AS-update	$S_{upd} \leftarrow S_{iter} \cup \{s_{bs}\}$ (s_{bs} is best found solution) <u>weights:</u> $w_s = 1 \ \forall s \in S_{iter}, w_{s_{bs}} = e \geq 1$
rank-based AS-update	$S_{upd} \leftarrow$ best $m - 1$ solutions of $S_{iter} \cup \{s_{bs}\}$ (ranked) <u>weights:</u> $w_s = m - r$ for solutions from $S_{iter}, w_{s_{bs}} = m$
IB-update:	$S_{upd} \leftarrow \operatorname{argmax}\{F(s) \mid s \in S_{iter}\}$ <u>weight</u> 1
BS-update:	$S_{upd} \leftarrow \{s_{bs}\}$ <u>weight</u> 1

Successful ACO variants

- ▶ Ant Colony System(ACS) [Dorigo, Gambardella, 1997]

M. Dorigo and L. M. Gambardella. **Ant colony system: a cooperative learning approach to the traveling salesman problem.** *IEEE Trans. Evolutionary Computation*, 1(1), 53–66, 1997

- ▶ $MAX-MIN$ Ant System($MMAS$) [Stützle, Hoos, 2000]

T. Stützle and H. H. Hoos. **MAX-MIN Ant System.** *Future Generation Computer Systems*, 16(8), 889–914, 2000

- ▶ The hyper-cube framework (HCF) for ACO [Blum, Dorigo, 2004]

C. Blum and M. Dorigo. **The hyper-cube framework for ant colony optimization.** *IEEE Transactions on Systems, Man, and Cybernetics, Part B*, 34(2), 1161–1172, 2004

- ▶ Population-based ACO (P-ACO) [Guntzsch, Middendorf, 2002]

M. Guntzsch and M. Middendorf. **A population based approach for ACO.** In: *Proceedings of EvoWorkshops 2002*, Springer LNCS, pages 71–80, 2002