

Validating Forecasting Strategies of Simple Epidemic Models on the 2015-2016 Zika Epidemic

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Introduction and Background



Epidemic Forecasting

- Forecasting is
- Accurate forecasting of infectious disease outbreaks is vital in safeguarding global health and the well-being of individuals
- Model-based forecasts enable public health officials to:
 - Test what-if scenarios
 - Evaluate control strategies
 - Develop informed policy



Epidemic Forecasting - Challenges

- Accurate data availability is critical to inform models and produce reliable forecasts
- Human behavior during an epidemic can significantly impact assumed transmission dynamics
- Forecasting validation*







- Zika virus is a mosquito-borne disease characterized by dengue-like symptoms
 - Fever, rash, muscle, and joint pain
- Zika has multiple transmission pathways, including:
 - Mosquito-to-human transmission, human-to-human sexual transmission, and vertical transmission
- Most people who become infected are asymptomatic



2015-2016 Zika Epidemic

- On February 1, 2016, the World Health Organization (WHO) declared Zika-related microcephaly a Public Health Emergency of International Concern (PHEIC)
 - Lasted until November of 2016
- Zika spread throughout South America, heavily affecting Brazil and Colombia



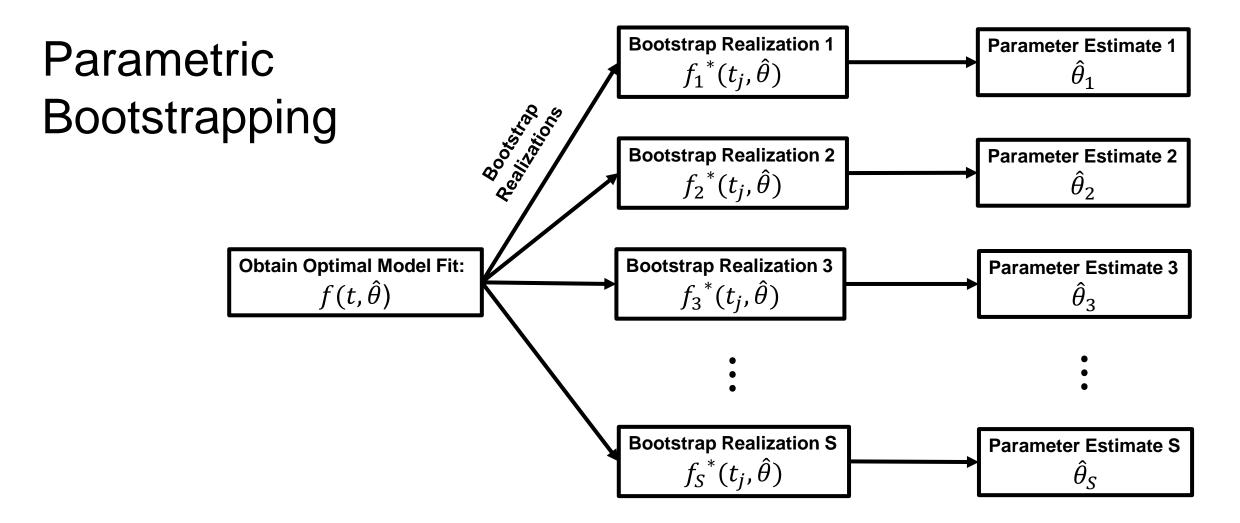
Thesis Question

- How do model-based forecasts of simple epidemic models compare under a Parametric Bootstrapping and Ensemble Kalman Filtering approach?
- Does the top-performing model change as the epidemic progresses, and how do spikes in Zika incidence affect the forecasting performance of each model?



Methodology





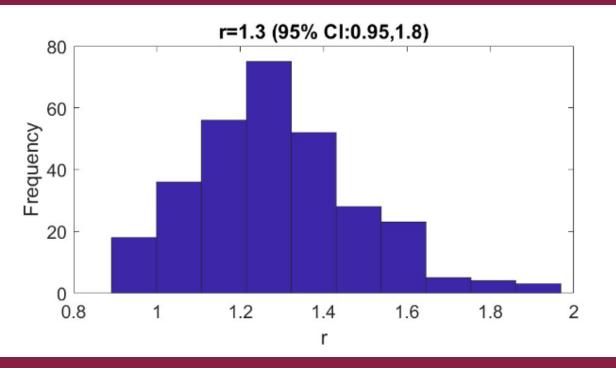
Cumulative Curve Function:

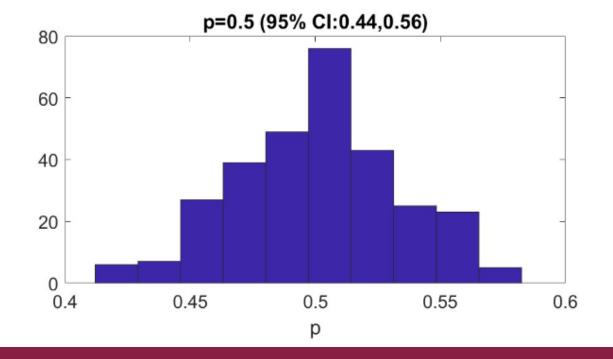
$$F(t_j, \hat{\theta}) = \sum_{l=1}^{j} f(t_l, \hat{\theta})$$

Dataset Resampling:

$$f_k^*(t_j, \hat{\theta}) = \text{Po}(F(t_j, \hat{\theta}) - F(t_{j-1}, \hat{\theta}))$$









Ensemble Kalman Filter (EnKF)

Forecast Step:

$$\begin{split} S_{j|j} &= \{x_{j|j}^1, x_{j|j}^2, ..., x_{j|j}^N\} \\ X_{j+1} &= F(X_j) + V_{j+1}, \ V_{j+1} \sim \mathcal{N}(0, \mathbf{C}_{j+1}) \\ Y_{j+1} &= G(X_{j+1}) + W_{j+1}, \ W_{j+1} \sim \mathcal{N}(0, \mathbf{D}_{j+1}), \end{split}$$

Analysis Step:

$$x_{j+1|j+1} = x_{j+1|j} + K_{j+1}(y_{j+1}^n - \hat{y}_{j+1}^n), n = 1, ..., N$$

$$y_{j+1}^n = y_{j+1} + w_{j+1}^n, w_{j+1} \sim N(0, \mathbf{D}_{j+1}),$$

$$S_{j+1|j+1} = \{x_{j+1|j+1}^1, x_{j+1|j+1}^2, ..., x_{j+1|j+1}^N\}$$



Models of interest - Growth Models

Generalized Growth Model (GGM):

$$\frac{dC}{dt} = rC^p(t)$$

Generalized Logistic Model (GLM):

$$\frac{dC}{dt} = rC^p[1 - (\frac{C}{K})]$$

Generalized Richards Model (GRM):

$$\frac{dC}{dt} = rC^p[1 - (\frac{C}{K})^a]$$

- $\frac{dC}{dt}$ describes the growth in disease incidence at time t
- C described the cumulative incidence at time t
- Parameters:
- r is a growth parameter
- *K* represents the size of an epidemic
- p and a are growth scaling parameters, with $0 \le p \le 1$



