

# Nisan Kotik

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## Professional Summary

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MEng Aerospace Engineering student from the University of Bath with a successful year-long placement at Moog Controls. Demonstrated hands-on experience in mechanical design, stress analysis (Ansys), and simulation (Python). Proven ability to lead design projects, manage complex assemblies in Teamcenter, and develop custom software solutions. Eager to apply a strong technical foundation and a collaborative mindset to solve complex challenges in a fast-paced, technical environment.

## Education

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**University of Bath** - MEng Aerospace Engineering *Sept 2021 – June 2026*

**Hinchley Wood Sixth Form** *Sept 2018 – Aug 2020*

- A-Levels: Further Mathematics, Mathematics, Physics

## Technical Skills

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**Engineering Software:** Siemens NX, Ansys, AutoCAD, Inventor Pro.

**Programming Languages:** Python, C, MATLAB

**Machine learning frameworks:** Darknet, TensorFlow.

**Development Tools:** Teamcenter, Git, Linux

## Professional Experience

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**Mechanical Engineering Placement, Research and Development** *Aug 2023 – Sept 2024*  
**Moog Controls Ltd**, Tewkesbury, UK

### *Design Engineer Lead*

- Led the mechanical design of a novel levelling platform for a semi-autonomous mobile solar panel lift-assist system (“CrewMate”).
- Managed the mechanical design from concept and prototyping through manufacturing and delivery, ensuring the final product could withstand up to 2 tonnes of force.
- Coordinated with an international team, including a U.S.-based division, to integrate the new platform into existing machinery.
- Utilised Siemens NX for 3D design and Ansys for stress analysis, delivering over 50 new part drawings. Managed configuration for an assembly of over 200 parts in Teamcenter.

### *Excavator Mechanics Simulation*

- Developed a predictive simulation in Python to model excavator mechanics, optimise design configurations, and inform key design decisions.
- The model identified a novel configuration resulting in a 15 percent improvement in force demand.
- This analytical tool is now used as a design benchmark for future development.

### ***Automated Production Rig***

- Identified an inefficiency in production and engineered an automated solution, designing a vacuum degassing rig to improve operational workflow.
- Programmed an Arduino in C for automated processes, implementing over 10 functions including time settings and emergency abort.
- Integrated the system with hardware such as solenoid valves and relay switches. The initiative demonstrates a clear ability to optimize processes for time and cost savings.

## **Personal Projects**

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### **Basketball Object Detection**

- Developed a Python path-tracking programme using OpenCV and YOLOv4 to detect, track, and trace basketball motion.
- Utilised the NVIDIA CUDA environment to take advantage of the laptop's Nvidia 1660Ti GPU.
- Significantly improved model precision (mAP) compared to existing models by training on over 2000 labelled images and optimising for small objects.
- Built a strong foundation in machine learning for computer vision and eager to apply this knowledge professionally.

### **Business Venture**

*2020-2021*

- Launched and managed a start-up retail business selling mystery boxes with random football shirts from around the world.
- **Business Operations & Financial Metrics:** Achieved over 100 sales within the first 6 months during the Covid-19 period.
- **Revenue Model & Customer Retention:** Implemented a hybrid one-time purchase and subscription model, securing a 20 percent customer conversion rate to the subscription and building a recurring revenue stream.
- Applied project management skills to lead a small team and establish sales targets, and foster an inclusive environment that encouraged collaborative brainstorming and idea generation.

## **Personal Interests and Languages**

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I enjoy playing basketball recreationally at the university.

I enjoy reading literature, particularly science fiction by authors like Cixin Liu that explores themes of technology and its future impact.

**Languages:** English – Native, Russian – Native.