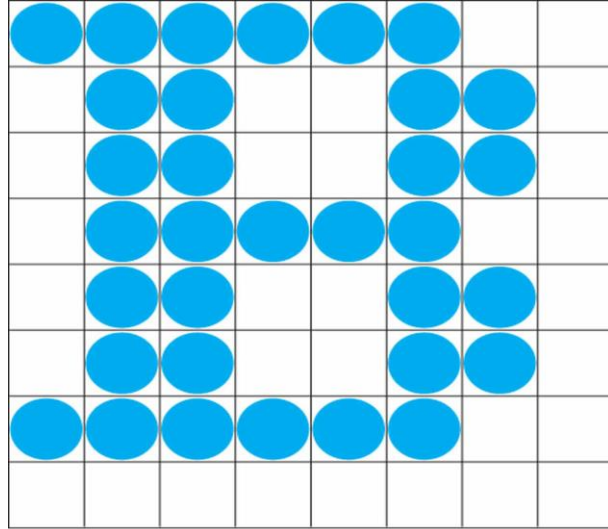


2D & 3D Graphics Summary

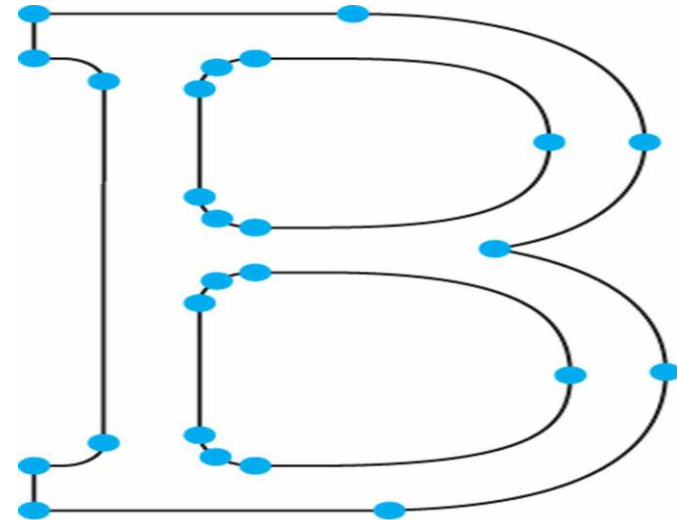
M.K.

Raster vs. Vector Graphics

- Raster graphics produced by defining a pix map that creates a picture by setting the color of all pixels in the display window. Vector Graphics on the other hand define graphics using mathematical formulae that only color specific pixels



Copyright ©2011 Pearson Education, publishing as PearsonIT



Copyright ©2011 Pearson Education, publishing as PearsonIT

Graphics Implementation Algorithms

- Line Drawing
- Circle Drawing
- Ellipse
- Other Curves
- Fill Algorithms
- Anti Aliasing
- OpenGL Attributes and Primitives for these

Line Drawing Algorithms

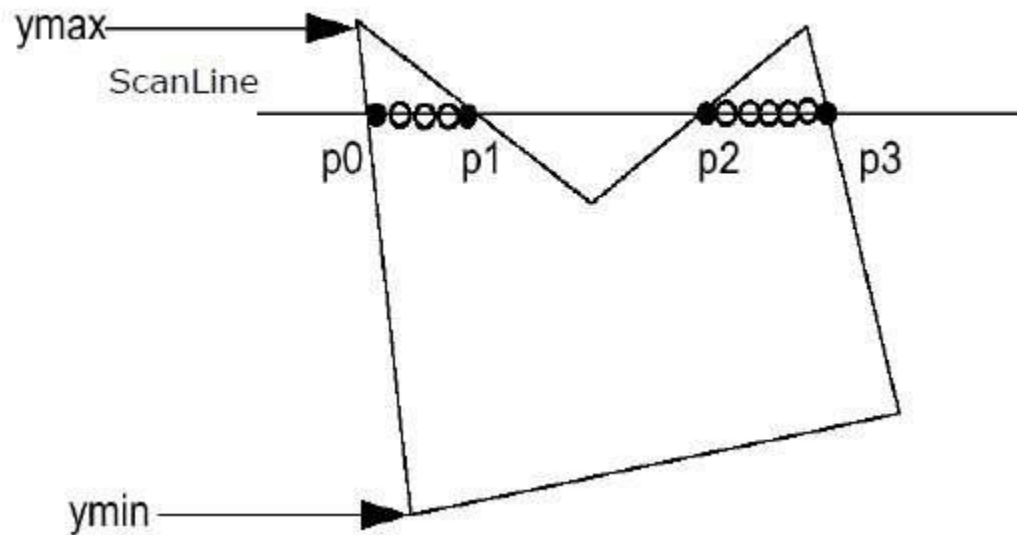
- Line Equation – uses line equation to determine pixels along the line
- DDA Algorithm – determines next pixel from previous
- Bresenham's Line Algorithm

