

Basic representation of gridworld

s : State =

type **Object** =

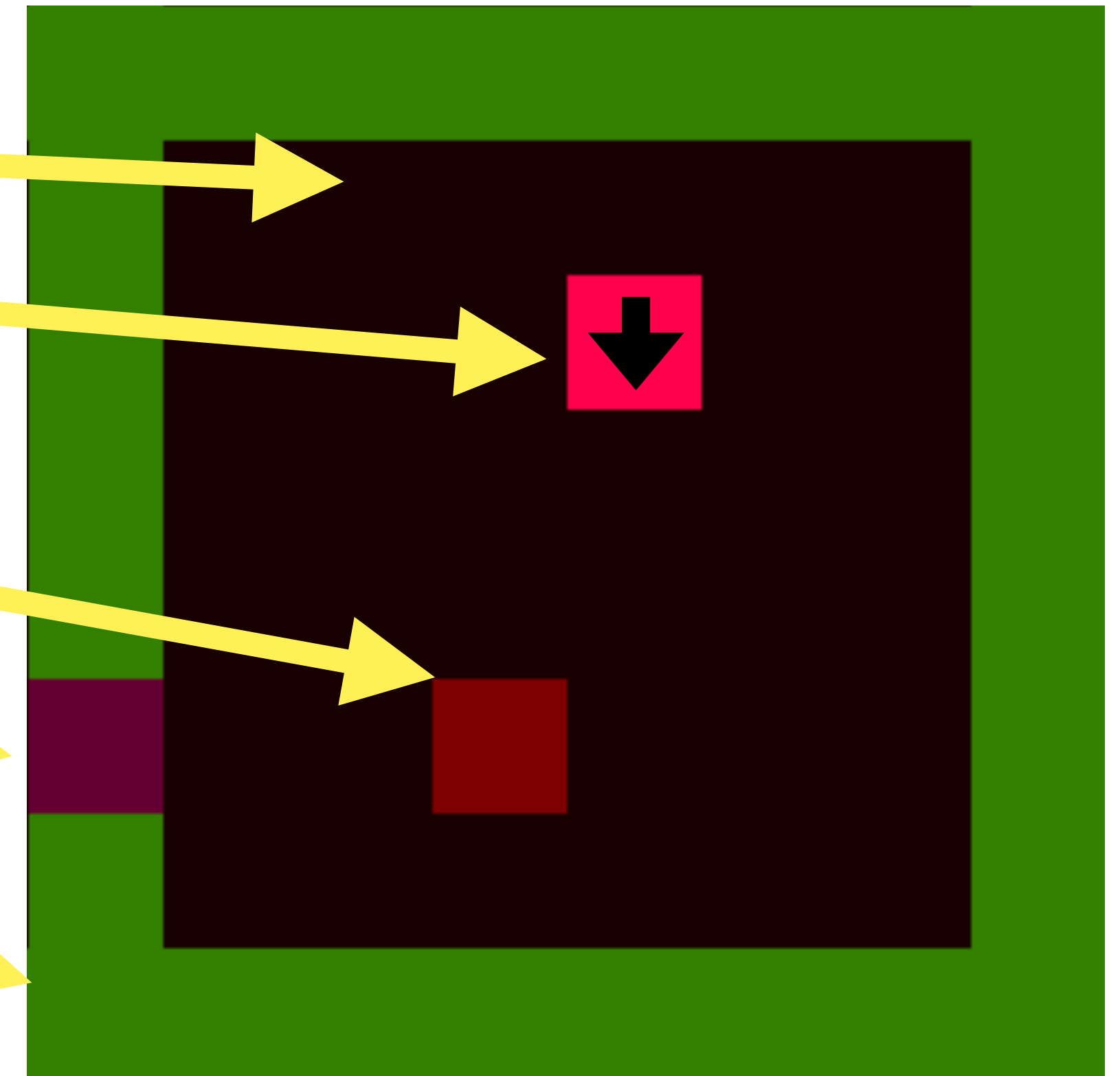
{ empty,
agent,
key,
door,
wall }

type **Action** =

{ start, forward, left, right, pickup, toggle }

feature **Action** : State -> Action

e.g. Action(s) = start



Bird's-eye features

type **Quadrant** = {1,2,3,4}

type **Orientation** = {N,E,S,W}

feature **AgentQuad** : State -> Quadrant