Susceptible-Infected-Recovered (SIR) Model

$$\frac{dS}{dt} = -\frac{\beta SI}{N}$$

$$\frac{dI}{dt} = \frac{\beta SI}{N} - \gamma I$$

$$\frac{dR}{dt} = \gamma I$$

$$\frac{dC}{dt} = \frac{\beta SI}{N}$$

- State variables S, I, and R represent the susceptible, infected, and recovered populations
- C is an auxiliary state variable that tracks cumulative disease incidence
- Parameters:
- β constant transmission parameter
- $\frac{1}{\nu}$ mean infectious period
- *N* population size



Susceptible-Exposed-Infected-Recovered (SEIR) Model

$$\frac{dS}{dt} = -\frac{\beta SI}{N}$$

$$\frac{dE}{dt} = \frac{\beta SI}{N} - \kappa E$$

$$\frac{dI}{dt} = \kappa E - \gamma I$$

$$\frac{dR}{dt} = \gamma I$$

$$\frac{dC}{dt} = \kappa E$$

- State variable E represent the exposed population
- C is an auxiliary state variable that tracks cumulative disease incidence
- Parameters:
- β constant transmission parameter
- ¹/_κ mean latent period
 ¹/_κ mean infectious period
- *N* population size



Performance Metrics

- To evaluate forecast prediction error, we used the following three metrics:
 - Mean Absolute Error (MAE): MAE = $\frac{1}{n}\sum_{i=1}^{n}|f(t_i,\hat{\theta})-y_{t_i}|$
 - Mean Squared Error (MSE): $MSE = \frac{1}{n} \sum_{i=1}^{n} (f(t_i, \hat{\theta}) y_{t_i})^2$
 - Root-Mean Squared Error (RMSE): RMSE = $\sqrt{\frac{1}{n}\sum_{i=1}^{n}(f(t_i,\hat{\theta}) y_{t_i})^2}$



Performance Metrics

- We use the follow two metrics to evaluate predictive uncertainty:
 - Coverage rate of the $(1 \alpha)x100\%$ Prediction Interval:
 - Proportion of observations falling within the PI
 - Weighted Interval Score (WIS):

$$IS_{\alpha}(F, y) = (u - l) + \frac{2}{\alpha} * (l - y) * \mathbf{I}(y < l) + \frac{2}{\alpha} * (y - u) * \mathbf{I}(y > u)$$



Case Study Construction

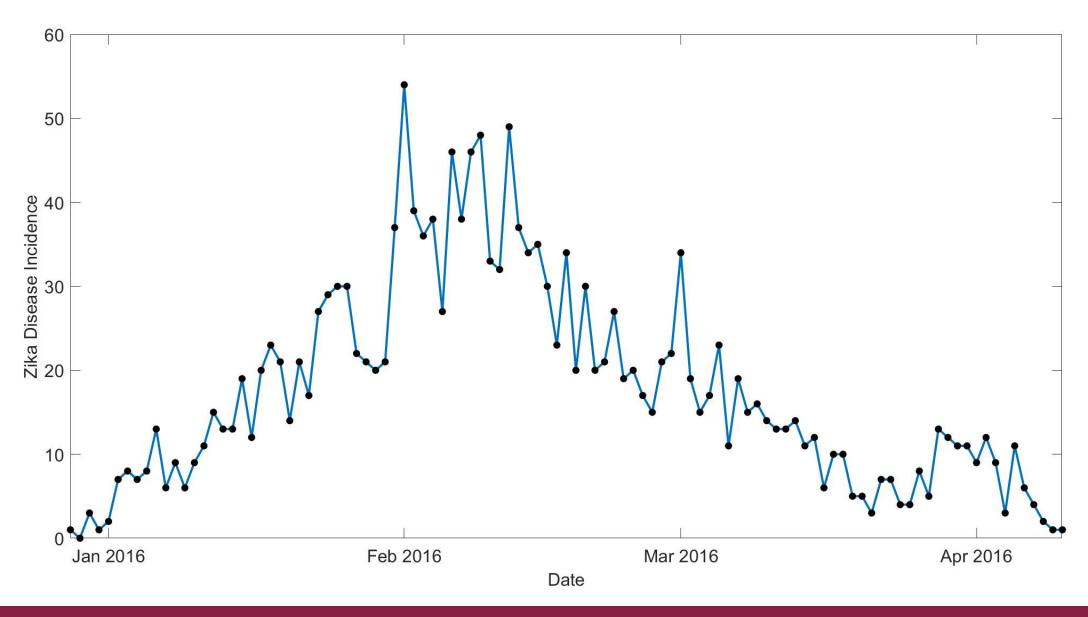
- In total, we conduced five case studies
- Case Study 1: Calibrate models on first 35 days of data
 - Generate 14-day-ahead forecast up to day 49
 - Why 14 days?
- Each successive Case Study assimilates data predicted against from previous Case Study, and then refits each model:
 - Case Study 2: Calibrate models on first 49 days of data
 - Forecasts up to day 63 of Zika epidemic



Zika Incidence Data

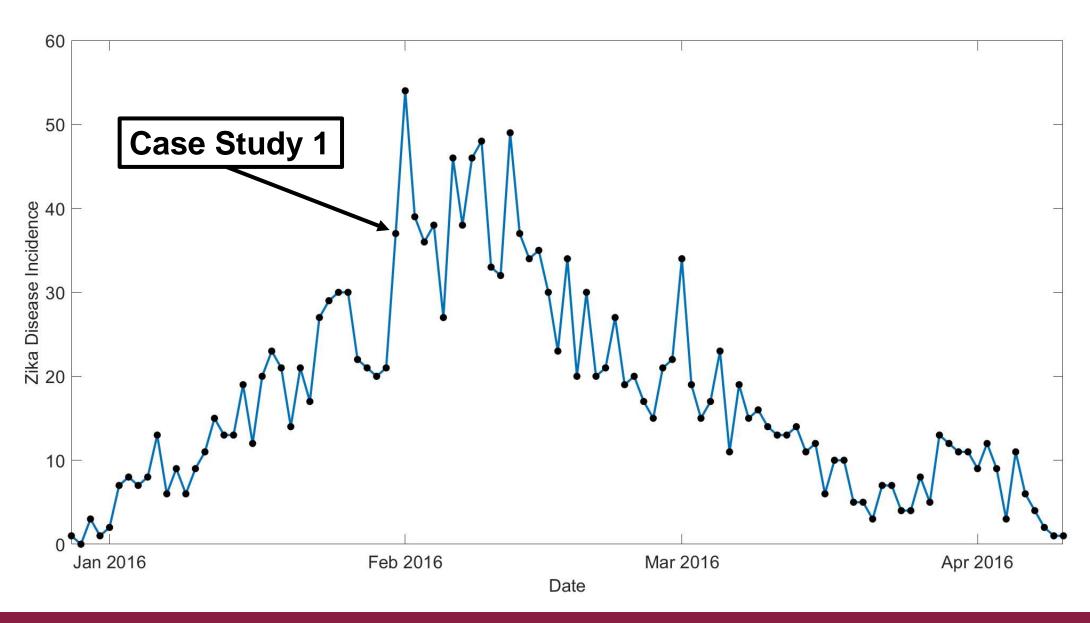
- Zika incidence data was collected from Antioquia, Colombia, from the Ministry of Health of Colombia
 - At the time of collection, Antioquia had an estimated population size of 6.3 million
- Disease reporting is based off onset of symptoms
 - Approximately 5% of cases were laboratory tested