Circle Drawing Algorithms

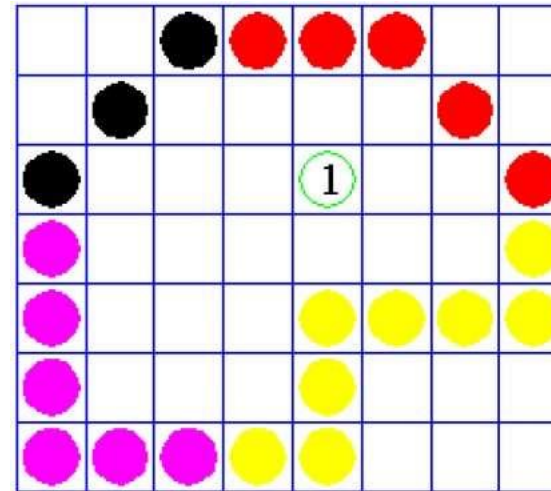
- Bresenham's Circle Algorithm
- Mid Point Circle Algorithm

Polygon Filling Algorithms

- Scanline Algorithm – as the screen is scanned top to bottom, the pixels between the boundaries are filled

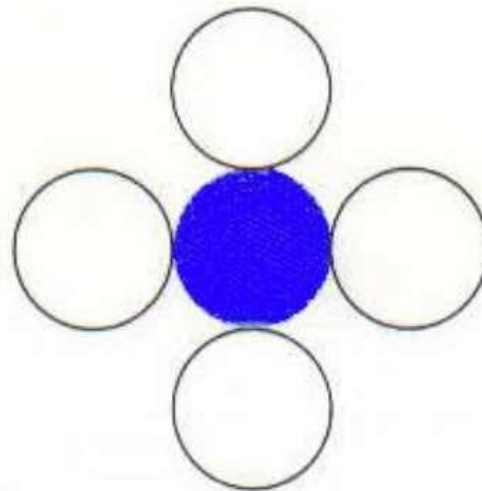


- Flood Fill Algorithm – relies on the color of the pixels and changes their color until no more of a particular color are found



Polygon Filling Algorithms

- Boundary Fill Algorithm – requires different colors for fill area and boundary to work, picks a point in the area and fills it in a line until it finds a different color
- 4 Connected Polygon/8 Connected Polygon – picks a pixel and fills the adjacent 4 pixels and continues until area is filled.



Algorithms Summary

- Inside Outside Test – Reading assignment

Introduction to Graphics Transformations

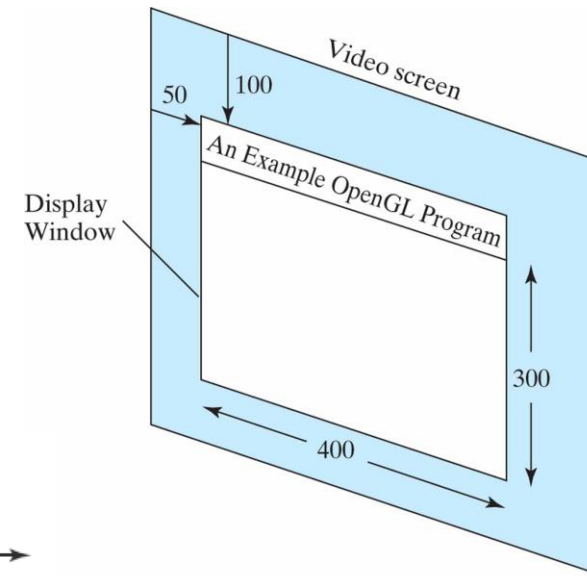
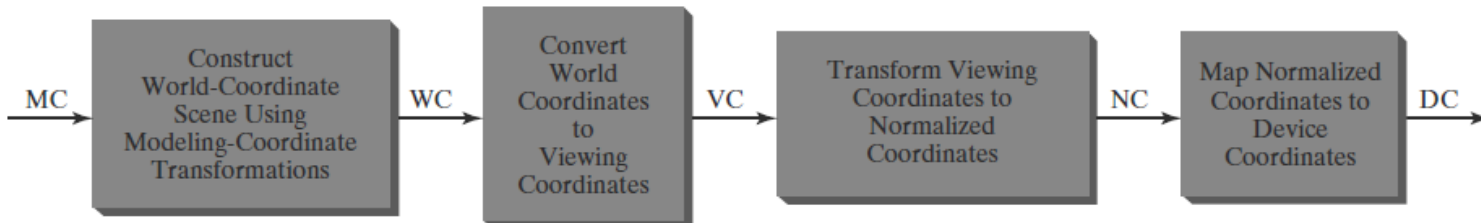
These are operations applied to objects to reposition, orient or resize them and include:-

