





Technical Skills

- Languages: Python, Java, JavaScript, C, C++, React, React Native, Node, Express, SQL, HTML, CSS
- Technologies: Git, Linux, MongoDB, PostgreSQL, SQLite, OpenCV, Keras, Tensorflow, MobX

Work Experience

Intel Corporation

Software Engineering Intern

Developed a telemetry query application; Used a SQL-based relational database, Python and Flask for the server, and JavaScript, HTML, and CSS for the GUI.

Automated essential workflows using Python.

- Took initiative to optimize and contribute to Intel's existing **Python** libraries and APIs.
- Exposed errors by writing Bash tests to validate Intel's development environment.
- Awarded several times, for quality, completeness, and detail of work!

TRIUMF - Canada's Particle Accelerator

Atom Beta-Decay Trap Researcher

Increased camera's frame rate by over 300% by using C++ to implement dynamic memory allocation and multithreading – crucial for capturing the quickly decaying atoms.

Optimized data acquisition, using camera's software development kit to process images.

Exposed and corrected errors and contradictions previously missed by the research team.

Education

University of British Columbia

Engineering Physics & Computer Science, Bachelor of Applied Science

Coursework: Algorithm Design & Analysis, Data Structures, Software Engineering

Involvements: Dean's Honour List, Science One, Orbit: Satellite Design Team, Physics Teaching Assistant, Math Teaching Assistant

Technical Projects

Daily Dash – Mobile Application

Won 1st place in UBC's 2020 Software Engineering Competition against 26 teams and 100+ participants.

- Mission: to empower users across all walks of life to achieve their goals.
- Core Philosophy: Small efforts everyday can accumulate to yield life changing results.
- Dynamically rendered forms using React Native and MobX State Tree.
- Push notifications via Google Firebase; User authentication via Google Authentication.

Machine Learning Robot Competition

Fall 2019

- Placed 4th out of 20 teams in a machine learning competition using Robot Operating System.
- Implemented autonomous navigation in the simulation using **OpenCV**, reinforcement learning, and image processing tools in **Python**.
- Trained a neural network to identify alphanumeric characters using **Keras** and **TensorFlow**.

Autonomous Stone-Collecting Robot

Summer 2019

- Prototyped and built a robot that follows tape and collects stones for a student competition.
- Implemented PID control using C++ on an STM32 microcontroller, resulting in accurate autonomous navigation and functionality.
- Programmed a state machine in C++, optimizing software safety, control, and performance.

Vancouver.

BC, Canada May – Dec

2020

Vancouver.

BC, Canada Jan - Apr

2019

Expected

Graduation

2022

Fall 2020