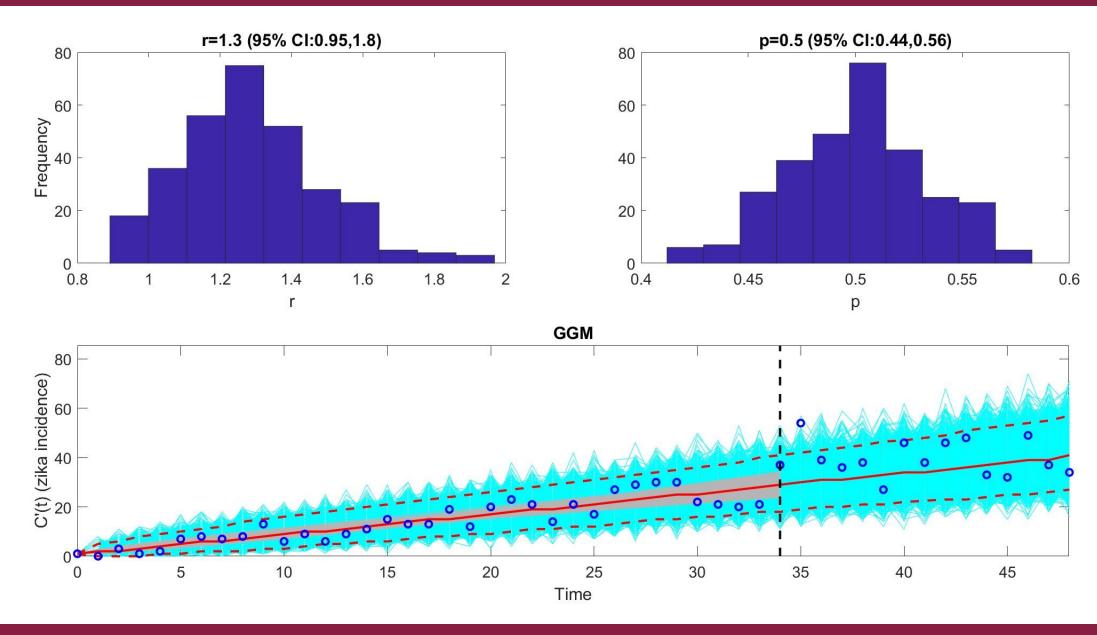


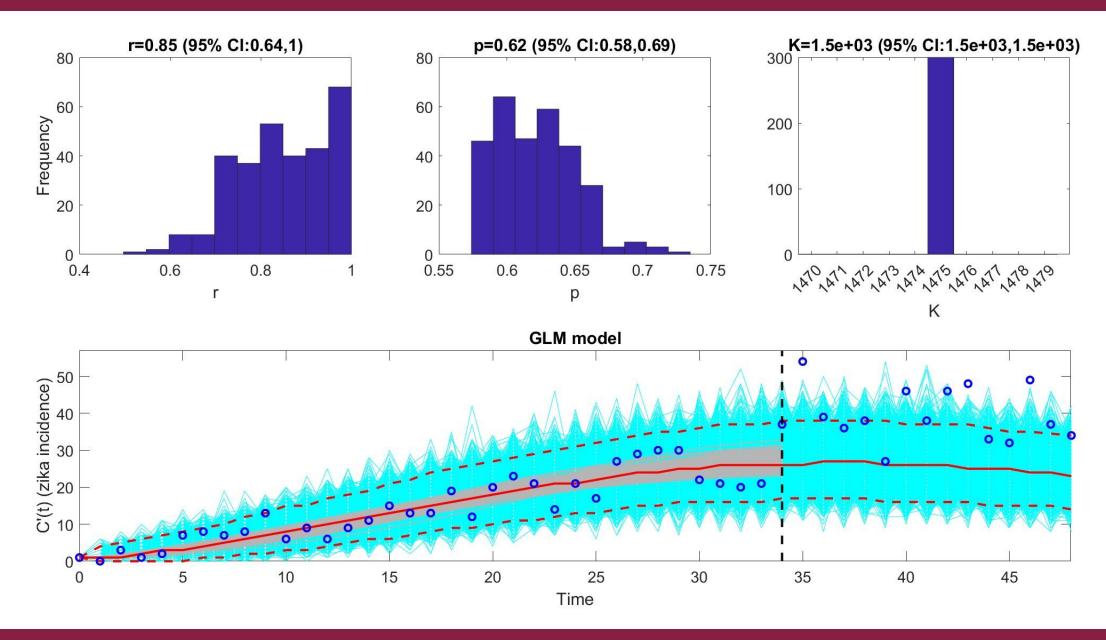


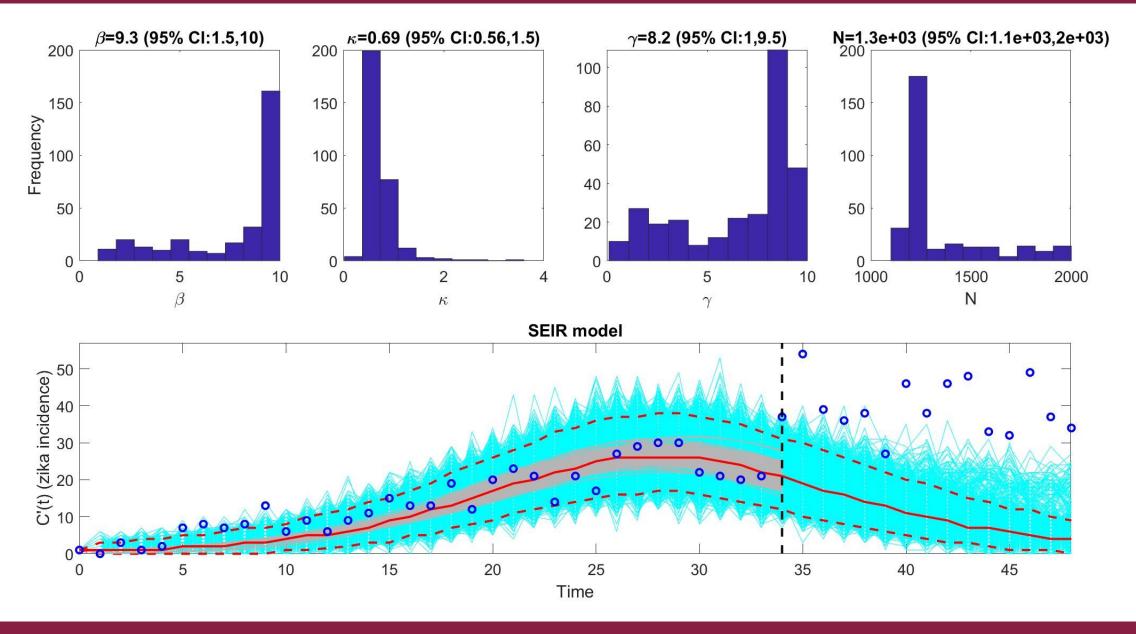
Simulations and Results

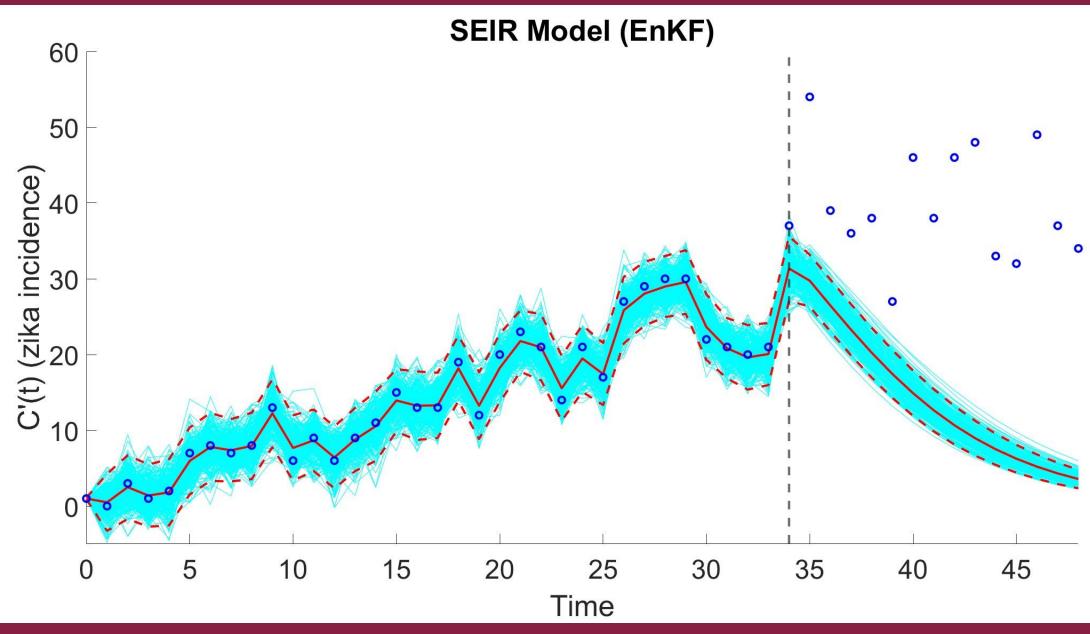








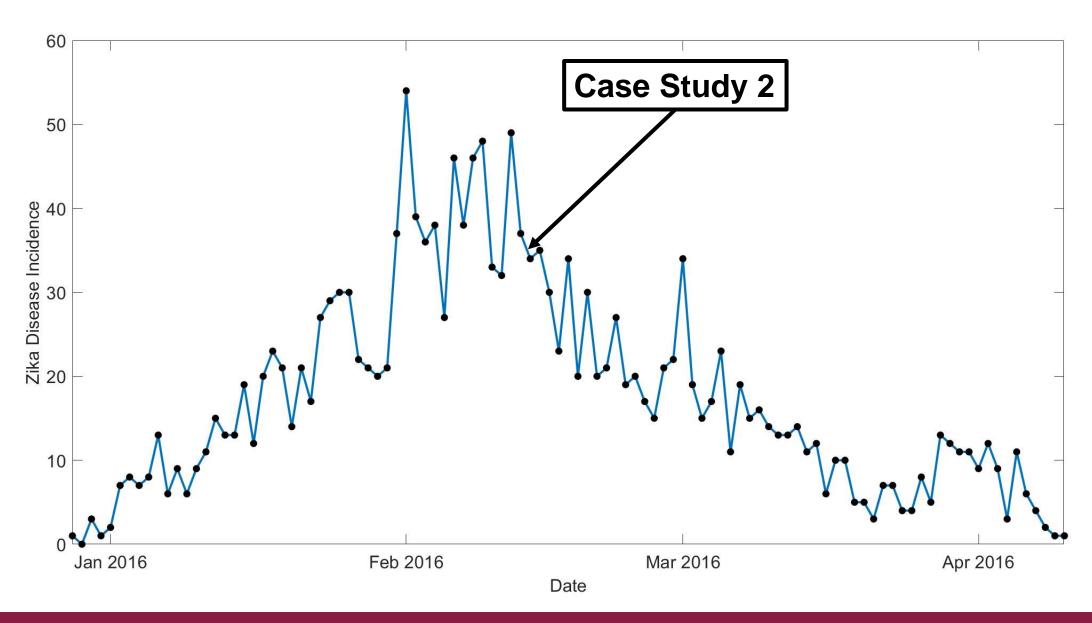


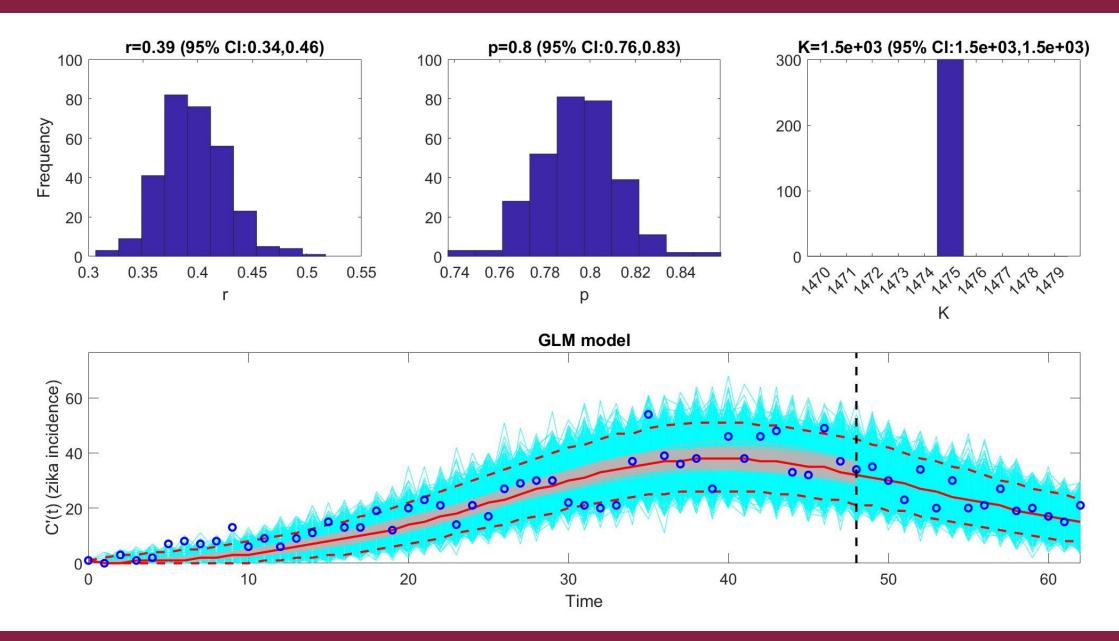


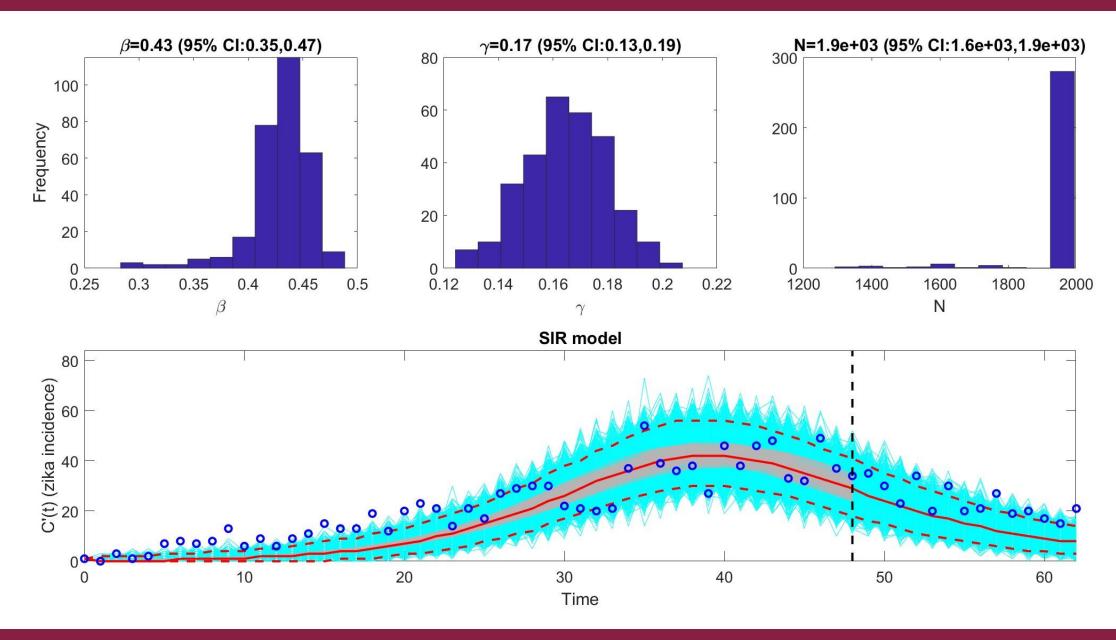