- Translation
- Rotation
- Scaling
- Reflection?
- Shearing?
- Clipping?

Introduction to Graphics Transformations

- Viewing routines convert these world coordinate system descriptions to be displayed on either a raster or vector device viewport that may vary in size to the world coordinate system used to construct the object
- Operations include viewport transformations e.g. scaling and translation, viewing and clipping functions for lines, circles, polygons etc and these are implemented using various algorithms

Viewport and display window:-



OpenGL Viewing Functions

TABLE 8 - 1

Summary of OpenGL Two-Dimensional Viewing Functions

Function	Description
<code>gluOrtho2D</code>	Specifies clipping-window coordinates as parameters for a two-dimensional orthogonal projection.
<code>glViewport</code>	Specifies screen-coordinate parameters for a viewport.
<code>glGetIntegerv</code>	Uses arguments <code>GL_VIEWPORT</code> and <code>vpArray</code> to obtain parameters for the currently active viewport.
<code>glutInit</code>	Initializes the GLUT library.
<code>glutInitWindowPosition</code>	Specifies coordinates for the top-left corner of a display window.
<code>glutInitWindowSize</code>	Specifies width and height for a display window.
<code>glutCreateWindow</code>	Creates a display window (which is assigned an integer identifier) and specify a display-window title.
<code>glutInitDisplayMode</code>	Selects parameters such as buffering and color mode for a display window.
<code>glClearColor</code>	Specifies a background RGB color for a display window.
<code>glClearIndex</code>	Specifies a background color for a display window using color-index mode.
<code>glutDestroyWindow</code>	Specifies an identifier number for a display window that is to be deleted.
<code>glutSetWindow</code>	Specifies the identifier number for a display window that is to be the current display window.
<code>glutPositionWindow</code>	Resets the screen location for the current display window.
<code>glutReshapeWindow</code>	Resets the width and height for the current display window.
<code>glutFullScreen</code>	Sets current display window to the size of the video screen.
<code>glutReshapeFunc</code>	Specifies a function that is to be invoked when display-window size is changed.
<code>glutIconifyWindow</code>	Converts the current display window to an icon.
<code>glutSetIconTitle</code>	Specifies a label for a display-window icon.
<code>glutSetWindowTitle</code>	Specifies new title for the current display window.
<code>glutPopWindow</code>	Moves current display window to the “top”; i.e., in front of
<code>glutPushWindow</code>	Moves current display window to the “bottom”; i.e., behind all other windows.
<code>glutShowWindow</code>	Returns the current display window to the screen.
<code>glutCreateSubWindow</code>	Creates a second-level window within a display window.
<code>glutSetCursor</code>	Selects a shape for the screen cursor.
<code>glutDisplayFunc</code>	Invokes a function to create a picture within the current display window.
<code>glutPostRedisplay</code>	Renews the contents of the current display window.
<code>glutMainLoop</code>	Executes the computer-graphics program.
<code>glutIdleFunc</code>	Specifies a function to execute when the system is idle.
<code>glutGet</code>	Queries the system about a specified state parameter.

Introduction to Graphics Transformations

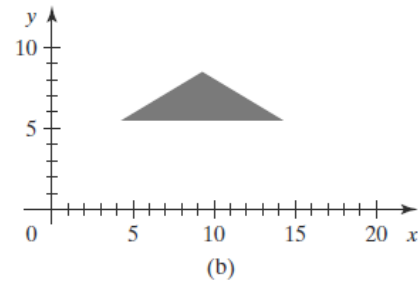
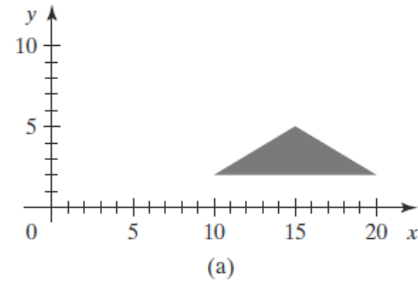
- Zooming can be used to scale up or down a viewport and is defined at pixel level
- Panning – moving the selected zoom area to screen center
- Inking & Scissoring?

