





Technical Skills

- Languages: Python, Java, JavaScript, C, C++, React, React Native, Node, Express, SQL, HTML, CSS
- Technologies: Git, Linux, MongoDB, PostgreSQL, SQLite, OpenCV, Keras, Tensorflow, MobX

Work Experience

Intel Corporation

Software Engineering Intern

 Developed a telemetry query application; Used a SQL-based relational database, Python and Flask for the server, and JavaScript, HTML, and CSS for the GUI.

Took initiative to optimize and contribute to Intel's **Python** workflows, libraries, and APIs.

Awarded several times, for quality, completeness, and detail of work!

TRIUMF – Canada's Particle Accelerator

Atom Beta-Decay Trap Researcher

 Increased camera's frame rate by over 300%, using C++ to implement dynamic memory allocation and multithreading - crucial in capturing the quickly decaying atoms.

Optimized data acquisition using camera's software development kit to process images.

Exposed and corrected errors and contradictions previously missed by the research team.

Vancouver.

Vancouver.

BC, Canada

May – Dec

2020

BC, Canada

Jan – Apr

2019

Education

University of British Columbia

Engineering Physics & Computer Science, Bachelor of Applied Science

Coursework: Algorithm Design & Analysis, Data Structures, Software Engineering, Principles of Software Construction

Involvements: Dean's Honour List, Science One, Orbit: Satellite Design Team, Physics Teaching Assistant, Math Teaching Assistant

Expected Graduation 2022

Technical Projects

3D-O – Web Application

Winter 2021

- Mission: to combat COVID19 by sharing my lifelong hobby, 3d-origami, to promote social distancing.
- Paint-by-pixel coloring interface implemented via React and MobX State Tree.
- User-friendly project modelling interface utilising Three.js for 3D rendering.

Daily Dash – Mobile Application

Fall 2020

- Won 1st place in UBC's 2020 Software Engineering Competition against 26 teams and 100+ participants.
- Mission: to empower users across all walks of life to achieve their life goals via regular, repeated efforts.
- Dynamically rendered forms using React Native and MobX State Tree.
- Push notifications via Google Firebase; User authentication via Google Authentication.

Machine Learning Robot Competition

Fall 2019

- Placed 4th out of 20 teams in a machine learning competition using Robot Operating System.
- Autonomous navigation via OpenCV, reinforcement learning, and image processing tools in Python.
- Convoluted neural network, using Keras and TensorFlow, identifies alphanumeric characters.

Autonomous Stone-Collecting Robot

Summer 2019

- Goal: To prototype and build a tape-following, stone-collecting robot for a student competition.
- Accurate PID control algorithm via C++ enables autonomous navigation and functionality.
- State machine programmed in C++ prioritizes software safety, control, and performance.