

# KISHAN REDDY NAGIREDLA

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## SUMMARY

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A highly motivated and hard-working PhD. candidate with a strong background in Robotics and Mechatronics Engineering, seeking to apply research and development skills to innovative robot systems.

## EDUCATION

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### **Doctor of Philosophy** (2021 – Present)

**Applied Artificial Intelligence Institute, Deakin University**

Implementing novel machine learning algorithms to learn design and control together for robots, using PyTorch libraries and popular codebases.

### **Masters in Robotics and Mechatronics** (2017-2019)

**RMIT University**

Designed, developed and 3D printed a mechatronic gripper capable of handling eggs without dropping or crushing.

### **Bachelors in Electronics Engineering** (2012-2016)

**Andhra University, India**

Developed an early fire-detection system for train cabins.

## SKILLS

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Python ●●●●●

C++ ●●●●●

ROS ●●●●●

Linux ●●●●●

Prototyping ●●●●●

## WORK EXPERIENCE

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06/2023 to 10/2024

### **Sessional Academic**

**Deakin University – Geelong, Victoria**

- Delivered 30+ tutorial sessions in Software Deployment, Data Structures & Algorithms, Robotics and Computer Vision courses.
- Created and adapted 5 course materials with practical examples to enhance student learning.
- Provided constructive feedback to 50+ students per semester, resulting in a 15% average improvement across assignment scores.
- Facilitated interactive discussions and problem-solving sessions to strengthen understanding complex concepts.

04/2020 to 09/2021

### **Vision Systems Engineer**

**Australian Machine Vision Pty. Ltd. – Frankston, Victoria**

- Led automation efforts in Bosch's deployment of a 16-line COVID test

kit manufacturing system to Ellume Health.

- Authored and optimized technical user manuals, streamlining client onboarding by 25% across multiple high-profile projects.
- Collaborated with 3+ teams through weekly face-to-face meetings and Git-based version control, managing multiple concurrent projects.
- Integrated vision systems and testing pipelines for label identification and segmentation in fast moving images across 4 projects.
- Designed and implemented 5+ mechanical structures for cameras, lighting solutions and electrical housing, enhancing system effectiveness and personnel safety.

07/2019 to 12/2021

### **Robotics Engineer**

**Exaptec Pty. Ltd. – Lilydale, Victoria**

- Prepared detailed mechanical designs and CAD drawings for 3+ new add-on components for social robots including Temi and Beam.
- Developed standard operating procedures (SOPs) for robot testing, reducing debugging time by 30% in some cases.
- Managed integration of robots in client workspaces, writing Python, Android Studio-based applications for seamless deployment.
- Developed user manuals and technical documentation for 3+ robot applications, reducing client onboarding time by 20%

## ACCOMPLISHMENTS

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- **Best Poster Presentation Award Runner up** at Australasian Joint Conference on Artificial Intelligence, Melbourne (2024).
- **Best Hack Award Winner** for developing an AR experience for Wilsons Transformers Company in the ThingWorx AR + IoT Hackathon@RMIT (2018).

## REFERENCES

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| • Nicci Rossouw<br><i>CEO</i><br>Exaptec Pty. Ltd. | • Dr. Santu Rana<br><i>Associate Professor</i><br>A2I2, Deakin University | • Ken Razga<br><i>Director</i><br>AMV Pty. Ltd. |
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