| Forecasting Performance Metrics | | | | | | | |
|---------------------------------|--------|---------|--------|----------|--------|--|--|
| Model | MAE | MSE | RMSE | Coverage | WIS | | |
| GGM | 8.305 | 97.596 | 9.879 | 92.857 | 5.190 | | |
| GLM | 14.301 | 257.892 | 16.059 | 42.857 | 10.613 | | |
| GRM | 13.357 | 230.465 | 15.181 | 64.286 | 8.988 | | |
| SIR | 29.353 | 925.239 | 30.418 | 0 | 26.604 | | |
| SEIR | 29.716 | 947.150 | 30.776 | 0 | 26.523 | | |
| SIR(EnKF) | 26.218 | 773.657 | 27.815 | * | * | | |
| SEIR(EnKF) | 27.472 | 850.308 | 29.160 | * | * | | |

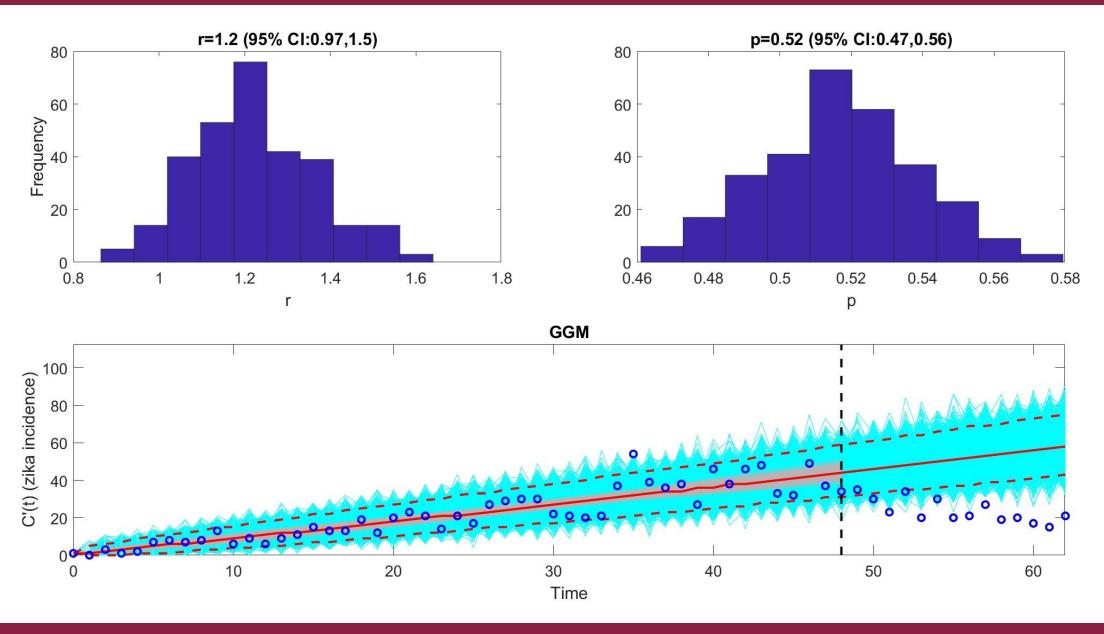
Table 4.1: Performance metrics of model-based forecasts from Case Study 1