2D Transformations: Translation

Move object rigidly without deformation from one position to another.

Can simply use a transformation vector that is applied to all points

$$\mathbf{P} = \begin{bmatrix} x \\ y \end{bmatrix}, \quad \mathbf{P}' = \begin{bmatrix} x' \\ y' \end{bmatrix}, \quad \mathbf{T} = \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$



2D Transformations: Rotation

- Rotate an object about a point by a certain angle:-

$$P' = R \cdot P$$

where the rotation matrix is

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

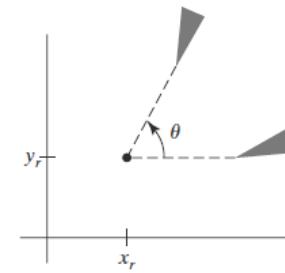


FIGURE 3
Rotation of an object through angle
about the pivot point (x_r, y_r) .

2D Transformations: Scaling

- Scaling matrix and example:-

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\mathbf{P}' = \mathbf{S} \cdot \mathbf{P}$$

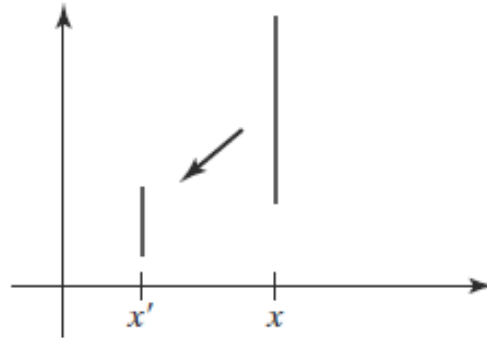


FIGURE 7

A line scaled with Equation 12 using $s_x = s_y = 0.5$ is reduced in size and moved closer to the coordinate origin.

Composite Transformations

- Can do a single or composite transformation using homogenous coordinates and 3x3 matrix

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \quad \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} \quad \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\mathbf{P}' = \mathbf{R}(\theta) \cdot \mathbf{P}$$

$$\mathbf{P}' = \mathbf{S}(s_x, s_y) \cdot \mathbf{P}$$

Inverse Transformations

- These produce the same transformations but in the opposite direction and are usually accomplished by negating the factors in the transformation matrices e.g. for translation , rotation and scaling:-

$$\mathbf{T}^{-1} = \begin{bmatrix} 1 & 0 & -t_x \\ 0 & 1 & -t_y \\ 0 & 0 & 1 \end{bmatrix} \quad \mathbf{R}^{-1} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \mathbf{S}^{-1} = \begin{bmatrix} \frac{1}{s_x} & 0 & 0 \\ 0 & \frac{1}{s_y} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Other Transformations: Reflection

- Reflection on the X and y axes or both:-

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

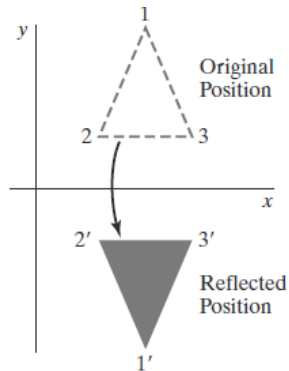


FIGURE 16
Reflection of an object about the x axis.

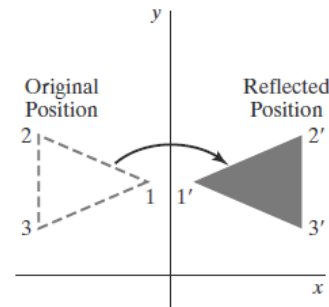


FIGURE 17
Reflection of an object about the y axis.

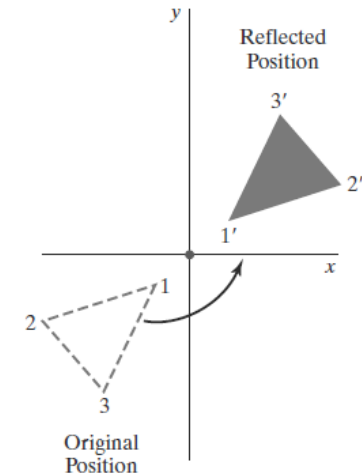


FIGURE 18
Reflection of an object relative to the coordinate origin. This transformation can be accomplished with a rotation in the xy plane about the coordinate origin.

