Parameterization

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Barycentric Mapping

Introduction

According to Tuttear's barycentric mapping theorem,

Given a triangulated surface homeomorphic to a disk, if the (u, v) coordinates at the boundary vertices lie on a convex polygon, and if the coordinates of the internal vertices are a convex combination of their neighbors, then the (u, v) coordinates form a valid parameterization (without self-intersections).

$$\forall i \in 1, 2, ..., n_{in}, \qquad -a_{i,i} \begin{pmatrix} u_i \\ v_i \end{pmatrix} = \sum_{j \neq i} a_{i,j} \begin{pmatrix} u_i \\ v_i \end{pmatrix}$$

Implement

- 1. judge whether the model is a patch
- 2. build half-edge structure
- 3. get the boundary edges and the texture coordinates of the boundary vertices
- 4. get the texture coordinates of the inner vertices

Result

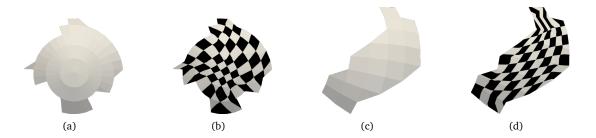


Figure 1: barycentering mapping, a and c are origin models, b and d are models with texture coordinates

Least Squares Conformal Mapping

Introduction

Conformal mapping: the anisotropy ellipse is a circle for all points of the surface.

$$\mathbf{x}_{i} = \frac{\mathbf{x}_{j} - \mathbf{x}_{i}}{\|\mathbf{x}_{j} - \mathbf{x}_{i}\|}$$

$$\mathbf{x}_{i} = \frac{\mathbf{X} \times (\mathbf{x}_{k} - \mathbf{x}_{i})}{\|\mathbf{X} \times (\mathbf{x}_{k} - \mathbf{x}_{i})\|}$$

$$\mathbf{y} = \mathbf{n} \times \mathbf{X}$$
(a)
(b)

Figure 2: a: mapping X to u. b: local X, Y basis in a triangle

Conformal condition: $\boldsymbol{X}_{\mu} = \boldsymbol{n} \times \boldsymbol{X}_{u}$, $\nabla \mu = \boldsymbol{n} \times \nabla u$

$$\nabla u = \begin{bmatrix} \frac{\partial u}{\partial X} \\ \frac{\partial u}{\partial Y} \end{bmatrix} = \underbrace{\frac{1}{2A_T} \begin{bmatrix} Y_j - Y_k & Y_k - Y_i & Y_i - Y_j \\ X_k - X_j & X_i - X_k & X_j - X_i \end{bmatrix}}_{=\mathbf{M}_T} \begin{pmatrix} u_i \\ u_j \\ u_k \end{pmatrix}$$

conformal condition,

$$\nabla v = (\nabla u)^{\perp} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \nabla u$$

$$\mathbf{M}_T \begin{pmatrix} v_i \\ v_j \\ v_k \end{pmatrix} - \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \mathbf{M}_T \begin{pmatrix} u_i \\ u_j \\ u_k \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

energe to be optimed,

$$E_{\text{LSCM}} = \sum_{T=(i,j,k)} A_T \left\| \mathbf{M}_T \begin{pmatrix} v_i \\ v_j \\ v_k \end{pmatrix} - \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \mathbf{M}_T \begin{pmatrix} u_i \\ u_j \\ u_k \end{pmatrix} \right\|^2$$

$$E_{\text{LSCM}} = \sum_{T=(i,j,k)} \left\| \sqrt{A_T} \mathbf{M}_T \begin{pmatrix} v_i \\ v_j \\ v_k \end{pmatrix} - \sqrt{A_T} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \mathbf{M}_T \begin{pmatrix} u_i \\ u_j \\ u_k \end{pmatrix} \right\|^2$$

Implement

- 1. get trianlge area and construct triangle transformation matrix
- 2. fix two vertices in parameter domain in order to reduce the degrees
- 3. construct global coefficient matrix and sparse equations
- 4. solver sparse equation though QR decomposition

Result

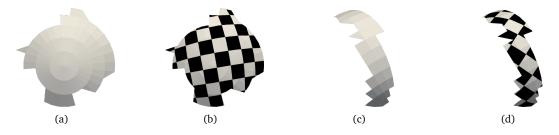


Figure 3: barycentering mapping, a and c are origin models, b and d are models with texture coordinates