e.g. AgentQuad(s) = 2

feature **KeyQuad** : State -> Quadrant

e.g. KeyQuad(s) = 3

feature **DoorQuad** : State -> Quadrant

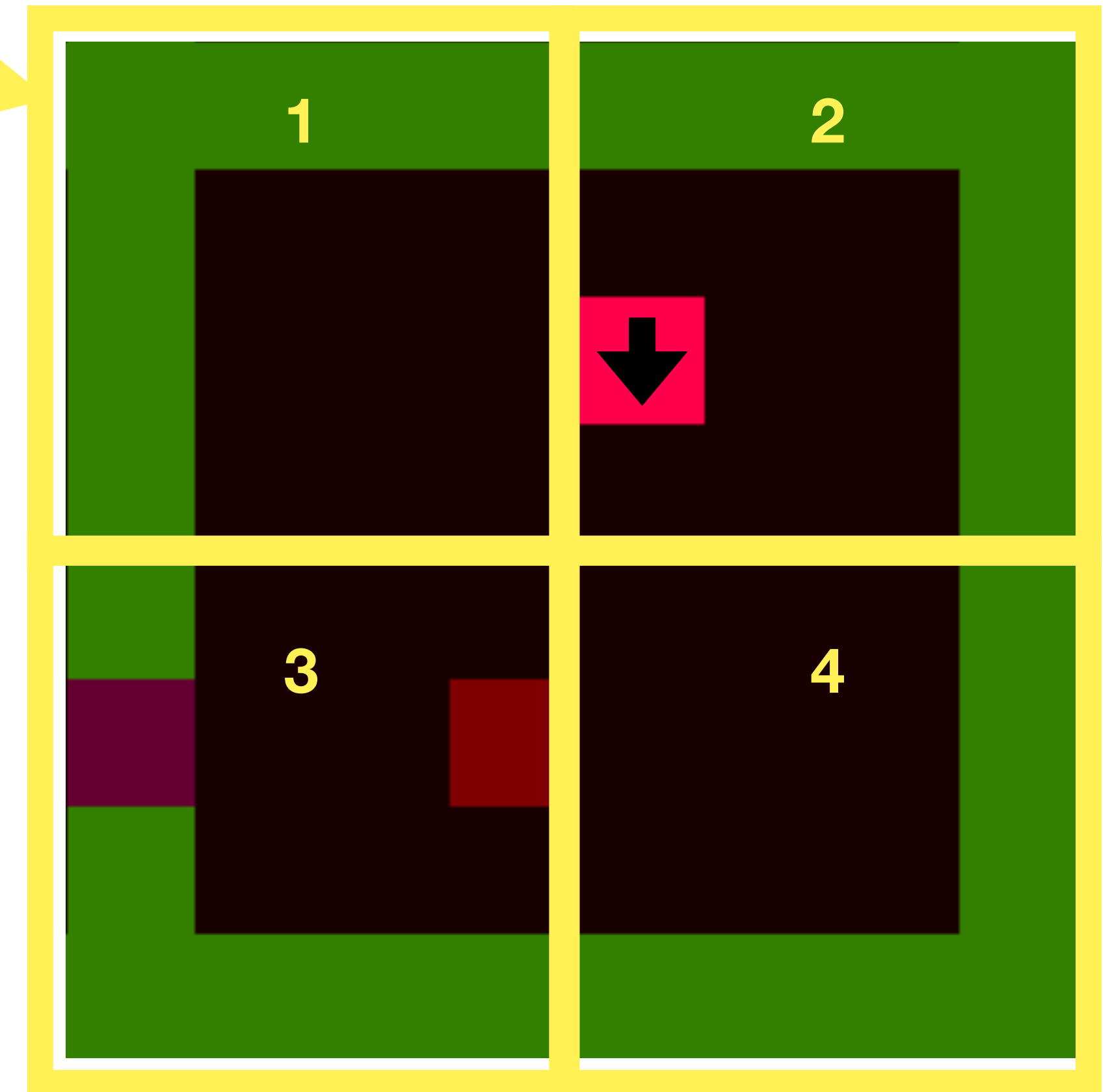
e.g. DoorQuad(s) = 3

feature **Orientation** : State -> Orientation

e.g. Orientation(s) = S

quadrant

s : State =



First-person features

Features capturing the contents of the squares surrounding the agent:

feature *AgentInFront* : State -> Object

feature *AgentLeft* : State -> Object

feature *AgentRight* : State -> Object

feature *AgentBehind* : State -> Object

feature *AgentInFrontLeft* : State -> Object

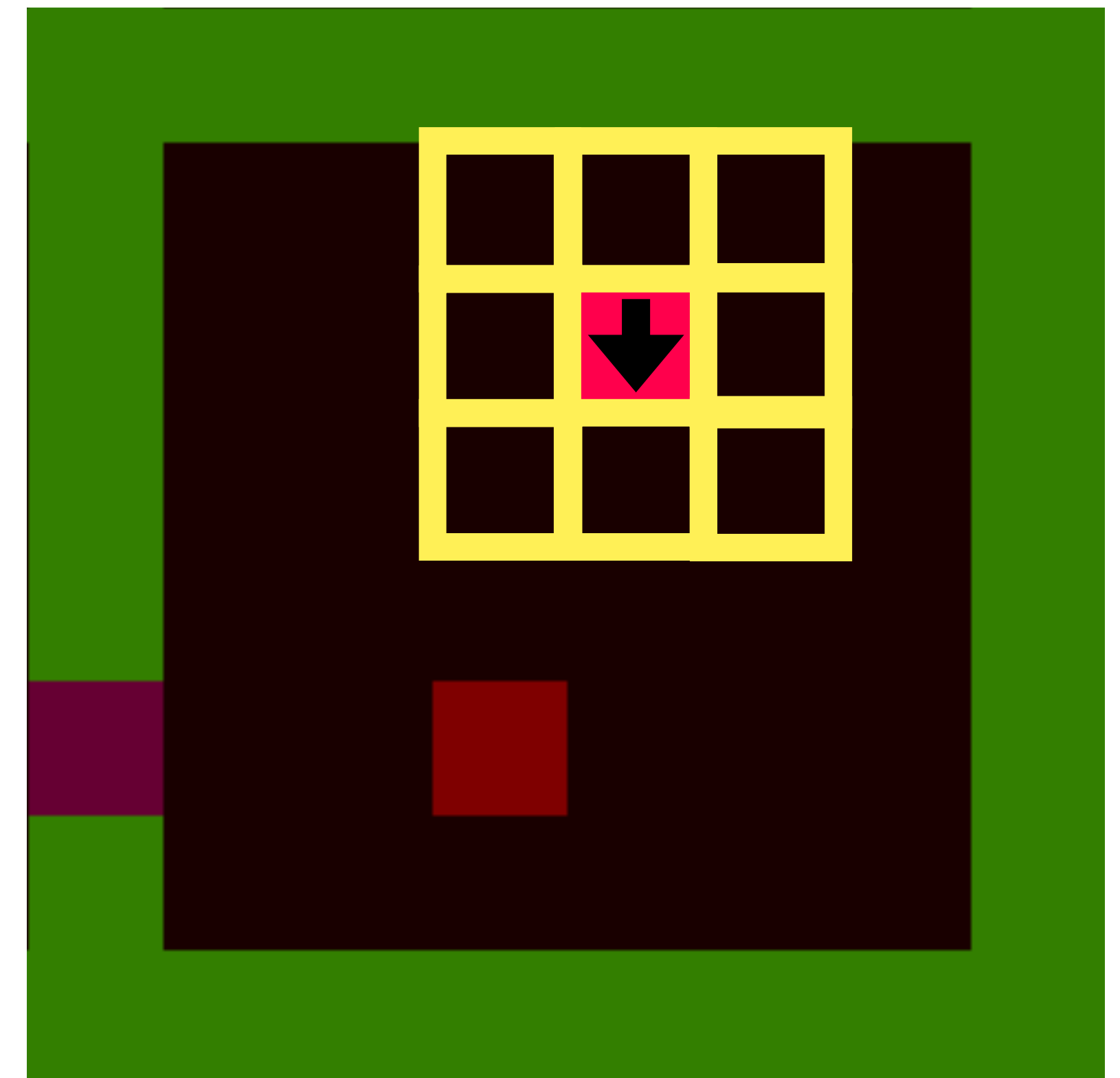
feature *AgentInFrontRight* : State -> Object

feature *AgentBehindLeft* : State -> Object

feature *AgentBehindRight* : State -> Object

e.g. *AgentInFront*(s) = empty

s : State =



Other viewpoints

Features capturing the basic relationship between agent, door, key and the far wall.

viewpoint *CanSeeKey* : State -> Bool

CanSeeKey(s) = true

viewpoint *CanSeeDoor* : State -> Bool

CanSeeDoor(s) = true

viewpoint *Distance* : State -> Integer

Distance(s) = 4

s : State =