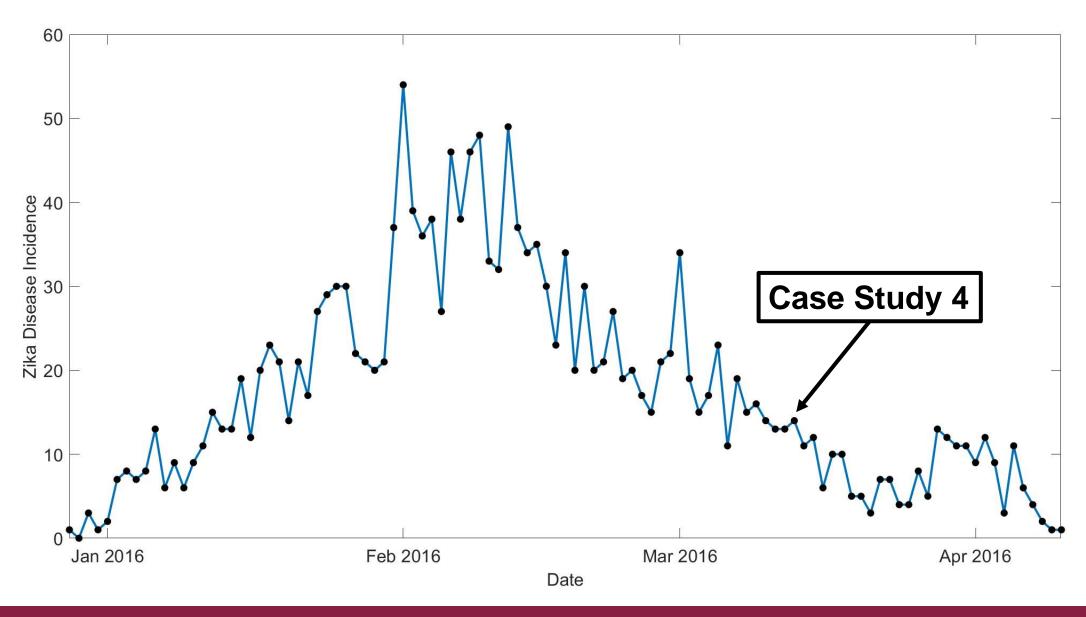


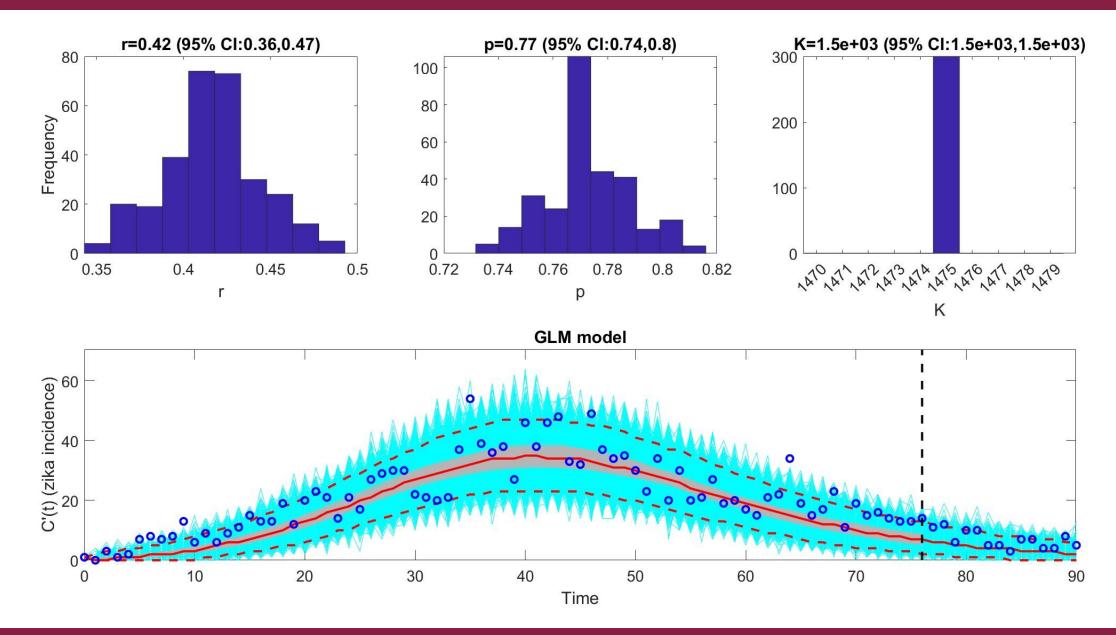


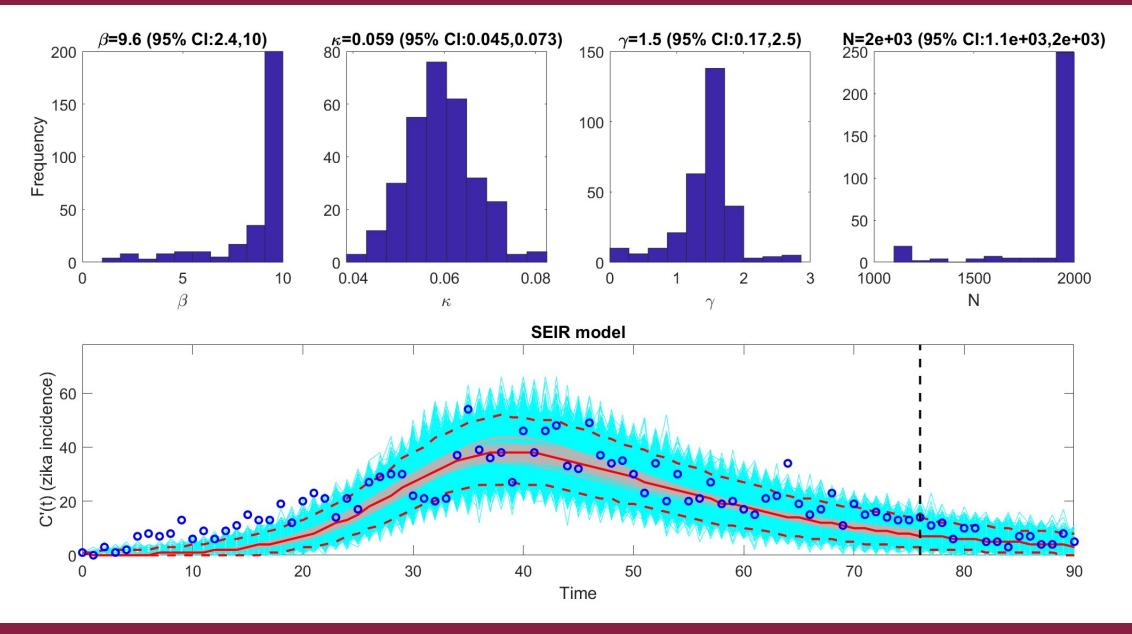
| Forecasting Performance Metrics | | | | | | | |
|---------------------------------|--------|---------|--------|----------|--------|--|--|
| Model | MAE | MSE | RMSE | Coverage | WIS | | |
| GGM | 27.997 | 871.994 | 29.530 | 7.143 | 22.442 | | |
| GLM | 3.380 | 17.858 | 4.226 | 100 | 2.180 | | |
| GRM | 3.524 | 19.240 | 4.386 | 100 | 2.248 | | |
| SIR | 8.182 | 84.585 | 9.197 | 57.143 | 5.815 | | |
| SEIR | 5.559 | 41.893 | 6.472 | 85.714 | 3.588 | | |
| SIR(EnKF) | 6.956 | 64.424 | 8.027 | * | * | | |
| SEIR(EnKF) | 5.585 | 42.138 | 6.491 | * | * | | |

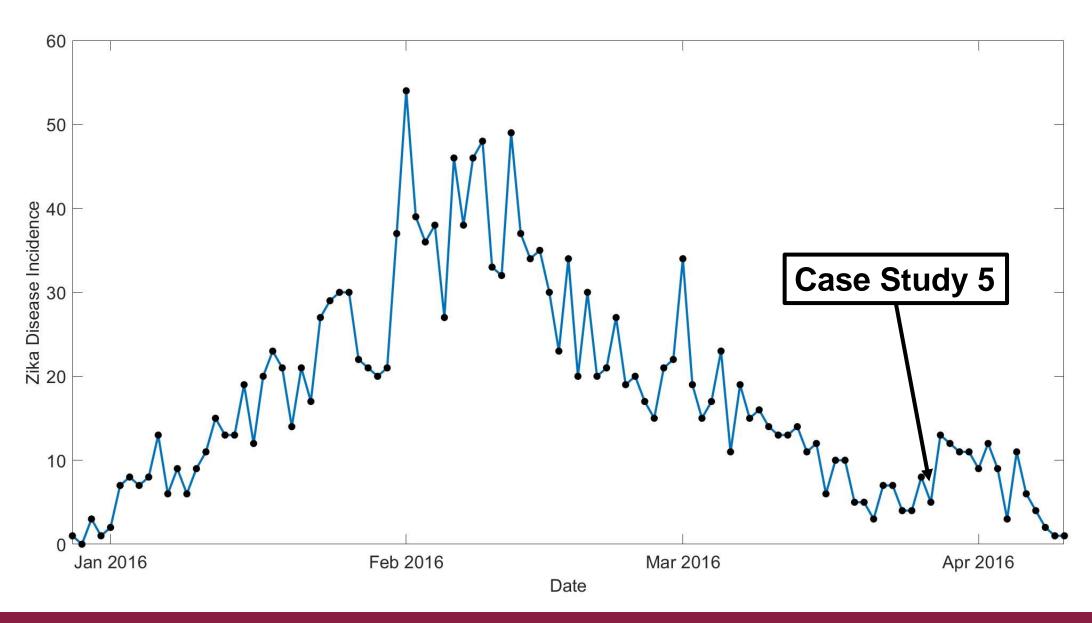
Table 4.2: Performance metrics of models-based forecasts from Case Study 2