Other Transformations: Shear

- Shearing matrix:-

$$\begin{bmatrix} 1 & sh_x & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

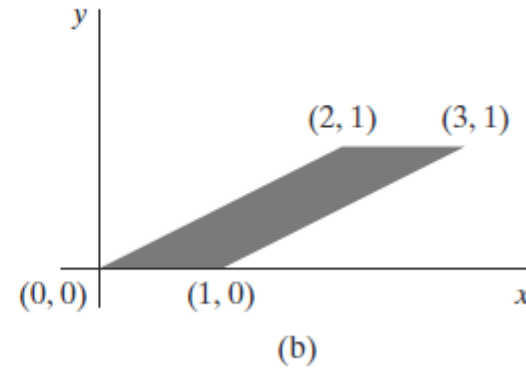
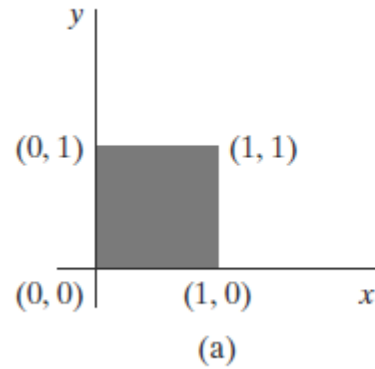
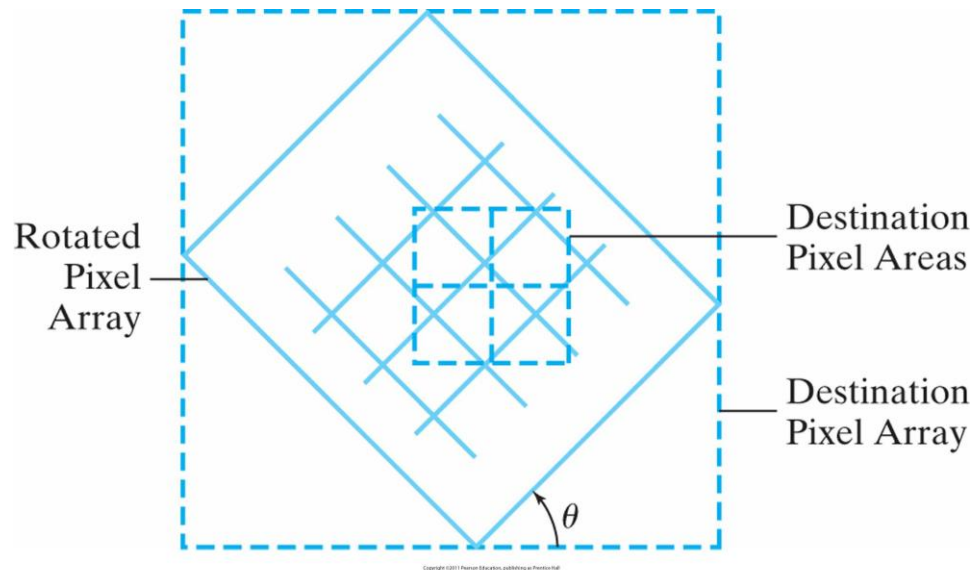


FIGURE 3.2

Raster Graphics Transformations

- These are accomplished by either translating, rotating or scaling an entire array of pixels e.g.



OpenGL Raster Primitive examples among others:-

- `glCopyPixels`
- `glDrawPixels`
- `glReadPixels`
- `glPixelZoom`

3D Transformations

- Main difference is presence of 3rd dimension z but same transformations apply with same methods but a few unique to 3D come into play

T A B L E 7 - 1**Summary of OpenGL Geometric Transformation Functions**

Function	Description
<code>glTranslate*</code>	Specifies translation parameters.
<code>glRotate*</code>	Specifies parameters for rotation about any axis through the origin.
<code>glScale*</code>	Specifies scaling parameters with respect to coordinate origin.
<code>glMatrixMode</code>	Specifies current matrix for geometric-viewing transformations, projection transformations, texture transformations, or color transformations.
<code>glLoadIdentity</code>	Sets current matrix to identity.
<code>glLoadMatrix* (elems);</code>	Sets elements of current matrix.
<code>glMultMatrix* (elems);</code>	Postmultiplies the current matrix by the specified matrix.
<code>glPixelZoom</code>	Specifies two-dimensional scaling parameters for raster operations.