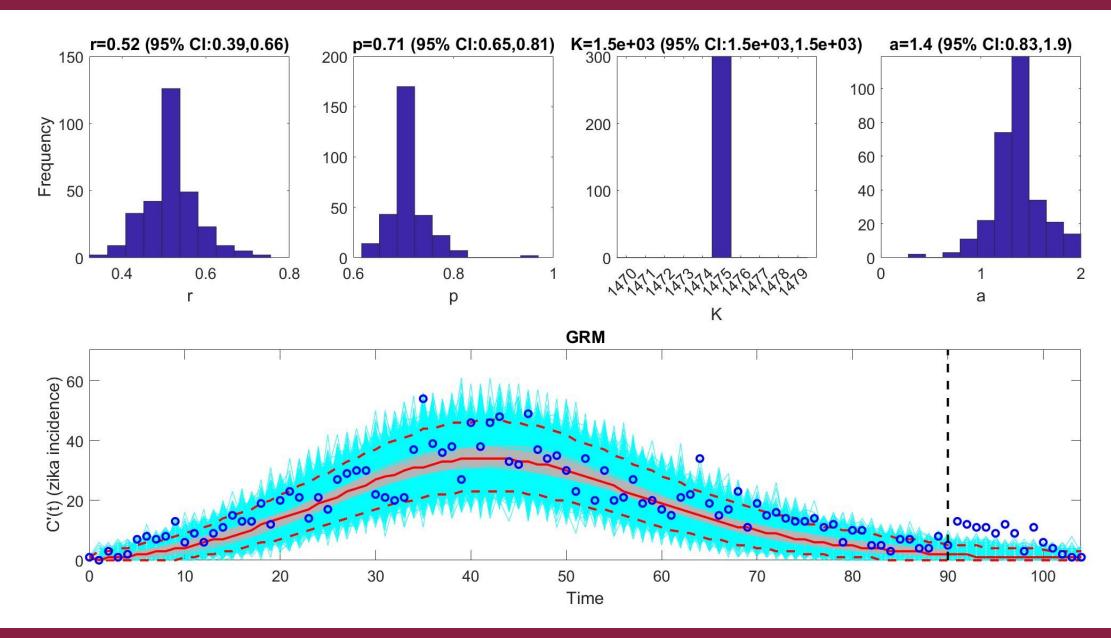


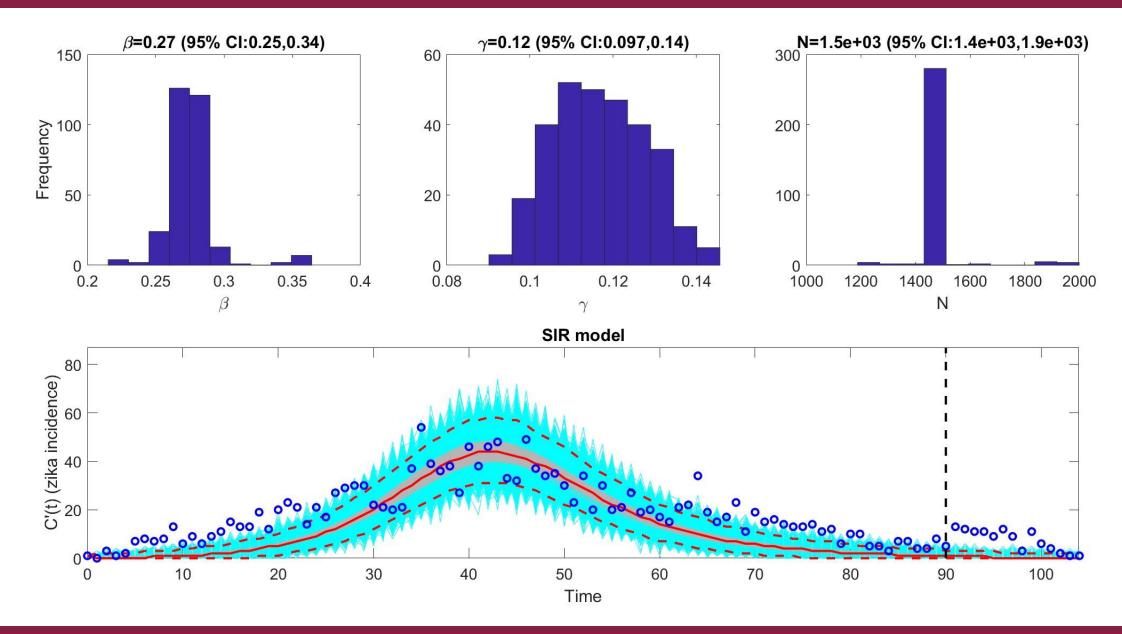


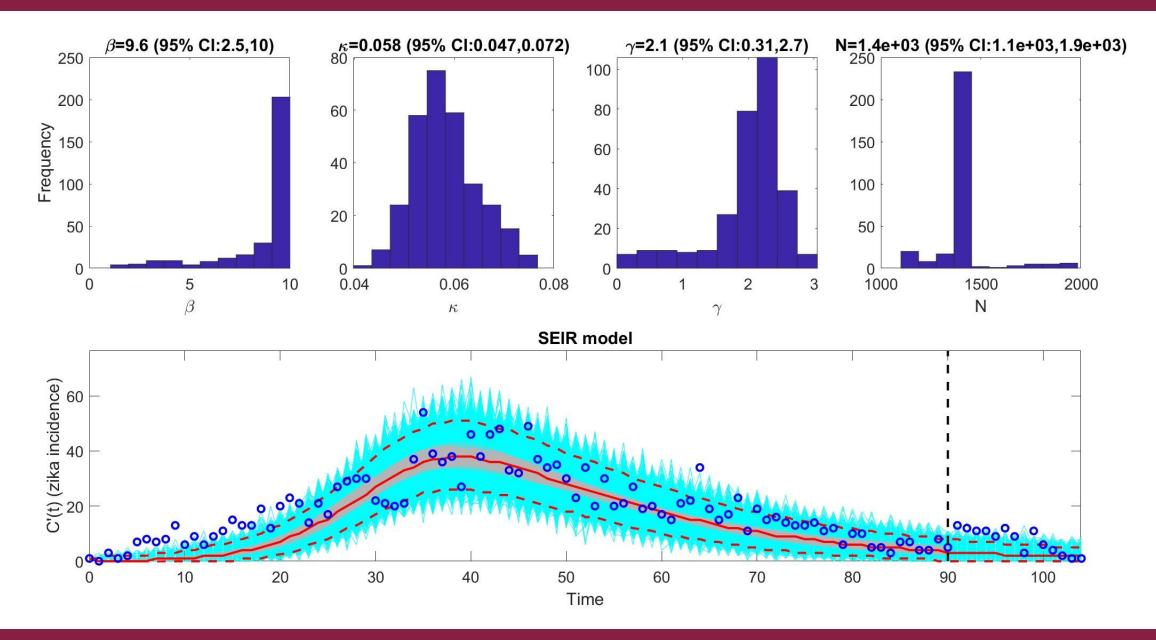


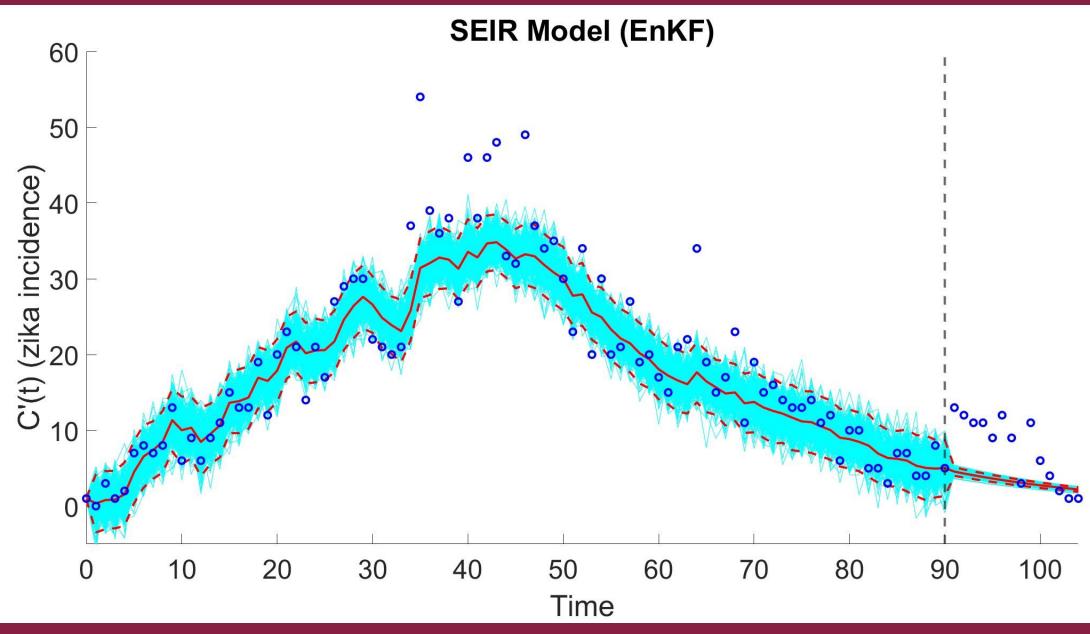












| Forecasting Performance Metrics | | | | | |
|---------------------------------|--------|---------|--------|----------|-------|
| Model | MAE | MSE | RMSE | Coverage | WIS |
| GGM | 13.961 | 214.476 | 14.645 | 100 | 4.841 |
| GLM | 6.079 | 52.778 | 7.265 | 28.571 | 5.300 |
| GRM | 6.265 | 55.329 | 7.438 | 28.571 | 5.515 |
| SIR | 6.922 | 65.236 | 8.077 | 21.429 | 6.393 |
| SEIR | 5.120 | 39.638 | 6.296 | 42.857 | 4.236 |
| SIR(EnKF) | 5.709 | 47.053 | 6.860 | * | * |
| SEIR(EnKF) | 4.691 | 31.860 | 5.644 | * | * |

Table 4.5: Performance metrics of model-based forecasts from Case Study 5



Conclusions

- GGM performs well before the peak in Zika incidence
 - The naïve case
- GLM and GRM result in consistent performance across all case studies
- SEIR model demonstrates improvements in forecasting performance as the epidemic progress
 - Including disease mechanism is key
- EnKF technique yields a reduction in prediction errors for the SIR and SEIR models



Limitations

- This study did not include a vector-dynamics into the modeling framework
 - Mosquito transmission is key in understanding Zika
 - However, this study seeks to validate simple models and create a benchmark
- Ensemble Kalman Filter
 - Fixed error structures for state and observational noise



Future Work

- Incorporate vector-borne disease models into forecasting frameworks:
 - Is there an improvement in forecast accuracy when incorporating vector dynamics?
- Investigate observation noise process for the EnKF:
 - Error estimation techniques
- Investigate parameter identifiability of SEIR model
 - Parameter distributions are a diagnostic tool



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Thank you to my friends for lifting my spirits when I struggled.

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Finally, thank you to my family for all the love and support.



Thank you! Any Questions?

References



| Forecasting Performance Metrics | | | | | |
|---------------------------------|--------|---------|--------|----------|--------|
| Model | MAE | MSE | RMSE | Coverage | WIS |
| GGM | 21.920 | 489.729 | 22.130 | 0 | 17.867 |
| GLM | 2.989 | 13.016 | 3.608 | 85.714 | 2.008 |
| GRM | 3.801 | 19.240 | 4.386 | 50 | 2.694 |
| SIR | 5.104 | 31.759 | 5.636 | 42.857 | 4.123 |
| SEIR | 2.208 | 7.775 | 2.788 | 100 | 1.459 |
| SIR(EnKF) | 2.589 | 9.919 | 3.149 | * | * |
| SEIR(EnKF) | 1.846 | 4.765 | 2.183 | * | * |

Table 4.4: Performance metrics of model-based forecasts from Case Study 4



| GGM Parameters | | | | |
|----------------|-----------------|---------------|--|--|
| Parameter | Search Interval | Initial Value | | |
| r | [0,9] | 0.9 | | |
| p | [0,1] | 0.5 | | |
| | GLM Parameter | s | | |
| Parameter | Search Interval | Initial Value | | |
| r | [0,1] | 0.5 | | |
| p | [0,1] | 0.5 | | |
| K | Fixed | 1475 | | |
| GRM Parameters | | | | |
| Parameter | Search Interval | Initial Value | | |
| r | [0,9] | 0.9 | | |
| p | [0,1] | 0.5 | | |
| a | [0,2] | $ $ | | |
| K | Fixed | 1475 | | |

Table A.1: Parameter Search Bounds and Initial Values for GGM, GLM, and GRM Model Fitting

| SIR Parameters | | | | | |
|----------------|-----------------|---------------|--|--|--|
| Parameter | Search Interval | Initial Value | | | |
| β | [0,10] | 4 | | | |
| γ | [0,10] | 4 | | | |
| N | [1100, 2000] | 1475 | | | |
| | SEIR Parameters | | | | |
| Parameter | Search Interval | Initial Value | | | |
| β | [0,10] | 4 | | | |
| κ | [0,4] | 1 | | | |
| $ \gamma $ | [0,10] | 4 | | | |
| N | [1100, 2000] | 1475 | | | |

Table A.2: Parameter Search Bounds and Initial Conditions for SIR and SEIR Model Fitting



| SIR Optimal Parameter Sets | | | | |
|----------------------------|---------|----------|------|--|
| Case Study | β | γ | N | |
| 1 | 0.78 | 0.6 | 1500 | |
| 2 | 0.43 | 0.17 | 1960 | |
| 3 | 0.34 | 0.13 | 1689 | |
| 4 | 0.31 | 0.12 | 1653 | |
| 5 | 0.27 | 0.12 | 1477 | |

Table A.3: SIR optimal parameter sets for EnKF under each case study



| SEIR Optimal Parameter Sets | | | | | |
|-----------------------------|---------|----------|----------|------|--|
| Case Study | β | κ | γ | N | |
| 1 | 9.35 | 0.69 | 8.17 | 1260 | |
| 2 | 8.79 | 0.14 | 4.35 | 1171 | |
| 3 | 9.62 | 0.07 | 3.14 | 1171 | |
| 4 | 9.64 | 0.06 | 1.51 | 1987 | |
| 5 | 9.62 | 0.06 | 2.14 | 1405 | |

Table A.4: SEIR optimal parameter Sets for EnKF under each case study



